

Processor Power Management Subsystem

DESCRIPTION

The WM8326 is an integrated power-management subsystem which provides a cost-effective, flexible, single-chip solution for power management. It is specifically targeted at the requirements of a range of low-power portable consumer products, but is suitable to any application with a multimedia processor. The WM8326 is designed to operate as a system PMIC supporting the ARM9[™], ARM11[™] and ARM Cortex-A[™] processors, but is also capable of supporting the majority of application and mobile processors at the heart of a wide range of low-power consumer multimedia applications.

The start-up behaviour and configuration is fully programmable in an integrated OTP non-volatile memory. This highly flexible solution helps reduce time-to-market, as changing application requirements can be very easily accommodated in the OTP. The InstantConfig[™] interface enables an external EEPROM to configure the WM8326.

The WM8326 power management subsystem comprises four programmable DC-DC converters and eleven LDO regulators (four of which are low-noise for supplying sensitive analogue subsystems). The integrated OTP bootstrap circuitry controls the start-up sequencing and voltages of the converters and regulators as well as the sequencing of system clocks.

The DC-DC converters deliver high performance and high efficiency across a wide range of operating conditions. They are optimised to support the high load current transients seen in modern processor core domains. DC-DC3 / DC-DC4 can be connected together and operated in 'dual' mode to support an increased current load of up to 1.6A.

An on-chip regulator provides power for always-on PMIC functions such as register map and the RTC. The device provides autonomous backup battery switchover. A low-power LDO is included to support 'Alive' processor power domains external to the WM8326.

A 12-bit Auxiliary ADC supports a wide range of applications for internal as well as external analogue sampling, such as voltage detection and temperature measurement.

WM8326 includes a crystal oscillator and an internal RC oscillator to generate all clock signals for autonomous system start-up and processor clocking. A Secure Real-time Clock (S-RTC) and alarm function is included, capable of waking up the system from low-power modes. A watchdog function is provided to ensure system integrity.

To maximise battery life, highly-granular power management enables each function in the WM8326 subsystem to be independently powered down through a control interface or alternatively through register and OTP-configurable GPIOs. The device offers a standby power consumption of <7uA, making it particularly suitable for portable applications.

The WM8326 is supplied in an 8x8mm 81-lead QFN package, ideal for use in portable systems. The WM8326 forms part of the Wolfson series of audio and power management solutions, and is widely register compatible with the WM831X devices.

FEATURES

Power Management

- 2 x DC-DC synchronous buck converters (0.6V - 1.8V, 2.5A, DVS)
- 2 x DC-DC synchronous buck converters (0.85V - 3.4V, 1A)
- 1 x LDO regulator (0.9V - 3.3V, 300mA, 1 Ω)
- 2 x LDO regulators (0.9V - 3.3V, 200mA, 1 Ω)
- 3 x LDO regulators (0.9V - 3.3V, 100mA, 2 Ω)
- 2 x Low-noise LDO regulators (1.0V - 3.5V, 200mA, 1 Ω)
- 2 x Low-noise LDO regulators (1.0V - 3.5V, 150mA, 2 Ω)
- 1 x 'Alive' regulator (0.8V - 1.55V, up to 25mA)

System Control

- I²C or SPI compatible primary control interface
- Comprehensive interrupt scheme
- Watchdog timer and system reset control
- Autonomous power sequencing and fault detection
- OTP memory bootstrap configuration function

Additional Features

- Auxiliary ADC for multi-function analogue measurement
- 128-bit pseudo-random unique ID
- Secure Real-Time Clock with wake-up alarm
- 12 x configurable multi-function (GPIO) pins
- Comprehensive clocking scheme: low-power 32kHz RTC crystal oscillator, GPIO clock output and 4MHz RC clock for power management
- System LED outputs indicating device power state, and fault status

Package Options

- 8 x 8 x 0.85mm, 81-lead QFN package

APPLICATIONS

- Cellular Handsets
- Smartphones
- Electronic Books
- Portable Media Players
- Mobile Internet Devices
- Electronic Gaming Devices
- Netbooks
- Smartbooks
- Set Top Box
- Digital Picture Frames

TYPICAL APPLICATIONS

The WM8326 is designed as a system PMIC device that generates configurable DC supplies to power processors and associated peripherals within a system. The WM8326 provides four DC-DC synchronous buck (step-down) converters. Two of these can operate in dual mode, providing an increased current capability. Eleven LDO regulators provide a high degree of flexibility to provide power to multiple devices, with the capability to power-up and power-down different circuits independently.

Two of the DC-DC buck converters incorporate Wolfson's BuckWise™ technology specifically designed to handle rapid changes in load current; programmable slew rate DVS is also provided, as required by modern application processors. Selectable operating modes on all of the DC-DC converters allow each converter to be optimally configured for light, heavy or transient load conditions. Flexible operating configurations allow the converters to be tailored for minimum PCB area, maximum performance, or for maximum efficiency. The analogue LDOs provide low-noise outputs suitable for powering sensitive circuits such as RF / Wi-Fi / cellular handset applications.

The WM8326 powers up the converters and LDOs according to a programmable sequence. A configurable 'SLEEP' state is also available, providing support for an alternate configuration, typically for low-power / standby operation. The power control sequences and many other parameters can be stored in an integrated user-configurable OTP (One-Time Programmable) memory or may be loaded from an external memory. The WM8326 supports the programming and verification of the integrated OTP memory.

A backup battery supply can be connected to the WM8326 in order to maintain the Real Time Clock (RTC) in the absence of the primary supply.

Programmable GPIO pins may be configured as hardware inputs for general use or for selecting different power management configurations. As outputs, the GPIOs can provide indications of the device status, or may be used as control signals for other power management circuits. The WM8326 also provides two LED drivers, which can be controlled manually or configured as status indicators for the OTP memory programmer or operating power state.

TABLE OF CONTENTS

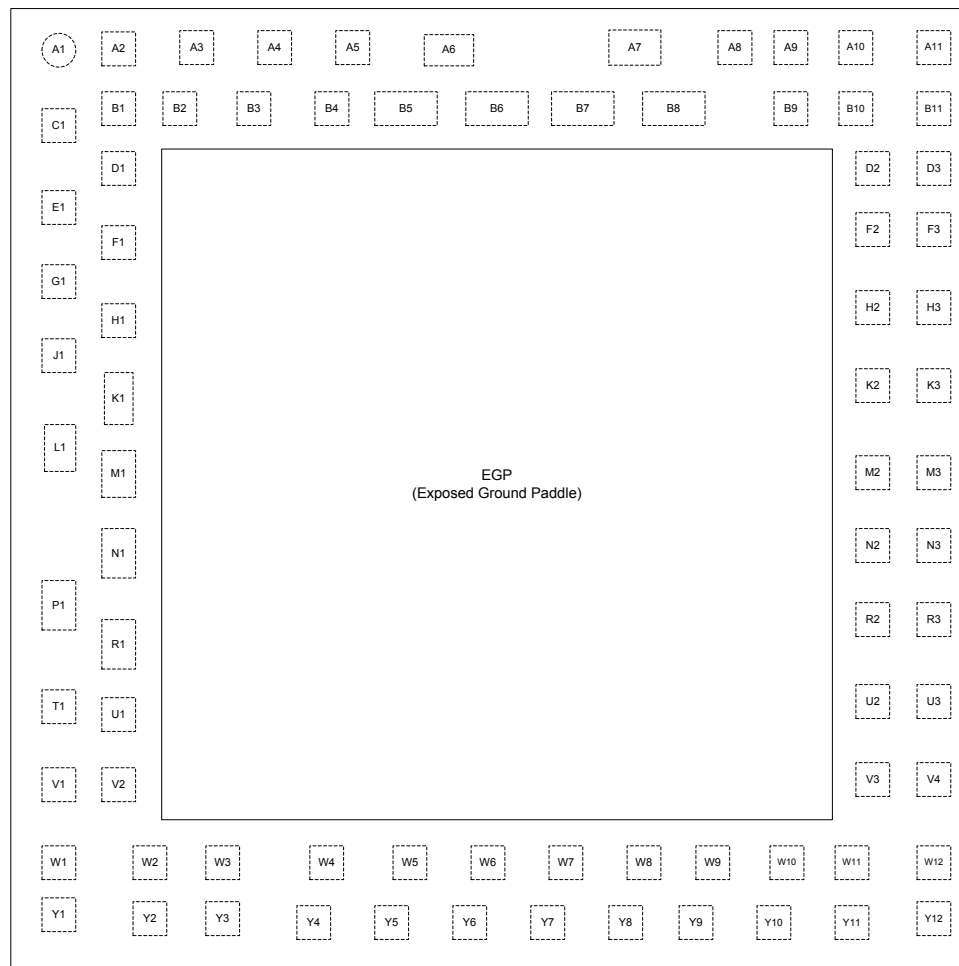
DESCRIPTION.....	1
FEATURES.....	1
APPLICATIONS.....	1
BLOCK DIAGRAM	2
TYPICAL APPLICATIONS	3
TABLE OF CONTENTS.....	4
1 PIN CONFIGURATION.....	8
2 ORDERING INFORMATION	8
3 PIN DESCRIPTION	9
4 THERMAL CHARACTERISTICS	13
5 ABSOLUTE MAXIMUM RATINGS.....	14
6 RECOMMENDED OPERATING CONDITIONS	15
7 ELECTRICAL CHARACTERISTICS	16
7.1 DC-DC SYNCHRONOUS BUCK CONVERTERS	16
7.2 LDO REGULATORS.....	18
7.3 RESET THRESHOLDS	22
7.4 REFERENCES	22
7.5 GENERAL PURPOSE INPUTS / OUTPUTS (GPIO).....	23
7.6 DIGITAL INTERFACES	24
7.7 AUXILIARY ADC.....	24
7.8 SYSTEM STATUS LED DRIVERS	24
8 TYPICAL POWER CONSUMPTION	25
9 TYPICAL PERFORMANCE DATA.....	26
9.1 DC-DC CONVERTERS	26
9.2 LDO REGULATORS.....	26
10 SIGNAL TIMING REQUIREMENTS	27
10.1 CONTROL INTERFACE.....	27
11 DEVICE DESCRIPTION	29
11.1 GENERAL DESCRIPTION	29
11.2 POWER STATES	29
11.3 POWER STATE CONTROL	31
11.4 POWER STATE INTERRUPTS.....	36
11.5 POWER STATE GPIO INDICATION	36
11.6 ON PIN FUNCTION.....	37
11.7 RESET PIN FUNCTION	38
12 CONTROL INTERFACE.....	40
12.1 GENERAL DESCRIPTION	40
12.2 2-WIRE (I2C) CONTROL MODE	40
12.3 4-WIRE (SPI) CONTROL MODE.....	43
12.4 REGISTER LOCKING	43
12.5 SOFTWARE RESET AND CHIP ID.....	44
12.6 SOFTWARE SCRATCH REGISTER.....	44
13 CLOCKING AND OSCILLATOR CONTROL	45
13.1 GENERAL DESCRIPTION	45
13.2 CRYSTAL OSCILLATOR INTERRUPTS	47
13.3 CRYSTAL OSCILLATOR CONNECTIONS.....	48
14 INSTANTCONFIG™ (ICE) AND OTP MEMORY CONTROL.....	49

14.1	GENERAL DESCRIPTION	49
14.2	ICE AND OTP MEMORY DEFINITION	49
14.3	BOOTSTRAP (START-UP) FUNCTION.....	50
14.3.1	START-UP FROM OTP MEMORY	50
14.3.2	START-UP FROM ICE MEMORY (DEVELOPMENT MODE).....	51
14.3.3	START-UP FROM DCRW REGISTER SETTINGS	51
14.3.4	EXTERNAL ICE MEMORY CONNECTION	51
14.4	OTP / ICE MEMORY CONTROL.....	52
14.4.1	ENTERING / EXITING THE PROGRAM STATE	53
14.4.2	OTP / ICE READ COMMAND	53
14.4.3	OTP WRITE COMMAND	54
14.4.4	OTP VERIFY COMMAND	54
14.4.5	OTP FINALISE COMMAND	55
14.4.6	OTP CONTROL REGISTER.....	55
14.5	OTP / ICE INTERRUPTS	57
14.6	DCRW MEMORY CONTENTS.....	57
14.6.1	DCRW PAGE 0	57
14.6.2	DCRW PAGE 1	58
14.6.3	DCRW PAGE 2	58
14.6.4	DCRW PAGE 3	59
14.6.5	DCRW PAGE 4	61
15	POWER MANAGEMENT	62
15.1	GENERAL DESCRIPTION	62
15.2	DC-DC CONVERTER AND LDO REGULATOR ENABLE	62
15.3	TIMESLOT CONTROL AND HARDWARE ENABLE (GPIO) CONTROL.....	63
15.4	OPERATING MODE CONTROL	64
15.4.1	DC-DC SYNCHRONOUS BUCK CONVERTERS.....	64
15.4.2	LDO REGULATORS	64
15.5	OUTPUT VOLTAGE CONTROL	64
15.5.1	DC-DC SYNCHRONOUS BUCK CONVERTERS.....	64
15.5.2	LDO REGULATORS 1-10	65
15.5.3	LDO REGULATOR 11.....	65
15.6	DC-DC SYNCHRONOUS BUCK CONVERTER CONTROL.....	65
15.6.1	DC-DC3 / DC-DC4 DUAL MODE	66
15.7	LDO REGULATOR CONTROL	67
15.8	HARDWARE CONTROL (GPIO).....	67
15.9	FAULT PROTECTION.....	68
15.10	MONITORING AND FAULT REPORTING	68
15.11	POWER MANAGEMENT REGISTER DEFINITIONS	69
15.11.1	DC-DC CONVERTER AND LDO REGULATOR ENABLE	69
15.11.2	DC-DC SYNCHRONOUS BUCK CONVERTER CONTROL.....	69
15.11.3	LDO REGULATOR CONTROL	76
15.11.4	EXTERNAL POWER ENABLE (EPE) CONTROL.....	84
15.11.5	MONITORING AND FAULT REPORTING.....	85
15.12	POWER MANAGEMENT INTERRUPTS	86
15.13	POWER GOOD INDICATION	88
15.14	DC-DC SYNCHRONOUS BUCK CONVERTER OPERATION	90
15.14.1	OVERVIEW.....	90
15.14.2	DC-DC SYNCHRONOUS BUCK CONVERTERS.....	90
15.15	LDO REGULATOR OPERATION.....	94
15.15.1	OVERVIEW.....	94
15.15.2	LDO REGULATORS	95
16	RESERVED	96
17	POWER SUPPLY CONTROL	97

17.1	GENERAL DESCRIPTION	97
17.2	POWER PATH MANAGEMENT INTERRUPTS	97
17.3	BACKUP POWER	97
18	AUXILIARY ADC	98
18.1	GENERAL DESCRIPTION	98
18.2	AUXADC CONTROL	98
18.3	AUXADC READBACK	99
18.4	DIGITAL COMPARATORS	101
18.5	AUXADC INTERRUPTS	103
19	RESERVED	104
20	REAL-TIME CLOCK (RTC)	105
20.1	GENERAL DESCRIPTION	105
20.2	RTC CONTROL	105
20.3	RTC INTERRUPTS	107
20.4	DIGITAL RIGHTS MANAGEMENT	108
20.5	BACKUP MODE CLOCKING OPTIONS	108
21	GENERAL PURPOSE INPUTS / OUTPUTS (GPIO)	109
21.1	GENERAL DESCRIPTION	109
21.2	GPIO FUNCTIONS	109
21.3	CONFIGURING GPIO PINS	111
21.4	GPIO INTERRUPTS	115
22	SYSTEM STATUS LED DRIVERS	116
22.1	GENERAL DESCRIPTION	116
22.2	LED DRIVER CONTROL	116
22.2.1	OTP PROGAM STATUS	116
22.2.2	POWER STATE STATUS	117
22.2.3	MANUAL MODE	117
22.3	LED DRIVER CONNECTIONS	119
23	INTERRUPT CONTROLLER	120
23.1	PRIMARY INTERRUPTS	121
23.2	SECONDARY INTERRUPTS	123
23.2.1	POWER STATE INTERRUPT	123
23.2.2	THERMAL INTERRUPTS	123
23.2.3	GPIO INTERRUPTS	124
23.2.4	ON PIN INTERRUPTS	124
23.2.5	WATCHDOG INTERRUPTS	125
23.2.6	AUXADC INTERRUPTS	125
23.2.7	POWER PATH MANAGEMENT INTERRUPTS	126
23.2.8	REAL TIME CLOCK AND CRYSTAL OSCILLATOR INTERRUPTS	126
23.2.9	OTP MEMORY INTERRUPTS	127
23.2.10	HIGH CURRENT INTERRUPTS	127
23.2.11	UNDERVOLTAGE INTERRUPTS	128
24	RESETS AND SUPPLY VOLTAGE MONITORING	129
24.1	RESETS	129
24.2	HARDWARE RESET	131
24.3	SOFTWARE RESET	131
24.4	SUPPLY VOLTAGE MONITORING	133
25	WATCHDOG TIMER	135
26	TEMPERATURE SENSING	137
27	VOLTAGE AND CURRENT REFERENCES	138
27.1	VOLTAGE REFERENCE (VREF)	138
27.2	CURRENT REFERENCE (IREF)	138

28	REGISTER MAP OVERVIEW	139
29	REGISTER BITS BY ADDRESS	146
30	APPLICATIONS INFORMATION	247
30.1	TYPICAL CONNECTIONS	247
30.2	VOLTAGE AND CURRENT REFERENCE COMPONENTS	248
30.3	DC-DC BUCK CONVERTER EXTERNAL COMPONENTS	248
30.3.1	DC-DC3 / DC-DC4 DUAL MODE	250
30.4	LDO REGULATOR EXTERNAL COMPONENTS	251
30.5	PCB LAYOUT	252
31	PACKAGE DIAGRAM	253
32	IMPORTANT NOTICE	254
33	REVISION HISTORY	255

1 PIN CONFIGURATION



Top View – WM8326

2 ORDERING INFORMATION

ORDER CODE	OTP	TEMPERATURE RANGE (T _A)	PACKAGE	MOISTURE SENSITIVITY LEVEL	PEAK SOLDERING TEMPERATURE
WM8326GEFL/V	Unprogrammed	-40°C to +85°C	81-lead QFN (8 x 8mm) (Pb-free)	MSL3	260°C
WM8326GEFL/RV	Unprogrammed	-40°C to +85°C	81-lead QFN (8 x 8mm) (Pb-free, tape and reel)	MSL3	260°C
WM8326GEFLxxx/RV*	Custom	-40°C to +85°C	81-lead QFN (8 x 8mm) (Pb-free, tape and reel) **	MSL3	260°C

Note:

Reel quantity = 2200

* xxx = Unique OTP part number

** Custom OTP minimum order quantity 22,000.

3 PIN DESCRIPTION

Notes:

1. Pins are sorted by functional groups.
2. The power domain associated with each pin is noted; VPMIC is the domain powered by LDO12 for the 'always-on' functions internal to the WM8326.
3. Note that an external level-shifter may be required when interfacing between different power domains.

PIN	NAME	TYPE	POWER DOMAIN	DESCRIPTION
Clocking and Real Time Clock				
Y12	XT0	Analogue Output	VPMIC	Crystal Drive Output
Y11	XTI	Analogue Input		Crystal Drive Input or 32.768kHz CMOS Clock Input
W11	XOSCGND	Supply		Crystal Oscillator Ground
H1	CLKOUT	Digital Output	DBVDD	CMOS Clock Output Configurable Open Drain / CMOS mode. (External 4.7kΩ pull-up recommended in Open Drain mode.)
General Purpose Input / Output and Auxiliary ADC				
D3	GPIO1	Digital I/O	DBVDDor VPMIC	GPIO Pin 1 Selectable pull-up/pull-down.
F2	GPIO2	Digital I/O		GPIO Pin 2 Selectable pull-up/pull-down.
F3	GPIO3	Digital I/O		GPIO Pin 3 Selectable pull-up/pull-down.
W4	GPIO4	Digital I/O	DBVDDor PVDD	GPIO Pin 4 Selectable pull-up/pull-down.
Y4	GPIO5	Digital I/O		GPIO Pin 5 Selectable pull-up/pull-down.
W5	GPIO6	Digital I/O		GPIO Pin 6 Selectable pull-up/pull-down.
H2	GPIO7	Digital I/O	DBVDDor VPMIC	GPIO Pin 7 Selectable pull-up/pull-down.
H3	GPIO8	Digital I/O		GPIO Pin 8 Selectable pull-up/pull-down.
K3	GPIO9	Digital I/O		GPIO Pin 9 Selectable pull-up/pull-down.
Y5	GPIO10	Digital I/O	DBVDDor PVDD	GPIO Pin 10 / Auxiliary ADC input Selectable GPIO pull-up/pull-down.
Y6	GPIO11	Digital I/O		GPIO Pin 11 / Auxiliary ADC input Selectable GPIO pull-up/pull-down.
W6	GPIO12	Digital I/O		GPIO Pin 12 / Auxiliary ADC input Selectable GPIO pull-up/pull-down.

PIN	NAME	TYPE	POWER DOMAIN	DESCRIPTION	
Processor Interface and IC Control					
W9	$\overline{\text{ON}}$	Digital Input	VPMIC	ON Request Pin (Internal pull-up)	
B10	$\overline{\text{RESET}}$	Digital I/O	DBVDD	System Reset Input and Open Drain Output. (Internal pull-up)	
A11	$\overline{\text{IRQ}}$	Digital Output	DBVDD	PMIC Interrupt Flag Output. Configurable Open Drain / CMOS mode. (Internal pull-up in Open Drain mode.)	
E1	CIFMODE	Digital Input	DBVDD	Primary Control Interface Mode Select: 0 = I ² C Compatible Control Interface Mode 1 = SPI Compatible Control Interface Mode	
				SPI Compatible Control Interface Mode	I ² C Compatible Control Interface Mode
D2	SDOUT1	Digital Output	DBVDD	Control Interface Serial Data Out. Open Drain output; external 4.7kΩ pull-up recommended.	No Function
B9	SCLK1	Digital Input		Control Interface Serial Clock	Control Interface Serial Clock
A9	SDA1	Digital I/O		Control Interface Serial Data In	Control Interface Serial Data Input and Open Drain Output. External 4.7kΩ pull-up recommended. (Output can extend above DBVDD domain.)
A10	$\overline{\text{CS}}$	Digital Input		Control Interface Chip Select	I ² C Address Select: 0 = 68h 1 = 6Ch
Y10	SCLK2	Digital I/O	VPMIC	Control Interface Serial Clock for external InstantConfig™ EEPROM (ICE) (Internal pull-down)	
W10	SDA2	Digital I/O		Control Interface Serial Data to/from external InstantConfig™ EEPROM (ICE) (Internal pull-down)	
B11	DBVDD1	Supply		Digital Buffer Supply	
F1	DBVDD2	Supply		Digital Buffer Supply	
OTP Memory					
Y3	PROGVDD	Supply		High-voltage input for OTP programming.	

PIN	NAME	TYPE	POWER DOMAIN	DESCRIPTION
DC-DC Converters and LDO Regulators				
B7	DC1GND	Supply	DC1VDD	DC-DC1 Power Ground
A8	DC1FB	Analogue Input		DC-DC1 Feedback Pin
A7	DC1LX	Analogue I/O		DC-DC1 Inductor Connection
B8	DC1VDD	Supply		DC-DC1 Power Input (connect to PVDD system supply)
B6	DC2GND	Supply	DC2VDD	DC-DC2 Power Ground
A5	DC2FB	Analogue Input		DC-DC2 Feedback Pin
A6	DC2LX	Analogue I/O		DC-DC2 Inductor Connection
B5	DC2VDD	Supply		DC-DC2 Power Input (connect to PVDD system supply)
M1	DC3GND	Supply	DC3VDD	DC-DC3 Power Ground
J1	DC3FB	Analogue Input		DC-DC3 Feedback Pin
L1	DC3LX	Analogue I/O		DC-DC3 Inductor Connection
K1	DC3VDD	Supply		DC-DC3 Power Input (connect to PVDD system supply)
N1	DC4GND	Supply	DC4VDD	DC-DC4 Power Ground
T1	DC4FB	Analogue Input		DC-DC4 Feedback Pin
P1	DC4LX	Analogue I/O		DC-DC4 Inductor Connection
R1	DC4VDD	Supply		DC-DC4 Power Input (connect to PVDD system supply)
A3	LDO1_2VDD	Supply		LDO1 & LDO2 Power Input
B2	LDO1VOUT	Analogue Output	LDO1VDD	LDO1 Power Output
B3	LDO2VOUT	Analogue Output	LDO2VDD	LDO2 Power Output
B4	LDO3VDD	Supply		LDO3 Power Input
A4	LDO3VOUT	Analogue Output	LDO3VDD	LDO3 Power Output
W3	LDO4VDD	Supply		LDO4 Power Input
Y2	LDO4VOUT	Analogue Output	LDO4VDD	LDO4 Power Output
Y1	LDO5VDD	Supply		LDO5 Power Input
W2	LDO5VOUT	Analogue Output	LDO5VDD	LDO5 Power Output
W1	LDO6VDD	Supply		LDO6 Power Input
V1	LDO6VOUT	Analogue Output	LDO6VDD	LDO6 Power Output
R3	LDO7_8VDD	Supply		LDO7 & LDO8 Power Input
N2	LDO7VOUT	Analogue Output	LDO7VDD	LDO7 Power Output
R2	LDO8VOUT	Analogue Output	LDO8VDD	LDO8 Power Output
M2	LDO9_10VDD	Supply		LDO9 Power Input
M3	LDO9VOUT	Analogue Output	LDO9VDD	LDO9 Power Output
N3	LDO10VOUT	Analogue Output	LDO10VDD	LDO10 Power Output
V3	LDO11VOUT	Analogue Output	PVDD	LDO11 (Alive) Power Output
Y8	LDO12VOUT	Analogue I/O	PVDD	LDO12 (Internal VPMIC) Output; Backup battery supply input / output
W7	LDO13VOUT1	Analogue I/O	PVDD	LDO13 (Internal INTVDD) Output; not for general use
K2	LDO13VOUT2	Analogue I/O	PVDD	LDO13 - Connect to LDO13VOUT1 (W7)
Voltage and Current References				
W8	VREFC	Analogue I/O	VPMIC	Voltage Reference capacitor connection point
Y9	IREFR	Analogue I/O		Current Reference resistor connection point
System LED Drivers				
U3	LED1	Digital Output	PVDD	Status LED Driver 1. Open Drain Output
U2	LED2	Digital Output		Status LED Driver 2. Open Drain Output

PIN	NAME	TYPE	POWER DOMAIN	DESCRIPTION
System Power				
U1	PVDD1	Supply		System VDD Supply
Y7	PVDD2	Supply		System VDD Supply
V4	PVDD3	Supply		System VDD Supply
EGP	Exposed Ground Paddle	Analogue Ground		Ground
Miscellaneous				
A1, A2, B1, C1, D1, V2, W12	DNC			Do Not Connect
G1, W12	TEST			Test function (connect to GND)

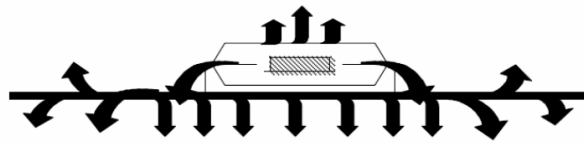
4 THERMAL CHARACTERISTICS

Thermal analysis must be performed in the intended application to prevent the WM8326 from exceeding maximum junction temperature. Several contributing factors affect thermal performance most notably the physical properties of the mechanical enclosure, location of the device on the PCB in relation to surrounding components and the number of PCB layers. Connecting the GND balls through thermal vias and into a large ground plane will aid heat extraction.

Three main heat transfer paths exist to surrounding air:

- Package top to air (convection and radiation).
- Package bottom to PCB (convection and radiation).
- Package leads to PCB (conduction).

(Note that radiation is not normally significant at the moderate temperatures experienced in typical applications.)



The temperature rise T_R is given by $T_R = P_D \cdot \Theta_{JA}$

- P_D is the power dissipated by the device.
- Θ_{JA} is the thermal resistance from the junction of the die to the ambient temperature and is therefore a measure of heat transfer from the die to surrounding air.
- For WM8326, $\Theta_{JA} = 24^\circ\text{C/W}$
- The quoted Θ_{JA} is based on testing to the EIA/JEDEC-51-2 test environment (ie. 1ft³ box, still air, with specific PCB stack-up and tracking rules). Note that this is not guaranteed to reflect all typical end applications.

The junction temperature T_J is given by $T_J = T_A + T_R$

- T_A , is the ambient temperature.

The worst case conditions are when the WM8326 is operating in a high ambient temperature, and under conditions which cause high power dissipation, such as the DC-DC converters operating at low supply voltage, high duty cycle and high output current. Under such conditions, it is possible that the heat dissipated could cause the maximum junction temperature of the device to be exceeded. Care must be taken to avoid this situation. An example calculation of the junction temperature is given below.

- $P_D = 500\text{mW}$ (example figure)
- $\Theta_{JA} = 24^\circ\text{C/W}$
- $T_R = P_D \cdot \Theta_{JA} = 12^\circ\text{C}$
- $T_A = 85^\circ\text{C}$ (example figure)
- $T_J = T_A + T_R = 97^\circ\text{C}$

The minimum and maximum operating junction temperatures for the WM8326 are quoted in Section 5. The maximum junction temperature is 125°C . Therefore, the junction temperature in the above example is within the operating limits of the WM8326.

5 ABSOLUTE MAXIMUM RATINGS

Absolute Maximum Ratings are stress ratings only. Permanent damage to the device may be caused by continuously operating at or beyond these limits. Device functional operating limits and guaranteed performance specifications are given under Electrical Characteristics at the test conditions specified.



ESD Sensitive Device. This device is manufactured on a CMOS process. It is therefore generically susceptible to damage from excessive static voltages. Proper ESD precautions must be taken during handling and storage of this device.

Wolfson tests its package types according to IPC/JEDEC J-STD-020B for Moisture Sensitivity to determine acceptable storage conditions prior to surface mount assembly. These levels are:

MSL1 = unlimited floor life at <30°C / 85% Relative Humidity. Not normally stored in moisture barrier bag.

MSL2 = out of bag storage for 1 year at <30°C / 60% Relative Humidity. Supplied in moisture barrier bag.

MSL3 = out of bag storage for 168 hours at <30°C / 60% Relative Humidity. Supplied in moisture barrier bag.

The WM8326 has been classified as MSL3.

CONDITION	MIN	MAX
OTP Programming Supply (PROGVDD)	-0.3V	7.0V
System supply (PVDD1, PVDD2, PVDD3)	-0.3V	7.0V
Input voltage for LDO regulators	-0.3V	7.0V
Input voltage for DC-DC converters	-0.3V	7.0V
Digital buffer supply (DBVDD1, DBVDD2)	-0.3V	4.5V
Voltage range for digital inputs	-0.3V	DBVDD + 0.3V
Operating Temperature Range, T _A	-40°C	+85°C
Junction Temperature, T _J	-40°C	+125°C
Thermal Impedance Junction to Ambient, θ _{JA}		24°C/W
Storage temperature prior to soldering	30°C max / 60% RH max	
Storage temperature after soldering	-65°C	+150°C
Soldering temperature (10 seconds)		+260°C
Note: These ratings assume that all ground pins are at 0V.		

6 RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS
System power source	PVDD1, PVDD2, PVDD3	2.7		5.5	V
Digital buffer supply	DBVDD1, DBVDD2	1.71		3.6	V
OTP Programming Supply (see note)	PROGVDD	6.25	6.5	6.75	V
	LDO12VOUT		3.3		V
Ground	Exposed Ground Paddle (EGP), DC1GND, DC2GND, DC3GND, DC4GND, XOSCGND		0		V

Note:

The OTP Programming Supply PROGVDD should only be present when programming the OTP. At other times, this pin should be left unconnected. The LDO12VOUT must be overdriven by an external supply when programming the OTP. At other times, the voltage at this pin is driven by the internal circuits of the WM8326.

7 ELECTRICAL CHARACTERISTICS

7.1 DC-DC SYNCHRONOUS BUCK CONVERTERS

DC-DC1 and DC-DC2

Unless otherwise noted: $V_{IN} = 3.8V$, $V_{OUT} = 1.2V$, MODE = FCCM⁽¹⁾, $T_J = -40^{\circ}C$ to $+125^{\circ}C$; typical values are at $T_J = 25^{\circ}C$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage	V_{IN}		2.7		5.5	V
Programmable Output Voltage	V_{OUT}	$F_{SW} = 2MHz$	0.6		1.8	V
		$F_{SW} = 4MHz$	0.6		1.4	
V_{OUT} Step Size	V_{OUT_STEP}			12.5		mV
V_{OUT} Accuracy	V_{OUT_ACC}	$V_{IN} = 2.7V$ to $5.5V$, $I_{OUT} = 0mA$ to $2500mA$	-2.5		+2.5	%
Undervoltage margin	V_{UV}	$0.6V \leq V_{OUT} < 0.9V$		50		mV
		$0.9V \leq V_{OUT} < 1.3V$		80		
		$1.3V \leq V_{OUT} \leq 1.8V$		100		
Overvoltage margin	V_{OV}	$0.6V \leq V_{OUT} \leq 1.8V$		100		mV
Output Current	I_{OUT}	FCCM ⁽¹⁾ and Auto (CCM/DCM with PS ⁽²⁾) Modes	$F_{SW} = 2MHz$	0	2500	mA
			$F_{SW} = 4MHz$	0	1250	
		Hysteretic Mode		0	150	
		LDO Mode		0	10	
P-channel Current Limit	I_{P_LIM}			3650		mA
Quiescent Current	I_Q	$I_{OUT} = 0mA$, FCCM ⁽¹⁾ and Auto (CCM/DCM with PS ⁽²⁾) Modes (excluding switching losses)		585		μA
		$I_{OUT} = 0mA$, Hysteretic Mode		100		
		$I_{OUT} = 0mA$, LDO Mode		25		
Shutdown Current	I_{SD}	$DCM_ENA = 0$		0.01		μA
P-channel On Resistance	R_{DSP}	$V_{IN} = V_{GS} = 3.8V$, $I_{DCMLX} = 100mA$		115		$m\Omega$
N-channel On Resistance	R_{DSN}	$V_{IN} = V_{GS} = 3.8V$, $I_{DCMLX} = -100mA$		105		$m\Omega$
Switching Frequency	F_{SW}	$DCM_FREQ = 01$		2		MHz
		$DCM_FREQ = 10$		4		

Notes:

1. Forced Continuous Conduction Mode
2. Continuous / Discontinuous Conduction with Pulse-Skipping Mode

DC-DC3 and DC-DC4

Unless otherwise noted: $V_{IN} = 3.8V$, $V_{OUT} = 1.8V$, MODE = FCCM⁽¹⁾, $T_J = -40^{\circ}C$ to $+125^{\circ}C$; typical values are at $T_J = 25^{\circ}C$

PARAMETER	SYMBOL	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Input Voltage	V_{IN}			2.7		5.5	V
Programmable Output Voltage	V_{OUT}			0.85 ⁽⁴⁾		3.4	V
V_{OUT} Step Size	V_{OUT_STEP}				25		mV
V_{OUT} Accuracy	V_{OUT_ACC}	$V_{IN} = 2.7V$ to $5.5V$, $I_{OUT} = 0mA$ to $1000mA$		-4		+4	%
Undervoltage margin	V_{UV}	$0.85V \leq V_{OUT} \leq 3.4V$			50		mV
Output Current	I_{OUT}	FCCM ⁽¹⁾ and Auto (CCM/DCM with PS ⁽²⁾) Modes	Independent operation (DC4_SLV=0)	0		1000	mA
			Dual mode operation (DC4_SLV=1)	0		800 ⁽⁵⁾	
		Hysteretic Mode, DCm_STNBY_LIM=01		0		100 ⁽³⁾	
		LDO Mode		0		10	
P-channel Current Limit	I_{P_LIM}				1600		mA
Quiescent Current	I_Q	$I_{OUT} = 0mA$, FCCM ⁽¹⁾ and Auto (CCM/DCM with PS ⁽²⁾) Modes (excluding switching losses)			330		μA
		$I_{OUT} = 0mA$, Hysteretic Mode			110		
		$I_{OUT} = 0mA$, LDO Mode			20		
Shutdown Current	I_{SD}	DCm_ENA = 0			0.01		μA
P-channel On Resistance	R_{DSP}	$V_{IN} = V_{GS} = 3.8V$, $I_{DCmLX} = 100mA$			165		m Ω
N-channel On Resistance	R_{DSN}	$V_{IN} = V_{GS} = 3.8V$, $I_{DCmLX} = -100mA$			155		m Ω
Switching Frequency	F_{SW}				2		MHz

Notes:

1. Forced Continuous Conduction Mode
2. Continuous / Discontinuous Conduction with Pulse-Skipping Mode
3. The maximum output current in Hysteretic mode can be adjusted using the DCm_STNBY_LIM registers
4. In FCCM mode, the minimum V_{OUT} is 1.2V
5. In Dual mode operation, the ratings are 'per converter'. The combined maximum output current is 1600mA

7.2 LDO REGULATORS

LDO1

Unless otherwise noted: $V_{IN} = 3.8V$, $V_{OUT} = 1.8V$, $T_J = -40^{\circ}C$ to $+125^{\circ}C$; Typical values are at $T_J = +25^{\circ}C$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage	V _{IN}		1.5		5.5	V
Programmable Output Voltage	V _{OUT}		0.9		3.3	V
V _{OUT} Step Size	V _{OUT_STEP}	V _{OUT} = 0.9V to 1.6V		50		mV
		V _{OUT} = 1.7V to 3.3V		100		
Output Current	I _{OUT}	Normal mode	0		300	mA
		Low power mode, LDO _{n_LP_MODE} =0	0		50	
		Low power mode, LDO _{n_LP_MODE} =1	0		20	
V _{OUT} Accuracy	V _{OUT_ACC}	I _{LOAD} = 1mA	-3		+3	%
Line Regulation	V _{OUT LINE}	V _{IN} = (V _{OUT} + 0.5) to 5.5V, I _{LOAD} = 150mA Note that V _{IN} must be >= 1.5V		0.1		%/V
Load Regulation	V _{OUT LOAD}	I _{LOAD} =1mA to 300mA		0.011		%/mA
Dropout Voltage	V _{IN} - V _{OUT}	I _{LOAD} =150mA, V _{OUT} > 2.7V		250		mV
		I _{LOAD} =150mA, V _{OUT} 1.8V to 2.7V		300		
		I _{LOAD} =150mA, V _{OUT} < 1.8V		500		
Undervoltage level	V _{OUT}	V _{OUT} Falling		88		%
Quiescent Current	I _Q	Normal mode, no load		30		μA
		Low power mode, LDO _{n_LP_MODE} =0, no load		10		
		Low power mode, LDO _{n_LP_MODE} =1, no load		5		
		I _{LOAD} = 1mA to 300mA	I _Q (no load) + 1% of load			
Power Supply Rejection Ratio	PSRR	I _{LOAD} = 150mA, <= 1kHz		53		dB
		I _{LOAD} = 150mA, 10kHz		53		
		I _{LOAD} = 150mA, 100kHz		32		
On Resistance (Switch mode)	R _{DSON}	V _{IN} = 1.5V, I _{LOAD} = 100mA		1.5		Ω
		V _{IN} = 1.8V, I _{LOAD} = 100mA		1.2		
		V _{IN} = 2.5V, I _{LOAD} = 100mA		0.85		
		V _{IN} = 3.3V, I _{LOAD} = 100mA		0.7		
Current Limit (Switch mode)	I _{CL}	V _{OUT} = 0V		600		mA
Start-up time	t _{start_up}	No load, Output cap 2.2 μF, 90% of V _{OUT}		10		μs
Shutdown time	t _{shut_down}	No load, Output cap 2.2 μF, 10% of V _{OUT}			10	ms

LDO2, LDO3

Unless otherwise noted: $V_{IN} = 3.8V$, $V_{OUT} = 1.8V$, $T_J = -40^{\circ}C$ to $+125^{\circ}C$; Typical values are at $T_J = +25^{\circ}C$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage	V_{IN}		1.5		5.5	V
Programmable Output Voltage	V_{OUT}		0.9		3.3	V
V_{OUT} Step Size	V_{OUT_STEP}	$V_{OUT} = 0.9V$ to $1.6V$		50		mV
		$V_{OUT} = 1.7V$ to $3.3V$		100		
Output Current	I_{OUT}	Normal mode	0		200	mA
		Low power mode, $LDO_{n_LP_MODE}=0$	0		50	
		Low power mode, $LDO_{n_LP_MODE}=1$	0		20	
V_{OUT} Accuracy	V_{OUT_ACC}	$I_{LOAD} = 1mA$	-3		+3	%
Line Regulation	V_{OUT_LINE}	$V_{IN} = (V_{OUT} + 0.5)$ to $5.5V$, $I_{LOAD} = 100mA$ Note that V_{IN} must be $\geq 1.5V$		0.1		%/V
Load Regulation	V_{OUT_LOAD}	$I_{LOAD} = 1mA$ to $200mA$		0.011		%/mA

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Dropout Voltage	V _{IN} - V _{OUT}	I _{LOAD} =100mA, V _{OUT} > 2.7V		200		mV
		I _{LOAD} =100mA, V _{OUT} 1.8V to 2.7V		250		
		I _{LOAD} =100mA, V _{OUT} < 1.8V		400		
Undervoltage level	V _{OUT}	V _{OUT} Falling		88		%
Quiescent Current	I _Q	Normal mode, no load		30		μA
		Low power mode, LDO _n _LP_MODE=0, no load		10		
		Low power mode, LDO _n _LP_MODE=1, no load		5		
		I _{LOAD} = 1mA to 200mA	I _Q (no load) + 1% of load			
Power Supply Rejection Ratio	PSRR	I _{LOAD} = 100mA, <= 1kHz		55		dB
		I _{LOAD} = 100mA, 10kHz		55		
		I _{LOAD} = 100mA, 100kHz		32		
On Resistance (Switch mode)	R _{DS(on)}	V _{IN} = 1.5V, I _{LOAD} = 100mA		1.5		Ω
		V _{IN} = 1.8V, I _{LOAD} = 100mA		1.2		
		V _{IN} = 2.5V, I _{LOAD} = 100mA		0.85		
		V _{IN} = 3.3V, I _{LOAD} = 100mA		0.7		
Current Limit (Switch mode)	I _{CL}	V _{OUT} = 0V		400		mA
Start-up time	t _{start_up}	No load, Output cap 2.2 μF, 90% of V _{OUT}		10		μs
Shutdown time	t _{shut_down}	No load, Output cap 2.2 μF, 10% of V _{OUT}			10	ms

LDO4, LDO5, LDO6

Unless otherwise noted: $V_{IN} = 3.8V, V_{OUT} = 1.8V, T_J = -40^\circ C \text{ to } +125^\circ C$; Typical values are at $T_J = +25^\circ C$.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage	V _{IN}		1.5		5.5	V
Programmable Output Voltage	V _{OUT}		0.9		3.3	V
V _{OUT} Step Size	V _{OUT_STEP}	V _{OUT} = 0.9V to 1.6V		50		mV
		V _{OUT} = 1.7V to 3.3V		100		
Output Current	I _{OUT}	Normal mode	0		100	mA
		Low power mode, LDO _n _LP_MODE=0	0		50	
		Low power mode, LDO _n _LP_MODE=1	0		20	
V _{OUT} Accuracy	V _{OUT_ACC}	I _{LOAD} = 1mA	-3		+3	%
Line Regulation	V _{OUT_LINE}	V _{IN} = (V _{OUT} + 0.5) to 5.5V, I _{LOAD} = 50mA Note that V _{IN} must be >= 1.5V		0.1		%/V
Load Regulation	V _{OUT_LOAD}	I _{LOAD} =1mA to 100mA		0.022		%/mA
Dropout Voltage	V _{IN} - V _{OUT}	I _{LOAD} =100mA, V _{OUT} > 2.7V		200		mV
		I _{LOAD} =100mA, V _{OUT} 1.8V to 2.7V		250		
		I _{LOAD} =100mA, V _{OUT} < 1.8V		400		
Undervoltage level	V _{OUT}	V _{OUT} Falling		88		%
Quiescent Current	I _Q	Normal mode, no load		30		μA
		Low power mode, LDO _n _LP_MODE=0, no load		10		
		Low power mode, LDO _n _LP_MODE=1, no load		5		
		I _{LOAD} = 1mA to 100mA	I _Q (no load) + 1% of load			
Power Supply Rejection Ratio	PSRR	I _{LOAD} = 50mA, <= 1kHz		55		dB
		I _{LOAD} = 50mA, 10kHz		55		
		I _{LOAD} = 50mA, 100kHz		32		
On Resistance (Switch mode)	R _{DS(on)}	V _{IN} = 1.5V, I _{LOAD} = 100mA		3.2		Ω
		V _{IN} = 1.8V, I _{LOAD} = 100mA		2.1		
		V _{IN} = 2.5V, I _{LOAD} = 100mA		1.35		
		V _{IN} = 3.3V, I _{LOAD} = 100mA		1.1		

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Current Limit (Switch mode)	I_{CL}	$V_{OUT} = 0V$		230		mA
Start-up time	t_{start_up}	No load, Output cap 2.2 μF , 90% of V_{OUT}		10		μs
Shutdown time	t_{shut_down}	No load, Output cap 2.2 μF , 10% of V_{OUT}			10	ms

LDO7, LDO8

Unless otherwise noted: $V_{IN} = 3.8V$, $V_{OUT} = 1.8V$, $T_J = -40^{\circ}C$ to $+125^{\circ}C$; Typical values are at $T_J = +25^{\circ}C$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage	V _{IN}		1.71		5.5	V
Programmable Output Voltage	V _{OUT}		1.0		3.5	V
V _{OUT} Step Size	V _{OUT_STEP}	V _{OUT} = 1.0V to 1.6V		50		mV
		V _{OUT} = 1.7V to 3.5V		100		
Output Current	I _{OUT}	Normal mode	0		200	mA
		Low Power mode	0		50	
V _{OUT} Accuracy	V _{OUT_ACC}	I _{LOAD} = 1mA	-2.5		+2.5	%
Line Regulation	V _{OUT_LINE}	V _{IN} = (V _{OUT} + 0.5) to 5.5V, I _{LOAD} = 100mA Note that V _{IN} must be >= 1.71V		0.025		%/V
Load Regulation	V _{OUT_LOAD}	I _{LOAD} =1mA to 200mA		0.003		%/mA
Dropout Voltage	V _{IN} - V _{OUT}	I _{LOAD} =100mA, V _{OUT} =1.8V		95		mV
		I _{LOAD} =100mA, V _{OUT} =2.5V		65		
		I _{LOAD} =100mA, V _{OUT} =3.3V		60		
Undervoltage level	V _{OUT}	V _{OUT} Falling		93		%
Quiescent Current	I _Q	Normal mode, no load		110		μA
		Low Power mode, no load		70		
		I _{LOAD} = 1mA to 200mA	I _Q (no load) + 0.1% of load			
Power Supply Rejection Ratio	PSRR	I _{LOAD} = 100mA, <= 1kHz		70		dB
		I _{LOAD} = 100mA, 10kHz		67		
		I _{LOAD} = 100mA, 100kHz		48		
Output noise voltage	V _{OUT}	f=10Hz to 100kHz; V _{OUT} =2.8V, I _{LOAD} = 1mA		30		μV _{RMS}
		f=10Hz to 100kHz; V _{OUT} =2.8V, I _{LOAD} = 10mA		32		
		f=10Hz to 100kHz; V _{OUT} =2.8V, I _{LOAD} = 100mA		32		
On Resistance (Switch mode)	R _{DS(on)}	V _{IN} = 1.71V, I _{LOAD} = 100mA		550		mΩ
		V _{IN} = 1.8V, I _{LOAD} = 100mA		500		
		V _{IN} = 2.5V, I _{LOAD} = 100mA		330		
		V _{IN} = 3.5V, I _{LOAD} = 100mA		250		
Current Limit (Switch mode)	I _{CL}	V _{OUT} = 0V		320		mA
Start-up time	t _{start_up}	No load, Output cap 4.7 μF, 90% of V _{OUT}		50		μs
Shutdown time	t _{shut_down}	No load, Output cap 4.7 μF, 10% of V _{OUT}			10	ms

LDO9, LDO10

Unless otherwise noted: $V_{IN} = 3.8V$, $V_{OUT} = 1.8V$, $T_J = -40^{\circ}C$ to $+125^{\circ}C$; Typical values are at $T_J = +25^{\circ}C$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input Voltage	V_{IN}		1.71		5.5	V
Programmable Output Voltage	V_{OUT}		1.0		3.5	V
V_{OUT} Step Size	V_{OUT_STEP}	$V_{OUT} = 1.0V$ to $1.6V$		50		mV
		$V_{OUT} = 1.7V$ to $3.5V$		100		
Output Current	I_{OUT}	Normal mode	0		150	mA
		Low Power mode	0		50	

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{OUT} Accuracy	V _{OUT_ACC}	I _{LOAD} = 1mA	-2.5		+2.5	%
Line Regulation	V _{OUT LINE}	V _{IN} = (V _{OUT} + 0.5) to 5.5V, I _{LOAD} = 75mA Note that V _{IN} must be >= 1.71V		0.025		%/V
Load Regulation	V _{OUT LOAD}	I _{LOAD} =1mA to 150mA		0.004		%/mA
Dropout Voltage	V _{IN} - V _{OUT}	I _{LOAD} =100mA, V _{OUT} =1.8V		135		mV
		I _{LOAD} =100mA, V _{OUT} =2.5V		100		
		I _{LOAD} =100mA, V _{OUT} =3.3V		90		
Undervoltage level	V _{OUT}	V _{OUT} Falling		93		%
Quiescent Current	I _Q	Normal mode, no load		110		μA
		Low Power mode, no load		70		
		I _{LOAD} = 1mA to 150mA	I _Q (no load) + 0.1% of load			
Power Supply Rejection Ratio	PSRR	I _{LOAD} = 75mA, <= 1kHz		73		dB
		I _{LOAD} = 75mA, 10kHz		69		
		I _{LOAD} = 75mA, 100kHz		49		
Output noise voltage	V _{OUT}	f=10Hz to 100kHz; V _{OUT} =2.8V, I _{LOAD} = 1mA		30		μV _{RMS}
		f=10Hz to 100kHz; V _{OUT} =2.8V, I _{LOAD} = 10mA		32		
		f=10Hz to 100kHz; V _{OUT} =2.8V, I _{LOAD} = 100mA		32		
On Resistance (Switch mode)	R _{DS(ON)}	V _{IN} = 1.71V, I _{LOAD} = 100mA		1000		mΩ
		V _{IN} = 1.8V, I _{LOAD} = 100mA		930		
		V _{IN} = 2.5V, I _{LOAD} = 100mA		610		
		V _{IN} = 3.5V, I _{LOAD} = 100mA		430		
Current Limit (Switch mode)	I _{CL}	V _{OUT} = 0V		250		mA
Start-up time	t _{start_up}	No load, Output cap 4.7 μF, 90% of V _{OUT}		70		μs
Shutdown time	t _{shut_down}	No load, Output cap 4.7 μF, 10% of V _{OUT}			10	ms

LDO11

Unless otherwise noted: V_{IN} = 3.8V, V_{OUT} = 1.2V, T_J = -40°C to +125°C; Typical values are at T_J = +25°C

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Programmable Output Voltage	V _{OUT}		0.8		1.55	V
V _{OUT} Step Size	V _{OUT_STEP}			50		mV
Output Current	I _{OUT}	PVDD < 3.1V	0		10	mA
		PVDD ≥ 3.1V	0		25	
V _{OUT} Accuracy	V _{OUT}	V _{IN} = 2.7 to 5.5V; I _{LOAD} = 100μA	-4		+4	%
Line Regulation	V _{OUT_LINE}	V _{IN} = 2.7 to 5.5V; I _{LOAD} = 1mA		0.4		%/V
Load Regulation	V _{OUT_LOAD}	I _{LOAD} = 100μA to 10mA		0.2		%/mA
Quiescent Current	I _Q	No load		2.5		μA
Start-up time	t _{start_up}	No load, Output cap 0.1 μF, 90% of V _{OUT}		0.3	1	ms
Shutdown time	t _{shut_down}	No load, Output cap 0.1 μF, 10% of V _{OUT}		0.3	1	ms

7.3 RESET THRESHOLDS

Unless otherwise noted: $T_J = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$; Typical values are at $T_J = +25^{\circ}\text{C}$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Power On Reset						
Power on Reset threshold VPMIC (LDO12VOUT) voltage at which device transitions between NO POWER and BACKUP states	$V_{\text{POR, DE-ASSERT}}$	VPMIC rising		1.18		V
	$V_{\text{POR, ASSERT}}$	VPMIC falling		1.08		V
Power on Reset hysteresis	$V_{\text{POR, HYST}}$			100		mV
Device Reset Control						
Device Reset threshold VPMIC (LDO12VOUT) voltage at which device transitions between BACKUP and OFF states	$V_{\text{RES, DE-ASSERT}}$	VPMIC rising		1.89		V
	$V_{\text{RES, ASSERT}}$	VPMIC falling		1.80		V
Device Reset hysteresis	$V_{\text{RES, HYST}}$			90		mV
Device Shutdown						
Shutdown threshold PVDD voltage at which the device forces an OFF transition	V_{SHUTDOWN}	PVDD falling		2.7		V
SYSLO threshold accuracy PVDD voltage at which SYSLO is asserted.	V_{SYSLO}	PVDD falling, V_{SYSLO} set by SYSLO_THR (2.8V to 3.5V)	-3		+3	%
SYSOK threshold accuracy PVDD voltage at which SYSOK is asserted.	V_{SYSOK}	PVDD rising, V_{SYSOK} set by SYSOK_THR (2.8V to 3.5V) Note the SYSOK hysteresis margin ($V_{\text{SYSOK, HYST}}$) is added to SYSOK_THR.	-3		+3	%
SYSOK hysteresis	$V_{\text{SYSOK, HYST}}$			40		mV

7.4 REFERENCES

Unless otherwise noted: $T_J = +25^{\circ}\text{C}$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Voltage Reference	V_{VREFC}			0.8		V
Current Reference	V_{IREFR}	100k Ω to GND		0.5		V

7.5 GENERAL PURPOSE INPUTS / OUTPUTS (GPIO)

Unless otherwise noted: $T_J = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$; Typical values are at $T_J = +25^{\circ}\text{C}$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
GPIO1, GPIO2, GPIO3, GPIO7, GPIO8, GPIO9						
Input HIGH Level	V _{IH}		0.75 x VDD			V
Input LOW Level	V _{IL}				0.25 x VDD	V
Output HIGH Level	V _{OH}	I _{OH} = 1mA	0.8 x VDD			V
Output LOW Level	V _{OL}	I _{OL} = -1mA			0.2 x VDD	V
Pull-up resistance to VDD	R _{PU}	GPn_PWR_DOM=0 and DBVDD=1.8V or GPn_PWR_DOM=1		180		kΩ
Pull-down resistance	R _{PD}			180		kΩ
GPIO4, GPIO5, GPIO6, GPIO10, GPIO11, GPIO12						
Input HIGH Level	V _{IH}		0.85 x VDD			V
Input LOW Level	V _{IL}				0.2 x VDD	V
Output HIGH Level	V _{OH}	I _{OH} = 1mA	0.75 x VDD			V
Output LOW Level	V _{OL}	I _{OL} = -1mA			0.2 x VDD	V
Pull-up resistance to VDD	R _{PU}	GPn_PWR_DOM=0 and DBVDD=1.8V or GPn_PWR_DOM=1 and PVDD=3.8V		180		kΩ
Pull-down resistance	R _{PD}			180		kΩ

Notes:

1. 'VDD' is the voltage of the applicable power domain for each pin (selected by the corresponding GPn_PWR_DOM register).
2. Pull-up / pull-down resistance only applies when enabled using the GPn_PULL registers.
3. Pull-up / pull-down resistors are disabled when the GPIO pin is tri-stated.
4. Pull-up / pull-down resistance may change with the applicable power domain (as selected by GPn_PWR_DOM).

7.6 DIGITAL INTERFACES

Unless otherwise noted: $T_J = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$; Typical values are at $T_J = +25^{\circ}\text{C}$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$\overline{\text{ON}}$, $\overline{\text{RESET}}$, $\overline{\text{IRQ}}$, CIFMODE, SDOUT1, SCLK1, SDA1, $\overline{\text{CS}}$, SCLK2, SDA2						
Input HIGH Level	V_{IH}		$0.75 \times V_{DD}$			V
Input LOW Level	V_{IL}				$0.2 \times V_{DD}$	V
Output HIGH Level	V_{OH}	$I_{OH} = 1\text{mA}$	$0.8 \times V_{DD}$			V
Output LOW Level	V_{OL}	$I_{OL} = -1\text{mA}$			$0.2 \times V_{DD}$	V
'VDD' is the voltage of the applicable power domain for each pin, as defined in Section 3.						
ON pin pull-up resistance	R_{PU}			140		k Ω
RESET pin pull-up resistance	R_{PU}	DBVDD=1.8V		180		k Ω
		DBVDD=3.6V		85		
IRQ pin pull-up resistance	R_{PU}	DBVDD=1.8V		180		k Ω
		DBVDD=3.6V		85		
SCLK2 pin pull-down resistance	R_{PD}			100		k Ω
SDA2 pin pull-down resistance	R_{PD}			100		k Ω

7.7 AUXILIARY ADC

Unless otherwise noted: $T_J = +25^{\circ}\text{C}$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input resistance	$R_{GPIO10, 11, 12}$	During measurement		400		k Ω
Input voltage range	$V_{GPIO10, 11, 12}$	GPn_PWR_DOM = 0	0		V_{DBVDD}	V
		GPn_PWR_DOM = 1	0		V_{PVDD}	
Input capacitance	$C_{GPIO10, 11, 12}$			2		pF
AUXADC Resolution				12		bits
AUXADC Conversion Time				39		μs
AUXADC accuracy		Input voltage = 3V	-2.5		+2.5	%

7.8 SYSTEM STATUS LED DRIVERS

Unless otherwise noted: $T_J = +25^{\circ}\text{C}$

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
LED1 and LED2						
Sink current		$V_{LED1/2} = 1\text{V}$		10		mA

8 TYPICAL POWER CONSUMPTION

Data to follow

9 TYPICAL PERFORMANCE DATA

9.1 DC-DC CONVERTERS

Data to follow

9.2 LDO REGULATORS

Data to follow

10 SIGNAL TIMING REQUIREMENTS

10.1 CONTROL INTERFACE

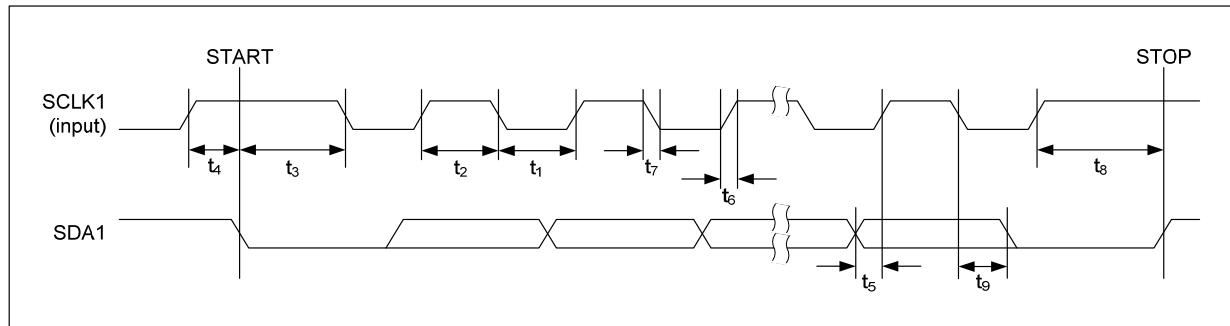


Figure 1 Control Interface Timing - 2-wire (I2C) Control Mode

Test Conditions

$T_j = -40^\circ\text{C}$ to $+125^\circ\text{C}$ unless otherwise stated.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
SCLK1 Frequency		0		400	kHz
SCLK1 Low Pulse-Width	t_1	1300			ns
SCLK1 High Pulse-Width	t_2	600			ns
Hold Time (Start Condition)	t_3	600			ns
Setup Time (Start Condition)	t_4	600			ns
Data Setup Time	t_5	100			ns
SDA1, SCLK1 Rise Time	t_6			300	ns
SDA1, SCLK1 Fall Time	t_7			300	ns
Setup Time (Stop Condition)	t_8	600			ns
Data Hold Time	t_9			900	ns
Pulse width of spikes that will be suppressed	t_{ps}	0		5	ns

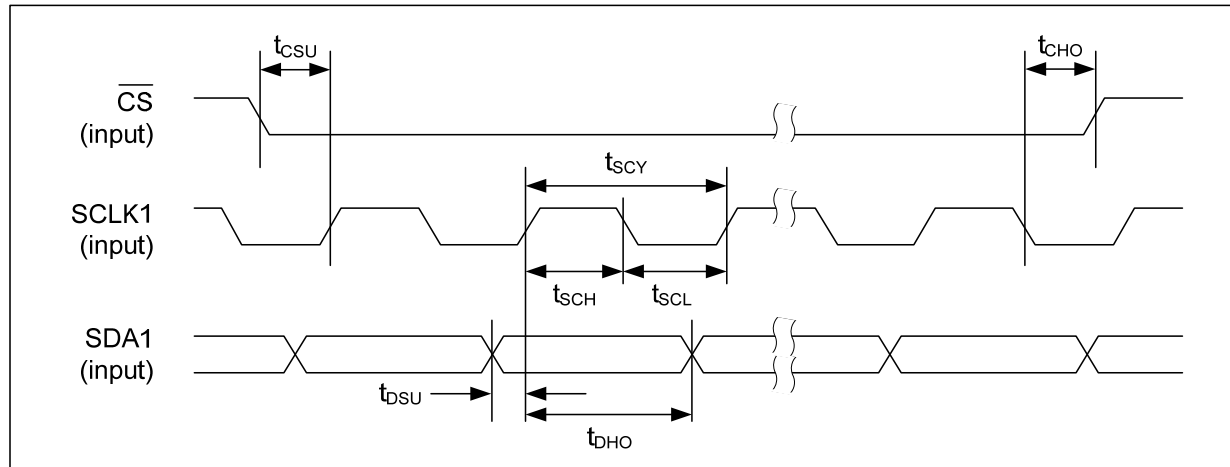


Figure 2 Control Interface Timing - 4-wire (SPI) Control Mode (Write Cycle)

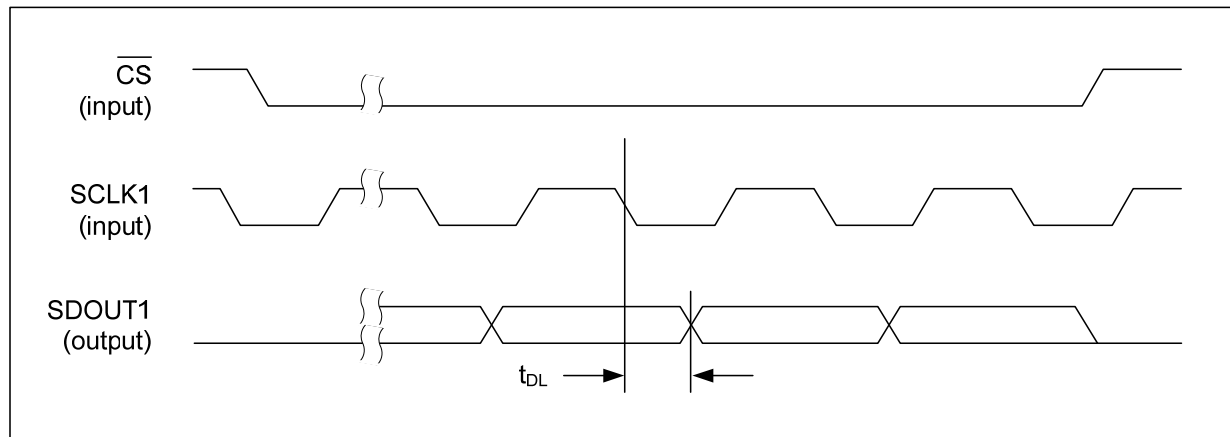


Figure 3 Control Interface Timing - 4-wire (SPI) Control Mode (Read Cycle)

Test Conditions

$T_J = -40^{\circ}\text{C}$ to $+125^{\circ}\text{C}$ unless otherwise stated.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
$\overline{\text{CS}}$ falling edge to SCLK1 rising edge	t_{CSU}	40			ns
SCLK1 falling edge to $\overline{\text{CS}}$ rising edge	t_{CHO}	10			ns
SCLK1 pulse cycle time	t_{SCY}	200			ns
SCLK1 pulse width low	t_{SCL}	80			ns
SCLK1 pulse width high	t_{SCH}	80			ns
SDA1 to SCLK1 set-up time	t_{DSU}	40			ns
SDA1 to SCLK1 hold time	t_{DHO}	10			ns
Pulse width of spikes that will be suppressed	t_{ps}	0		5	ns
SCLK1 falling edge to SDOUT1 transition	t_{DL}			40	ns

The $\overline{\text{CS}}$ pin must be held high for at least $1\mu\text{s}$ after every register write operation in SPI mode.

11 DEVICE DESCRIPTION

11.1 GENERAL DESCRIPTION

The WM8326 is a multi-purpose Power Management device with a comprehensive range of features. The WM8326 provides 4 DC-DC synchronous buck converters and 11 LDO regulators which are all programmable to application-specific requirements. The on-board oscillator and two additional LDOs support the clocking and control functions for the DC-DC converters and other core functions.

The WM8326 provides a 32.768kHz crystal oscillator and secure Real Time Clock (SRTC). An auxiliary ADC is included, for measurement of external voltages. Other features include flexible GPIO capability, and LED outputs for system status indications.

Under typical operating conditions, the device is powered up and shut down under the control of the $\overline{\text{ON}}$ pin. The device executes a programmable sequence of enabling or disabling the DC-DC converters, LDOs and other functions when commanded to power up or shut down respectively. An alternate device state (SLEEP power state) is provided, in which selected functions may be separately configured for a low-power or other operating condition. The configuration of the normal operating state may be programmed into an integrated OTP non-volatile memory. If desired, the OTP memory can be programmed during device manufacture in accordance with the user's specification. See Section 14 for details of the OTP and associated bootstrap configuration functions.

In the absence of a main power supply, the WM8326 automatically reverts to a backup state, under which a minimal functionality is maintained to enable a smooth return to normal operation when the supply is restored. With a backup battery present, the RTC is updated in the backup state, allowing the main battery to be depleted or changed without loss of RTC function. Without a backup battery, a small capacitor is sufficient to maintain the RTC (unlocked) for up to 5 minutes.

11.2 POWER STATES

The WM8326 has 6 main power states, which are described below. Different levels of functionality are associated with each of the power states. Some of the state transitions are made autonomously by the WM8326 (eg. transitions to/from BACKUP are scheduled according to the available power supply conditions). Other transitions are initiated as a result of instructions issued over the Control Interface or as a result of software functions (eg. Watchdog timer) or hardware functions such as the $\overline{\text{ON}}$ pin. The valid transitions and the associated conditions are detailed below.

NO POWER - This is the device state when no power is available. All functions are disabled and all register data is lost.

OFF - This is the device state when power is available but the device is switched off. The RTC is enabled and the register map contents are maintained. The RESET pin is pulled low in this state. LDO11 may optionally be enabled in this state; all other DC-DCs and LDOs are disabled (apart from LDO12, which supports internal functions).

ON - This is the normal operating state when the device is switched on. All device functions are available in this state.

SLEEP - This is a user-configurable operating state which is intended for a low-power operating condition. Selected functions may be enabled, disabled or re-configured according to the user's requirements. A programmable configuration sequence for the DC-DCs and LDOs is executed on transition to/from SLEEP mode.

BACKUP - This is the operating state when the PVDD power supply is below the reset threshold of the device. Typically, this means that the PVDD supply has been removed. All DC-DC converters and LDO regulators are disabled in this state. The RTC and oscillator and a 'software scratch' memory area can be maintained from the backup supply (if available) in this state. All other functions and registers are reset in BACKUP. (Note that, for power saving, an 'unlocked' mode, in which the RTC is held constant, may be selected if required.)

PROGRAM - This is a special operating state which is used for programming the integrated OTP memory with the device configuration data. The settings stored in the OTP define the device configuration in the ON state, and also the time/sequencing data associated with ON/OFF power state transitions. See Section 14 for details of the OTP features.

The valid power state transitions are illustrated in Figure 4.

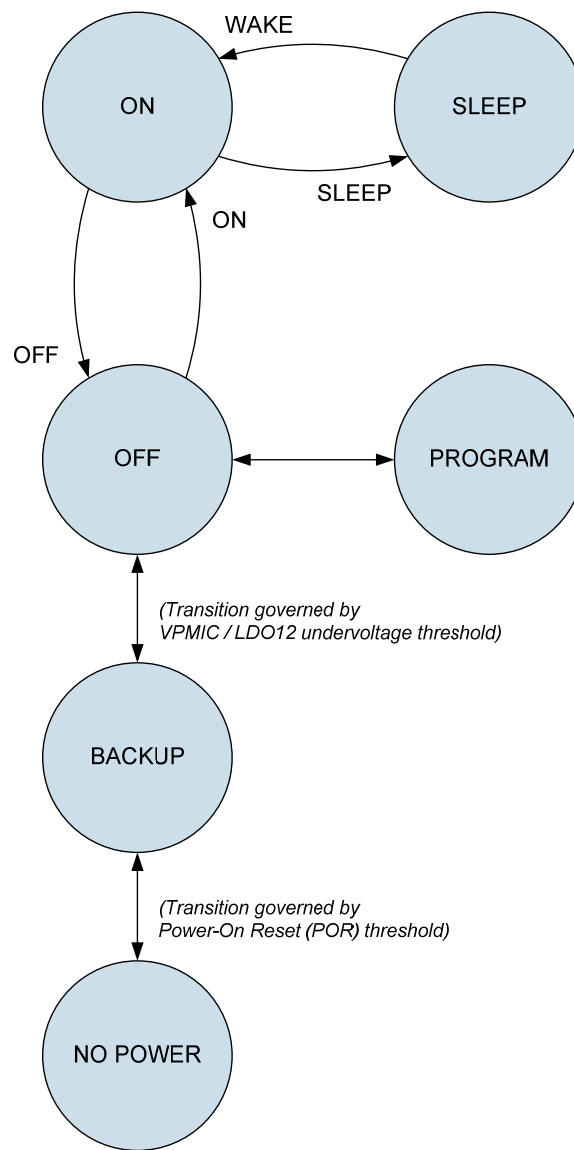


Figure 4 Power States and Transitions

State transitions to/from the NO POWER state are controlled automatically by the internal supply (VPMIC) voltage generated by LDO12. The device is in the NO POWER state when this voltage is below the Power-On Reset (POR) threshold. See Section 24 for more details on Power-On Reset.

State transitions to/from the BACKUP state are controlled automatically by the internal supply (VPMIC) voltage generated by LDO12. The device is in the BACKUP state when this voltage is below the Device Reset threshold. See Section 24 for more details on Resets.

State transitions to/from the PROGRAM state are required to follow specific control sequences. See Section 14 for details of the PROGRAM functions.

The remaining transitions between the OFF, ON and SLEEP states may be initiated by a number of different mechanisms - some of them automatic, some of them user-controlled. Transitions between these states are time-controlled sequences of events. These are the OFF, ON, SLEEP and WAKE sequences shown in Figure 4. These transitions are programmable, using data stored in the integrated OTP memory or else data loaded from an external InstantConfig™ EEPROM (ICE) memory. See Section 14 for details.

Note that a transition from the SLEEP state to the OFF state is not a controlled transition. If an 'OFF' event occurs whilst in the SLEEP state, then the WM8326 will select the OFF state, but all the

enabled converters and regulators will be disabled immediately; the time-controlled sequence is not implemented in this case. See Section 11.3 for details of the WM8326 'OFF' events.

The current power state of the WM8326 can be read from the MAIN_STATE register field. A restricted definition of this field is shown in Table 1. Note that other values of MAIN_STATE are defined for transition states, but it is recommended that only the values quoted below should be used to confirm power state transitions.

A power state transition to the BACKUP, SLEEP, ON or OFF state is indicated by the Interrupt bits described in Section 11.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16397 (400Dh) System Status	4:0	MAIN_STATE [4:0]	0_0000	Main State Machine condition 0_0000 = OFF 0_1011 = PROGRAM 1_1100 = SLEEP 1_1111 = ACTIVE (ON)

Table 1 Power State Readback

11.3 POWER STATE CONTROL

The OFF, ON, SLEEP and WAKE sequences are initiated by many different conditions. When such a condition occurs, the WM8326 schedules a series of 5 timeslots, enabling a sequence of enable/disable events to be controlled. The nominal duration of the timeslots is fixed at 2ms, though this may be extended if any selected circuit has not started up within this time, as described later in this section. The OFF, SLEEP and WAKE sequences commence after a programmable delay set by PWRSTATE_DLY. This allows a host processor to request a WM8326 state transition and then complete other tasks before the transition actually occurs.

The ON sequence is the transition from OFF to ON power states. Each LDO and each DC-DC Converter may be associated with any one of the available timeslots in the ON sequence. This determines the time, within the sequence, at which that DC-DC Converter or LDO will be enabled following an 'ON' event.

The clock output (CLKOUT) and GPIO pins configured as External Power Enable (EPE) outputs can also be associated with any one of the available timeslots in the ON sequence. The EPE function is a logic output that may be used to control external circuits, including external DC-DC converters.

An example 'ON' state transition sequence is illustrated in Figure 5. Each of the DC-DC Converters and LDO regulators can be individually assigned to one of the five timeslots (shown as T1, T2, T3, T4, T5), providing total flexibility in the power sequence.

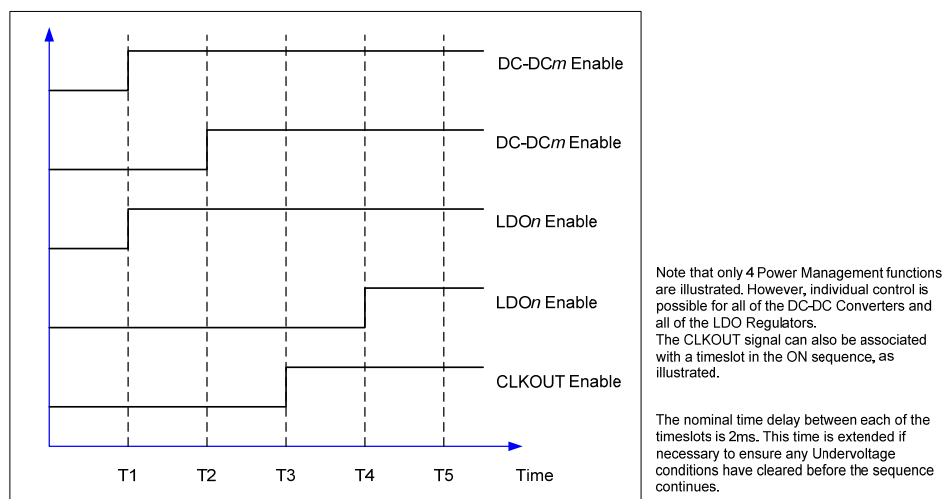


Figure 5 Example Control Sequence for 'ON' State Transition

The possible 'ON' events that may trigger the ON sequence are listed in Table 3. The ON sequence is only permitted when the supply voltage PVDD exceeds a programmable threshold SYSOK. See Section 24 for details of PVDD voltage monitoring.

The OFF sequence is the reverse of the ON sequence. Each DC-DC Converter, LDO Regulator or GPIO output that is associated with a timeslot in the ON sequence is switched off in the reverse sequence following an 'OFF' event. If CLKOUT is assigned to a timeslot in the ON sequence, then this is disabled in the reverse (OFF) sequence also.

The possible 'OFF' events are listed in Table 3. Note that it is possible to modify the OFF sequence by writing to the associated registers in the ON power state if required; this allows the OFF sequence to be independent of the ON sequence.

The SLEEP sequence is the transition from ON to SLEEP power states. Each LDO and each DC-DC Converter may be associated with any one of the available timeslots in the SLEEP sequence. This determines the time, within the sequence, at which that DC Converter or LDO will be disabled following a 'SLEEP' event.

The clock output (CLKOUT) and GPIO pins configured as External Power Enable (EPE) outputs can also be associated with any one of the available timeslots in the SLEEP sequence. The possible 'SLEEP' events are listed in Table 3.

The WAKE sequence is the reverse of the SLEEP sequence. Each DC-DC Converter, LDO Regulator or GPIO output that is associated with a timeslot in the SLEEP sequence is switched on in the reverse sequence following a 'WAKE' event. If CLKOUT is assigned to a timeslot in the SLEEP sequence, then this is disabled in the reverse (WAKE) sequence also.

The possible 'WAKE' events are listed in Table 3. Note that it is possible to modify the WAKE sequence by writing to the associated registers in the SLEEP power state if required; this allows the WAKE sequence to be independent of the SLEEP sequence.

Any DC-DC Converter or LDO that is not associated with one of the 5 timeslots in the ON sequence may, instead, be configured to be hardware controlled via a GPIO pin configured as one of the Hardware Enable inputs. See Section 21 for details of the GPIO functions. Any DC-DC Converter or LDO that is not under Hardware control may be enabled or disabled under Software control in the ON state, regardless of whether it is associated with any timeslot in the ON sequence.

When a valid OFF event occurs, any DC-DC Converter or LDO which is not allocated a timeslot in the ON sequence is disabled immediately. This includes any DC-DC Converter or LDO which is under GPIO (Hardware Enable) control. The only exception is LDO11 which may, optionally, be configured to be enabled in the OFF state.

The WM8326 monitors the DC-DC Converters and LDOs during the ON sequence to ensure that the required circuits have powered up successfully before proceeding to the next timeslot. The nominal timeslot durations are extended if necessary in order to wait for the selected DC-DC Converters or LDOs to power up. If the ON sequence has not completed within 2 seconds of starting the transition, then a Power Sequence Failure has occurred, resulting in the OFF state being forced.

The most recent ON or WAKE event can be determined by reading the bits in the "ON Source" register, R400Eh. The most recent OFF event can be determined by reading the bits in the "OFF Source" register, R400Fh.

The "ON Source" register is updated when a new ON event occurs. The "OFF Source" register is updated when a new OFF event occurs. Note that some Reset conditions (see Section 24) result in an OFF transition followed by an ON transition; these events are recorded as Reset events in the "ON Source" register.

The ON Source and OFF Source register fields are defined in Table 2.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16387 (4003h) Power State	15	CHIP_ON	0	Indicates whether the system is ON or OFF. 0 = OFF 1 = ON (or SLEEP) OFF can be commanded by writing CHIP_ON = 0. Note that writing CHIP_ON = 1 is not a valid 'ON' event, and will not trigger an ON transition.
	14	CHIP_SLP	0	Indicates whether the system is in the SLEEP state. 0 = Not in SLEEP 1 = SLEEP WAKE can be commanded by writing CHIP_SLP = 0. SLEEP can be commanded by writing CHIP_SLP = 1.
	11:10	PWRSTATE_DLY	10	Power State transition delay 00 = No delay 01 = No delay 10 = 1ms 11 = 10ms
R16398 (400Eh) ON Source	15	ON_TRANS	0	Most recent ON/WAKE event type 0 = WAKE transition 1 = ON transition
	11	ON_GPIO	0	Most recent ON/WAKE event type 0 = Not caused by GPIO input 1 = Caused by GPIO input
	10	ON_SYSLO	0	Most recent WAKE event type 0 = Not caused by PVDD 1 = Caused by SYSLO threshold. Note that the SYSLO threshold cannot trigger an ON event.
	7	ON_WDOG_TO	0	Most recent WAKE event type 0 = Not caused by Watchdog timer 1 = Caused by Watchdog timer
	6	ON_SW_REQ	0	Most recent WAKE event type 0 = Not caused by software WAKE 1 = Caused by software WAKE command (CHIP_SLP = 0)
	5	ON_RTC_ALM	0	Most recent ON/WAKE event type 0 = Not caused by RTC Alarm 1 = Caused by RTC Alarm
	4	ON_ON_PIN	0	Most recent ON/WAKE event type 0 = Not caused by the ON pin 1 = Caused by the ON pin
	3	RESET_CNV_UV	0	Most recent ON event type 0 = Not caused by undervoltage 1 = Caused by a Device Reset due to a Converter (LDO or DC-DC) undervoltage condition
	2	RESET_SW	0	Most recent ON event type 0 = Not caused by Software Reset 1 = Caused by Software Reset

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	1	RESET_HW	0	Most recent ON event type 0 = Not caused by Hardware Reset 1 = Caused by Hardware Reset
	0	RESET_WDOG	0	Most recent ON event type 0 = Not caused by the Watchdog 1 = Caused by a Device Reset triggered by the Watchdog timer
R16399 (400Fh) OFF Source	13	OFF_INTLDO_ERR	0	Most recent OFF event type 0 = Not caused by LDO13 Error condition 1 = Caused by LDO13 Error condition
	12	OFF_PWR_SEQ	0	Most recent OFF event type 0 = Not caused by Power Sequence Failure 1 = Caused by a Power Sequence Failure
	11	OFF_GPIO	0	Most recent OFF event type 0 = Not caused by GPIO input 1 = Caused by GPIO input
	10	OFF_PVDD	0	Most recent OFF event type 0 = Not caused by PVDD 1 = Caused by the SYSLO or SHUTDOWN threshold
	9	OFF_THERR	0	Most recent OFF event type 0 = Not caused by temperature 1 = Caused by over-temperature
	6	OFF_SW_REQ	0	Most recent OFF event type 0 = Not caused by software OFF 1 = Caused by software OFF command (CHIP_ON = 0)
	4	OFF_ON_PIN	0	Most recent OFF event type 0 = Not caused by the ON pin 1 = Caused by the ON pin

Table 2 Power State Control Registers

Table 3 lists all of the events which can trigger an ON, WAKE, OFF or SLEEP transition sequence. It also lists the associated status bits of the 'ON Source' and 'OFF Source' register bits which are asserted under each condition.

TRANSITION SEQUENCE	EVENT	NOTES	ON SOURCE / OFF SOURCE
ON (see note 1)	RTC alarm	An ON request occurs if the RTC Alarm occurs in the OFF power state. See Section 20.	ON_TRANS, ON_RTC_ALM
	GPIO ON request	Requires a GPIO to be configured as "Power On request" or "Power On/Off request". See Section 21.	ON_TRANS, ON_GPIO
	$\overline{\text{ON}}$ pin request	Requires the $\overline{\text{ON}}$ pin to be configured to generate ON request. See Section 11.6.	ON_TRANS, ON_ON_PIN
WAKE	Software WAKE	Writing CHIP_SLP = 0. See Table 2.	ON_SW_REQ
	Watchdog timeout	Requires the Watchdog to be configured to generate WAKE request. See Section 25.	ON_WDOG_TO
	RTC alarm	A WAKE request occurs if the RTC Alarm occurs in the SLEEP power state. See Section 20.	ON_RTC_ALM
	GPIO WAKE request	Requires a GPIO to be configured as "Sleep/Wake request". See Section 21.	ON_GPIO
	PVDD undervoltage	Requires the PVDD monitor circuit to be configured to generate WAKE request. See Section 24.4.	ON_SYSLO
	$\overline{\text{ON}}$ pin request	Requires the $\overline{\text{ON}}$ pin to be configured to generate WAKE request. See Section 11.6.	ON_ON_PIN
OFF	Watchdog timeout	Requires the Watchdog to be configured to generate Device Reset. See Section 25.	RESET_WDOG (See note 2)
	Hardware Reset	See Section 24.	RESET_HW (See note 2)
	Software Reset	See Section 24.	RESET_SW (See note 2)
	Power Management Undervoltage Reset	Configurable option for each LDO/DC-DC converter. See Section 15.	RESET_CNV_UV (See note 2)
	Software OFF request	Writing CHIP_ON = 0. See Table 2.	OFF_SW_REQ
	ON pin request	Requires the $\overline{\text{ON}}$ pin to be configured to generate OFF request. See Section 11.6.	OFF_ON_PIN
	Thermal shutdown	See Section 26.	OFF_THERR
	PVDD undervoltage	Requires the PVDD monitor circuit to be configured to generate OFF request. See Section 24.4.	OFF_PVDD
	PVDD shutdown	PVDD has fallen below the SHUTDOWN threshold. See Section 24.4.	OFF_PVDD
	GPIO OFF request	Requires a GPIO to be configured as "Power On/Off request". See Section 21.	OFF_GPIO
	Power Sequence failure	DC-DC converters, LDOs or CLKOUT circuits have failed to start up within the permitted time.	OFF_PWR_SEQ
	Internal LDO error	Error condition detected in LDO13	OFF_INTLDO_ERR
	Software SLEEP request	Writing CHIP_SLP = 1. See Table 2.	See note 3
	GPIO SLEEP request	Requires a GPIO to be configured as "Sleep request" or "Sleep/Wake request". See Section 21.	See note 3

Table 3 Power State Transition Events

Notes:

1. An ON sequence is only permitted when the supply voltage PVDD exceeds a programmable threshold V_{SYSOK} . See Section 24.4 for details of PVDD voltage monitoring.
2. These Reset conditions result in an OFF transition followed by an ON transition. These events are recorded as Reset events in the 'ON Source' register.
3. SLEEP events are not recorded in the 'OFF Source' register.

11.4 POWER STATE INTERRUPTS

Power State transitions are associated with a number of Interrupt event flags. Transitions to BACKUP, SLEEP, ON or OFF states are indicated by the Interrupt bits described in Table 4. Each of these secondary interrupts triggers a primary Power State Interrupt, PS_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 4.

ADDRESS	BIT	LABEL	DESCRIPTION
R16402 (4012h) Interrupt Status 2	2	PS_POR_EINT	Power On Reset interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	1	PS_SLEEP_OFF_EINT	SLEEP or OFF interrupt (Power state transition to SLEEP or OFF states) (Rising Edge triggered) Note: Cleared when a '1' is written.
	0	PS_ON_WAKE_EINT	ON or WAKE interrupt (Power state transition to ON state) (Rising Edge triggered) Note: Cleared when a '1' is written.
R16410 (401Ah) Interrupt Status 2 Mask	2	IM_PS_POR_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	1	IM_PS_SLEEP_OFF_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	0	IM_PS_ON_WAKE_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 4 Power State Interrupts

11.5 POWER STATE GPIO INDICATION

The WM8326 can be configured to generate logic signals via GPIO pins to indicate the current Power State. See Section 21 for details of configuring GPIO pins.

A GPIO pin configured as "ON state" output will be asserted when the WM8326 is in the ON state.

A GPIO pin configured as "SLEEP state" output will be asserted when the WM8326 is in the SLEEP state.

11.6 ON PIN FUNCTION

The $\overline{\text{ON}}$ pin is intended for connection to the master power switch on the user's application. It can be used to start-up the WM8326 from the SLEEP or OFF states and also to power down the system. This pin operates on the LDO12 (VPMIC) power domain and has an internal pull-up resistor. This pin is asserted by shorting it to GND. A de-bounce circuit is provided on this input pin.

The behaviour of the $\overline{\text{ON}}$ pin is programmable. The primary action taken on asserting this pin is determined by the ON_PIN_PRIMACT register field. Note that the ON_PIN_INT interrupt event is always raised when the $\overline{\text{ON}}$ pin is asserted.

If the pin is held asserted for longer than the timeout period set by ON_PIN_TO, then a secondary action is executed. The secondary action is determined by the ON_PIN_SECACT register field.

If the pin is held asserted for a further timeout period, then a tertiary action is executed. The tertiary action is not programmable, and is to generate an OFF request.

The status of the $\overline{\text{ON}}$ pin can be read at any time via the ON_PIN_STS register.

Note that the $\overline{\text{ON}}$ pin control registers are locked by the WM8326 User Key. These registers can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16389 (4005h) ON Pin Control	9:8	ON_PIN_SECACT	01	Secondary action of $\overline{\text{ON}}$ pin (taken after 1 timeout period) 00 = Interrupt 01 = ON request 10 = OFF request 11 = Reserved <i>Protected by user key</i>
	5:4	ON_PIN_PRIMACT	00	Primary action of $\overline{\text{ON}}$ pin 00 = Ignore 01 = ON request 10 = OFF request 11 = Reserved Note that an Interrupt is always raised. <i>Protected by user key</i>
	3	ON_PIN_STS	0	Current status of $\overline{\text{ON}}$ pin 0 = Asserted (logic 0) 1 = Not asserted (logic 1)
	1:0	ON_PIN_TO	00	$\overline{\text{ON}}$ pin timeout period 00 = 1s 01 = 2s 10 = 4s 11 = 8s <i>Protected by user key</i>

Table 5 ON Pin Control Registers

The $\overline{\text{ON}}$ pin interrupt event is always raised as part of the primary action when the $\overline{\text{ON}}$ pin is asserted or de-asserted. (Note that the $\overline{\text{ON}}$ pin interrupt is raised on the rising and falling edges of this $\overline{\text{ON}}$ pin input signal.) The $\overline{\text{ON}}$ pin interrupt is a selectable option as the secondary action.

The $\overline{\text{ON}}$ pin interrupt event is indicated by the ON_PIN_CINT register field. This secondary interrupt triggers a primary ON Pin Interrupt, ON_PIN_INT (see Section 23). This can be masked by setting the mask bit as described in Table 6.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	12	ON_PIN_CINT	ON pin interrupt. (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	12	IM_ON_PIN_CINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 6 ON Pin Interrupt

11.7 RESET PIN FUNCTION

The $\overline{\text{RESET}}$ pin is an active low input/output which is used to command Hardware Resets in the WM8326 and in other connected devices. The pin is an open-drain type, with integrated pull-up; it can be driven low by external sources or by the WM8326 itself.

The WM8326 drives the $\overline{\text{RESET}}$ pin low in the OFF state. The output status of the $\overline{\text{RESET}}$ pin in SLEEP is configurable; this is determined by the RST_SLPENA register bit as defined in Table 7.

The WM8326 clears the $\overline{\text{RESET}}$ pin following the transition to ON. On completion of the state transition, the $\overline{\text{RESET}}$ pin is held low for a further delay time period, extending the $\overline{\text{RESET}}$ low duration. The $\overline{\text{RESET}}$ delay period is set by the RST_DUR register bit. See Figure 6 for further details.

The WM8326 detects a Hardware Reset request whenever the $\overline{\text{RESET}}$ pin is driven low by an external source. In this event, the WM8326 resets the internal control registers (excluding the RTC) and initiates a start-up sequence. See Section 24.

It is possible to mask the $\overline{\text{RESET}}$ pin input in the SLEEP state by setting the RST_SLP_MSK register bit. In SLEEP mode, if RST_SLP_MSK is set, the WM8326 will take no action if the $\overline{\text{RESET}}$ pin is pulled low.

Note that the $\overline{\text{RESET}}$ pin control registers are locked by the WM8326 User Key. These registers can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16390 (4006h) Reset Control	5	RST_SLP_MSK	1	Masks the $\overline{\text{RESET}}$ pin input in SLEEP mode 0 = External $\overline{\text{RESET}}$ active in SLEEP 1 = External $\overline{\text{RESET}}$ masked in SLEEP <i>Protected by user key</i>
	4	RST_SLPENA	1	Sets the output status of $\overline{\text{RESET}}$ pin in SLEEP 0 = $\overline{\text{RESET}}$ high (not asserted) 1 = $\overline{\text{RESET}}$ low (asserted) <i>Protected by user key</i>
	1:0	RST_DUR	11	Delay period for releasing $\overline{\text{RESET}}$ after ON or WAKE sequence 00 = 3ms 01 = 11ms 10 = 51ms 11 = 101ms <i>Protected by user key</i>

Table 7 RESET Pin Control Registers

The WM8326 can generate an Auxiliary Reset output via a GPIO pin configured as "Auxiliary Reset" output (see Section 21). This signal is asserted in the OFF state. The status of the Auxiliary Reset in the SLEEP state is configurable, using the AUXRST_SLPENA register bit as defined in Table 8.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16390 (4006h) Reset Control	6	AUXRST_SLPENA	1	Sets the output status of Auxiliary Reset (GPIO) function in SLEEP 0 = Auxiliary Reset not asserted 1 = Auxiliary Reset asserted <i>Protected by user key</i>

Table 8 Auxiliary Reset (GPIO) Control

The timing details of the $\overline{\text{RESET}}$ pin relative to an ON state transition are illustrated in Figure 6.

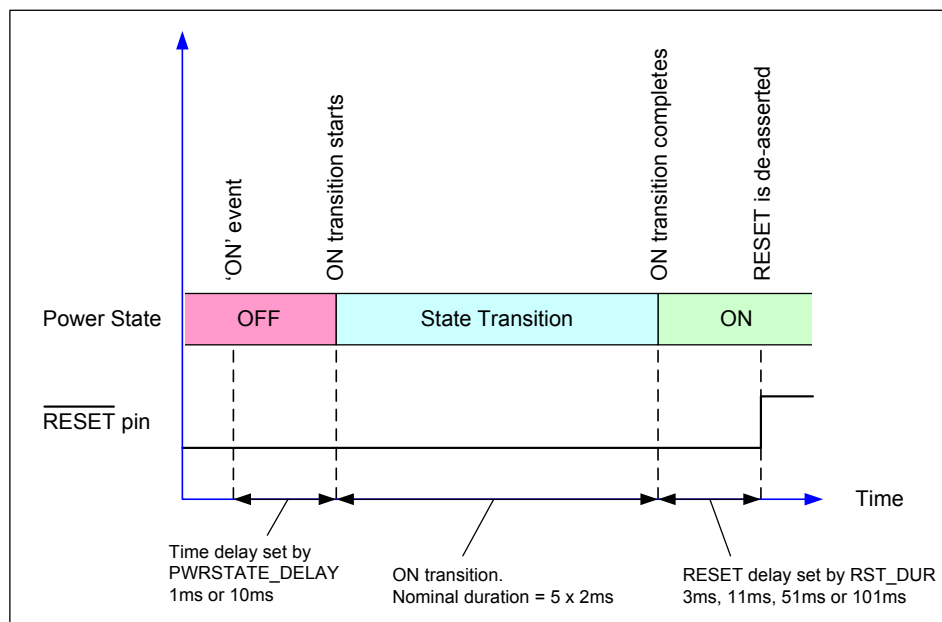


Figure 6 RESET Pin Output

12 CONTROL INTERFACE

12.1 GENERAL DESCRIPTION

The WM8326 is controlled by writing to its control registers. Readback is available for all registers, including Chip ID, power management status and GPIO status. The control interface can operate as a 2-wire (I2C) or 4-wire (SPI) control interface. Readback is provided on the bi-directional pin SDA1 in 2-wire (I2C) mode. The WM8326 Control Interface is powered by the DBVDD power domain.

The control interface mode is determined by the logic level on the CIFMODE pin as shown in Table 9.

CIFMODE	INTERFACE FORMAT
Low	2-wire (I2C) mode
High	4-wire (SPI) mode

Table 9 Control Interface Mode Selection

12.2 2-WIRE (I2C) CONTROL MODE

In 2-wire (I2C) mode, the WM8326 is a slave device on the control interface; SCLK1 is a clock input, while SDA1 is a bi-directional data pin. To allow arbitration of multiple slaves (and/or multiple masters) on the same interface, the WM8326 transmits logic 1 by tri-stating the SDA1 pin, rather than pulling it high. An external pull-up resistor is required to pull the SDA1 line high so that the logic 1 can be recognised by the master.

In order to allow many devices to share a single 2-wire control bus, every device on the bus has a unique 8-bit device ID (this is not the same as the 16-bit address of each register in the WM8326). The device ID is determined by the logic level on the $\overline{CS}$ pin as shown in Table 10. The LSB of the device ID is the Read/Write bit; this bit is set to logic 1 for "Read" and logic 0 for "Write".

$\overline{CS}$	DEVICE ID
Low	0110 100x = 68h(write) / 69h(read)
High	0110 110x = 6Ch(write) / 6Dh(read)

Table 10 Control Interface Device ID Selection

The WM8326 operates as a slave device only. The controller indicates the start of data transfer with a high to low transition on SDA1 while SCLK1 remains high. This indicates that a device ID, register address and data will follow. The WM8326 responds to the start condition and shifts in the next eight bits on SDA1 (8-bit device ID including Read/Write bit, MSB first). If the device ID received matches the device ID of the WM8326, then the WM8326 responds by pulling SDA1 low on the next clock pulse (ACK). If the device ID is not recognised or the R/W bit is '1' when operating in write only mode, the WM8326 returns to the idle condition and waits for a new start condition and valid address.

If the device ID matches the device ID of the WM8326, the data transfer continues as described below. The controller indicates the end of data transfer with a low to high transition on SDA1 while SCLK1 remains high. After receiving a complete address and data sequence the WM8326 returns to the idle state and waits for another start condition. If a start or stop condition is detected out of sequence at any point during data transfer (i.e. SDA1 changes while SCLK1 is high), the device returns to the idle condition.

The WM8326 supports the following read and write operations:

- Single write
- Single read
- Multiple write using auto-increment
- Multiple read using auto-increment

The sequence of signals associated with a single register write operation is illustrated in Figure 7.

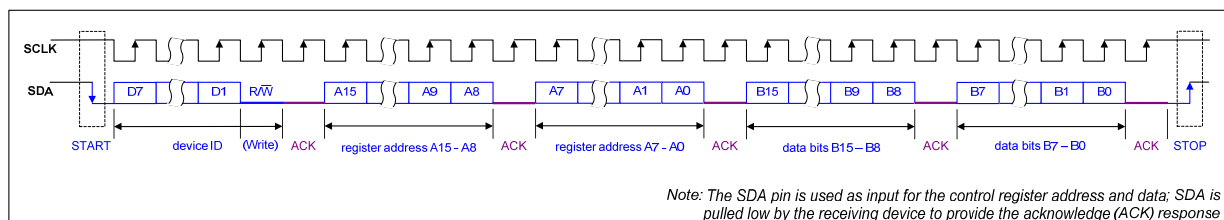


Figure 7 Control Interface 2-wire (I2C) Register Write

The sequence of signals associated with a single register read operation is illustrated in Figure 8.

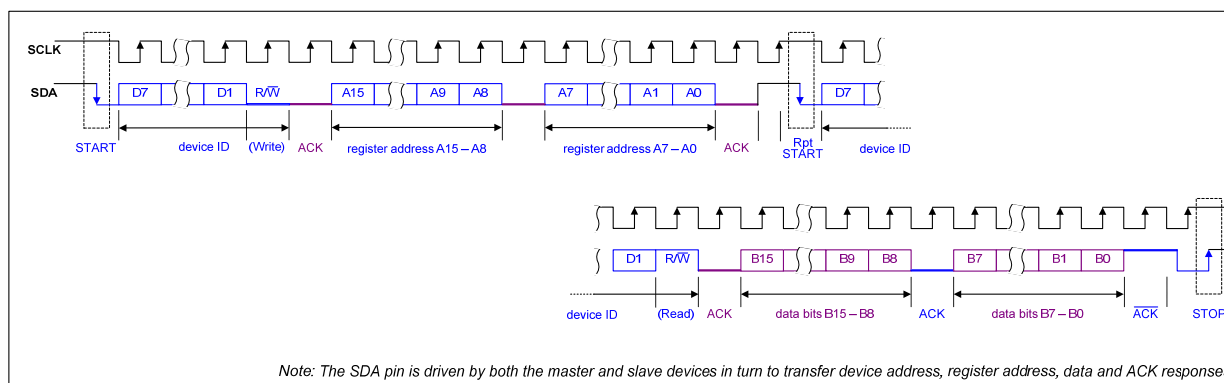


Figure 8 Control Interface 2-wire (I2C) Register Read

The Control Interface also supports other register operations, as listed above. The interface protocol for these operations is summarised below. The terminology used in the following figures is detailed in Table 11.

Note that, for multiple write and multiple read operations, the auto-increment option must be enabled. This feature is enabled by default; it is described in Table 12 below.

TERMINOLOGY	DESCRIPTION	
S	Start Condition	
Sr	Repeated start	
A	Acknowledge (SDA Low)	
$\bar{A}$	Not Acknowledge (SDA High)	
P	Stop Condition	
R/W	ReadNotWrite	0 = Write 1 = Read
[White field]	Data flow from bus master to WM8326	
[Grey field]	Data flow from WM8326 to bus master	

Table 11 Control Interface Terminology

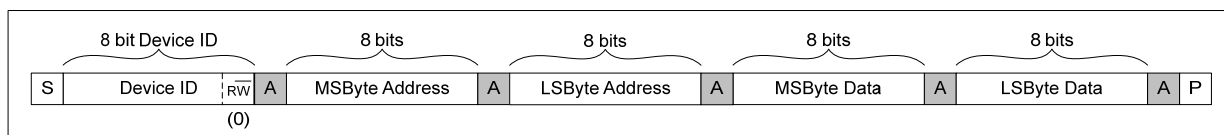


Figure 9 Single Register Write to Specified Address

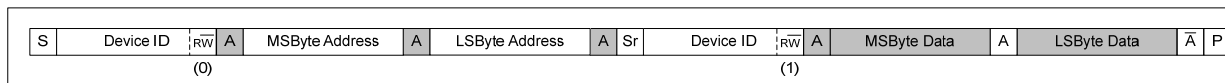


Figure 10 Single Register Read from Specified Address

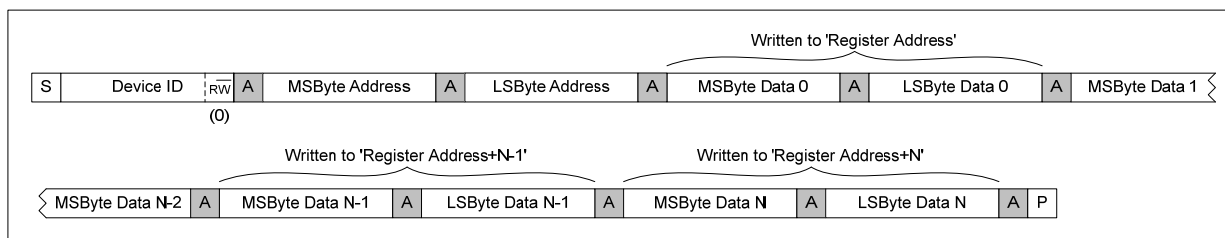


Figure 11 Multiple Register Write to Specified Address using Auto-increment

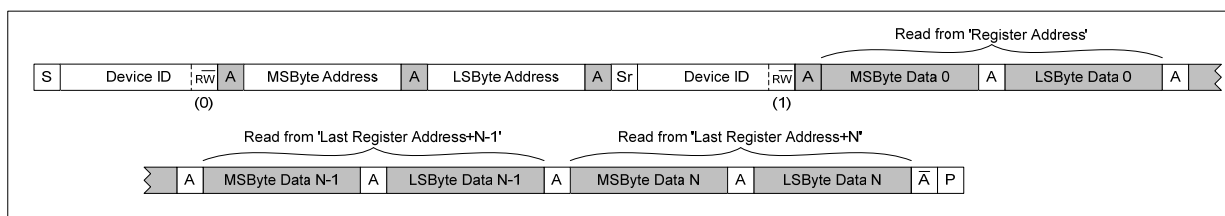


Figure 12 Multiple Register Read from Specified Address using Auto-increment

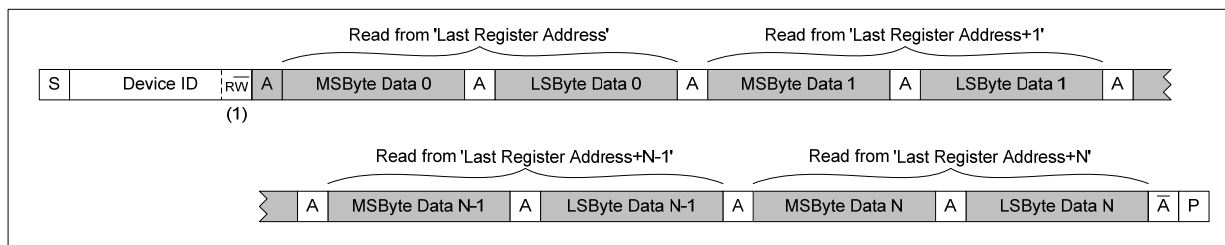


Figure 13 Multiple Register Read from Last Address using Auto-increment

Multiple Write and Multiple Read operations enable the host processor to access sequential blocks of the data in the WM8326 register map faster than is possible with single register operations. The auto-increment option is enabled when the AUTOINC register bit is set. This bit is defined in Table 12. Auto-increment is enabled by default.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16391 (4007h) Control Interface	2	AUTOINC	1	Enable Auto-Increment function 0 = Disabled 1 = Enabled

Table 12 Auto-Increment Control

12.3 4-WIRE (SPI) CONTROL MODE

In this mode, the WM8326 registers are accessed using a 4-wire serial control interface. The $\overline{CS}$ and SCLK1 pins provide the 'Chip Select' and 'Serial Data Clock' functions respectively. Serial data input is supported on the SDA1 pin; serial data output is supported on the SDOUT1 pin.

A control word consists of 32 bits. The first bit is the read/write bit (R/W), which is followed by 15 address bits (A14 to A0) that determine which control register is accessed. The remaining 16 bits (B15 to B0) are data bits, corresponding to the 16 bits in each control register.

In Write operations (R/W=0), all SDA1 bits are driven by the controlling device. Each rising edge of SCLK1 clocks in one data bit from the SDA1 pin. A rising edge on $\overline{CS}$ latches in a complete control word consisting of the last 32 bits.

In Read operations, the SDA1 pin is ignored following receipt of the valid register address. The data bits are output by the WM8326 on the SDOUT1 pin. SDOUT1 is undriven (high impedance) when not outputting register data bits.

The SDOUT1 pin is an Open Drain output; an external pull-up resistor to DBVDD is required on SDOUT1 in 4-wire (SPI) mode.

The sequence of signals associated with a register write operation is illustrated in Figure 14.

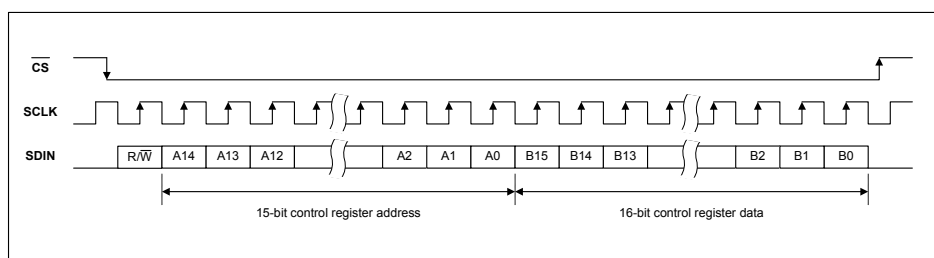


Figure 14 Control Interface 4-wire (SPI) Register Write

The sequence of signals associated with a register read operation is illustrated in Figure 15.

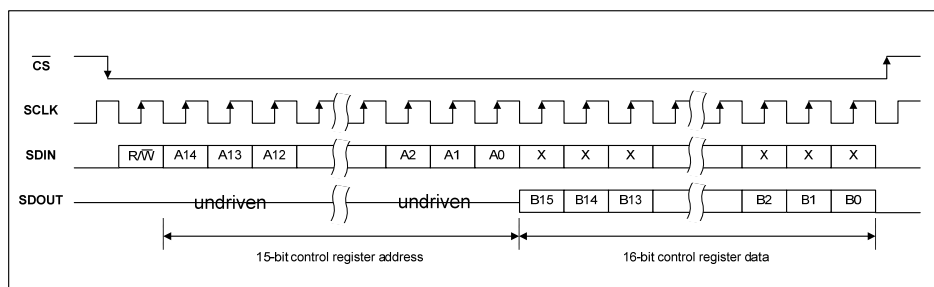


Figure 15 Control Interface 4-wire (SPI) Register Read

12.4 REGISTER LOCKING

Selected registers are protected by a security key. These registers can only be written to when the appropriate 'unlock' code has been written to the Security Key register.

The protected registers include those associated with Reset Control, OTP Programming and RTC Trim. Other selected functions also include protected registers; the affected registers are identified in the Register Map definitions throughout the document, and also in Section 29.

To unlock the protected registers, a value of 9716h must be written to the Security register (R16392), as defined in Table 13.

It is recommended to re-lock the protected registers immediately after writing to them. This helps protect the system against accidental overwriting of register values. To lock the protected registers, a value of 0000h should be written to the Security register.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16392 (4008h) Security Key	15:0	SECURITY [15:0]	0000h	Security Key A value of 9716h must be written to this register to access the user-keyed registers.

Table 13 Security Key Registers

12.5 SOFTWARE RESET AND CHIP ID

A Software Reset can be commanded by writing to Register 0000h. This is a read-only register field and the contents of this register will not be affected by a write operation. For more details of the different reset types, see Section 24.

Note that a maximum of 6 Software Resets is permitted. If more than 6 Software Resets are scheduled, the WM8326 will remain in the OFF state until the next valid ON state transition event occurs.

The Chip ID can be read back from Register 0000h. Other ID fields can be read from the registers defined in Table 14.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R0 (0000h) Reset/ID	15:0	CHIP_ID [15:0]	0000h	Writing to this register causes a Software Reset. The register map contents may be reset, depending on SW_RESET_CFG. Reading from this register will indicate Chip ID.
R1 (0001h) Revision	15:8	PARENT_REV [7:0]	00h	The revision number of the parent die
	7:0	CHILD_REV [7:0]	00h	The revision number of the child die (when present)
R16384 (4000h) Parent ID	15:0	PARENT_ID [15:0]	6246h	The ID of the parent die

Table 14 Reading Device Information

12.6 SOFTWARE SCRATCH REGISTER

The WM8326 provides one 16-bit register as a “Software Scratch” register. This is available for use by the host processor to store data for any purpose required by the application.

The contents of the Software Scratch register are retained in the BACKUP power state.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16393 (4009h) Software Scratch	15:0	SW_SCRATCH [15:0]	0000h	Software Scratch Register for use by the host processor. Note that this register's contents are retained in the BACKUP power state.

Table 15 Software Scratch Register

13 CLOCKING AND OSCILLATOR CONTROL

13.1 GENERAL DESCRIPTION

The WM8326 incorporates a 32.768kHz crystal oscillator in order to maintain the Real Time Clock (RTC). An external crystal is normally required. Alternatively, a 32.768kHz signal may be input directly on the XTI pin. The crystal oscillator and RTC are enabled at all times, including the OFF and BACKUP power states. It is possible to disable the crystal oscillator in BACKUP for power-saving RTC 'unclocked' mode if desired. The WM8326 clock functions are illustrated in Figure 16.

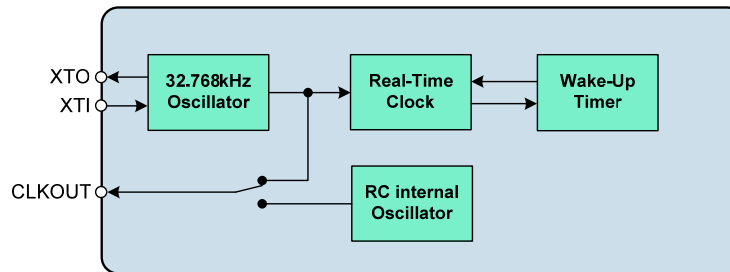


Figure 16 Clocking Configuration

The 32.768kHz crystal oscillator is enabled using the XTAL_ENA register. The crystal oscillator is enabled in the OFF, ON and SLEEP power states when XTAL_ENA = 1. The status of the crystal oscillator in BACKUP is selected using the XTAL_BKUPENA register.

Note that the XTAL_ENA field is set via OTP/ICE settings only; it cannot be changed by writing to the control register. If the crystal is omitted, and an external 32.768kHz signal is connected as an input to the XTI pin, it is still required to set XTAL_ENA = 1 for normal operation.

The crystal oscillator can be disabled in the BACKUP state by setting the XTAL_BKUPENA register bit to 0. This feature may be used to minimise the device power consumption in the BACKUP state, as described in Section 20.5. The crystal oscillator is maintained in the BACKUP state if both XTAL_ENA and XTAL_BKUPENA are set to 1.

The CLKOUT signal, derived from the 32.768kHz oscillator, can be enabled or disabled directly by writing to the CLKOUT_ENA register in the ON or SLEEP power states. The CLKOUT can also be controlled as part of the power state transitions using the CLKOUT_SLOT and CLKOUT_SLP_SLOT register fields. See Section 11.3 for a description of the state transition timeslots.

The CLKOUT pin may be configured as a CMOS output or as an Open-Drain output. The CLKOUT signal is referenced to the DBVDD power domain.

The status of the crystal oscillator is indicated by the XTAL_OK register bit. If the crystal oscillator fails to start, or if it stops for any reason, then the XTAL_OK register will be set to 0.

An internal RC oscillator is available in order to provide CLKOUT functionality during start-up of the crystal oscillator. This function is selectable using the XTAL_INH register bit, as described below.

If XTAL_INH = 0, then the internal RC oscillator provides the CLKOUT signal in the event that the crystal oscillator has not fully started up prior to an 'ON' state transition event. A glitch-free transition between the clock sources is implemented after the crystal oscillator is ready.

If XTAL_INH = 1, then an 'ON' state transition is delayed until the crystal oscillator has fully started up. This may be desirable if the CLKOUT signal is used as a clock for another circuit, to ensure that CLKOUT signal has been verified before the 'ON' state transition occurs. Note that the CLKOUT output is always disabled in the OFF power state; it is typically enabled as part of the 'ON' state transition sequence. Setting XTAL_INH = 1 ensures that the CLKOUT output cannot be enabled until the crystal frequency has been verified.

If XTAL_INH = 1, and the crystal oscillator fails to start, then a System Reset will be scheduled after a timeout period of approximately 32 seconds. See Section 24 for details of System Resets.

The WM8326 provides two interrupt flags associated with the crystal oscillator, as described in Section 13.2. These interrupts will provide indication of a crystal oscillator start-up failure, or detection of an interruption to the crystal oscillator (eg, due to tampering).

The CLKOUT control fields are described in Table 16. Some of these controls may also be stored in the integrated OTP memory. See Section 14 for details.

The 32.768kHz oscillator may also be output on a GPIO pin, as described in Section 21. Note that a GPIO pin configured as 32.768kHz output will continue to output the oscillator clock in the OFF power state; this may be used to provide clocking to the processor in the OFF state, provided that the selected power domain for that GPIO pin remains enabled in the OFF state. The CLKOUT output is always disabled in the OFF power state.

The internal RC oscillator generates the required clocks for the integrated DC-DC Converters on the WM8326. Note that a 2MHz 'External Power Clock', derived from this oscillator, may be output on a GPIO pin to provide synchronised clocking of external DC-DC Converters if required (see Section 21). The 2MHz External Power Clock is only enabled when either of the External Power Enable signals EPE1 or EPE2 is asserted. The External Power Enable (EPE) signals are controlled as described in Section 15.3.

Note that the CLKOUT_ENA control register is locked by the WM8326 User Key. This register can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16397 (400Dh) System Status	7	XTAL_OK	0	Crystal Oscillator Status 0 = Disabled or in start-up phase 1 = Enabled and verified
R16528 (4090h) Clock Control 1	15	CLKOUT_ENA	0	CLKOUT output enable 0 = Disabled 1 = Enabled <i>Protected by user key</i>
	13	CLKOUT_OD	0	CLKOUT pin configuration 0 = CMOS 1 = Open Drain
	10:8	CLKOUT_SLOT	000	CLKOUT output enable ON slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Do not enable 111 = Do not enable
	6:4	CLKOUT_SLP SLOT	000	CLKOUT output SLEEP slot select 000 = Controlled by CLKOUT_ENA 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = Controlled by CLKOUT_ENA 111 = Controlled by CLKOUT_ENA

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16529 (4091h) Clock Control 2	15	XTAL_INH	0	Crystal Start-Up Inhibit 0 = Disabled 1 = Enabled When XTAL_INH=0, the internal RC oscillator will provide CLKOUT until the crystal oscillator is valid. When XTAL_INH=1, the 'ON' transition is inhibited until the crystal oscillator is valid.
	13	XTAL_ENA	0	Crystal Oscillator Enable 0 = Disabled at all times 1 = Enabled in OFF, ON, SLEEP states (Note that the BACKUP behaviour is determined by XTAL_BKUPENA.) This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.
	12	XTAL_BKUPE NA	1	Selects the RTC and 32.768kHz oscillator in BACKUP state 0 = RTC unclocked in BACKUP 1 = RTC maintained in BACKUP (Note that XTAL_ENA must also be set if the RTC is to be maintained in BACKUP)

Table 16 Clocking Control

13.2 CRYSTAL OSCILLATOR INTERRUPTS

The Crystal Oscillator (XTAL) is associated with two Interrupt event flags.

The XTAL_START_EINT interrupt is set if the crystal oscillator fails to start-up within a timeout period of approximately 24 seconds.

The XTAL_TAMPER_EINT interrupt is set if the crystal oscillator is stopped unexpectedly (eg. due to tampering). Note that this interrupt is only supported if the crystal oscillator has previously started up successfully. The XTAL_TAMPER_EINT is also set if the crystal oscillator is re-started following an unexpected interruption.

Each of these secondary interrupts triggers a primary Real Time Clock and Crystal Oscillator Interrupt, RTC_INT (see Section 23). In the case of XTAL_START_EINT, this can be masked by setting the mask bit(s) as described in Table 17.

ADDRESS	BIT	LABEL	DESCRIPTION
R16404 (4014h) Interrupt Status 4	7	XTAL_START_EINT	Crystal Oscillator Start Failure interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	6	XTAL_TAMPER_EINT	Crystal Oscillator Tamper interrupt (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.
R16412 (401Ch) Interrupt Status 4 Mask	7	IM_XTAL_START_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 17 Crystal Oscillator (XTAL) Interrupts

13.3 CRYSTAL OSCILLATOR CONNECTIONS

The crystal oscillator generates a 32.768kHz reference clock, which is used to provide reference clock for the Real Time Clock (RTC) in the WM8326. The oscillator requires an external crystal on the XTI and XTO pins, as well as two capacitors, connected as shown in Figure 17.

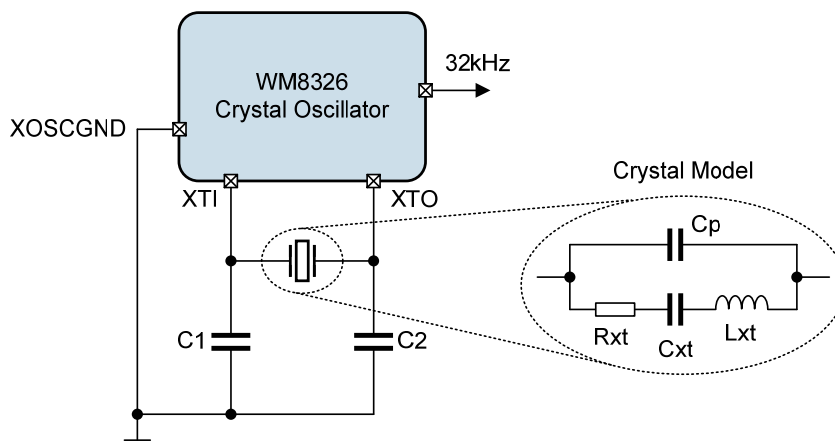


Figure 17 Crystal Oscillator

A suitable crystal oscillator should be selected in accordance with the following requirements:

PARAMETER	MIN	MAX	UNITS
Nominal frequency	32.768		kHz
Series resistance	50	70	kΩ
Maximum driving level	0.5		μW

Table 18 Selection of Crystal Oscillator Component

The load capacitors C1 and C2 should be selected according to the recommended load capacitance, C_L of the crystal, which is given by the following equation:

$$\text{Load Capacitance } C_L = \frac{C1 \times C2}{C1 + C2} + C_{\text{STRAY}}$$

Assuming $C1 = C2$ and $C_{\text{STRAY}} = 2.75\text{pF}$ (typical pad i/o capacitance), then:

$$C1 = C2 = 2 \times (C_L - 2.75\text{pF}).$$

For example, if the crystal has a load capacitance $C_L = 9\text{pF}$, then $C1 = C2 = 12.5\text{pF}$.

If a suitable 32.768kHz clock is already present elsewhere in the system, it is possible for the WM8326 to use that external clock instead. The external clock should be applied to pin XTI, and the XTO pin left floating in this case.

14 INSTANTCONFIG™ (ICE) AND OTP MEMORY CONTROL

14.1 GENERAL DESCRIPTION

The WM8326 is a highly configurable device which can be tailored specifically to the requirements of a complex system application. The sequencing and voltage control of the integrated DC-DC Converters and LDOs in power-up, shut-down and SLEEP conditions is crucial to the robust operation of the application.

In development, the WM8326 allows designers to modify or experiment with different settings of the control sequences by writing to the applicable registers in the OFF state prior to commanding an 'ON' state transition. Configuration settings can also be stored on an external EEPROM and loaded onto the WM8326 as required, using the InstantConfig™ EEPROM (ICE) interface.

For production use, the WM8326 provides an on-chip One-Time Programmable (OTP) memory, in which the essential parameters for starting up the device can be programmed. This allows the WM8326 to start up and shut down the system with no dependency on any other devices for application-specific configuration parameters.

14.2 ICE AND OTP MEMORY DEFINITION

An illustration of the WM8326 memory locations is shown in Figure 18. The main Register Map of the WM8326 contains a block of data in a 'Window' area which is mirrored in the OTP and/or the ICE Memory. Data from the external ICE Memory can be loaded into the Window area. Data can be transferred from the Window into OTP Memory and also from the OTP Memory into the Window. The Window is called the Device Configuration Register Window (DCRW); the data in this Window is mirrored in other locations within the WM8326 Register Map.

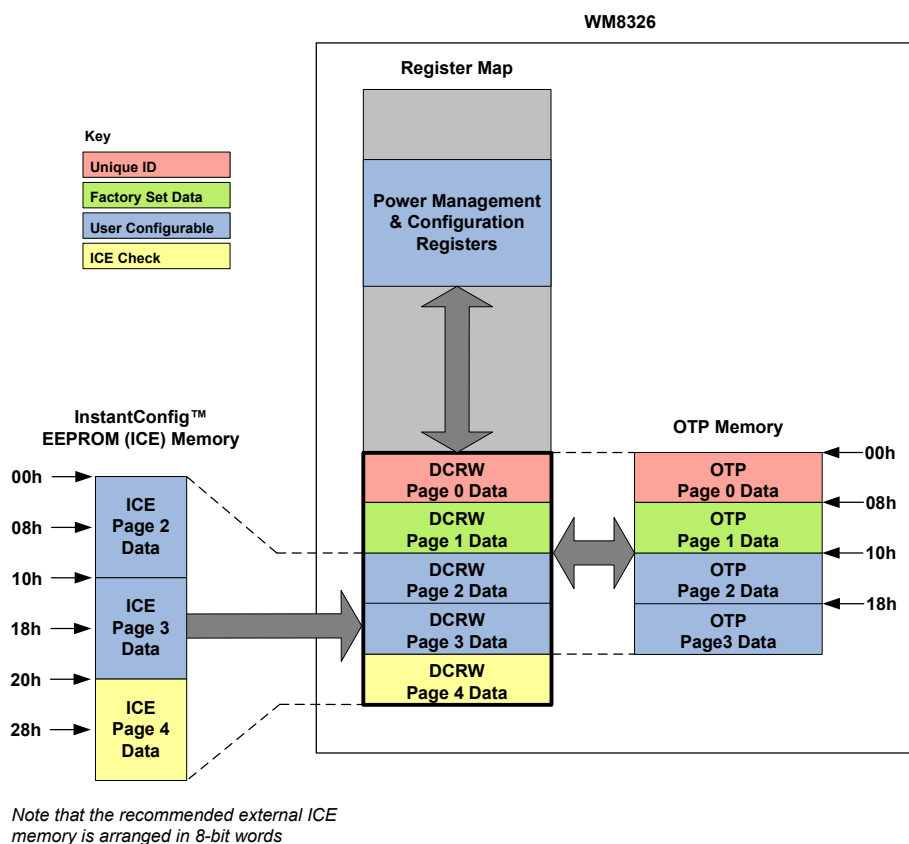


Figure 18 ICE and OTP Memory Layout

The DCRW contains 5 pages of data, as illustrated in Figure 18.

Page 0 of the DCRW contains a 128-bit pseudo-random unique ID. The unique ID is written to the OTP at the time of manufacture. It is copied to the DCRW when the WM8326 schedules an 'ON' transition. This data cannot be changed.

Page 1 of the DCRW contains factory-set calibration and configuration data. This data is written to the OTP at the time of manufacture. It is copied to the DCRW when the WM8326 schedules an 'ON' transition. This data cannot be changed.

Page 2 and Page 3 of the DCRW contain bootstrap configuration data. This defines the sequence and voltage requirements for powering up the WM8326, and for configuring functions such as the clocks, GPIO1-6 and LED status indicators. Under default conditions, the bootstrap data is loaded into the DCRW when the WM8326 schedules an 'ON' transition. The WM8326 automatically determines whether to load the bootstrap data from ICE or from OTP as described in Section 14.3.

Page 4 of the DCRW contains a register that is used for ICE validity checking. It is copied to the DCRW whenever the bootstrap configuration data is loaded from ICE in response to a start-up request in development mode. This register field enables the ICE data to be checked for valid content.

The OTP contains 4 pages of data, as illustrated in Figure 18. The contents of the OTP pages correspond to Pages 0, 1, 2 and 3 of the DCRW register map addresses.

The ICE memory contains 3 pages of data, as illustrated in Figure 18. The contents of the ICE pages correspond to Pages 2, 3 and 4 of the DCRW register map addresses.

Note that the ICE memory (recommended component) is arranged as 8-bit words in "big-endian" format, and is therefore addressed as 6 pages of 8-bit data, corresponding to 3 pages of 16-bit data. For example, the ICE memory address 00h corresponds to bits 15:8 of the first register map word in DCRW Page 2, and ICE address 01h corresponds to bits 7:0 of that same register word in DCRW.

The DCRW can be accessed directly using the Control Interface in the OFF, ON and SLEEP power states. Note that Read/Write access to the ICE or OTP memories is not possible directly; these can only be accessed by copying to/from the DCRW.

In the PROGRAM state, Page 2 and Page 3 of the DCRW can be written to the OTP.

14.3 BOOTSTRAP (START-UP) FUNCTION

Under default conditions, the WM8326 bootstrap configuration data is loaded when the WM8326 schedules an 'ON' transition. The bootstrap configuration data is loaded into Page 2 and Page 3 of the DCRW from either an external ICE or from the integrated OTP. (The factory-set data in Page 0 and Page 1 is always loaded from the integrated OTP memory.)

If Development mode is selected, then the bootstrap data is loaded from the InstantConfig™ EEPROM (ICE). If Development mode is not selected, then the bootstrap data is loaded from the OTP memory.

14.3.1 START-UP FROM OTP MEMORY

In volume production, development mode is not usually selected. In this case, the bootstrap configuration data is loaded from the internal OTP memory.

The WM8326 performs a check for valid OTP data; if the OTP_CUST_ID field is set to zero, then the WM8326 remains in the OFF power state. A non-zero OTP_CUST_ID field is used to confirm valid OTP contents.

The OTP memory contents are defined similarly to Pages 0, 1, 2 and 3 of the DCRW memory contents listed in Section 14.6.

14.3.2 START-UP FROM ICE MEMORY (DEVELOPMENT MODE)

Development mode is selected if a logic high level (referenced to the LDO12 VPMIC voltage) is present on SCLK2. This should be implemented using a pull-up resistor. See Section 14.3.4 for details of the External ICE Memory connection.

If development mode is selected, then the WM8326 performs a check for valid ICE data; if the ICE is not connected or contains invalid data, then the WM8326 remains in the OFF power state. The ICE data is deemed valid if the ICE_VALID_DATA field contains the value A596h.

The WM8326 also performs a check for valid contents in the OTP_CUST_ID field in development mode; if the OTP_CUST_ID field is set to zero, then the WM8326 remains in the OFF power state. A non-zero OTP_CUST_ID field is used to confirm valid ICE contents.

Note that, if a GPIO pin is configured in ICE memory as “Power On/Off request” (GPn_FN=02h), then inverted (active low) polarity should be selected for that GPIO (GPn_POL=0). The non-inverted (active high) polarity cannot be fully supported for this function in development mode.

This restriction is only applicable in development mode, and applies only to the GPIO “Power On/Off request” function. See Section 21 for details of the GPIO pin configuration registers.

The non-inverted (active high) polarity can be supported for the GPIO “Power On/Off request” function in development mode if the corresponding GPn_POL register bit in the OTP memory is set to 1. Note that, if the OTP memory is unprogrammed, the GPn_POL bits will default to 0.

14.3.3 START-UP FROM DCRW REGISTER SETTINGS

Under default settings, the bootstrap configuration data is always loaded when an ON transition is scheduled. For development purposes, this can be disabled by clearing the RECONFIG_AT_ON register bit. (Note that RECONFIG_AT_ON only selects whether Page 2/3/4 data is loaded; Page 0/1 data is always loaded from OTP whenever an ON transition is scheduled.)

When RECONFIG_AT_ON = 1, the bootstrap data is reloaded from either the ICE or OTP when an ON transition is scheduled. The logic level on SCLK2 is checked to determine whether the ICE or the OTP memory should be used. If RECONFIG_AT_ON = 0, then the latest contents of the DCRW are used to configure the start-up sequence.

Note that, when WM8326 start-up is scheduled using this method, the contents of OTP_CUST_ID is still checked for valid contents. In development mode, the ICE_VALID_DATA field is also checked. See Section 14.3.2 for details.

Note that the RECONFIG_AT_ON control register is locked by the WM8326 User Key. This register can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16390 (4006h) Reset Control	15	RECONFIG_A T_ON	1	Selects if the bootstrap configuration data should be reloaded when an ON transition is scheduled 0 = Disabled 1 = Enabled <i>Protected by user key</i>

Table 19 Bootstrap Configuration Reload Control

14.3.4 EXTERNAL ICE MEMORY CONNECTION

The recommended component for the external ICE is the Microchip 24AA32A, which provides 32 bytes of memory space. The ICE interfaces with the WM8326 via the SCLK2 and SDA2 pins, and initiates an I2C transfer of data from the ICE when required. The necessary electrical connections for this device are illustrated in Figure 19. The WM8326 assumes an EEPROM device ID of 1010 0001 (A1h) for ICE read cycles.

The ICE memory contents are defined similarly to Pages 2, 3 and 4 of the DCRW memory contents listed in Section 14.6.

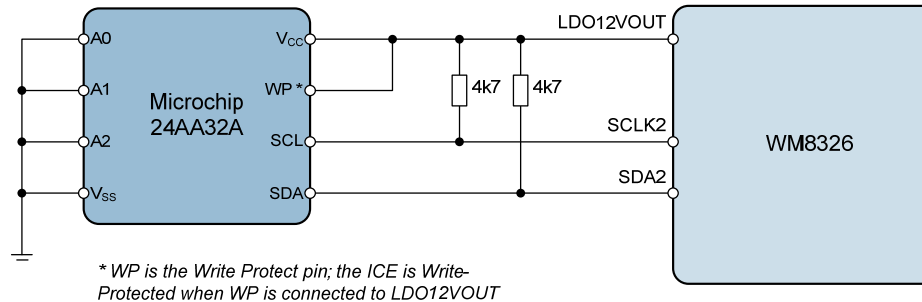


Figure 19 ICE Memory Connection

Note that the WM8326 does not support programming the external ICE memory.

External programming of ICE whilst physically connected to the WM8326 is possible by putting the WM8326 in the OFF state. This is supported on the evaluation board, provided the voltage levels on SCLK2 and SDA2 are less than or equal to the LDO12 VPMIC voltage. Note that the Write-Protect (WP) pin on the ICE must be connected to GND (Vss) in this case.

14.4 OTP / ICE MEMORY CONTROL

The OTP and ICE Memory commands are initiated by writing to the OTP Control Register, as defined in Section 14.4.6. The supported commands are described below.

READ ICE MEMORY - This command instructs the WM8326 to load data from the external ICE into the WM8326 DCRW memory area. Note that this command is performed automatically when the WM8326 starts up in development mode.

READ OTP MEMORY - This command instructs the WM8326 to load data from the integrated OTP memory area into the WM8326 DCRW memory area. Note that this command is performed automatically when the WM8326 starts up in normal (ie. non-development) mode.

WRITE OTP MEMORY - This command instructs the WM8326 to program the integrated OTP, by writing a copy of the DCRW memory area (Pages 0, 1, 2 and 3) to the OTP memory. This command should be performed after the required settings have been configured in the DCRW memory. The required settings can be configured in the DCRW either as a result of a ICE Read command, or else through register writes in the PROGRAM power state. Note that the Write OTP command should only be performed once on each OTP page; after the Write OTP command has been performed, the contents of the affected page(s) cannot be erased or re-programmed.

VERIFY OTP MEMORY - This command instructs the WM8326 to compare the contents of the OTP memory with the contents of the DCRW memory. The Verify OTP command performs a check that the OTP data is identical to the DCRW contents, in order to confirm the success of the Write OTP operation. For increased reliability, the WM8326 can apply a 'Margin Read' function when verifying the OTP memory; it is recommended that the Margin Read option is used, as described in Section 14.4.4.

FINALISE OTP PAGES - This command instructs the WM8326 to set the OTP_CUST_FINAL bit in the OTP memory. The Finalise OTP command ensures that any subsequent OTP_WRITE commands to Page 2 or Page 3 of the OTP will have no effect and that the OTP contents are maintained securely.

The OTP and ICE Memory commands are each described in the following sections. Note that, in some cases, commands may be executed on a single page of memory or may be executed as a Bulk operation on all available memory pages.

Completion of each OTP or ICE Memory command is indicated via an Interrupt flag, as described in Section 14.5. The pass/fail outcome of any OTP command is also indicated by the Interrupt bits. Note that read/write access to the WM8326 Register Map is not supported while a ICE/OTP command is in progress. It is recommended that the $\overline{\text{IRQ}}$ pin is configured to indicate any ICE/OTP Interrupt event; the host processor should read the OTP/ICE Interrupt event flags to confirm the OTP/ICE command status following the assertion of the $\overline{\text{IRQ}}$ pin.

The programming supply voltage PROGVD is required for the OTP Write commands and the OTP Finalise command. It is also necessary to overdrive the LDO12VOUT pin from an external supply. See Section 6 for details of the required supply voltages.

14.4.1 ENTERING / EXITING THE PROGRAM STATE

The ICE and OTP commands are only supported when the WM8326 is in the PROGRAM state. The WM8326 can only enter the PROGRAM state as a transition from the OFF state. This is commanded by setting the OTP_PROG register bit.

Important note - when the PROGRAM state is selected, the WM8326 will read all pages of the OTP memory into the corresponding pages of the DCRW. This is required in order to confirm if the OTP contents have already been finalised (see Section 14.4.5). The previous contents of the DCRW registers will be lost when the PROGRAM state is entered.

The transition into the PROGRAM state can be confirmed by reading the MAIN_STATE register field as defined in Section 11.2. When the MAIN_STATE register reads back a value of 01011, then the WM8326 is in the PROGRAM state.

In the PROGRAM state, the ICE and OTP commands are initiated by further writes to the OTP Control Register (R16394), as described in the following sections.

To exit the PROGRAM state and resume normal operations, a Device Reset must be scheduled.

14.4.2 OTP / ICE READ COMMAND

The Read command loads either one or all data pages from the ICE or OTP into the corresponding page(s) of the DCRW. The Read commands are selected by writing 1 to the OTP_READ bit.

To read the OTP, the OTP_MEM bit should be set to 1. To read the ICE, the OTP_MEM bit should be set to 0.

The Read Margin Level is selected by setting the OTP_READ_LVL. Note that this register relates to the OTP only; it has no effect on ICE Read commands. The recommended setting for the OTP Read command is 'Normal' level. The OTP_READ_LVL field should be set to 00b.

To read a single memory page, the applicable page is selected by setting the OTP_PAGE field. To read all memory pages, the OTP_BULK bit should be set to 1.

Note that the OTP_PAGE field is defined differently for ICE pages and for OTP pages, as detailed in Section 14.4.6.

All other bits in the OTP Control Register should be set to 0 when a Read command is issued. (Note that OTP_PROG should be set to 0 when a Read command is issued.)

For typical applications, the Bulk Read commands are recommended. The OTP Control Register contents for the OTP / ICE Bulk Read Commands are detailed in Table 20.

READ COMMAND	OTP CONTROL REGISTER VALUE
ICE Read All	0120h
OTP Read All	2120h

Table 20 OTP / ICE Read Command

14.4.3 OTP WRITE COMMAND

The Write command programs one or all data pages of the OTP with data from the corresponding page(s) of the DCRW. The Write commands are selected by writing 1 to the OTP_WRITE bit.

The OTP memory is selected by setting the OTP_MEM bit to 1. (Note that the WM8326 does not support programming the external ICE memory.)

To write a single memory page, the applicable page is selected by setting the OTP_PAGE field. To write all memory pages, the OTP_BULK bit should be set to 1.

Note that Page 0 and Page 1 will be programmed during manufacture, and cannot be re-written. OTP Write is then only possible to Page 2 and Page 3. Selecting the OTP_BULK bit will select OTP Write to Page 2 and Page 3 only.

Note that selecting the OTP_BULK option will cause an OTP Error to be indicated (see Section 14.5). This is because the Bulk Write to Page 0 and Page 1 is not permitted after the factory configuration of the WM8326. It is still possible to Verify the OTP Bulk Write, but the OTP_ERR_EINT flag must be cleared before doing so. The recommended procedure is to Write Page 2 and Page 3 using single page OTP Write commands.

All other bits in the OTP Control Register should be set to 0 when a Write command is issued. (Note that OTP_PROG should be set to 0 when a Write command is issued.)

The programming supply voltage PROGVD is required for the OTP Write command. It is also necessary to overdrive the LDO12VOUT pin from an external supply. See Section 6 for details of the required supply voltages.

For typical applications, it is recommended to Write Page 2 and Page 3 in two separate commands. The OTP Control Register contents for these OTP Write Commands are detailed in Table 21.

WRITE COMMAND	OTP CONTROL REGISTER VALUE
OTP Write Page 2	2202h
OTP Write Page 3	2203h

Table 21 OTP Write Command

14.4.4 OTP VERIFY COMMAND

The Verify command compares one or all data pages of the OTP with data in the corresponding page(s) of the DCRW. The Verify commands are selected by writing 1 to the OTP_VERIFY bit.

The OTP memory is selected by setting the OTP_MEM bit to 1. (Note that the WM8326 does not support verifying the external ICE memory.)

The Read Margin Level is selected by setting the OTP_READ_LVL. The recommended setting for the OTP Verify command is Margin 1. The OTP_READ_LVL field should be set to 10b.

To verify a single memory page, the applicable page is selected by setting the OTP_PAGE field. To verify all memory pages, the OTP_BULK bit should be set to 1.

All other bits in the OTP Control Register should be set to 0 when a Verify command is issued. (Note that OTP_PROG should be set to 0 when a Verify command is issued.)

If the OTP Verify operation is unsuccessful (ie. the WM8326 detects a difference between the selected pages of the OTP and DCRW memories), then this is indicated by the OTP_ERR_EINT Interrupt flag, as described in Section 14.5.

Note that, when Verifying the OTP after it has been Finalised, the CUST_OTP_FINAL bit needs to be set in the DCRW using a register write to R30736 prior to the OTP_VERIFY operation. This is because the OTP_FINAL command does not set the CUST_OTP_FINAL bit in the DCRW; it only sets it in the OTP memory. If the CUST_OTP_FINAL bit is not set in DCRW, then the OTP_VERIFY command will result in an OTP error indication.

The OTP Control Register contents for all OTP Verify Commands are detailed in Table 22.

VERIFY COMMAND	OTP CONTROL REGISTER VALUE
OTP Verify Page 0	2480h
OTP Verify Page 1	2481h
OTP Verify Page 2	2482h
OTP Verify Page 3	2483h
OTP Verify All	24A0h

Table 22 OTP Verify Command (Margin 1)

14.4.5 OTP FINALISE COMMAND

The Finalise command sets the OTP finalise bit for the user-programmable pages of the OTP memory. The Finalise commands are selected by writing 1 to the OTP_FINAL bit.

Note that Page 0 and Page 1 will be programmed and finalised during manufacture; these memory pages cannot be re-written by users. Following the user Finalise command, Page 2 and Page 3 of the OTP memory will be prevented from any further OTP Write commands. Each page of the OTP memory can be programmed only once; the OTP Finalise command ensures that any subsequent Write commands will have no effect and that the OTP contents are maintained securely.

The OTP memory is selected by setting the OTP_MEM bit to 1. (Note that the WM8326 does not support this function on the external ICE memory.)

The Customer Finalise bit (CUST_OTP_FINAL) is in Page 2. This page is selected by setting OTP_PAGE = 10. Note that the Page 2 finalise bit locks the contents of Page 2 and Page 3.

All other bits in the OTP Control Register should be set to 0 when a Finalise command is issued. (Note that OTP_PROG should be set to 0 when a Finalise command is issued.)

The programming supply voltage PROG_VDD is required for the OTP Finalise command. It is also necessary to overdrive the LDO12VOUT pin from an external supply. See Section 6 for details of the required supply voltages.

Note that the OTP_FINAL command does not set the CUST_OTP_FINAL bit in the DCRW; it only sets it in the OTP memory. Care is required when verifying a Finalised OTP page, to avoid an OTP error indication, as described in Section 14.4.4.

The OTP Control Register contents for the OTP Finalise Command is detailed in Table 23. This is the only recommended OTP Finalise Command; no variants of the Finalise Command should be used.

FINALISE COMMAND	OTP CONTROL REGISTER VALUE
OTP Finalise Page 2 (Note that this command finalises the contents of OTP Page 2 and Page 3.)	2802h

Table 23 OTP Finalise Command

14.4.6 OTP CONTROL REGISTER

The OTP Control register (R16394) is defined in Table 24. Note that some of the OTP Programming registers are locked by the WM8326 User Key. These registers can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16394 (400Ah) OTP Control	15	OTP_PROG	0	Selects the PROGRAM device state. 0 = No action 1 = Select PROGRAM mode Note that, after PROGRAM mode has been selected, the chip will remain in PROGRAM mode until a Device Reset. <i>Protected by user key</i>
	13	OTP_MEM	1	Selects ICE or OTP memory for Program commands. 0 = ICE 1 = OTP <i>Protected by user key</i>
	11	OTP_FINAL	0	Selects the FINALISE command, preventing further OTP programming. 0 = No action 1 = Finalise Command <i>Protected by user key</i>
	10	OTP_VERIFY	0	Selects the VERIFY command for the selected OTP memory page(s). 0 = No action 1 = Verify Command <i>Protected by user key</i>
	9	OTP_WRITE	0	Selects WRITE command for the selected OTP memory page(s). 0 = No action 1 = Write Command <i>Protected by user key</i>
	8	OTP_READ	0	Selects READ command for the selected memory page(s). 0 = No action 1 = Read Command <i>Protected by user key</i>
	7:6	OTP_READ_L VL [1:0]	00	Selects the Margin Level for READ or VERIFY OTP commands. 00 = Normal 01 = Reserved 10 = Margin 1 11 = Margin 2 <i>Protected by user key</i>
	5	OTP_BULK	0	Selects the number of memory pages for ICE / OTP commands. 0 = Single Page 1 = All Pages
	1:0	OTP_PAGE [1:0]	00	Selects the single memory page for ICE / OTP commands (when OTP_BULK=0). If OTP is selected (OTP_MEM = 1): 00 = Page 0 01 = Page 1 10 = Page 2 11 = Page 3 If ICE is selected (OTP_MEM = 0): 00 = Page 2 01 = Page 3 10 = Page 4 11 = Reserved

Table 24 OTP Memory Control

14.5 OTP / ICE INTERRUPTS

The OTP and ICE memories are associated with two Interrupt event flags.

The OTP_CMD_END_EINT interrupt is set each time an OTP / ICE Command has completed or if OTP Auto-Program has completed. (See Section 14.4 for a definition of the OTP and ICE Commands. See Section 14.6.3 for details of the OTP Auto-Program function.)

The OTP_ERR_EINT interrupt is set when an OTP / ICE Error has occurred. The errors detected include ICE Read Failure, OTP Verify Failure and attempted OTP Write to a page that has been 'Finalised'.

Each of these secondary interrupts triggers a primary OTP Memory Interrupt, OTP_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 25.

ADDRESS	BIT	LABEL	DESCRIPTION
R16402 (4012h) Interrupt Status 2	5	OTP_CMD_END_EINT	OTP / ICE Command End interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	4	OTP_ERR_EINT	OTP / ICE Command Fail interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16410 (401Ah) Interrupt Status 2 Mask	5	IM_OTP_CMD_END_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	4	IM_OTP_ERR_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 25 OTP Memory Interrupts

14.6 DCRW MEMORY CONTENTS

The DCRW is the ICE/OTP Register Window, as described in Section 14.2. Under normal operating conditions, this memory area is initialised with data from the integrated OTP or an external ICE memory. The DCRW memory addresses range from R30720 (7800h) to R30759 (7827h). The complete register map definition is described in Section 28.

The register fields in the DCRW allow the start-up configuration of the DC-DC Converters, the LDO Regulators, GPIO pins 1-6 and Status LED outputs to be programmed. The DCRW also provides control of selected Clocking functions and the Start-Up (SYSOK) voltage threshold.

Most of the DCRW contents are duplicates of control registers that exist in the main register area below the DCRW addresses. In these cases, reading or writing to either address will have the same effect.

Some register fields are defined only in the DCRW area; a detailed description of these fields is provided in the following sub-sections.

14.6.1 DCRW PAGE 0

Page 0 of the DCRW occupies register addresses R30720 (7800h) to R30727 (7807h). This contains factory-preset data which is loaded from OTP when an 'ON' state transition is scheduled.

Page 0 of the DCRW contains a 128-bit unique ID. Note that these fields are Read-Only in the OTP and cannot be changed.

14.6.2 DCRW PAGE 1

Page 1 of the DCRW occupies register addresses R30728 (7808h) to R30735 (780Fh). This contains factory-preset data which is loaded from OTP when an 'ON' state transition is scheduled.

Page 1 of the DCRW contains trim parameters that ensure the accuracy of the voltage references and the power management RC oscillator. Note that these fields are Read-Only in the OTP and cannot be changed.

14.6.3 DCRW PAGE 2

Page 2 of the DCRW occupies register addresses R30736 (7810h) to R30743 (7817h). This contains user-programmable data.

This page of data is normally loaded from OTP when 'ON' state transition is scheduled (except in Development Mode or if RECONFIG_AT_ON = 0). This page of data can also be loaded from OTP using the OTP_READ command; it can be written to the OTP using the OTP_WRITE command.

This page of data is loaded from the first page of ICE memory (00h to 0Fh) when 'ON' state transition is scheduled in Development Mode (if RECONFIG_AT_ON = 1). This page of data can also be loaded from ICE using the ICE Read command. Note that ICE Address 00h corresponds to bits 15:8 at the start address of DCRW Page 2; ICE Address 01h corresponds to bits 7:0 at the same DCRW address.

If the WM8326 configuration data is loaded from external ICE in response to an 'ON' state transition request, and the OTP_AUTO_PROG register bit is set, then the WM8326 will program the OTP with the contents Page 2 and Page 3 of the DCRW data, after the ICE data has been loaded and confirmed as valid. The WM8326 will also perform a Margin 1 Verify as part of the auto-program function.

The programming supply voltage PROG_VDD is required for the OTP_AUTO_PROG command. It is also necessary to overdrive the LDO12VOUT pin from an external supply. See Section 6 for details of the required supply voltages.

Using the auto-program function described above, the OTP will be finalised if the OTP_CUST_FINAL bit is set in the ICE data. Completion of the auto-program is indicated using the OTP interrupts, as described in Section 14.5. The auto-program completion is also indicated on the Status LED outputs, as described in Section 22.

The OTP_CUST_ID field is used to hold a Customer Identifier for the OTP data contents. Whenever an 'ON' state transition is requested, then the OTP_CUST_ID field is checked to confirm valid OTP data. If the OTP_CUST_ID field is set to zero, then the WM8326 remains in the OFF power state. A non-zero OTP_CUST_ID field is used to confirm valid OTP contents.

The OTP_CUST_FINAL bit is used to control whether the user-programmable OTP data (Page 2 and Page 3) is finalised. If OTP_CUST_FINAL is set in the OTP and also set in the DCRW, then the WM8326 prevents any further Writes to the OTP. If the DCRW has been loaded from the OTP, then the OTP_CUST_FINAL bit indicates whether any further Write operations are possible. If the DCRW has been loaded from the ICE, and the OTP auto-programming option is selected (see above), then the value of the OTP_CUST_FINAL bit will be copied from the ICE memory to the OTP memory.

The above registers are defined in Table 26.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R30736 (7810h) Customer OTP ID	15	OTP_AUTO_PROG	0	If this bit is set when bootstrap data is loaded from ICE (in development mode), then the ICE contents will be programmed in the OTP.
	14:1	OTP_CUST_ID [13:0]	0000h	This field is checked when an 'ON' transition is requested. A non-zero value is used to confirm valid data.
	0	OTP_CUST_FINAL	0	If OTP_CUST_FINAL is set in the OTP and also set in the DCRW, then no further Writes are possible to the OTP.

Table 26 OTP Registers - DCRW Page 2

The remaining contents of DCRW Page 2 include the registers listed in Table 27, which are defined in other sections of this datasheet.

REGISTER	FUNCTION	REFERENCE
DC1_ON_SLOT [2:0]	DC-DC Converter 1	See Section 15.11.2
DC1_FREQ [1:0]		See Section 15.11.2
DC1_PHASE		See Section 15.11.2
DC1_ON_VSEL [6:2]		See Section 15.11.2
DC1_CAP [1:0]		See Section 15.11.2
DC2_ON_SLOT [2:0]	DC-DC Converter 2	See Section 15.11.2
DC2_FREQ [1:0]		See Section 15.11.2
DC2_PHASE		See Section 15.11.2
DC2_ON_VSEL [6:2]		See Section 15.11.2
DC2_CAP [1:0]		See Section 15.11.2
DC3_ON_SLOT [2:0]	DC-DC Converter 3	See Section 15.11.2
DC3_PHASE [1:0]		See Section 15.11.2
DC3_ON_VSEL [6:2]		See Section 15.11.2
DC3_CAP [1:0]		See Section 15.11.2
DC4_ON_SLOT [2:0]	DC-DC Converter 4	See Section 15.11.2
DC4_PHASE [1:0]		See Section 15.11.2
DC4_ON_VSEL [6:2]		See Section 15.11.2
DC4_CAP [1:0]		See Section 15.11.2
LDO1_ON_SLOT [2:0]	LDO Regulator 1	See Section 15.11.3
LDO1_ON_VSEL [4:0]		See Section 15.11.3
LDO2_ON_SLOT [2:0]	LDO Regulator 2	See Section 15.11.3
LDO2_ON_VSEL [4:0]		See Section 15.11.3
LDO3_ON_SLOT [2:0]	LDO Regulator 3	See Section 15.11.3
LDO3_ON_VSEL [4:0]		See Section 15.11.3
LDO4_ON_SLOT [2:0]	LDO Regulator 4	See Section 15.11.3
LDO4_ON_VSEL [4:0]		See Section 15.11.3
LDO5_ON_SLOT [2:0]	LDO Regulator 5	See Section 15.11.3
LDO5_ON_VSEL [4:0]		See Section 15.11.3
LDO6_ON_SLOT [2:0]	LDO Regulator 6	See Section 15.11.3
LDO6_ON_VSEL [4:0]		See Section 15.11.3
LDO7_ON_SLOT [2:0]	LDO Regulator 7	See Section 15.11.3
LDO7_ON_VSEL [4:0]		See Section 15.11.3
LDO8_ON_SLOT [2:0]	LDO Regulator 8	See Section 15.11.3
LDO8_ON_VSEL [4:0]		See Section 15.11.3

Table 27 DCRW Page 2

14.6.4 DCRW PAGE 3

Page 3 of the DCRW occupies register addresses R30744 (7818h) to R30751 (781Fh). This contains user-programmable data.

This page of data is normally loaded from OTP when 'ON' state transition is scheduled (except in Development Mode or if RECONFIG_AT_ON = 0). This page of data can also be loaded from OTP using the OTP_READ command; it can be written to the OTP using the OTP_WRITE command.

This page of data is loaded from the second page of ICE memory (10h to 1Fh) when 'ON' state transition is scheduled in Development Mode (if RECONFIG_AT_ON = 1). This page of data can also be loaded from ICE using the ICE Read command. Note that ICE Address 10h corresponds to bits 15:8 at the start address of DCRW Page 3; ICE Address 11h corresponds to bits 7:0 at the same DCRW address.

The contents of DCRW Page 3 include the registers listed in Table 28.

REGISTER	FUNCTION	REFERENCE
LDO9_ON_SLOT [2:0]	LDO Regulator 9	See Section 15.11.3
LDO9_ON_VSEL [4:0]		See Section 15.11.3
LDO10_ON_SLOT [2:0]	LDO Regulator 10	See Section 15.11.3
LDO10_ON_VSEL [4:0]		See Section 15.11.3
LDO11_ON_SLOT [2:0]	LDO Regulator 11	See Section 15.11.3
LDO11_ON_VSEL [3:0]		See Section 15.11.3
DC4_SLV	DC-DC Converter 4	See Section 15.6.1
EPE1_ON_SLOT [2:0]	External Power Converter Enable	See Section 15.11.4
EPE2_ON_SLOT [2:0]		See Section 15.11.4
GP1_DIR	GPIO1	See Section 21.3
GP1_PULL [1:0]		See Section 21.3
GP1_INT_MODE		See Section 21.3
GP1_PWR_DOM		See Section 21.3
GP1_POL		See Section 21.3
GP1_OD		See Section 21.3
GP1_ENA		See Section 21.3
GP1_FN [3:0]		See Section 21.3
GP2_DIR	GPIO2	See Section 21.3
GP2_PULL [1:0]		See Section 21.3
GP2_INT_MODE		See Section 21.3
GP2_PWR_DOM		See Section 21.3
GP2_POL		See Section 21.3
GP2_OD		See Section 21.3
GP2_ENA		See Section 21.3
GP2_FN [3:0]		See Section 21.3
GP3_DIR	GPIO3	See Section 21.3
GP3_PULL [1:0]		See Section 21.3
GP3_INT_MODE		See Section 21.3
GP3_PWR_DOM		See Section 21.3
GP3_POL		See Section 21.3
GP3_OD		See Section 21.3
GP3_ENA		See Section 21.3
GP3_FN [3:0]		See Section 21.3
GP4_DIR	GPIO4	See Section 21.3
GP4_PULL [1:0]		See Section 21.3
GP4_INT_MODE		See Section 21.3
GP4_PWR_DOM		See Section 21.3
GP4_POL		See Section 21.3
GP4_OD		See Section 21.3
GP4_ENA		See Section 21.3
GP4_FN [3:0]		See Section 21.3
GP5_DIR	GPIO5	See Section 21.3
GP5_PULL [1:0]		See Section 21.3
GP5_INT_MODE		See Section 21.3
GP5_PWR_DOM		See Section 21.3
GP5_POL		See Section 21.3
GP5_OD		See Section 21.3
GP5_ENA		See Section 21.3
GP5_FN [3:0]		See Section 21.3
GP6_DIR	GPIO6	See Section 21.3
GP6_PULL [1:0]		See Section 21.3
GP6_INT_MODE		See Section 21.3

REGISTER	FUNCTION	REFERENCE
GP6_PWR_DOM		See Section 21.3
GP6_POL		See Section 21.3
GP6_OD		See Section 21.3
GP6_ENA		See Section 21.3
GP6_FN [3:0]		See Section 21.3
CLKOUT_SLOT [2:0]	Clocking	See Section 13.1
XTAL_ENA		See Section 13.1
XTAL_INH		See Section 13.1
WDOG_ENA	Watchdog Timer	See Section 25
LED1_SRC [1:0]	System Status LED Drivers	See Section 22.2
LED2_SRC [1:0]		See Section 22.2
SYSOK_THR [2:0]	Supply Voltage Monitoring	See Section 24.4

Table 28 DCRW Page 3

14.6.5 DCRW PAGE 4

Page 4 of the DCRW occupies register addresses R30752 (7820h) to R30759 (7827h).

This page of data is loaded from the third page of ICE memory (20h to 2Fh) when 'ON' state transition is scheduled in Development Mode. This page of data can also be loaded from ICE using the ICE Read command. Note that ICE Address 20h corresponds to bits 15:8 at the start address of DCRW Page 4; ICE Address 21h corresponds to bits 7:0 at the same DCRW address.

The ICE_VALID_DATA register is used to hold a validation field for the ICE data contents. If the WM8326 configuration data is loaded from the external ICE in response to an 'ON' state transition request in Development Mode, then the ICE_VALID_DATA field is checked to confirm valid ICE data.

The ICE data is deemed valid if the ICE_VALID_DATA field contains the value A596h. If the ICE is not connected or contains invalid data, then the WM8326 remains in the OFF power state until a Device Reset.

The ICE_VALID_DATA register is defined in Table 29.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R30759 (7827h) ICE CHECK DATA	15:0	ICE_VALID_ DATA [15:0]	0000h	This field is checked in development mode when an 'ON' transition is requested. A value of A596h is required to confirm valid data.

Table 29 ICE Registers - DCRW Page 5

15 POWER MANAGEMENT

15.1 GENERAL DESCRIPTION

The WM8326 provides 4 DC-DC synchronous buck converters and 11 LDO regulators. The regulators comprise general purpose LDOs (LDO1 - LDO6) and low-noise analogue LDOs (LDO7 - LDO10). The analogue LDOs offer superior PSRR, noise and load-transient performance. LDO11 is a low power LDO intended for powering “always on” circuits connected to the WM8326; this LDO can be configured to remain enabled in the OFF state.

These power management components are designed to support application processors and associated peripherals. DC-DC1 and DC-DC2 are intended to provide power to the processor voltage domains; DC-DC3 is suitable for powering memory circuits or for use as a pre-regulator for the LDOs. The output voltage of each of the buck converters and regulators is programmable in software through control registers. DC-DC3 and DC-DC4 can be ganged together in dual mode, providing an increased current capability for higher power processor voltage domains.

The WM8326 can execute programmable sequences of enabling and disabling the DC-DC Converters and LDO Regulators as part of the transitions between the ON, OFF and SLEEP power states. The WM8326 power management circuits can also interface with configurable hardware control functions supported via GPIO pins. These include GPIO inputs for selecting alternate voltages or operating modes, and GPIO outputs for controlling external power management circuits.

The configuration of the power management circuits, together with some of the GPIO pins and other functions, may be stored in the integrated OTP memory. This avoids any dependence on a host processor to configure the WM8326 at start-up. See Section 14 for details of the OTP memory.

15.2 DC-DC CONVERTER AND LDO REGULATOR ENABLE

The integrated DC-DC Converters and LDO Regulators can each be enabled in the ON or SLEEP power states by setting the *DCm_ENA* or *LDO_n_ENA* bits as defined in Section 15.11.1. Note that setting the *DCm_ENA* or *LDO_n_ENA* bits in the OFF state will not enable the DC-DC Converters or LDO Regulators. These bits should not be written to when the WM8326 is in the OFF state; writing to these bits in the OFF state may cause a malfunction.

In many applications, there will be no need to write to the *DCm_ENA* or *LDO_n_ENA* bits, as these bits are controlled by the WM8326 when a power state transition is scheduled. Dynamic, run-time control of the DC-DC Converters or LDO Regulators is also possible by writing to these registers.

The DC-DC Converters and LDO Regulators can be assigned to a Hardware Enable (GPIO) input for external enable/disable control. In this case, the converter or regulator is not affected by the associated *DCm_ENA* or *LDO_n_ENA* bits. See Section 15.3 for further details.

The WM8326 can also control other circuits, including external DC-DC Converters or LDO Regulators using the External Power Enable (EPE) outputs. The External Power Enable outputs are alternate functions supported via GPIO - see Section 21. The External Power Enable outputs can be controlled in the same way as the internal DC-DC Converters and LDO Regulators. The associated control bits are *EPE1_ENA* and *EPE2_ENA*, as defined in Section 15.11.1.

LDO Regulator 11 is a Low Power LDO Regulator, which is configured differently to the other LDOs. It is a low-power LDO intended for “Always-On” functions external to the WM8326 and can be enabled when the WM8326 is in the OFF power state.

When *LDO11_FRCENA* is set, then LDO11 is enabled at all times in the OFF, ON and SLEEP states. Note that LDO11 is always disabled in the BACKUP and NO POWER states. See Section 15.11.3 for the definition of *LDO11_FRCENA*.

The current commanded state of each of the DC-DC Converters, LDO Regulators and EPE outputs is indicated in the *DCm_STS*, *LDO_n_STS* and *EPE_n_STS* register bits.

If a fault condition causes any converter or regulator to be disabled, then the associated *_ENA* and *_STS* fields are reset to 0.

15.3 TIMESLOT CONTROL AND HARDWARE ENABLE (GPIO) CONTROL

The DC-DC Converters (1-4) and LDO Regulators (1-11) may be programmed to switch on in a selected timeslot within the ON sequence using the `DCm_ON_SLOT` or `LDOn_ON_SLOT` fields. These register fields are defined in Section 15.11.2 and Section 15.11.3. Alternatively, these fields can be used to assign a converter / regulator to one of the Hardware Enable Inputs. (The Hardware Enable Inputs are alternate functions supported via GPIO - see Section 21.)

Converters / regulators which are assigned to one of the Hardware Enable Inputs are enabled or disabled according to the logic level of the respective GPIO input in the ON or SLEEP power states. The Hardware Enable Inputs are effective from the end of the ON sequence until the start of the OFF sequence. Note that the GPIO Hardware Enable function is not the same as the GPIO Hardware Control function.

Any converters / regulators which are assigned to timeslots within the ON sequence will be disabled in the reverse sequence when an OFF sequence is scheduled. Any converters / regulators which are not assigned to timeslots, or are assigned to Hardware Enable Inputs, will be disabled immediately at the start of the OFF sequence.

Each of the converters / regulators may also be programmed to be disabled in a selected timeslot within the SLEEP sequence using the `DCm_SLP_SLOT` or `LDOn_SLP_SLOT` fields. In the case of converters / regulators which are not disabled by the SLEEP sequence, these fields determine in which timeslot each converter or regulator enters its SLEEP configuration.

Any converters / regulators which are disabled as part of the SLEEP sequence will be enabled in the reverse sequence when a WAKE transition is scheduled.

By default, the OFF sequence is the reverse of the ON sequence. Similarly, the WAKE sequence is the reverse of the SLEEP sequence. If a different behaviour is required, this can be achieved by writing to the `_ON_SLOT` or `_SLP_SLOT` registers between transitions in order to re-define the sequences.

Any converters / regulators which are assigned to Hardware Enable Inputs will remain under control of the Hardware Enable Inputs in the SLEEP power state. In this case, the `DCm_SLP_SLOT` or `LDOn_SLP_SLOT` fields determine in which timeslot the converter / regulator enters its SLEEP configuration.

The WM8326 will control the `DCm_ENA` or `LDOn_ENA` bit (see Section 15.2) for any converter / regulator that is enabled or disabled during the power state transitions. In the case of a converter / regulator assigned to a Hardware Enable (GPIO) input, the `DCm_ENA` or `LDOn_ENA` bit is not controlled and the converter / regulator is not affected by this bit.

The DC-DC converters include a soft-start feature that limits in-rush current at start-up. However, in order to further reduce supply in-rush current, it is recommended that the individual converters are programmed to start up in different time slots within the start-up sequence, as described in Section 11.3.

Similarly, it is recommended that the individual LDO regulators are programmed to start up in different time slots within the start-up sequence, as described in Section 11.3.

The External Power Enable (EPE) outputs, EPE1 and EPE2, may also be assigned to timeslots in the ON / SLEEP sequences or assigned to Hardware Enable inputs using the `EPEn_ON_SLOT` and `EPEn_SLP_SLOT` fields described in 15.11.4.

Note that a transition from the SLEEP state to the OFF state is not a controlled transition. If an 'OFF' event occurs whilst in the SLEEP state, then the WM8326 will select the OFF state, but all the enabled converters and regulators will be disabled immediately; the time-controlled sequence is not implemented in this case. See Section 11.3 for details of the WM8326 'OFF' events.

15.4 OPERATING MODE CONTROL

15.4.1 DC-DC SYNCHRONOUS BUCK CONVERTERS

The DC-DC Converters DC-DC1 - DC-DC4 can be configured to operate in four different operating modes. The operating modes are summarised in Table 30. For more detailed information on the DC-DC (Buck) Converter operating modes, see Section 15.14.2.

DC-DC CONVERTER OPERATING MODE	DESCRIPTION
Forced Continuous Conduction Mode (FCCM)	High performance mode for all static and transient load conditions.
Auto Mode: Continuous / Discontinuous Conduction with Pulse-Skipping Mode (CCM/DCM with PS)	High efficiency mode for all static and transient load conditions. Performance may be less than FCCM mode for heavy load transients.
Hysteretic Mode	High efficiency mode for light static and light transient loads only. Maximum load current is restricted; output voltage ripple is increased.
LDO Mode	Power saving mode for light loads only. High efficiency for ultra light loads. Low current soft-start control.

Table 30 DC-DC Synchronous Buck Converter Operating Modes

The operating mode of the DC-DC Converters in the ON power state is selected using the `DCm_ON_MODE` register fields. The operating mode of the DC-DC Converters in the SLEEP power state is selected using the `DCm_SLP_MODE` register fields.

When changing the operating mode of the DC-DC Converters in preparation for an increased load, a set-up time of 100µs should be allowed for the operating mode to be established before applying the new load.

Note that the operating mode of the DC-DC Converters may also be controlled by the Hardware Control inputs. The Hardware Control inputs are alternate functions supported via GPIO. See Section 15.8 for details of Hardware Control.

15.4.2 LDO REGULATORS

The LDO Regulators LDO1 - LDO10 can be configured to operate in Normal operating mode or in Low Power mode.

The operating mode of the LDO Regulators in the ON power state is selected using the `LDOn_ON_MODE` register fields. The operating mode of the LDO Regulators in the SLEEP power state is selected using the `LDOn_SLP_MODE` register fields.

For the standard LDOs, LDO1 - LDO6, two different Low Power modes are provided, offering limited load current capability and reduced quiescent current. When Low Power mode is selected in the ON or SLEEP power states, then the `LDOn_LP_MODE` register bits determine which Low Power mode is selected.

Note that the operating mode and output voltage of the LDO Regulators may also be controlled by the Hardware Control inputs. The Hardware Control inputs are alternate functions supported via GPIO. See Section 15.8 for details of Hardware Control.

15.5 OUTPUT VOLTAGE CONTROL

15.5.1 DC-DC SYNCHRONOUS BUCK CONVERTERS

The output voltage of the DC-DC Converters 1-4 in the ON power state is selected using the `DCm_ON_VSEL` register fields. The output voltage of these converters in the SLEEP power state is selected using the `DCm_SLP_VSEL` register fields.

DC-DC Converters 1 and 2 support two different switching frequencies, as described in Section 15.6. Note that the supported output voltage range for these converters is restricted in the 4MHz mode; for output voltages greater than 1.4V, the 2MHz mode must be used.

The DC-DC Converters are dynamically programmable - the output voltage may be adjusted in software at any time. These converters are step-down converters; their output voltage can therefore be lower than the input voltage, but cannot be higher.

Note that the output voltage of DC-DC Converters 1 and 2 may also be controlled using the Dynamic Voltage Scaling features described in Section 15.6. Software control (using register writes) and hardware control (using the Hardware DVS Control inputs supported via GPIO) is supported.

Note that the output voltage of the DC-DC Converters may also be controlled by the Hardware Control inputs. The Hardware Control inputs are alternate functions supported via GPIO. See Section 15.8 for details of Hardware Control.

When changing the output voltage of DC-DC Converters 1 and 2, the GPIO output "DC-DC m DVS Done" can be used to confirm the DVS Control has completed; see Section 15.6 for details.

15.5.2 LDO REGULATORS 1-10

The output voltage of the LDO Regulators 1-10 in the ON power state is selected using the LDO n _ON_VSEL register fields. The output voltage of the LDO Regulators in the SLEEP power state is selected using the LDO n _SLP_VSEL register fields.

The LDO Regulators are dynamically programmable - the output voltage may be adjusted in software at any time.

Note that the output voltage of the LDO Regulators may also be controlled by the Hardware Control inputs. The Hardware Control inputs are alternate functions supported via GPIO. See Section 15.8 for details of Hardware Control.

15.5.3 LDO REGULATOR 11

The output voltage of LDO11 can be set in two ways - it can be commanded directly, or it can be commanded to follow the DC-DC Converter 1 output voltage.

When LDO11_VSEL_SRC = 0, then the output voltage of LDO11 is set by LDO11_ON_VSEL (in the ON state) or by LDO11_SLP_VSEL (in the SLEEP state) in the same way as the other LDOs.

When LDO11_VSEL_SRC = 1, the output voltage of LDO11 follows the output voltage of DC-DC Converter 1. This enables both domains to be changed at the same time, eg. the processor core and processor 'alive' domains. In this case, the LDO11 output voltage follows DC1_ON_VSEL or DC1_SLP_VSEL in the ON state or SLEEP state respectively.

Note that, when LDO11_VSEL_SRC = 1, the LDO11 regulator adopts the nearest achievable output voltage, which may not be identical to the DC-DC1 voltage, due to the more limited range and resolution of LDO11 - the output voltage of LDO11 is in the range 0.8V to 1.55V in 50mV steps; the output voltage of DC-DC1 is in the range 0.6V to 1.8V in 12.5mV steps. If DC-DC1 is disabled, then the LDO11 voltage tracking feature is not supported, and the LDO11 output voltage will be 0.8V.

15.6 DC-DC SYNCHRONOUS BUCK CONVERTER CONTROL

Soft-Start control is provided for each of the DC-DC synchronous buck converters, using the DC m _SOFT_START register fields. When a DC-DC Converter is switched on, the soft-start circuit will apply current limiting in order to control the in-rush current. For DC-DC1 and DC-DC2, the current limit is increased through up to 8 stages to the full load condition. The DC m _SOFT_START registers select the duration of these stages. (Note that, under light loads, the full start-up may be achieved in fewer than 8 stages.) A similar function is provided for DC-DC3 and DC-DC4, but only 3 intermediate stages are implemented for these converters.

When DC-DC3 or DC-DC4 is operating in Hysteretic Mode, the maximum DC output current can be set using the DC3_STNBY_LIM and DC4_STNBY_LIM registers. See Section 15.4.1 for details of the DC-DC3 and DC-DC4 operating modes.

To ensure stable operation, the register fields `DCm_CAP` must be set for each of the DC-DC Converters according to the output capacitance. (Note that these fields are set via OTP/ICE settings only; they cannot be changed by writing to the control register.) The choice of output capacitor is described in Section 30.3.

When a DC-DC Converter is disabled, the output pin can be configured to be floating or to be actively discharged. This is selected using `DCm_FLT`.

DC-DC Converters 1 and 2 also support selectable switching frequency. This can either be 2MHz or 4MHz, according to the `DCm_FREQ` register field. (Note that these fields are set via OTP/ICE settings only; they cannot be changed by writing to the control register.) The switching frequency of DC-DC3 is fixed at 2MHz.

Note that the supported output voltage range for DC-DC Converters 1 and 2 is restricted in the 4MHz mode; for output voltages greater than 1.4V, the 2MHz mode must be used.

Note that the maximum output current for DC-DC Converters 1 and 2 is limited to 1250mA in the 4MHz mode; for output currents up to 2500mA, the 2MHz mode must be used.

The switching phase of each DC-DC converter can be set using the `DCm_PHASE` bits. Where two converters are operating at the same switching frequency, the supply current ripple can be minimised by selecting a different switching phase for each converter.

The Dynamic Voltage Scaling (DVS) feature on DC-DC1 and DC-DC2 enables hardware or software selection of an alternate output voltage, `DCm_DVS_VSEL`. This may be useful if a short-term variation in output voltage is required.

The DVS voltage (set by `DCm_DVS_VSEL`) may be selected by setting `DCm_DVS_SRC` = 01. Alternatively, the DVS voltage may be selected under control of one of the Hardware DVS Control inputs supported via the GPIO pins. See Section 21 for details of configuring the GPIO pins as Hardware DVS Control inputs.

Whenever the DVS voltage is selected by any method, the DVS selection takes precedence over the ON, SLEEP or Hardware Control (HWC) configuration. See Section 15.8 for details of Hardware Control options.

The output voltage ramp rate is selectable for DC-DC Converters 1 and 2. The `DCm_RATE` field selects the rate of change of output voltage, whether this is in response to an operating mode transition, or any hardware or software command. Note that the `DCm_RATE` field is accurate in Forced Continuous Conduction Mode (FCCM); in other modes, the actual slew rate may be longer in the case of a decreasing output voltage selection, especially under light load conditions.

The WM8326 can indicate the status of the Dynamic Voltage Scaling via a GPIO pin configured as a "DC-DC1 DVS Done" or "DC-DC2 DVS Done" output (see Section 21). When a GPIO pin is configured to indicate the DVS status, this signal is temporarily de-asserted during a DVS transition on the associated DC-DC Converter, and is subsequently asserted to indicate the transition has completed.

Note that the GPIO DVS outputs indicate the progress of all output voltage slews; they are not limited to transitions associated with `DCm_DVS_SRC`; the GPIO DVS output also indicates the status of a slew caused by a write to the `DCm_ON_VSEL` register, or a slew to the `DCm_SLP_VSEL` voltage. Note also that the GPIO DVS outputs are indicators of the DVS control mechanism only; they do not confirm the output voltage accuracy. The output voltage can be checked using the voltage status bits if required (see Section 15.2).

15.6.1 DC-DC3 / DC-DC4 DUAL MODE

DC-DC Converters 3 and 4 can be configured to operate in 'Dual' mode, where the two converters are ganged together to support an increased current capability. In this mode, the two converters employ a common voltage feedback circuit in order to ensure the two outputs are accurately aligned. The dual mode is selected by configuring DC-DC4 as a 'Slave' to DC-DC3.

When the `DC4_SLV` register is set, then DC-DC4 comes under the control of the DC-DC3 registers, and both converters are controlled together. All other DC-DC4 control registers have no effect when `DC4_SLV` is set. Note that the `DC4_SLV` register can only be controlled via OTP/ICE configuration; it cannot be changed by writing to the control register.

Note that, when DC-DC3 and DC-DC4 are operating in dual mode, then discontinuous conduction mode operation is not possible. If the selected operating mode of DC-DC3 is Auto mode (Continuous / Discontinuous Conduction with Pulse Skipping), then Forced Continuous Conduction mode (FCCM) will be implemented.

In Forced Continuous Conduction mode, the dual ganged converters support an increased current capability, as detailed in the Electrical Characteristics - see Section 7.1. In the Hysteretic and LDO operating modes, the current limit of the dual-ganged converters is the same as for a single buck converter, DC-DC3.

15.7 LDO REGULATOR CONTROL

The LDO Regulators 1-10 can be configured to act as Current Limited Switches by setting the LDO_n_SWI field. When this bit is selected, there is no voltage regulation and the operating mode and output voltage controls of the corresponding LDO are ignored. In Switch mode, the switch is enabled (closed) and disabled (opened) by enabling or disabling the LDO.

Note that Switch mode cannot be selected via the OTP memory settings, and must be configured after the WM8326 has entered the ON state.

When the LDO Regulator is disabled (and Switch mode is not selected), the output pin can be configured to be floating or to be actively discharged. This is selected using LDO_n_FLT.

15.8 HARDWARE CONTROL (GPIO)

The DC-DC Converters, LDO Regulators and EPE outputs may be controlled by the Hardware Control inputs supported via the GPIO pins. The DC_m_HWC_SRC, LDO_n_HWC_SRC or EPE_n_HWC_SRC fields determine which of these Hardware Control inputs is effective.

See Section 21 for details of configuring the GPIO pins as Hardware Control inputs. Note that the GPIO Hardware Control function is not the same as the GPIO Hardware Enable function.

Hardware Control is only possible when the applicable DC_m_ENA, LDO_n_ENA or EPE_n_ENA control bit is set (see Section 15.2), or if a Hardware Enable has been assigned to the relevant function and is asserted.

The action taken in response to the selected Hardware Control inputs is configurable for each DC-DC Converter, LDO Regulator or EPE output. The available options are described below.

When a Hardware Control input is assigned to a DC-DC Buck Converter, and is asserted, the operating mode and output voltage of the relevant DC-DC Converter is determined by the DC_m_HWC_VSEL and DC_m_HWC_MODE fields; this takes precedence over the normal ON or SLEEP settings.

Note that the Hardware Control input can be used to disable a DC-DC Buck Converter if required, by setting DC_m_HWC_MODE = 01.

When a Hardware Control input is assigned to LDO Regulators 1-10, and is asserted, the operating mode and output voltage of the relevant LDO Regulators is determined by the LDO_n_HWC_VSEL and LDO_n_HWC_MODE fields; this takes precedence over the normal ON or SLEEP settings.

Note that, for the standard LDOs (LDO1 - LDO6), when Low Power Mode is selected (LDO_n_HWC_MODE = 00 or 10), then the Low Power mode type is determined by the LDO_n_LP_MODE register bits.

When a Hardware Control input is assigned to the External Power Enable (EPE) outputs, and is asserted, the relevant EPE outputs are controlled as determined by the EPE_n_HWC_ENA field; this takes precedence over the normal ON or SLEEP settings. The available options are to de-assert the EPE, or for the EPE to remain under control of EPE_n_ENA.

15.9 FAULT PROTECTION

Each of the DC-DC Buck Converters (1 to 4) is monitored for voltage accuracy and fault conditions. An undervoltage condition is set if the output voltage falls below the required level by more than the applicable undervoltage margin, as specified in Section 7.1.

Each LDO Regulator (1 to 10) is monitored for voltage accuracy and fault conditions. An undervoltage condition is set if the output voltage falls below the required level by more than the undervoltage margin, as specified in Section 7.2.

The `DCm_ERR_ACT` and `LDOm_ERR_ACT` fields configure the fault response to an Undervoltage condition. An Interrupt is always triggered under this condition (see Section 15.12); additional action can also be selected independently for each converter / regulator. The options are to ignore the fault, shut down the converter, or to shut down the system. To prevent false alarms during short current surges, faults are only signalled if the fault condition persists.

If a fault condition is detected, and the selected response is to shut down the converter or regulator, then the associated `_ENA` and `_STS` fields are reset to 0, as described in Section 15.2.

If a fault condition is detected, and the selected response is to shut down the system, then a Device Reset is triggered, as described in Section 24.1, forcing a transition to the OFF state. The WM8326 will automatically return to the ON state after performing the Device Reset.

Note that, if the fault condition persists, then a maximum of 6 Device Resets will be attempted to initiate the start-up sequence. If the sequence fails more than 6 times, the WM8326 will remain in the OFF state until the next valid ON state transition event occurs.

Note that DC-DC1 and DC-DC2 overvoltage and high current conditions can be detected and reported as described in Section 15.10. The `DCm_ERR_ACT` fields have no relation to these conditions.

The DC-DC3 and DC-DC4 Converters have a selectable overvoltage protection feature, controlled by `DC3_OVP` or `DC4_OVP`. This affects the converter response when the applicable converter is enabled or when its output voltage is increased. When the overvoltage protection is enabled, there is less overshoot in the output voltage, but some oscillation may occur as the voltage settles. This function should only be enabled if steep load transients are present on the output of the DC-DC Converter and if voltage overshoot is critical.

15.10 MONITORING AND FAULT REPORTING

Each of the DC-DC Converters (1 to 4) and LDOs (1 to 10) is monitored for voltage accuracy and fault conditions. An undervoltage condition is detected if the voltage falls below the required level by more than a pre-determined tolerance. If an undervoltage condition occurs, then this is indicated using the corresponding status bit(s) defined in Section 15.11.5. An undervoltage condition also triggers an Undervoltage Interrupt (see Section 15.12). Additional actions to shut down the converter or perform a Device Reset may also be selected.

The Internal LDO (LDO13) is also monitored for voltage accuracy and fault conditions. An undervoltage condition in LDO13 is indicated using the `INTLDO_UV_STS` bit. This undervoltage condition also causes an OFF transition to be scheduled, as described in Section 11.3.

DC-DC Converters 1 and 2 are monitored for overvoltage conditions. An overvoltage condition is set if the voltage is more than 100mV above the required level. If an overvoltage condition occurs, then this is indicated using the corresponding status bit(s). Note that there is no Interrupt or other selectable response to an overvoltage condition.

The current draw on DC-DC Converters 1 and 2 can be monitored against user-programmable thresholds in order to detect a high current condition. This feature is enabled using `DCm_HC_IND_ENA` and the current threshold is set using `DCm_HC_THR`. Note that the high current threshold is not the same as the maximum current capability of the DC-DC Converters, but is set according to the application requirements. If a high current condition occurs, then this is indicated using the corresponding status bit(s). A high current condition also triggers a High Current Interrupt (see Section 15.12).

15.11 POWER MANAGEMENT REGISTER DEFINITIONS

15.11.1 DC-DC CONVERTER AND LDO REGULATOR ENABLE

The Enable and Status register bits for the DC-DC Converters and LDO Regulators are defined in Table 31.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16464 (4050h) DCDC Enable	3:0	DCm_ENA	0	DC-DCm Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in DCm_STS)
R16465 (4051h) LDO Enable	10:0	LDO _n _ENA	0	LDO _n Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO _n _STS)
R16466 (4052h) DCDC Status	3:0	DCm_STS	0	DC-DCm Status 0 = Disabled 1 = Enabled
R16467 (4053h) LDO Status	10:0	LDO _n _STS	0	LDO _n Status 0 = Disabled 1 = Enabled
Notes: 1. <i>n</i> is a number between 1 and 11 that identifies the individual LDO Regulator. 2. <i>m</i> is a number between 1 and 4 that identifies the individual DC-DC Converter.				

Table 31 DC-DC Converter and LDO Regulator Control

The Enable and Status register bits for the External Power Enable (EPE) Controls are defined in Table 32.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16464 (4050h) DCDC Enable	7	EPE2_ENA	0	EPE2 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in EPE2_STS)
	6	EPE1_ENA	0	EPE1 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in EPE1_STS)
R16466 (4052h) DCDC Status	7	EPE2_STS	0	EPE2 Status 0 = Disabled 1 = Enabled
	6	EPE1_STS	0	EPE1 Status 0 = Disabled 1 = Enabled

Table 32 External Power Enable (EPE) Control

15.11.2 DC-DC SYNCHRONOUS BUCK CONVERTER CONTROL

The register controls for configuring the DC-DC synchronous buck converters 1-4 are defined in Table 33.

Note that the DCm_ON_SLOT fields and the 5 MSBs of DCm_ON_VSEL may also be stored in the integrated OTP memory. See Section 14 for details.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16470 (4056h) DC1 Control 1	15:14	DC1_RATE [1:0]	10	DC-DC1 Voltage Ramp rate 00 = 1 step every 32us 01 = 1 step every 16us 10 = 1 step every 8us 11 = Immediate voltage change
	12	DC1_PHASE	0	DC-DC1 Clock Phase Control 0 = Normal 1 = Inverted
	9:8	DC1_FREQ [1:0]	00	DC-DC1 Switching Frequency 00 = Reserved 01 = 2.0MHz (2.2uH output inductor) 10 = 4.0MHz (1uH output inductor) 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.
	7	DC1_FLT	0	DC-DC1 Output float 0 = DC-DC1 output discharged when disabled 1 = DC-DC1 output floating when disabled
	5:4	DC1_SOFT_START [1:0]	00	DC-DC1 Soft-Start Control (Duration in each of the 8 startup current limiting steps.) 00 = 32us steps 01 = 64us steps 10 = 128us steps 11 = 256us steps
	1:0	DC1_CAP [1:0]	00	DC-DC1 Output Capacitor 00 = Reserved 01 = Reserved 10 = 22uF to 47uF 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.
R16471 (4057h) DC1 Control 2	15:14	DC1_ERR_A CT [1:0]	00	DC-DC1 Error Action (Undervoltage) 00 = Ignore 01 = Shut down converter 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.
	12:11	DC1_HWC_SRC [1:0]	00	DC-DC1 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2
	10	DC1_HWC_VSEL	0	DC-DC1 Hardware Control Voltage select 0 = Set by DC1_ON_VSEL 1 = Set by DC1_SLP_VSEL

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	9:8	DC1_HWC_MODE [1:0]	11	DC-DC1 Hardware Control Operating Mode 00 = Forced Continuous Conduction Mode 01 = Disabled 10 = LDO Mode 11 = Hysteretic Mode
	6:4	DC1_HC_THR [2:0]	000	DC-DC1 High Current threshold 000 = 250mA 001 = 500mA 010 = 750mA 011 = 1000mA 100 = 1250mA 101 = 1500mA 110 = 1750mA 111 = 2000mA
	0	DC1_HC_IN D_ENA	0	DC-DC1 High Current detect enable 0 = Disabled 1 = Enabled
R16472 (4058h) DC1 ON Config	15:13	DC1_ON_SLOT [2:0]	000	DC-DC1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2
	9:8	DC1_ON_MODE [1:0]	00	DC-DC1 ON Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode
	6:2	DC1_ON_VSEL [6:2]	00000	DC-DC1 ON Voltage select

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	1:0	DC1_ON_VSEL [1:0]	00	DC1_ON_VSEL[6:0] selects the DC-DC1 output voltage from 0.6V to 1.8V in 12.5mV steps. DC1_ON_VSEL[6:2] also exist in ICE/OTP memory, controlling the voltage in 50mV steps. DC1_ON_VSEL[6:0] is coded as follows: 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).
R16473 (4059h) DC1 SLEEP Control	15:13	DC1_SLP_SLOT [2:0]	000	DC-DC1 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If DC-DC1 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the converter enters its SLEEP condition.
	9:8	DC1_SLP_MODE [1:0]	00	DC-DC1 SLEEP Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode
	6:0	DC1_SLP_VSEL [6:0]	000_0000	DC-DC1 SLEEP Voltage select 0.6V to 1.8V in 12.5mV steps 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16474 (405Ah) DC1 DVS Control	12:11	DC1_DVS_S RC [1:0]	00	DC-DC1 DVS Control Source 00 = Disabled 01 = Enabled 10 = Controlled by Hardware DVS1 11 = Controlled by Hardware DVS2
	6:0	DC1_DVS_V SEL [6:0]	000_0000	DC-DC1 DVS Voltage select 0.6V to 1.8V in 12.5mV steps 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).
R16475 (405Bh) DC2 Control 1	15:14	DC2_RATE [1:0]	10	Same as DC-DC1
	12	DC2_PHASE	0	Same as DC-DC1
	9:8	DC2_FREQ [1:0]	00	Same as DC-DC1
	7	DC2_FLT	0	Same as DC-DC1
	5:4	DC2_SOFT_ START [1:0]	00	Same as DC-DC1
	1:0	DC2_CAP [1:0]	00	Same as DC-DC1
R16476 (405Ch) DC2 Control 2	15:14	DC2_ERR_A CT [1:0]	00	Same as DC-DC1
	12:11	DC2_HWC_ SRC [1:0]	00	Same as DC-DC1
	10	DC2_HWC_ VSEL	0	Same as DC-DC1
	9:8	DC2_HWC_ MODE [1:0]	11	Same as DC-DC1
	6:4	DC2_HC_TH R [2:0]	000	Same as DC-DC1
	0	DC2_HC_IN D_ENA	0	Same as DC-DC1
R16477 (405Dh) DC2 ON Config	15:13	DC2_ON_SL OT [2:0]	000	Same as DC-DC1
	9:8	DC2_ON_M ODE [1:0]	00	Same as DC-DC1
	6:2	DC2_ON_VS EL [6:2]	00000	Same as DC-DC1
	1:0	DC2_ON_VS EL [1:0]	00	
R16478 (405Eh) DC2 SLEEP Control	15:13	DC2_SLP_S LOT [2:0]	000	Same as DC-DC1
	9:8	DC2_SLP_M ODE [1:0]	00	Same as DC-DC1
	6:0	DC2_SLP_V SEL [6:0]	000_0000	Same as DC-DC1
R16479 (405Fh)	12:11	DC2_DVS_S RC [1:0]	00	Same as DC-DC1

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
DC2 DVS Control	6:0	DC2_DVS_VSEL [6:0]	000_0000	<i>Same as DC-DC1</i>
R16480 (4060h) DC3 Control 1	12	DC3_PHASE	0	<i>Same as DC-DC1</i>
	7	DC3_FLT	0	<i>Same as DC-DC1</i>
	5:4	DC3_SOFT_START [1:0]	01	DC-DC3 Soft-Start Control (Duration in each of the 3 intermediate startup current limiting steps.) 00 = Immediate start-up 01 = 512us steps 10 = 4.096ms steps 11 = 32.768ms steps
	3:2	DC3_STNBY_LIM [1:0]	01	DC-DC3 Current Limit Sets the maximum DC output current in Hysteretic Mode. 00 = 50mA 01 = 100mA 10 = 200mA 11 = 400mA <i>Protected by user key</i>
	1:0	DC3_CAP [1:0]	00	DC-DC3 Output Capacitor 00 = 10uF to 20uF 01 = 10uF to 20uF 10 = 22uF to 45uF 11 = 47uF to 100uF This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.
R16481 (4061h) DC3 Control 2	15:14	DC3_ERR_ACT [1:0]	00	<i>Same as DC-DC1</i>
	12:11	DC3_HWC_SRC [1:0]	00	<i>Same as DC-DC1</i>
	10	DC3_HWC_VSEL	0	<i>Same as DC-DC1</i>
	9:8	DC3_HWC_MODE [1:0]	11	<i>Same as DC-DC1</i>
	7	DC3_OVP	0	DC-DC3 Overvoltage Protection 0 = Disabled 1 = Enabled
R16482 (4062h) DC3 ON Config	15:13	DC3_ON_SLOTT [2:0]	000	<i>Same as DC-DC1</i>
	9:8	DC3_ON_MODE [1:0]	00	<i>Same as DC-DC1</i>
	6:2	DC3_ON_VSEL [6:2]	00000	DC-DC3 ON Voltage select

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	1:0	DC3_ON_VSEL [1:0]	00	DC3_ON_VSEL[6:0] selects the DC-DC3 output voltage from 0.85V to 3.4V in 25mV steps. DC3_ON_VSEL[6:2] also exist in ICE/OTP memory, controlling the voltage in 100mV steps. DC3_ON_VSEL[6:0] is coded as follows: 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V
R16483 (4063h) DC3 SLEEP Control	15:13	DC3_SLP_S LOT [2:0]	000	Same as DC-DC1
	9:8	DC3_SLP_MODE [1:0]	00	Same as DC-DC1
	6:0	DC3_SLP_VSEL [6:0]	000_0000	DC-DC3 SLEEP Voltage select 0.85V to 3.4V in 25mV steps 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V
R16484 (4064h) DC4 Control 1	13	DC4_SLV	0	DC-DC4 Slave Mode select 0 = Disabled 1 = Enabled DC4_SLV = 1, then DC-DC4 is a slave to DC-DC3, and both converters are controlled by the DC-DC3 registers. This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.
	12	DC4_PHASE	0	Same as DC-DC1
	7	DC4_FLT	0	Same as DC-DC1
	5:4	DC4_SOFT_START [1:0]	01	Same as DC-DC3
	3:2	DC4_STNBY_LIM [1:0]	01	Same as DC-DC3
	1:0	DC4_CAP [1:0]	00	Same as DC-DC3
R16485 (4065h) DC4 Control 2	15:14	DC4_ERR_ACT [1:0]	00	Same as DC-DC1
	12:11	DC4_HWC_SRC [1:0]	00	Same as DC-DC1
	10	DC4_HWC_VSEL	0	Same as DC-DC1
	9:8	DC4_HWC_MODE [1:0]	11	Same as DC-DC1
	7	DC4_OVP	0	Same as DC-DC3
R16486 (4066h) DC4 ON Config	15:13	DC4_ON_SLOTT [2:0]	000	Same as DC-DC1
	9:8	DC4_ON_MODE [1:0]	00	Same as DC-DC1

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6:2	DC4_ON_VSEL [6:2]	00000	Same as DC-DC3
	1:0	DC4_ON_VSEL [1:0]	00	Same as DC-DC3
R16487 (4067h) DC4 SLEEP Control	15:13	DC4_SLP_S LOT [2:0]	000	Same as DC-DC1
	9:8	DC4_SLP_M ODE [1:0]	00	Same as DC-DC1
	6:0	DC4_SLP_V SEL [6:0]	000_0000	Same as DC-DC3

Table 33 DC-DC Converter Control

15.11.3 LDO REGULATOR CONTROL

The register controls for configuring the LDO Regulators 1-6 are defined in Table 34.

Note that the LDO_n_ON_SLOT and LDO_n_ON_VSEL fields may also be stored in the integrated OTP memory. See Section 14 for details.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16488 (4068h) LDO1 Control	15:14	LDO1_ERR_ ACT [1:0]	00	LDO1 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.
	12:11	LDO1_HWC_ SRC [1:0]	00	LDO1 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2
	10	LDO1_HWC_ VSEL	0	LDO1 Hardware Control Voltage select 0 = Set by LDO1_ON_VSEL 1 = Set by LDO1_SLP_VSEL
	9:8	LDO1_HWC_ MODE	10	LDO1 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO1_ON_MODE
	7	LDO1_FLT	0	LDO1 Output float 0 = LDO1 output discharged when disabled 1 = LDO1 output floating when disabled
	6	LDO1_SWI	0	LDO1 Switch Mode 0 = LDO mode 1 = Switch mode

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	0	LDO1_LP_MODE	0	LDO1 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.
R16489 (4069h) LDO1 ON Control	15:13	LDO1_ON_SLOT [2:0]	000	LDO1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2
	8	LDO1_ON_MODE	0	LDO1 ON Operating Mode 0 = Normal mode 1 = Low Power mode
	4:0	LDO1_ON_VSEL [4:0]	00000	LDO1 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V
R16490 (406Ah) LDO1 SLEEP Control	15:13	LDO1_SLP_SLOT [2:0]	000	LDO1 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO1 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.
	8	LDO1_SLP_MODE	0	LDO1 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	4:0	LDO1_SLP_VSEL [4:0]	00000	LDO1 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V
R16491 (406Bh) LDO2 Control	15:14	LDO2_ERR_ACT [1:0]	00	Same as LDO1
	12:11	LDO2_HWC_SRC [1:0]	00	Same as LDO1
	10	LDO2_HWC_VSEL	0	Same as LDO1
	9:8	LDO2_HWC_MODE	10	Same as LDO1
	7	LDO2_FLT	0	Same as LDO1
	6	LDO2_SWI	0	Same as LDO1
	0	LDO2_LP_MODE	0	Same as LDO1
R16492 (406Ch) LDO2 ON Control	15:13	LDO2_ON_SLOT [2:0]	000	Same as LDO1
	8	LDO2_ON_MODE	0	Same as LDO1
	4:0	LDO2_ON_VSEL [4:0]	00000	Same as LDO1
R16493 (406Dh) LDO2 SLEEP Control	15:13	LDO2_SLP_SLOT [2:0]	000	Same as LDO1
	8	LDO2_SLP_MODE	0	Same as LDO1
	4:0	LDO2_SLP_VSEL [4:0]	00000	Same as LDO1
R16494 (406Eh) LDO3 Control	15:14	LDO3_ERR_ACT [1:0]	00	Same as LDO1
	12:11	LDO3_HWC_SRC [1:0]	00	Same as LDO1
	10	LDO3_HWC_VSEL	0	Same as LDO1
	9:8	LDO3_HWC_MODE	10	Same as LDO1
	7	LDO3_FLT	0	Same as LDO1
	6	LDO3_SWI	0	Same as LDO1
	0	LDO3_LP_MODE	0	Same as LDO1
R16495 (406Fh) LDO3 ON Control	15:13	LDO3_ON_SLOT [2:0]	000	Same as LDO1
	8	LDO3_ON_MODE	0	Same as LDO1
	4:0	LDO3_ON_VSEL [4:0]	00000	Same as LDO1
R16496 (4070h)	15:13	LDO3_SLP_SLOT [2:0]	000	Same as LDO1

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
LDO3 SLEEP Control	8	LDO3_SLP_MODE	0	Same as LDO1
	4:0	LDO3_SLP_VSEL [4:0]	00000	Same as LDO1
R16497 (4071h) LDO4 Control	15:14	LDO4_ERR_ACT [1:0]	00	Same as LDO1
	12:11	LDO4_HWC_SRC [1:0]	00	Same as LDO1
	10	LDO4_HWC_VSEL	0	Same as LDO1
	9:8	LDO4_HWC_MODE	10	Same as LDO1
	7	LDO4_FLT	0	Same as LDO1
	6	LDO4_SWI	0	Same as LDO1
	0	LDO4_LP_MODE	0	Same as LDO1
R16498 (4072h) LDO4 ON Control	15:13	LDO4_ON_SLOT [2:0]	000	Same as LDO1
	8	LDO4_ON_MODE	0	Same as LDO1
	4:0	LDO4_ON_VSEL [4:0]	00000	Same as LDO1
R16499 (4073h) LDO4 SLEEP Control	15:13	LDO4_SLP_SLOT [2:0]	000	Same as LDO1
	8	LDO4_SLP_MODE	0	Same as LDO1
	4:0	LDO4_SLP_VSEL [4:0]	00000	Same as LDO1
R16500 (4074h) LDO5 Control	15:14	LDO5_ERR_ACT [1:0]	00	Same as LDO1
	12:11	LDO5_HWC_SRC [1:0]	00	Same as LDO1
	10	LDO5_HWC_VSEL	0	Same as LDO1
	9:8	LDO5_HWC_MODE	10	Same as LDO1
	7	LDO5_FLT	0	Same as LDO1
	6	LDO5_SWI	0	Same as LDO1
	0	LDO5_LP_MODE	0	Same as LDO1
R16501 (4075h) LDO5 ON Control	15:13	LDO5_ON_SLOT [2:0]	000	Same as LDO1
	8	LDO5_ON_MODE	0	Same as LDO1
	4:0	LDO5_ON_VSEL [4:0]	00000	Same as LDO1
R16502 (4076h) LDO5 SLEEP Control	15:13	LDO5_SLP_SLOT [2:0]	000	Same as LDO1
	8	LDO5_SLP_MODE	0	Same as LDO1
	4:0	LDO5_SLP_VSEL [4:0]	00000	Same as LDO1
R16503 (4077h) LDO6 Control	15:14	LDO6_ERR_ACT [1:0]	00	Same as LDO1
	12:11	LDO6_HWC_SRC [1:0]	00	Same as LDO1
	10	LDO6_HWC_VSEL	0	Same as LDO1

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	9:8	LDO6_HWC_MODE	10	Same as LDO1
	7	LDO6_FLT	0	Same as LDO1
	6	LDO6_SWI	0	Same as LDO1
	0	LDO6_LP_MODE	0	Same as LDO1
R16504 (4078h) LDO6 ON Control	15:13	LDO6_ON_SLOT [2:0]	000	Same as LDO1
	8	LDO6_ON_MODE	0	Same as LDO1
	4:0	LDO6_ON_VSEL [4:0]	00000	Same as LDO1
R16505 (4079h) LDO6 SLEEP Control	15:13	LDO6_SLP_SLOT [2:0]	000	Same as LDO1
	8	LDO6_SLP_MODE	0	Same as LDO1
	4:0	LDO6_SLP_VSEL [4:0]	00000	Same as LDO1

Table 34 LDO Regulators 1-6 Control

The register controls for configuring the LDO Regulators 7-10 are defined in Table 35.

Note that the LDO_n_ON_SLOT and LDO_n_ON_VSEL fields may also be stored in the integrated OTP memory. See Section 14 for details.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16506 (407Ah) LDO7 Control	15:14	LDO7_ERR_ACT [1:0]	00	LDO7 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.
	12:11	LDO7_HWC_SRC [1:0]	00	LDO7 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2
	10	LDO7_HWC_VSEL	0	LDO7 Hardware Control Voltage select 0 = Set by LDO7_ON_VSEL 1 = Set by LDO7_SLP_VSEL
	9:8	LDO7_HWC_MODE	00	LDO7 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO7_ON_MODE
	7	LDO7_FLT	0	LDO7 Output float 0 = LDO7 output discharged when disabled 1 = LDO7 output floating when disabled

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6	LDO7_SWI	0	LDO7 Switch Mode 0 = LDO mode 1 = Switch mode
R16507 (407Bh) LDO7 ON Control	15:13	LDO7_ON_SLOT [2:0]	000	LDO7 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2
	8	LDO7_ON_MODE	0	LDO7 ON Operating Mode 0 = Normal mode 1 = Low Power mode
	4:0	LDO7_ON_VSEL [4:0]	00000	LDO7 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V
R16508 (407Ch) LDO7 SLEEP Control	15:13	LDO7_SLP_SLOT [2:0]	000	LDO7 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO7 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.
	8	LDO7_SLP_MODE	0	LDO7 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	4:0	LDO7_SLP_VSEL [4:0]	00000	LDO7 SLEEP Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V
R16509 (407Dh) LDO8 Control	15:14	LDO8_ERR_ACT [1:0]	00	Same as LDO7
	12:11	LDO8_HWC_SRC [1:0]	00	Same as LDO7
	10	LDO8_HWC_VSEL	0	Same as LDO7
	9:8	LDO8_HWC_MODE	00	Same as LDO7
	7	LDO8_FLT	0	Same as LDO7
	6	LDO8_SWI	0	Same as LDO7
R16510 (407Eh) LDO8 ON Control	15:13	LDO8_ON_S LOT [2:0]	000	Same as LDO7
	8	LDO8_ON_MODE	0	Same as LDO7
	4:0	LDO8_ON_VSEL [4:0]	00000	Same as LDO7
R16511 (407Fh) LDO8 SLEEP Control	15:13	LDO8_SLP_SLOT [2:0]	000	Same as LDO7
	8	LDO8_SLP_MODE	0	Same as LDO7
	4:0	LDO8_SLP_VSEL [4:0]	00000	Same as LDO7
R16512 (4080h) LDO9 Control	15:14	LDO9_ERR_ACT [1:0]	00	Same as LDO7
	12:11	LDO9_HWC_SRC [1:0]	00	Same as LDO7
	10	LDO9_HWC_VSEL	0	Same as LDO7
	9:8	LDO9_HWC_MODE	00	Same as LDO7
	7	LDO9_FLT	0	Same as LDO7
	6	LDO9_SWI	0	Same as LDO7
R16513 (4081h) LDO9 ON Control	15:13	LDO9_ON_S LOT [2:0]	000	Same as LDO7
	8	LDO9_ON_MODE	0	Same as LDO7
	4:0	LDO9_ON_VSEL [4:0]	00000	Same as LDO7
R16514 (4082h) LDO9 SLEEP Control	15:13	LDO9_SLP_SLOT [2:0]	000	Same as LDO7
	8	LDO9_SLP_MODE	0	Same as LDO7
	4:0	LDO9_SLP_VSEL [4:0]	00000	Same as LDO7

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16515 (4083h) LDO10 Control	15:14	LDO10_ERR_ACT [1:0]	00	Same as LDO7
	12:11	LDO10_HW_C_SRC [1:0]	00	Same as LDO7
	10	LDO10_HW_C_VSEL	0	Same as LDO7
	9:8	LDO10_HW_C_MODE	00	Same as LDO7
	7	LDO10_FLT	0	Same as LDO7
	6	LDO10_SWI	0	Same as LDO7
R16516 (4084h) LDO10 ON Control	15:13	LDO10_ON_SLOT [2:0]	000	Same as LDO7
	8	LDO10_ON_MODE	0	Same as LDO7
	4:0	LDO10_ON_VSEL [4:0]	00000	Same as LDO7
R16517 (4085h) LDO10 SLEEP Control	15:13	LDO10_SLP_SLOT [2:0]	000	Same as LDO7
	8	LDO10_SLP_MODE	0	Same as LDO7
	4:0	LDO10_SLP_VSEL [4:0]	00000	Same as LDO7

Table 35 LDO Regulators 7-10 Control

The register controls for configuring the LDO Regulator 11 are defined in Table 36.

Note that the LDO11_ON_SLOT and LDO11_ON_VSEL fields may also be stored in the integrated OTP memory. See Section 14 for details.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16519 (4087h) LDO11 ON Control	15:13	LDO11_ON_SLOT [2:0]	000	LDO11 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2
	12	LDO11_FRC_ENA	0	LDO11 Force Enable (forces LDO11 to be enabled at all times in the OFF, ON and SLEEP states) 0 = Disabled 1 = Enabled
	7	LDO11_VSEL_SRC	0	LDO11 Voltage Select source 0 = Normal (LDO11 settings) 1 = Same as DC-DC Converter 1

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	3:0	LDO11_ON_VSEL [3:0]		LDO11 ON Voltage select 0.80V to 1.55V in 50mV steps 0h = 0.80V 1h = 0.85V 2h = 0.90V ... Eh = 1.50V Fh = 1.55V
R16520 (4088h) LDO11 SLEEP Control	15:13	LDO11_SLP_SLOT [2:0]	000	LDO11 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO11 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.
	3:0	LDO11_SLP_VSEL [3:0]		LDO11 SLEEP Voltage select 0.80V to 1.55V in 50mV steps 0h = 0.80V 1h = 0.85V 2h = 0.90V ... Eh = 1.50V Fh = 1.55V

Table 36 LDO Regulator 11 Control

15.11.4 EXTERNAL POWER ENABLE (EPE) CONTROL

The register controls for configuring the External Power Enable (EPE) outputs are defined in Table 37.

Note that the EPE1_ON_SLOT and EPE2_ON_SLOT fields may also be stored in the integrated OTP memory. See Section 14 for details.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16521 (4089h) EPE1 Control	15:13	EPE1_ON_SLOT [2:0]	000	EPE1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	12:11	EPE1_HWC_SRC [1:0]	00	EPE1 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2
	8	EPE1_HWC_ENA	0	EPE1 Hardware Control Enable 0 = EPE1 is controlled by EPE1_ENA (Hardware Control input(s) are ignored) 1 = EPE1 is controlled by HWC inputs (Hardware Control input(s) force EPE1 to be de-asserted)
	7:5	EPE1_SLP_SLOT [2:0]	000	EPE1 SLEEP Slot select 000 = No action 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = No action 111 = No action
R1652 (408Ah) EPE2 Control	15:13	EPE2_ON_SLOT [2:0]	000	<i>Same as EPE1</i>
	12:11	EPE2_HWC_SRC [1:0]	00	<i>Same as EPE1</i>
	8	EPE2_HWC_ENA	0	<i>Same as EPE1</i>
	7:5	EPE2_SLP_SLOT [2:0]	000	<i>Same as EPE1</i>

Table 37 External Power Enable (EPE) Control

15.11.5 MONITORING AND FAULT REPORTING

The overvoltage, undervoltage and high current status registers are defined in Table 38.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16468 (4054h) DCDC UV Status	13	DC2_OV_STS	0	DC-DC2 Overvoltage Status 0 = Normal 1 = Overvoltage
	12	DC1_OV_STS	0	DC-DC1 Overvoltage Status 0 = Normal 1 = Overvoltage
	9	DC2_HC_STS	0	DC-DC2 High Current Status 0 = Normal 1 = High Current
	8	DC1_HC_STS	0	DC-DC1 High Current Status 0 = Normal 1 = High Current
	3:0	DCm_UV_STS	0	DC-DCm Undervoltage Status 0 = Normal 1 = Undervoltage
R16469 (4055h) LDO UV Status	15	INTLDO_UV_STS	0	LDO13 (Internal LDO) Undervoltage Status 0 = Normal 1 = Undervoltage

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	9:0	LDO _n _UV_STS	0	LDO _n Undervoltage Status 0 = Normal 1 = Undervoltage
Notes: 1. <i>n</i> is a number between 1 and 10 that identifies the individual LDO Regulator (LDO1 - 10). 2. <i>m</i> is a number between 1 and 4 that identifies the individual DC-DC Converter (DC-DC1 - 4).				

Table 38 DC Converter and LDO Regulator Status

15.12 POWER MANAGEMENT INTERRUPTS

Undervoltage monitoring is provided on all DC-DC Converters and LDO Regulators, as described in Section 15.10. The associated interrupt flags indicate an undervoltage condition in each individual DC-DC Converter or LDO Regulator. Each of these secondary interrupts triggers a primary Undervoltage Interrupt, UV_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 39.

Current monitoring is provided on DC-DC1 and DC-DC2, as described in Section 15.10. The interrupt flags HC_DC1_EINT and HC_DC2_EINT indicate a high current condition in DC-DC1 and DC-DC2 respectively. Each of these secondary interrupts triggers a primary High Current Interrupt, HC_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 39.

The high current thresholds are programmable; these are set by DC1_HC_THR and DC2_HC_THR for DC-DC1 and DC-DC2 respectively. See Section 15.11.2 for details of these register fields. Note that these functions are for current monitoring; they do not equate to the DC-DC Converter maximum current limit.

ADDRESS	BIT	LABEL	DESCRIPTION
R16403 (4013h) Interrupt Status 3	9:0	UV_LDO _n _EINT	LDO _n Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16404 (4014h) Interrupt Status 4	9	HC_DC2_EINT	DC-DC2 High current interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	8	HC_DC1_EINT	DC-DC1 High current interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	3:0	UV_DC _m _EINT	DC-DC _m Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16411 (401Bh) Interrupt Status 3 Mask	9:0	IM_UV_LDO _n _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
R16412 (401Ch) Interrupt Status 4 Mask	9	IM_HC_DC2_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	8	IM_HC_DC1_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	3:0	IM_UV_DC _m _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

ADDRESS	BIT	LABEL	DESCRIPTION
Notes:			
1. n is a number between 1 and 10 that identifies the individual LDO Regulator (LDO1 - 10).			
2. m is a number between 1 and 4 that identifies the individual DC-DC Converter (DC-DC1 - 4).			

Table 39 Power Management Interrupts

15.13 POWER GOOD INDICATION

The WM8326 can indicate the status of the DC-DC Converters and LDO Regulators via a GPIO pin configured as a "PWR_GOOD" output (see Section 21).

Each DC-DC Converter and LDO Regulator to be monitored in this way must be individually enabled as an input to the PWR_GOOD function using the register bits defined in Table 40.

When a GPIO pin is configured as a "PWR_GOOD" output, this signal is asserted when all selected DC-DC Converters and LDO Regulators are operating correctly. If any of the enabled DC-DC Converters or LDO Regulators is undervoltage, then the PWR_GOOD will be de-asserted. In this event, the host processor should read the Undervoltage Interrupt fields to determine which DC-DC Converter or LDO Regulator is affected.

Note that an Undervoltage condition may lead to a Converter being switched off automatically. In this case, the disabled Converter will not indicate the fault condition via PWR_GOOD. Accordingly, the PWR_GOOD signal may not be a reliable output in cases where the WM8326 is configured to shut down any Converters automatically under Undervoltage conditions. It is recommended that the host processor should read the Undervoltage Interrupts in response to PWR_GOOD being de-asserted. The host processor can then initiate the most appropriate response.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16526 (408Eh) Power Good Source 1	3	DC4_OK	0	DC-DC4 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	2	DC3_OK	1	DC-DC3 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	1	DC2_OK	1	DC-DC2 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	0	DC1_OK	1	DC-DC1 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
R16527 (408Fh) Power Good Source 2	9	LDO10_OK	1	LDO10 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	8	LDO9_OK	1	LDO9 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	7	LDO8_OK	1	LDO8 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	6	LDO7_OK	1	LDO7 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	5	LDO6_OK	1	LDO6 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	4	LDO5_OK	1	LDO5 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	3	LDO4_OK	1	LDO4 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	2	LDO3_OK	1	LDO3 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	1	LDO2_OK	1	LDO2 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled
	0	LDO1_OK	1	LDO1 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled

Table 40 PWR_GOOD (GPIO) Configuration

15.14 DC-DC SYNCHRONOUS BUCK CONVERTER OPERATION

15.14.1 OVERVIEW

The WM8326 provides four DC-DC switching converters. Each of these is a synchronous buck (step-down) converter. The principal characteristics of each DC-DC converter are shown below. Converters DC-DC3 and DC-DC4 can either be operated as single converters, or may be ganged together in 'dual' mode to provide an increased current capability.

	DC-DC1 / DC-DC2	DC-DC3 / DC-DC4
Converter Type	Buck (step-down)	Buck (step-down)
Input Voltage Range	2.7V to 5.5V	2.7V to 5.5V
Output Voltage Range	0.6V to 1.8V	0.85V to 3.4V
Load Current Rating	Up to 2500mA	Up to 1000mA (single mode) Up to 1600mA (dual mode)
Switching Frequency	2MHz or 4MHz	2MHz

Table 41 DC-DC Converter Overview

15.14.2 DC-DC SYNCHRONOUS BUCK CONVERTERS

DC-DC Converters 1, 2, 3 and 4 are synchronous buck converters which deliver high performance and high efficiency across a wide variety of operating conditions.

The high switching frequency, together with the current mode architecture, delivers exceptional transient performance suitable for supplying processor power domains and similar applications requiring high stability through fast-changing load (or line) conditions.

The current mode architecture enables extended bandwidth of the control loop, allowing the DC-DC converter to adapt for changes in input or output conditions more rapidly than can be achieved using other feedback mechanisms. This improves the converter's performance under transient load conditions.

The flexible design of the DC-DC Converters allows a selection of different operating configurations, which can be chosen according to the performance, efficiency, space or external component cost requirements.

The DC-DC Converter design achieves high performance with a small inductor component. This is highly advantageous in size-critical designs for portable applications. In the case of DC-DC1 and DC-DC2, the switching frequency is selectable (2MHz or 4MHz). The higher frequency supports best transient performance and the smallest external inductor, whilst the lower rate supports best power efficiency.

Note that the supported output voltage range for DC-DC Converters 1 and 2 is restricted in the 4MHz mode; for output voltages greater than 1.4V, the 2MHz mode must be used.

Note that the maximum output current for DC-DC Converters 1 and 2 is limited to 1250mA in the 4MHz mode; for output currents up to 2500mA, the 2MHz mode must be used.

The DC-DC Converters are compatible with a range of external output capacitors. A larger capacitor (eg. 47 μ F) will deliver best transient performance, whilst a smaller capacitor (eg. 4.7 μ F) may be preferred for size or cost reasons.

Four different operating modes can be selected, allowing the user to configure the converter performance and efficiency according to different demands. This includes power-saving modes for light load conditions and a high performance mode for best transient load performance. A low power LDO regulator mode is also provided. The DC-DC Converters maintain output voltage regulation when switching between operating modes.

Forced Continuous Conduction Mode (FCCM)

This mode delivers the best load transient performance across the entire operating load range of the converter. It also provides the best EMI characteristics due to the fixed, regular switching pattern.

For normal DC-DC buck converter operation, there is an inductor charging phase followed by a discharging phase. Under light load conditions, the inductor current may be positive or negative

during this cycle. (Note that the load current corresponds to the average inductor current.) The negative portion of the cycle corresponds to inefficient operation, as the output capacitor is discharged unnecessarily by the converter circuit. Accordingly, this mode is not optimally efficient for light load conditions.

This mode offers excellent performance under transient load conditions. It exceeds the performance of the other operating modes in the event of a decreasing current demand or a decreasing voltage selection. This is because FCCM mode can actively pull down the output voltage to the required level, whilst other modes rely on the load to pull the converter voltage down under these conditions.

Another important benefit of this mode is that the switching pattern is fixed, regardless of load conditions. This provides best compatibility with noise-sensitive circuits where the noise frequency spectrum must be well-defined.

Although this mode is not optimally efficient for light loads, it delivers the best possible transient load performance and fixed frequency switching. This mode should be selected when best performance is required, delivering minimum output voltage ripple across all static or transient load conditions.

Auto Mode: Continuous / Discontinuous Conduction with Pulse-Skipping (CCM/DCM with PS)

This is an automatic mode that selects different control modes according to the load conditions. The converter supports the full range of load conditions in this mode, and automatically selects power-saving mechanisms when the load conditions are suitable. Under light load conditions, the efficiency in this mode is superior to the FCCM mode. The transient load performance may be slightly worse than FCCM mode.

The converter operates in Continuous Conduction Mode (CCM) for heavy load conditions, and Discontinuous Conduction Mode (DCM) under lighter loads. Discontinuous conduction is when the inductor current falls to zero during the discharge phase, and the converter disables the synchronous rectifier transistor in order that the inductor current remains at zero until the next charge phase. Negative inductor current is blocked in this mode, eliminating the associated losses, and improving efficiency.

The transient response in this mode varies according to the operating conditions; it differs from FCCM in the case of a decreasing current demand or a decreasing voltage, as the converter uses the load to pull the output voltage down to the required level. A light load will result in a slow response time.

A minimum inductor charge time is applied in DCM mode; this leads to a minimum average inductor current when operating as described above. Under very light load conditions, pulse skipping is used to reduce the average inductor current to the level required by the load. In pulse-skipping mode, the charge phase of selected cycles is not scheduled, and the load is supported by the output capacitor over more than one cycle of the switching frequency. As well as supporting very light load current conditions, this mechanism offers power savings, as the switching losses associated with the skipped pulses are eliminated. A disadvantage of this is that the transient response is degraded even further with respect to DCM. When the pulse-skipping behaviour is invoked, an increased output voltage ripple may be observed under some load conditions.

This mode is suitable for a wide range of operating conditions. It supports the full range of load currents, and offers efficiency savings under light load conditions.

Hysteretic Mode

Hysteretic mode is a power-saving mode. It does not support the full load capability of the DC-DC converter, but offers efficiency improvements over the FCCM and Auto (CCM/DCM with PS) modes.

The control circuit in Hysteretic mode operates very differently to the Pulse-Skipping mode that is available in Auto mode. In Pulse-Skipping mode, selected switching cycles are dropped in order to reduce the output current to match a light load condition, whilst maintaining good output voltage ripple as far as possible. In Hysteretic mode, the converter uses switched operation on an adaptive intermittent basis to deliver the required average current to the load.

In the switched operation portion of the Hysteretic mode, the converter drives the output voltage up; this is followed by a power-saving period in which the control circuit is largely disabled whilst the load pulls the output voltage down again over a period of many switching cycles. The duration of the fixed frequency bursts and the time between bursts is adapted automatically by the output voltage monitoring circuit.

In this mode, the power dissipation is reduced to a very low level by disabling parts of the control circuitry for the duration of selected switching cycles. This improves the overall efficiency, but also leads to output voltage ripple and limited performance. This mode produces a larger output voltage ripple than the Pulse-Skipping mode. In order to limit the degradation of the DC-DC converter performance in Hysteretic mode, the control circuit is designed for a restricted range of load conditions only. Note that the irregular switching pattern also results in degraded EMI behaviour.

Hysteretic mode and Pulse Skipping mode are both Pulse Frequency Modulation (PFM)-type modes, where the switching pulse frequency is adjusted dynamically according to the load requirements. A consequence of this frequency modulation is that the circuit's EMI characteristics are less predictable. In Hysteretic mode in particular, the EMI effects arising from the DC-DC switching are present across a wider frequency band than is the case in CCM and DCM. It is more difficult to effectively suppress the wide band interference, and this factor may result in Hysteretic mode being unsuitable for some operating conditions.

Hysteretic mode is suitable for light load conditions only, and only suitable for operating modes that are not sensitive to wide band RF/EMI effects. The output voltage ripple (and frequency) is load dependent, and is generally worse than Pulse-Skipping operation in the Auto mode. Provided that the EMI and voltage ripple can be tolerated, the Hysteretic mode offers an efficiency advantage over the Auto (CCM/DCM with PS) mode.

LDO Mode

In this mode, there is no FET switching at all, and the converter operates as a Low Drop-Out (LDO) regulator. In this mode, the FET switching losses are eliminated, as is the power consumption of the DC-DC control circuit. Under suitable operating conditions, this provides the most efficient option for light loads, without any of the EMI or voltage ripple limitations of Hysteretic mode.

As with any LDO, the output voltage is constant, and there is no internal source of voltage ripple. Unlike the switching modes, the power efficiency of the LDO mode is highly dependent on the input and output voltages; the LDO is most efficient when the voltage drop between input and output is small. The power dissipated as heat loss by an LDO increases rapidly as the input - output voltage difference increases.

LDO mode is suitable for light loads, and provides a ripple-free output. The LDO mode features a very low start-up current; this mode can be used to avoid the higher in-rush current that occurs in the switching converter modes. The efficiency is dependent on the input - output voltage configuration; the LDO mode can be highly efficient, but may also be unacceptably inefficient. If an improvement in power efficiency is required, then Hysteretic mode may be the preferred choice or, for better EMI and voltage ripple, the Auto (CCM/DCM with PS) mode may be the optimum selection.

Operating Mode Summary

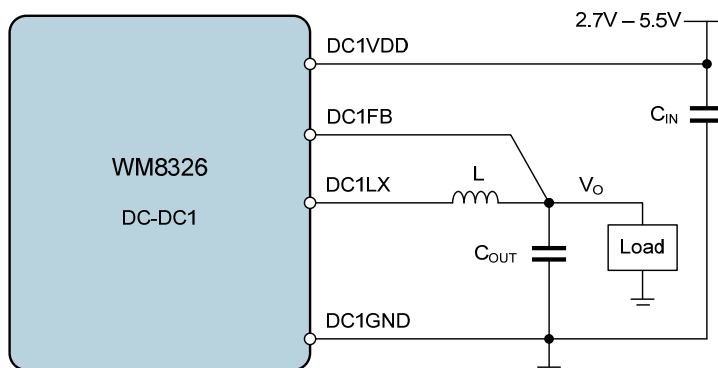
MODE	DESCRIPTION	APPLICATION
Forced Continuous Conduction Mode (FCCM)	Buck converter operation where inductor current is continuous at all times.	High performance for all static and transient load conditions. Fixed frequency switching offers best compatibility with sensitive circuits.
Auto Mode: Continuous / Discontinuous Conduction with Pulse-Skipping Mode (CCM/DCM with PS)	Buck converter operation where inductor current may be discontinuous under reduced loads; pulse-skipping also enabled under lighter loads.	High efficiency for all static and transient load conditions. Performance may be less than FCCM mode for heavy load transients.
Hysteretic Mode	The converter uses a hysteretic control scheme with pulsed switching operation. The control circuitry is disabled intermittently for power saving.	High efficiency for light static and light transient loads only. Maximum load current is restricted; output voltage ripple is increased.
LDO Mode	No FET switching at all; linear regulator operation.	Power saving mode for light loads only. High efficiency for ultra light loads. Low current soft-start control.

Table 42 DC-DCSynchronous Buck Converter Operating Modes Summary

Typical Connections

The typical connections to DC-DC Converter 1 are illustrated in Figure 20. The equivalent circuit applies to DC-DC Converters 2, 3 and 4 also.

The input voltage connection to DC-DC Converters 1-4 is provided on DC1VDD, DC2VDD, DC3VDD and DC3VDD respectively; these pins must be connected to the PVDD power supply voltage node.



Note: Equivalent circuit applies for DC-DC2, DC-DC3 and DC-DC4

Figure 20 DC-DC Synchronous Buck Converter Connections

The recommended output capacitor C_{OUT} varies according to the required transient response. Note that the DCm_CAP register field must be set according to the output capacitance on each DC-DC Converter in order to achieve best performance.

In the case of DC-DC1 and DC-DC2, the recommended inductor component varies according to the DCm_FREQ register field. This register supports a choice of different switching frequencies and inductor components.

See Section 30.3 for details of specific recommended external components.

DC-DC3 / DC-DC4 Dual Mode

DC-DC Converters 3 and 4 can be configured to operate in 'Dual' mode, where the two converters are ganged together to support an increased current capability. This mode is selected by setting the $DC4_SLV$ bit in the OTP/ICE memory configuration registers.

When DC-DC3 and DC-DC4 are operating in dual mode, the external component configuration for each converter is the same as previously noted for single converters. The output load connection points (V_O) are simply connected together as shown in Figure 21.

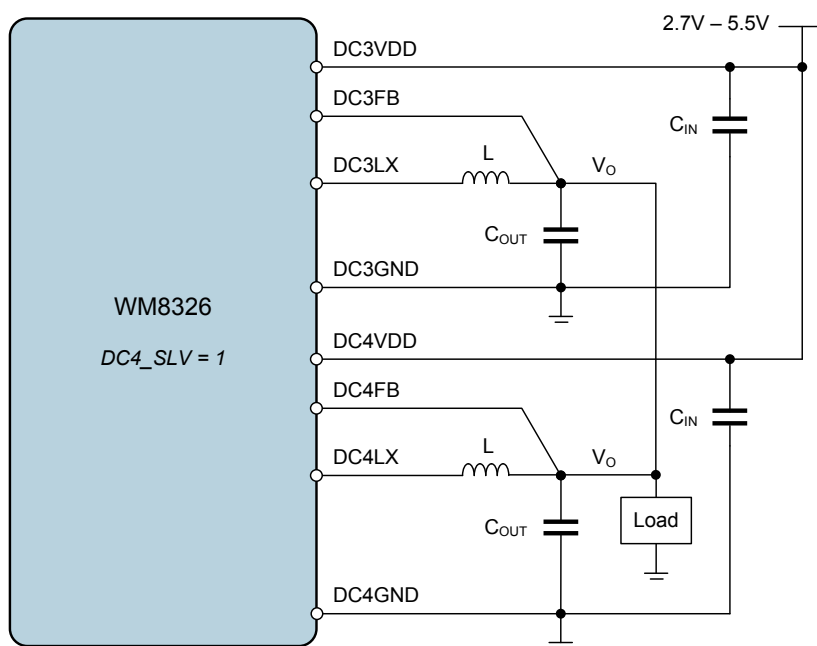


Figure 21 DC-DC3 / DC-DC4 Dual Mode Converter Connections

The recommended output capacitor C_{OUT} varies according to the required transient response. Note that the DCm_CAP register field must be set according to the output capacitance on each DC-DC Converter in order to achieve best performance.

See Section 30.3 for details of specific recommended external components.

15.15 LDO REGULATOR OPERATION

15.15.1 OVERVIEW

The WM8326 provides 11 LDO Regulators. Four of these are low-noise analogue LDOs. One of the LDO Regulators (LDO11) can be configured to be enabled even when the WM8326 is in the OFF state. The principal characteristics of the LDO Regulators are shown below.

	LDO1	LDO2, 3	LDO4, 5, 6	LDO7, 8	LDO9, 10	LDO11
Converter Type	General Purpose	General Purpose	General Purpose	Analogue	Analogue	General Purpose
Input Voltage Range	1.5V to 5.5V	1.5V to 5.5V	1.5V to 5.5V	1.71V to 5.5V	1.71V to 5.5V	1.8V to 5.5V
Output Voltage Range	0.9V to 3.3V	0.9V to 3.3V	0.9V to 3.3V	1.0V to 3.5V	1.0V to 3.5V	0.8V to 1.55V
Load Current Rating	Up to 300mA	Up to 200mA	Up to 100mA	Up to 200mA	Up to 150mA	Up to 25mA
Pass device impedance @ 2.5V	1 Ω	1 Ω	2 Ω	1 Ω	2 Ω	n/a

Table 43 LDO Regulator Overview

15.15.2 LDO REGULATORS

The LDO Regulators are configurable circuits which generate accurate, low-noise supply voltages for various system components. The LDO Regulators are dynamically programmable and can be re-configured at any time. Two low power modes are provided for the general purpose LDOs 1-6; a single low power mode is provided for the analogue LDOs 7-10; this enables the overall device power consumption to be minimised at all times.

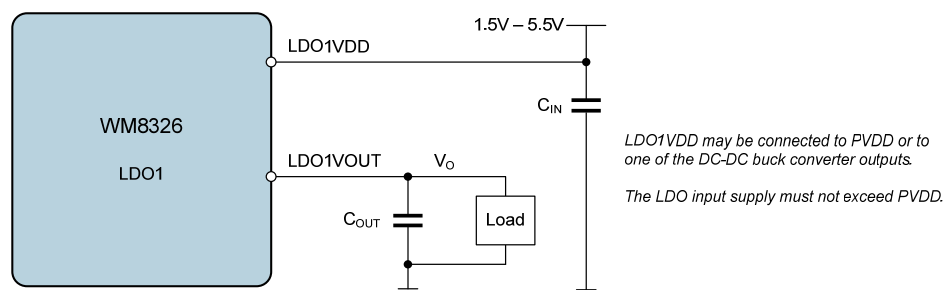
The LDOs 1-10 can also operate as current-limited switches, with no voltage regulation; this is useful for 'Hot Swap' outputs, i.e. supply rails for external devices that are plugged in when the system is already powered up - the current-limiting function prevents the in-rush current into the external device from disturbing other system power supplies.

The input voltage to these LDOs is provided on pins LDO3VDD, LDO4VDD, LDO5VDD, LDO6VDD for LDO3 through to LDO6 respectively. The other LDO inputs are shared on pins LDO1_2VDD, LDO7_8VDD and LDO9_10VDD for each corresponding pair of LDOs.

The LDO input supply pins may be connected to the PVDD power supply voltage node, or else can be connected to the output pin of one of the DC-DC buck converters. Note that the LDO input supply pins must not be connected to a voltage higher than PVDD.

LDO11 is a configurable LDO intended for 'always-on' functions external to the WM8326. The WM8326 contains a further two non-configurable LDOs which support internal functions only.

The connections to LDO Regulator 1 are illustrated in Figure 22. The equivalent circuit applies to LDO2 through to LDO10.



Note: Equivalent circuit applies for LDO2 through to LDO10.

Figure 22 LDO Regulator Connections

An input and output capacitor are recommended for each LDO Regulator, as illustrated above.

See Section 30.4 for details of specific recommended external components.

16 RESERVED

17 POWER SUPPLY CONTROL

17.1 GENERAL DESCRIPTION

The primary power supply to the WM8326 is provided via the PVDD pin. This supply is required for normal device functionality. The PVDD voltage is monitored internally to detect a low voltage condition where the device can no longer operate. A Power Path Management Interrupt is raised when PVDD falls below an undervoltage threshold, as described in Section 17.2.

A backup power source may be provided for the WM8326. This enables the Real Time Clock (RTC) and other selected registers to be maintained when PVDD is not available. This is described in Section 17.3.

17.2 POWER PATH MANAGEMENT INTERRUPTS

The Power Path Management circuit is associated with an Interrupt event flag.

The PPM_SYSLO_EINT interrupt bit is set when the internal signal SYSLO is asserted. This indicates a PVDD undervoltage condition, described in Section 24.4. This secondary interrupt triggers a primary Power Path Management Interrupt, PPM_INT (see Section 23). This can be masked by setting the mask bit as described in Table 44.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	15	PPM_SYSLO_EINT	Power Path SYSLO interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	15	IM_PPM_SYSLO_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 44 Power Path Management Interrupt

17.3 BACKUP POWER

As an option, a backup power source can be provided for the WM8326. This is provided using a coin cell, super/gold capacitor, or else a standard capacitor, connected to the LDO12VOUT pin.

Note that a 22kΩ series resistor should also be connected to the backup power source.

The LDO12VOUT pin provides a constant voltage output for charging the backup power source whenever the PVDD power domain is available.

The purpose of the backup is to power the always-on functions such as the crystal oscillator, RTC and ALARM control registers. The backup power also maintains a 'software scratch' memory area in the register map - see Section 12.6. Maintaining these functions at all times provides system continuity even when the main battery is removed and no other power supply is available.

The backup duration will vary depending upon the backup power source characteristics. A typical coin cell can provide power to the WM8326 in BACKUP mode for a month or more whilst also maintaining the RTC and the 'software scratch' register.

If a standard capacitor is used as the backup power source, then it is particularly important to minimise the device power consumption in the BACKUP state. A 22μF capacitor will maintain the device settings for up to 5 minutes in 'unlocked' mode, where power consumption is minimised by stopping the RTC in the BACKUP state. The RTC is unlocked in the BACKUP state if the XTAL_BKUPENA register field is set to 0, as described in Section 20.5.

18 AUXILIARY ADC

18.1 GENERAL DESCRIPTION

The WM8326 incorporates a 12-bit Auxiliary ADC (AUXADC). This can be used to perform a number of system measurements (including supply voltages and battery temperature) and can also be used to measure analogue voltages from external sources and sensors.

External inputs to the AUXADC should be connected to the pins GPIO10, GPIO11 and GPIO12. The maximum voltage that can be measured is determined by the power domain associated with each; this is selectable on a pin by pin basis as described in Section 21.3.

Note that, when GPIO10, GPIO11 or GPIO12 is used as an input to the AUXADC, then the normal GPIO functionality cannot be supported on the affected pin(s). In this case, it is recommended that the respective GPIO(s) are tri-stated, as described in Section 21.3.

18.2 AUXADC CONTROL

The AUXADC is enabled by setting the AUX_ENA register bit. By default, the AUXADC is not enabled in the SLEEP state, but this can be selected using the AUX_SLPENA field.

The AUXADC measurements can be initiated manually or automatically. For automatic operation, the AUX_RATE register is set according to the required conversion rate, and conversions are enabled by setting the AUX_CVT_ENA bit. For manual operation, the AUX_RATE register is set to 00h, and each manual conversion is initiated by setting the AUX_CVT_ENA bit. In manual mode, the AUX_CVT_ENA bit is reset by the WM8326 after each conversion. (Note that the conversion result is not available for readback until the AUXADC interrupt is asserted, as described in Section 18.5.)

The AUXADC has 5 available input sources. Each of these inputs is enabled by setting the respective bit in the AuxADC Source Register (R16431).

For each AUXADC measurement event (in Manual or Automatic modes), the WM8326 selects the next enabled input source. Any number of inputs may be selected simultaneously; the AUXADC will measure each one in turn. Note that only a single AUXADC measurement is made on any Manual or Automatic trigger.

For example, if the GPIO10, GPIO12 and PVDD voltages are enabled for AUXADC measurement, then GPIO10 would be measured in the first instance, and GPIO12 then PVDD would be measured on the next manual or automatic AUXADC triggers. In this case, a total of three manual or automatic AUXADC triggers would be required to measure all of the selected inputs.

The control fields associated with initiating AUXADC measurements are defined in Table 45.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16430 (402Eh) AuxADC Control	15	AUX_ENA	0	AUXADC Enable 0 = Disabled 1 = Enabled Note - this bit is reset to 0 when the OFF power state is entered.
	14	AUX_CVT_ENA	0	AUXADC Conversion Enable 0 = Disabled 1 = Enabled In automatic mode, conversions are enabled by setting this bit. In manual mode (AUX_RATE = 0), setting this bit will initiate a conversion; the bit is reset automatically after each conversion.
	12	AUX_SLPENA	0	AUXADC SLEEP Enable 0 = Disabled 1 = Controlled by AUX_ENA

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	5:0	AUX_RATE [5:0]	00_0000	AUXADC Conversion Rate 0 = Manual 1 = 2 samples/s 2 = 4 samples/s 3 = 6 samples/s ... 31 = 62 samples/s 32 = Reserved 33 = 16 samples/s 34 = 32 samples/s 35 = 48 samples/s ... 63 = 496 samples/s
R16431 (402Fh) AuxADC Source	6	AUX_PVDD_SEL	0	AUXADC PVDD input select 0 = Disable PVDD measurement 1 = Enable PVDD measurement
	4	AUX_CHIP_TEMP_SEL	0	AUXADC Chip Temp input select 0 = Disable Chip Temp measurement 1 = Enable Chip Temp measurement
	2	AUX_GPIO12_SELECT	0	AUXADC GPIO12 input select 0 = Disable GPIO12 measurement 1 = Enable GPIO12 measurement
	1	AUX_GPIO11_SELECT	0	AUXADC GPIO11 input select 0 = Disable GPIO11 measurement 1 = Enable GPIO11 measurement
	0	AUX_GPIO10_SELECT	0	AUXADC GPIO10 input select 0 = Disable GPIO10 measurement 1 = Enable GPIO10 measurement

Table 45 AUXADC Control

18.3 AUXADC READBACK

Measured data from the AUXADC is read via the AuxADC Data Register (R16429), which contains two fields. The AUXADC Data Source is indicated in the AUX_DATA_SRC field; the associated measurement data is contained in the AUX_DATA field.

Reading from the AuxADC Data Register returns a 12-bit code which represents the most recent AUXADC measurement on the associated channel. It should be noted that every time an AUXADC measurement is written to the AuxADC Data Register, the previous data is overwritten - the host processor should ensure that data is read from this register before it is overwritten. The AUXADC interrupts can be used to indicate when new data is available - see Section 18.5.

The 12-bit AUX_DATA field can be equated to the actual voltage (or temperature) according to the following equations, where AUX_DATA is regarded as an unsigned integer:

$$\text{Voltage (mV)} = \text{AUX_DATA} \times 1.465$$

$$\text{Chip Temp (}^{\circ}\text{C)} = \frac{498 - \text{AUX_DATA}}{1.09}$$

The maximum voltage that can be measured on the input pins GPIO10, GPIO11 and GPIO12 is determined by the power domain associated with each; this is selectable on a pin by pin basis using the GPN_PWR_DOM register bits described in Section 21.3. The input voltage at the GPIO pin must not exceed the voltage of the respective power domain (ie. DBVDD or PVDD).

In a typical application, it is anticipated that the AUXADC Interrupts would be used to control the AUXADC readback - the host processor should read the AUXADC Data Register in response to the AUXADC Interrupt event. See Section 18.5 for details of AUXADC Interrupts. In Automatic AUXADC mode, the processor should complete this action before the next measurement occurs, in order to avoid losing any AUXADC samples. In Manual conversion mode, the interrupt signal provides confirmation that the commanded measurement has been completed.

The control fields associated with initiating AUXADC readback are defined in Table 46.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16429 (402Dh) AuxADC Data	15:12	AUX_DATA_SRC [3:0]	000	AUXADC Data Source 1 = GPIO10 2 = GPIO11 3 = GPIO12 5 = Chip Temperature 7 = PVDD voltage All other values are Reserved
	11:0	AUX_DATA [11:0]	000h	AUXADC Measurement Data Voltage (mV) = AUX_DATA x 1.465 ChipTemp (°C) = (498 - AUX_DATA) / 1.09

Table 46 AUXADC Readback

18.4 DIGITAL COMPARATORS

The WM8326 has four digital comparators which may be used to compare AUXADC measurement data against programmable threshold values. Each comparator has a status bit, and also an associated interrupt flag (described in Section 18.5), which indicates that the associated data is beyond the threshold value.

The digital comparators are enabled using the DCMPn_ENA register bits as described in Table 45.

After an AUXADC conversion, the measured value is compared with the threshold level of any associated comparator(s). Note that this comparison is only performed following a conversion.

The source data for each comparator is selected using the DCMPn_SRC register bits; this selects one of the AUXADC channels for each comparator. If required, the same AUXADC channel may be selected for more than one comparator; this would allow more than one threshold to be monitored on the same AUXADC channel. Note that the Backup Battery voltage input can only be monitored using DCMP4.

The DCMPn_GT register bits select whether the status bit and associated interrupt flag will be asserted when the measured value is above the threshold or when the measured value is below the threshold. The output of the most recent threshold comparison is indicated in the DCOMPn_STS fields.

The threshold DCMPn_THR is a 12-bit code for each comparator. This field follows the same voltage or temperature coding as the associated AUXADC channel source (see Section 18.3).

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16432 (4030h) Comparator Control	11	DCOMP4_STS	0	Digital Comparator 4 status 0 = Comparator 4 threshold not detected 1 = Comparator 4 threshold detected (Trigger is controlled by DCMP4_GT)
	10	DCOMP3_STS	0	Digital Comparator 3 status 0 = Comparator 3 threshold not detected 1 = Comparator 3 threshold detected (Trigger is controlled by DCMP3_GT)
	9	DCOMP2_STS	0	Digital Comparator 2 status 0 = Comparator 2 threshold not detected 1 = Comparator 2 threshold detected (Trigger is controlled by DCMP2_GT)
	8	DCOMP1_STS	0	Digital Comparator 1 status 0 = Comparator 1 threshold not detected 1 = Comparator 1 threshold detected (Trigger is controlled by DCMP1_GT)
	3	DCMP4_ENA	0	Digital Comparator 4 Enable 0 = Disabled 1 = Enabled
	2	DCMP3_ENA	0	Digital Comparator 3 Enable 0 = Disabled 1 = Enabled
	1	DCMP2_ENA	0	Digital Comparator 2 Enable 0 = Disabled 1 = Enabled
	0	DCMP1_ENA	0	Digital Comparator 1 Enable 0 = Disabled 1 = Enabled
R16433 (4031h) Comparator 1	15:13	DCMP1_SRC [2:0]	000	Digital Comparator 1 source select 0 = Reserved

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage
	12	DCMP1_GT	0	Digital Comparator 1 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold
	11:0	DCMP1_THR	000h	Digital Comparator 1 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)
R16434 (4032h) Comparator 2	15:13	DCMP2_SRC [2:0]	000	Digital Comparator 2 source select 0 = Reserved 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage
	12	DCMP2_GT	0	Digital Comparator 2 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold
	11:0	DCMP2_THR	000h	Digital Comparator 2 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)
R16435 (4033h) Comparator 3	15:13	DCMP3_SRC [2:0]	000	Digital Comparator 3 source select 0 = Reserved 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage
	12	DCMP3_GT	0	Digital Comparator 3 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold
	11:0	DCMP3_THR	000h	Digital Comparator 3 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)
R16436 (4034h) Comparator 4	15:13	DCMP4_SRC [2:0]	000	Digital Comparator 4 source select 0 = Backup Battery voltage 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				5 = Chip Temperature 6 = Reserved 7 = PVDD voltage
	12	DCMP4_GT	0	Digital Comparator 4 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold
	11:0	DCMP4_THR	000h	Digital Comparator 4 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)

Table 47 AUXADC Digital Comparator Control

18.5 AUXADC INTERRUPTS

The AUXADC is associated with a number of Interrupt event flags to indicate when new AUXADC data is ready, or to indicate that one or more of the digital comparator thresholds has been crossed. Each of these secondary interrupts triggers a primary AUXADC Interrupt, AUXADC_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 48.

Note that AUXADC_DATA_EINT is not cleared by reading the measured AUXADC data, it can only be cleared by writing '1' to the AUXADC_DATA_EINT register.

The AUXADC interrupts can be programmed using bits in Table 48.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	8	AUXADC_DATA_EINT	AUXADC Data Ready interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	7:4	AUXADC_DCOMP n _EINT	AUXADC Digital Comparator n interrupt (Trigger is controlled by DCMP n _GT) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	8	IM_AUXADC_DATA_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	7:4	IM_AUXADC_DCOMP n _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
Note: n is a number between 1 and 4 that identifies the individual Comparator.			

Table 48 AUXADC Interrupts

19 RESERVED

20 REAL-TIME CLOCK (RTC)

20.1 GENERAL DESCRIPTION

The WM8326 provides a Real Time Clock (RTC) in the form of a 32-bit counter. The RTC uses the 32.768kHz crystal oscillator as its clock source and increments the register value once per second. (Note that a direct CMOS input may be used in place of the crystal oscillator; both options are described in Section 13.) To compensate for errors in the clock frequency, the RTC includes a frequency trim capability.

The RTC is enabled at all times, including when the WM8326 is in the BACKUP state. When required, the RTC can be maintained via a backup battery in the absence of any other power supply. In the absence of a backup battery, the RTC contents can be held (unlocked) for a limited period of up to 5 minutes via a 22µF capacitor.

The RTC incorporates an Alarm function. The Alarm time is held in a 32-bit register. When the RTC counter matches the Alarm time, a selectable response will be actioned.

For digital rights management purposes, the RTC includes security features designed to detect unauthorised modifications to the RTC counter.

20.2 RTC CONTROL

The 32-bit RTC counter value, RTC_TIME is held in two 16-bit registers, R16417 (4021h) and R16418 (4022h). The value of RTC_TIME is incremented by the WM8326 once per second. On initial power-up (from the NO POWER state), these registers will be initialised to default values. Once either of these registers has been written to, the RTC_VALID bit is set to indicate that the RTC_TIME registers contain valid data.

When RTC registers are updated, the RTC_SYNC_BUSY bit indicates that the RTC is busy. The RTC registers should not be written to when RTC_SYNC_BUSY = 1.

The RTC_WR_CNT field is provided as a security feature for the RTC. After initialisation, this field is updated on every write to R16417 (4021h) or to R16418 (4022h). This enables the host processor to detect unauthorised modifications to the RTC counter value. See Section 20.4 for more details.

For additional security, the WM8326 does not allow the RTC to be updated more than 8 times in a one-hour period. Additional write attempts will be ignored.

The RTC Alarm time is held in registers R16419 (4023h) and R16420 (4024h). The Alarm function is enabled when RTC_ALM_ENA is set. When the Alarm is enabled, and the RTC counter matches the Alarm time, the RTC Alarm Interrupt is triggered, as described in Section 20.3.

If the RTC Alarm occurs in the SLEEP power state, then a WAKE transition request is generated. If the RTC Alarm occurs in the OFF power state, then an ON transition request is generated. See Section 11.3 for details.

When updating the RTC Alarm time, it is recommended to disable the Alarm first, by setting RTC_ALM_ENA = 0. The RTC Alarm registers should not be written to when RTC_SYNC_BUSY = 1.

The RTC has a frequency trim feature to allow compensation for known and constant errors in the crystal oscillator frequency up to ±8Hz. The RTC_TRIM field is a 10-bit fixed point 2's complement number. MSB scaling = -8Hz. To compensate for errors in the clock frequency, this register should be set to the error (in Hz) with respect to the ideal (32768Hz) of the input crystal frequency.

For example, if the actual crystal frequency = 32769.00Hz, then the frequency error = +1Hz. The value of RTC_TRIM in this case is 0001_000000.

For example, if the actual crystal frequency = 32763.78Hz, then the frequency error = -4.218750Hz. The value of RTC_TRIM in this case is 1011_110010.

Note that the RTC_TRIM control register is locked by the WM8326 User Key. This register can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16416 (4020h) RTC Write Counter	15:0	RTC_WR_CNT	0000h	RTC Write Counter. This random number is updated on every write to the RTC_TIME registers.
R16417 (4021h) RTC Time 1	15:0	RTC_TIME [31:16]	0000h	RTC Seconds counter (MSW) RTC_TIME increments by 1 every second. This is the 16 MSBs.
R16418 (4022h) RTC Time 2	15:0	RTC_TIME [15:0]	0000h	RTC Seconds counter (LSW) RTC_TIME increments by 1 every second. This is the 16 LSBs.
R16419 (4023h) RTC Alarm 1	15:0	RTC_ALM [31:16]	0000h	RTC Alarm time (MSW) 16 MSBs of RTC_ALM
R16420 (4024h) RTC Alarm 2	15:0	RTC_ALM [15:0]	0000h	RTC Alarm time (LSW) 16 LSBs of RTC_ALM
R16421 (4025h) RTC Control	15	RTC_VALID	0	RTC Valid status 0 = RTC_TIME has not been set since Power On Reset 1 = RTC_TIME has been written to since Power On Reset
	14	RTC_SYNC_BUSY	0	RTC Busy status 0 = Normal 1 = Busy The RTC registers should not be written to when RTC_SYNC_BUSY = 1.
	10	RTC_ALM_ENA	0	RTC Alarm Enable 0 = Disabled 1 = Enabled
R16422 (4026h) RTC Trim	9:0	RTC_TRIM	000h	RTC frequency trim. Value is a 10bit fixed point <4,6> 2's complement number. MSB Scaling = -8Hz. The register indicates the error (in Hz) with respect to the ideal 32768Hz of the input crystal frequency. <i>Protected by user key</i>

Table 49 Real Time Clock (RTC) Control

20.3 RTC INTERRUPTS

The Real Time Clock (RTC) is associated with two Interrupt event flags.

The RTC_PER_EINT interrupt is set each time a periodic timeout occurs. The periodic timeout is configured using the RTC_PINT_FREQ field described in Table 51.

The RTC_ALM_EINT interrupt is set when the RTC Alarm is triggered. The RTC Alarm time is configured as described in Section 20.2.

Each of these secondary interrupts triggers a primary Real Time Clock Interrupt, RTC_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 50.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	3	RTC_PER_EINT	RTC Periodic interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	2	RTC_ALM_EINT	RTC Alarm interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	3	IM_RTC_PER_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	2	IM_RTC_ALM_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 50 Real Time Clock (RTC) Interrupts

The frequency of the RTC periodic interrupts is set by the RTC_PINT_FREQ field, as described in Table 51.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16421 (4025h) RTC Control	6:4	RTC_PINT_FREQ [2:0]	000	RTC Periodic Interrupt timeout period 000 = Disabled 001 = 2s 010 = 4s 011 = 8s 100 = 16s 101 = 32s 110 = 64s 111 = 128s

Table 51 Real Time Clock (RTC) Periodic Interrupt Control

20.4 DIGITAL RIGHTS MANAGEMENT

The Real Time Clock (RTC) maintains a continuous record of the time; this is maintained at all times, including when the WM8326 is powered down and the RTC function is maintained by the backup battery.

It is highly desirable to be able to write to the RTC counter in order to configure it for logical translation into hours/minutes and to support calendar functions. However, for digital rights management purposes, it is important that malicious modification of the RTC is either prevented or detected.

The security measure implemented on the WM8326 is the RTC Write Counter. This register is initialised to 0000h during Power On Reset, and is updated automatically whenever a Write operation is scheduled on either of the RTC_TIME registers. Note that, when the RTC Write Counter is updated, the new value is generated at random; it is not a sequential counter.

It is assumed that legitimate updates to the RTC_TIME are only those initiated by the Application Processor (AP). When the AP makes an update to the RTC_TIME, the AP can also read the new value of the RTC Write Counter, and should store the value in non-volatile memory. If the AP detects a change in value of the RTC Write Counter, and this was not caused by the AP itself writing to the RTC_TIME, this means that an unauthorised write to the RTC_TIME registers has occurred.

In order to make it difficult for an unauthorised RTC_TIME update to be masked by simply writing to the RTC Write Counter, the RTC_WR_CNT field is generated at random by the WM8326 whenever the RTC_TIME field is updated.

For additional security, the WM8326 does not allow the RTC to be updated more than 8 times in a one-hour period. Additional write attempts will be ignored.

The RTC Control registers are described in Table 49.

20.5 BACKUP MODE CLOCKING OPTIONS

The BACKUP state is entered when the PVDD power supply is below the reset threshold of the device. Typically, this means that the PVDD supply has been removed. Most of the device functions and registers are reset in this state.

The RTC and oscillator and a 'software scratch' memory area can be maintained from a backup power source in the BACKUP state. This is provided using a coin cell, super/gold capacitor, or else a standard capacitor, connected to the LDO12VOUT pin via a 22kΩ resistor. See Section 17.3 for further details.

The RTC and oscillator can be disabled in the BACKUP state by setting the XTAL_BKUPENA register bit to 0. This feature may be used to minimise the device power consumption in the BACKUP state. A 22μF capacitor connected to LDO12VOUT can maintain the RTC value, unclocked, for up to 5 minutes in BACKUP if the oscillator is disabled.

The XTAL_BKUPENA register bit is defined in Section 13.1. For more details on backup power, see Section 17.3.

21 GENERAL PURPOSE INPUTS / OUTPUTS (GPIO)

21.1 GENERAL DESCRIPTION

The WM8326 has 12 general-purpose input/output (GPIO) pins, GPIO1 - GPIO12. These can be configured as inputs or outputs, active high or active low, with optional on-chip pull-up or pull-down resistors. GPIO outputs can either be CMOS driven or Open Drain configuration. Each GPIO pin can be tri-stated and can also be used to trigger Interrupts.

The function of each GPIO pin is selected individually. Different voltage power domains are selectable on a pin by pin basis for GPIOs 1-12. Input de-bounce is automatically implemented on selected GPIO functions.

Note that, when GPIO10, GPIO11 or GPIO12 is used as an input to the AUXADC (see Section 18), then the normal GPIO functionality cannot be supported on the affected pin(s). It is recommended that the respective GPIO(s) are tri-stated, as described in Section 21.3.

21.2 GPIO FUNCTIONS

The list of GPIO functions supported by the WM8326 is contained in Table 52 (for input functions) and Table 53 (for output functions). The input functions are selected when the respective GPn_DIR register bit is 1. The output functions are selected when the respective GPn_DIR register bit is 0.

The selected function for each GPIO pin is selected by writing to the respective GPn_FN register bits. All functions are available on all GPIO pins. The polarity of each input or output GPIO function can be selected using the applicable GPn_POL register bit.

The available power domains for each pin are specific to different GPIOs.

The de-bounce time for the GPIO input functions is determined by the GPn_FN field. Some of the input functions allow a choice of de-bounce times, as detailed in Table 52.

The register controls for configuring the GPIO pins are defined in Section 21.3.

GPn_FN	GPIO INPUT FUNCTION	DESCRIPTION	DE-BOUNCE TIME
0h	GPIO	GPIO input. Logic level is read from the GPn_LVL register bits. See Section 21.3.	32 μ s to 64 μ s
1h			4ms to 8ms
2h	ON/OFF Request	Control input for requesting an ON/OFF state transition. See Section 11.3. Under default polarity ($GPn_POL=1$), a rising edge requests the ON state and a falling edge requests the OFF state.	32ms 64ms
3h	SLEEP/WAKE Request	Control input for requesting a SLEEP/WAKE state transition. See Section 11.3. Under default polarity ($GPn_POL=1$), a rising edge requests the SLEEP state and a falling edge requests the WAKE transition to the ON state.	32 μ s to 64 μ s
4h			32ms to 64ms
5h	SLEEP Request	Control input for requesting a SLEEP state transition. See Section 11.3. Under default polarity ($GPn_POL=1$), a rising edge requests the SLEEP state and a falling edge has no effect.	32 μ s to 64 μ s
6h	ON Request	Control input for requesting an ON state transition. See Section 11.3. Under default polarity ($GPn_POL=1$), a rising edge requests the ON state and a falling edge has no effect.	32 μ s to 64 μ s
7h	Watchdog Reset	Control input for resetting the Watchdog Timer. See Section 25.	32 μ s to 64 μ s

GPn_FN	GPIO INPUT FUNCTION	DESCRIPTION	DE-BOUNCE TIME
8h	Hardware DVS control 1	Control input for selecting the DVS output voltage in one or more DC-DC Converters. See Section 15.6.	None
9h	Hardware DVS control 2	Control input for selecting the DVS output voltage in one or more DC-DC Converters. See Section 15.6.	None
Ah	Hardware Enable 1	Control input for enabling one or more DC-DC Converters and LDO Regulators. See Section 15.	32 μ s to 64 μ s
Bh	Hardware Enable 2	Control input for enabling one or more DC-DC Converters and LDO Regulators. See Section 15.	32 μ s to 64 μ s
Ch	Hardware Control input 1	Control input for selecting the operating mode and/or output voltage of one or more DC-DC Converters and LDO Regulators. See Section 15.	32 μ s to 64 μ s
Dh	Hardware Control input 2	Control input for selecting the operating mode and/or output voltage of one or more DC-DC Converters and LDO Regulators. See Section 15.	32 μ s to 64 μ s
Eh	Hardware Control input 1	Control input for selecting the operating mode and/or output voltage of one or more DC-DC Converters and LDO Regulators. See Section 15.	32ms to 64ms
Fh	Hardware Control input 2	Control input for selecting the operating mode and/or output voltage of one or more DC-DC Converters and LDO Regulators. See Section 15.	32ms to 64ms

Table 52 List of GPIO Input Functions

Further details of the GPIO input de-bounce time are noted in Section 21.3.

GPn_FN	GPIO OUTPUT FUNCTION	DESCRIPTION
0h	GPIO	GPIO output. Logic level is set by writing to the GPn_LVL register bits. See Section 21.3.
1h	Oscillator clock	32.768kHz clock output. See Section 13.
2h	ON state	Logic output indicating that the WM8326 is in the ON state. See Section 11.5.
3h	SLEEP state	Logic output indicating that the WM8326 is in the SLEEP state. See Section 11.5.
4h	Power State Change	Logic output asserted whenever a Power On Reset, or an ON, OFF, SLEEP or WAKE transition has completed. Under default polarity (GPn_POL=1), the logic level is the same as the PS_INT interrupt status flag. Note that, if any of the associated Secondary interrupts is masked, then the respective event will not affect the Power State Change GPIO output. See Section 11.2 and Section 11.4.
8h	DC-DC1 DVS Done	Logic output indicating that DC-DC1 buck converter DVS slew has been completed. This signal is temporarily de-asserted during voltage transitions (including non-DVS transitions). See Section 15.6.
9h	DC-DC2 DVS Done	Logic output indicating that DC-DC2 buck converter DVS slew has been completed. This signal is temporarily de-asserted during voltage transitions (including non-DVS transitions). See Section 15.6.

GPn_FN	GPIO OUTPUT FUNCTION	DESCRIPTION
Ah	External Power Enable 1	Logic output assigned to one of the timeslots in the ON/OFF and SLEEP/WAKE sequences. This can be used for sequenced control of external circuits. See Section 15.3.
Bh	External Power Enable 2	Logic output assigned to one of the timeslots in the ON/OFF and SLEEP/WAKE sequences. This can be used for sequenced control of external circuits. See Section 15.3.
Ch	System Supply Good (PVDD Good)	Logic output from PVDD monitoring circuit. This function represents the internal SYSOK signal. See Section 24.4.
Dh	Converter Power Good (PWR_GOOD)	Status output indicating that all selected DC-DC converters and LDO regulators are operating correctly. Only asserted in ON and SLEEP modes. See Section 15.13.
Eh	External Power Clock	2MHz clock output suitable for clocking external DC-DC converters. This clock signal is synchronized with the WM8326 DC Converters clocking signal. See Section 13. This clock output is only enabled when either of the External Power Enable signals (EPE1 or EPE2) is asserted. These signals can be assigned to one of the timeslots in the ON/OFF and SLEEP/WAKE sequences. See Section 15.3.
Fh	Auxiliary Reset	Logic output indicating a Reset condition. This signal is asserted in the OFF state. The status in SLEEP mode is configurable. See Section 11.7. Note that the default polarity for this function (GPn_POL=1) is "Active High". Setting GPn_POL=0 will select "Active Low" function.

Table 53 List of GPIO Output Functions

21.3 CONFIGURING GPIO PINS

The GPIO pins are configured using the Resister fields defined in Table 54.

The function of each GPIO is selected using the GPn_FN register field. The pin direction field GPn_DIR selects between input functions and output functions. See Section 21.2 for a summary of the available GPIO functions.

The polarity of each GPIO can be configured using the GPn_POL bits. This inversion is effective both on GPIO inputs and outputs. When GPn_POL = 1, the non-inverted 'Active High' polarity applies. The opposite logic can be selected by setting GPn_POL = 0.

The voltage power domain of each GPIO is determined by the GPn_PWR_DOM register. Note that the available options vary between different GPIO pins, as described in Table 56.

A GPIO output may be either CMOS driven or Open Drain. This is selected using the GPn_OD bits.

Internal pull-up or pull-down resistors can be enabled on each pin using the GPn_PULL field. Both resistors are available for use when the associated GPIO is an input. When the GPIO pin is configured as an Open Drain output, the internal pull-up resistor may be required if no external pull-up resistors are present.

A GPIO pin may be tri-stated using the GPn_ENA register field. When GPn_ENA = 0, the respective pin is tri-stated. A tri-stated pin exhibits high impedance to any external circuit and is disconnected from the internal GPIO circuits. The pull-up and pull-down resistors are disabled when a GPIO pin is tri-stated.

GPIO pins can generate an interrupt (see Section 21.4). The GPn_INT_MODE field selects whether the interrupt occurs on a single active edge only, or else on both rising and falling edges. When single edge is selected, the active edge is the rising edge (when GPn_POL = 1) or the falling edge (when GPn_POL = 0).

When GPIO10, GPIO11 or GPIO12 is used as an input to the AUXADC (see Section 18), it is recommended that the respective GPIO(s) are tri-stated (ie. GPn_ENA = 0). The normal GPIO functionality cannot be supported on a GPIO pin that is enabled as an input to the AUXADC.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16440 (4038h)	15	GPn_DIR	1	GPION pin direction 0 = Output 1 = Input
to				
R16451 (4043h)	14:13	GPn_PULL [1:0]	01	GPION Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved
	12	GPn_INT_M ODE	0	GPION Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GPn_POL=1) or falling edge triggered (if GPn_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges
	11	GPn_PWR_D OM	0	GPION Power Domain See Table 56.
	10	GPn_POL	1	GPION Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)
	9	GPn_OD	0	GPION Output pin configuration 0 = CMOS 1 = Open Drain
	7	GPn_ENA	0	GPION Enable control 0 = GPIO pin is tri-stated 1 = Normal operation
	3:0	GPn_FN [3:0]	0000	GPION Pin Function See Table 57.
Note: <i>n</i> is a number between 1 and 12 that identifies the individual GPIO. Note: The default values noted are valid when the WM8326 powers up to the OFF state, or if the Register Map is reset following a Device Reset or Software Reset event. In the case of GPIO pins 1 to 6, these registers are overwritten with the respective ICE or OTP memory contents when an ON transition is scheduled.				

Table 54 GPIO Pin Configuration

When the GPIO output function is selected (GPn_FN = 0h, GPn_DIR = 0), the state of a GPIO output is controlled by writing to the corresponding GPn_LVL register bit, as defined in Table 55.

The logic level of a GPIO input is determined by reading the corresponding GPn_LVL register bit. If GPn_POL is set, then the read value of the GPn_LVL field for a GPIO input is the inverse of the external signal. Note that, when the GPIO input level changes, the logic level of GPn_LVL will only be updated after the maximum de-bounce period, as listed in Table 52. An input pulse that is shorter than the minimum de-bounce period will be filtered by the de-bounce function and will be ignored.

If a GPIO is configured as a CMOS output (ie. GPn_OD = 0), then the read value of the GPn_LVL field will indicate the logic level of that output. If GPn_POL is set, then the read value of the GPn_LVL field for a GPIO output is the inverse of the level on the external pad.

If a GPIO is configured as an Open Drain output, then the read value of GPn_LVL is only valid when the internal pull-up resistor is enabled on the pin (ie. when GPn_PULL = 10). The read value is also affected by the GPn_POL bit, as described above for the CMOS case.

If a GPIO is tri-stated (GPn_ENA = 0), then the read value of the corresponding GPn_LVL field is invalid.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16396 (400Ch) GPIO Level	11	GP12_LVL	0	GPIO n level. When GP n _FN = 0h and GP n _DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP n _POL is 0, the register contains the opposite logic level to the external pin.
	10	GP11_LVL	0	
	9	GP10_LVL	0	
	8	GP9_LVL	0	
	7	GP8_LVL	0	
	6	GP7_LVL	0	
	5	GP6_LVL	0	
	4	GP5_LVL	0	
	3	GP4_LVL	0	
	2	GP3_LVL	0	
	1	GP2_LVL	0	
	0	GP1_LVL	0	

Table 55 GPIO Level Register

The power domain for each GPIO is controlled using the GP n _PWR_DOM registers as described in Table 56.

The selected power domain for each GPIO affects the maximum input voltage that can be supported on the respective pin(s). Note that this is also applicable when GPIO10, GPIO11 or GPIO12 are used as inputs to the AUXADC (see Section 18). The input voltage at the GPIO pin must not exceed the voltage of the respective power domain.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16440 (4038h) GPIO1 Control	11	GP1_PWR_DOM	0	GPIO1 Power Domain select 0 = DBVDD 1 = VPMIC (LDO12)
R16441 (4039h) GPIO2 Control	11	GP2_PWR_DOM	0	GPIO2 Power Domain select 0 = DBVDD 1 = VPMIC (LDO12)
R16442 (403Ah) GPIO3 Control	11	GP3_PWR_DOM	0	GPIO3 Power Domain select 0 = DBVDD 1 = VPMIC (LDO12)
R16443 (403Bh) GPIO4 Control	11	GP4_PWR_DOM	0	GPIO4 Power Domain select 0 = DBVDD 1 = PVDD
R16444 (403Ch) GPIO5 Control	11	GP5_PWR_DOM	0	GPIO5 Power Domain select 0 = DBVDD 1 = PVDD
R16445 (403Dh) GPIO6 Control	11	GP6_PWR_DOM	0	GPIO6 Power Domain select 0 = DBVDD 1 = PVDD
R16446 (403Eh) GPIO7 Control	11	GP7_PWR_DOM	0	GPIO7 Power Domain select 0 = DBVDD 1 = VPMIC (LDO12)
R16447 (403Fh) GPIO8 Control	11	GP8_PWR_DOM	0	GPIO8 Power Domain select 0 = DBVDD 1 = VPMIC (LDO12)
R16448 (4040h) GPIO9 Control	11	GP9_PWR_DOM	0	GPIO9 Power Domain select 0 = DBVDD 1 = VPMIC (LDO12)
R16449 (4041h) GPIO10	11	GP10_PWR_DOM	0	GPIO10 Power Domain select 0 = DBVDD 1 = PVDD

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
Control				
R16450 (4042h) GPIO11 Control	11	GP11_PWR_D OM	0	GPIO11 Power Domain select 0 = DBVDD 1 = PVDD
R16451 (4043h) GPIO12 Control	11	GP12_PWR_D OM	0	GPIO12 Power Domain select 0 = DBVDD 1 = PVDD

Table 56 GPIO Power Domain Registers

The function of each GPIO is controlled using the GPN_FN registers defined in Table 57. Note that the selected function also depends on the associated GPN_DIR field described in Table 54.

See also Section 21.2 for additional details of each GPIO function, including the applicable de-bounce times for GPIO input functions.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16440 (4038h) GPIO1 Control	3:0	GP1_FN [3:0]	0000	Input functions: 0h = GPIO input (long de-bounce) 1h = GPIO input
R16441 (4039h) GPIO2 Control	3:0	GP2_FN [3:0]	0000	2h = Power On/Off request 3h = Sleep/Wake request 4h = Sleep/Wake request (long de-bounce)
R16442 (403Ah) GPIO3 Control	3:0	GP3_FN [3:0]	0000	5h = Sleep request 6h = Power On request 7h = Watchdog Reset input
R16443 (403Bh) GPIO4 Control	3:0	GP4_FN [3:0]	0000	8h = DVS1 input 9h = DVS2 input Ah = HW Enable1 input
R16444 (403Ch) GPIO5 Control	3:0	GP5_FN [3:0]	0000	Bh = HW Enable2 input Ch = HW Control1 input Dh = HW Control2 input
R16445 (403Dh) GPIO6 Control	3:0	GP6_FN [3:0]	0000	Eh = HW Control1 input (long de-bounce) Fh = HW Control2 input (long de-bounce)
R16446 (403Eh) GPIO7 Control	3:0	GP7_FN [3:0]	0000	Output functions: 0h = GPIO output 1h = 32.768kHz oscillator output 2h = ON state
R16447 (403Fh) GPIO8 Control	3:0	GP8_FN [3:0]	0000	3h = SLEEP state 4h = Power State Change 5h = Reserved
R16448 (4040h) GPIO9 Control	3:0	GP9_FN [3:0]	0000	6h = Reserved 7h = Reserved 8h = DC1 DVS Done
R16449 (4041h) GPIO10 Control	3:0	GP10_FN [3:0]	0000	9h = DC2 DVS Done Ah = External Power Enable1 Bh = External Power Enable2
R16450 (4042h) GPIO11 Control	3:0	GP11_FN [3:0]	0000	Ch = System Supply Good (SYSOK) Dh = Converter Power Good (PWR_GOOD)
R16451 (4043h) GPIO12 Control	3:0	GP12_FN [3:0]	0000	Eh = External Power Clock (2MHz) Fh = Auxiliary Reset

Table 57 GPIO Function Select Registers

Note that GPIO input functions 2h, 3h, 4h, 5h and 6h are edge-triggered only. The associated state transition(s) are scheduled only when a rising or falling edge is detected on the respective GPIO pin. At other times, it is possible that other state transition events may cause a state transition regardless of the state of the GPIO input. See Section 11.3 for details of all the state transition events.

21.4 GPIO INTERRUPTS

Each GPIO pin has an associated interrupt flag, GPn_EINT , in Register R16405 (4015h). Each of these secondary interrupts triggers a primary GPIO Interrupt, GP_INT (see Section 23). This can be masked by setting the mask bit(s) as described in Table 58.

See Section 28 and Section 29 for a definition of the register bit positions applicable to each GPIO.

ADDRESS	BIT	LABEL	DESCRIPTION
R16405 (4015h) Interrupt Status 5	15:0	GPn_EINT	GPIO interrupt. (Trigger is controlled by GPn_INT_MODE) Note: Cleared when a '1' is written.
R16413 (401Dh) Interrupt Status 5 Mask	15:0	IM_GPn_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
Note: n is a number between 1 and 12 that identifies the individual GPIO.			

Table 58 GPIO Interrupts

22 SYSTEM STATUS LED DRIVERS

22.1 GENERAL DESCRIPTION

The WM8326 provides two System Status LED Drivers. These are digital outputs intended for driving LEDs directly. The LED outputs can be assigned to indicate OTP Program status or Power State status. They can also be commanded directly via register control, in order to provide any other required functionality.

22.2 LED DRIVER CONTROL

LED Drivers are configurable in the ON and SLEEP power states only. The functionality of the LED Drivers is controlled by the LEDn_SRC register bits, as described in Table 59.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16460 (404Ch) Status LED1	15:14	LED1_SRC [1:0]	11	LED1 Source (Selects the LED1 function.) 00 = Off 01 = Power State Status 10 = Reserved 11 = Manual Mode Note - LED1 also indicates completion of OTP Auto Program
R16461 (404Dh) Status LED2	15:14	LED2_SRC [1:0]	11	LED2 Source (Selects the LED2 function.) 00 = Off 01 = Power State Status 10 = Reserved 11 = Manual Mode Note - LED2 also indicates an OTP Auto Program Error condition

Table 59 System Status LED Control

22.2.1 OTP PROGRAM STATUS

The LED drivers indicate the status of the OTP Auto Program function, where the contents of the external InstantConfig™ EEPROM (ICE) memory are automatically programmed into the OTP. See Section 14.6.3 for further details of the OTP Auto Program function.

When the OTP Auto Program function is executed, the System Status LED drivers follow the functionality defined in Table 60.

LED DRIVER	DESCRIPTION	DRIVE MODE	LED 'ON' TIME	ON:OFF DUTY CYCLE
LED1	OTP Auto Program Complete	Constant	n/a	n/a
LED2	OTP Auto Program Error	Constant	n/a	n/a

Table 60 System Status LED Outputs - OTP Program Status

The OTP Program Status LED outputs will continue until a Device Reset.

Note that the OTP Program Status is always indicated via the LED outputs, regardless of the LEDn_SRC register fields.

22.2.2 POWER STATE STATUS

Setting LEDn_SRC = 01 configures the associated LED to indicate Power State status. Under this selection, four different conditions may be indicated, as defined in Table 61.

LED DRIVER	DESCRIPTION	DRIVE MODE	LED 'ON' TIME	ON:OFF DUTY CYCLE
LED1 or LED2	Power Sequence Failure	Pulsed sequence (4 pulses)	1s	1:1
	PVDD Low	Continuous pulsed	250ms	1:3
	ON state	Constant	n/a	n/a
	SLEEP state	Continuous pulsed	250ms	1:7

Table 61 System Status LED Outputs - Power State Status

If more than one of the conditions listed occurs simultaneously, then the LED output pattern is controlled by the condition in the highest position within the list above.

For example, if the PVDD Low condition occurs while in the ON or SLEEP states, then the LED output follows the pattern defined for the PVDD Low condition.

The PVDD Low indication is asserted if PVDD is less than the user-selectable threshold SYSLO_THR, as described in Section 24.4.

Note that, in the case of Power Sequence Failure, the transition to OFF occurs after the 4 LED pulses have been emitted.

22.2.3 MANUAL MODE

Setting LEDn_SRC = 11 configures the associated LED to operate in Manual Mode, which is configured using additional register fields.

In Manual Mode, the LED output can be commanded as Off, On (Constant), Continuous Pulsed or Pulsed Sequence. The selected operation is determined by the LEDn_MODE registers as described in Table 62.

In Continuous Pulsed mode and Pulsed Sequence mode, the 'On' time and the Duty Cycle can be configured using the LEDn_DUR and LEDn_DUTY_CYC registers respectively.

In Pulsed Sequence mode, the number of pulses in the sequence can be selected using the LEDn_SEQ_LEN register. On completion of the commanded number of pulses, the LED remains off until LEDn_MODE or LEDn_SRC is changed to another value.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16460 (404Ch) Status LED1	9:8	LED1_MODE [1:0]	00	LED1 Mode (Controls LED1 in Manual Mode only.) 00 = Off 01 = Constant 10 = Continuous Pulsed 11 = Pulsed Sequence
	5:4	LED1_SEQ_LEN [1:0]	10	LED1 Pulse Sequence Length (when LED1_MODE = Pulsed Sequence) 00 = 1 pulse 01 = 2 pulses 10 = 4 pulses 11 = 7 pulses

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	3:2	LED1_DUR [1:0]	01	LED1 On time (when LED1_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1 second 01 = 250ms 10 = 125ms 11 = 62.5ms
	1:0	LED1_DUTY_C YC [1:0]	10	LED1 Duty Cycle (On:Off ratio) (when LED1_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1:1 (50% on) 01 = 1:2:(33.3% on) 10 = 1:3 (25% on) 11 = 1:7 (12.5% on)
R16461 (404Dh) Status LED2	9:8	LED2_MODE [1:0]	00	LED2 Mode (Controls LED2 in Manual Mode only.) 00 = Off 01 = Constant 10 = Continuous Pulsed 11 = Pulsed Sequence
	5:4	LED2_SEQ_LE N [1:0]	10	LED2 Pulse Sequence Length (when LED2_MODE = Pulsed Sequence) 00 = 1 pulse 01 = 2 pulses 10 = 4 pulses 11 = 7 pulses
	3:2	LED2_DUR [1:0]	01	LED2 On time (when LED2_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1 second 01 = 250ms 10 = 125ms 11 = 62.5ms
	1:0	LED2_DUTY_C YC [1:0]	10	LED2 Duty Cycle (On:Off ratio) (when LED2_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1:1 (50% on) 01 = 1:2:(33.3% on) 10 = 1:3 (25% on) 11 = 1:7 (12.5% on)

Table 62 System Status LED Outputs - Manual Mode Control

22.3 LED DRIVER CONNECTIONS

The recommended connection for System Status LEDs is illustrated in Figure 23. The LED outputs are referenced to the PVDD power domain. A series resistor may be required, depending on the LED characteristics and the PVDD voltage.

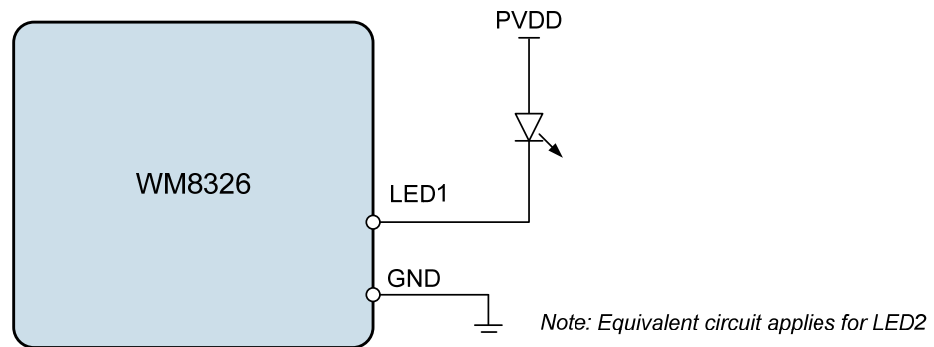


Figure 23 System Status LED Connections

23 INTERRUPT CONTROLLER

The WM8326 has a comprehensive Interrupt logic capability. The dedicated $\overline{\text{IRQ}}$ pin can be used to alert a host processor to selected events or fault conditions. Each of the interrupt conditions can be individually enabled or masked. Following an interrupt event, the host processor should read the interrupt registers in order to determine what caused the interrupt, and take appropriate action if required.

The WM8326 interrupt controller has two levels:

Secondary interrupts indicate a single event in one of the circuit blocks. The event is indicated by setting a register bit. This bit is a latching bit - once it is set, it remains at logic 1 even if the trigger condition is cleared. The secondary interrupts are cleared by writing a logic 1 to the relevant register bit. Note that reading the register does not clear the secondary interrupt.

Primary interrupts are the logical OR of the associated secondary interrupts (usually all the interrupts associated with one particular circuit block). Each of the secondary interrupts can be individually masked or enabled as an input to the corresponding primary interrupt. The primary interrupt register R16400 (4010h) is read-only.

The status of the $\overline{\text{IRQ}}$ pin reflects the logical NOR of the primary interrupts. A logic 0 indicates that one or more of the primary interrupts is asserted. Each of the primary interrupts can be individually masked or enabled as an input to the $\overline{\text{IRQ}}$ pin output.

The $\overline{\text{IRQ}}$ pin output can either be CMOS driven or Open Drain (integrated pull-up) configuration, as determined by the IRQ_OD register bit. When the $\overline{\text{IRQ}}$ pin is Open Drain, it is actively driven low when asserted; the pull-up causes a logic high output when not asserted. The Open Drain configuration enables multiple devices to share a common Interrupt line with the host processor.

The $\overline{\text{IRQ}}$ pin output can be masked by setting the IM_IRQ register bit. When the $\overline{\text{IRQ}}$ pin is masked, it is held in the logic 1 (or Open Drain) state regardless of any internal interrupt event.

Note that the secondary interrupt bits are always valid - they are set as normal, regardless of whether the bit is enabled or masked as an input to the corresponding primary interrupt. The primary interrupt bits are set and cleared as normal in response to any unmasked secondary interrupt, regardless of whether the primary interrupt bit is enabled or masked as an input to the $\overline{\text{IRQ}}$ pin output.

Note also that if any internal condition is configured to trigger an event other than an Interrupt (eg. the Watchdog timer triggers Reset), these events are always actioned, regardless of the state of any interrupt mask bits.

The $\overline{\text{IRQ}}$ pin output is configured using the register bits described in Table 63.

ADDRESS	BIT	LABEL	DESCRIPTION
R16407 (4017h) IRQ Config	1	IRQ_OD	IRQ pin configuration 0 = CMOS 1 = Open Drain (integrated pull-up)
	0	IM_IRQ	IRQ pin output mask 0 = Normal 1 = IRQ output is masked

Table 63 IRQ Pin Configuration

The interrupt logic is illustrated in Figure 24.

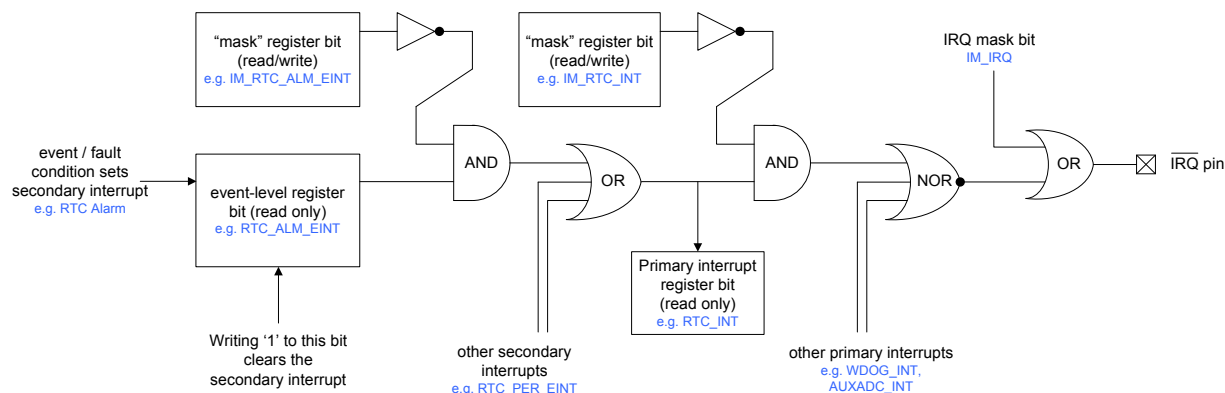


Figure 24 Interrupt Logic

Following the assertion of the $\overline{\text{IRQ}}$ pin to indicate an Interrupt event, the host processor can determine which primary interrupt caused the event by reading the primary interrupt register R16400 (4010h). This register is defined in Section 23.1.

After reading the primary interrupt register, the host processor must read the corresponding secondary interrupt register(s) in order to determine which specific event caused the $\overline{\text{IRQ}}$ pin to be asserted. The host processor clears the secondary interrupt bit by writing a logic 1 to that bit.

23.1 PRIMARY INTERRUPTS

The primary interrupts are defined in Table 64. These bits are Read Only. They are set when any of the associated unmasked secondary interrupts is set. They can only be reset when all of the associated secondary resets are cleared or masked.

Each primary interrupt can be masked. When a mask bit is set, the corresponding primary interrupt is masked and does not cause the $\overline{\text{IRQ}}$ pin to be asserted. The primary interrupt bits in R16408 (4018h) are valid regardless of whether the mask bit is set. The primary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16400 (4010h) System Interrupts	15	PS_INT	Power State primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	14	TEMP_INT	Thermal primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	13	GP_INT	GPIO primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	12	ON_PIN_INT	ON Pin primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	11	WDOG_INT	Watchdog primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	8	AUXADC_INT	AUXADC primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	7	PPM_INT	Power Path Management primary interrupt

ADDRESS	BIT	LABEL	DESCRIPTION
			0 = No interrupt 1 = Interrupt is asserted
	5	RTC_INT	Real Time Clock and Crystal Oscillator primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	4	OTP_INT	OTP Memory primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	1	HC_INT	High Current primary interrupt 0 = No interrupt 1 = Interrupt is asserted
	0	UV_INT	Undervoltage primary interrupt 0 = No interrupt 1 = Interrupt is asserted
R16408 (4018h) System Interrupts Mask	15	IM_PS_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	14	IM_TEMP_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	13	IM_GP_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	12	IM_ON_PIN_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	11	IM_WDOG_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	8	IM_AUXADC_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	7	IM_PPM_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	5	IM_RTC_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	4	IM_OTP_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	1	IM_HC_INT	Interrupt mask. 0 = Do not mask interrupt.

ADDRESS	BIT	LABEL	DESCRIPTION
			1 = Mask interrupt. Default value is 1 (masked)
	0	IM_UV_INT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 64 Primary Interrupt Status and Mask Bits

23.2 SECONDARY INTERRUPTS

The following sections define the secondary interrupt status and control bits associated with each of the primary interrupt bits defined in Table 64.

23.2.1 POWER STATE INTERRUPT

The primary PS_INT interrupt comprises three secondary interrupts as described in Section 11.4. The secondary interrupt bits are defined in Table 65.

Each of the secondary interrupts can be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a PS_INT interrupt. The secondary interrupt bits in R16402 (4012h) are valid regardless of whether the mask bit is set. The secondary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16402 (4012h) Interrupt Status 2	2	PS_POR_EINT	Power On Reset interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	1	PS_SLEEP_OFF_EINT	SLEEP or OFF interrupt (Power state transition to SLEEP or OFF states) (Rising Edge triggered) Note: Cleared when a '1' is written.
	0	PS_ON_WAKE_EINT	ON or WAKE interrupt (Power state transition to ON state) (Rising Edge triggered) Note: Cleared when a '1' is written.
R16410 (401Ah) Interrupt Status 2 Mask	2	IM_PS_POR_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	1	IM_PS_SLEEP_OFF_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	0	IM_PS_ON_WAKE_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 65 Power State Interrupts

23.2.2 THERMAL INTERRUPTS

The primary TEMP_INT interrupt comprises a single secondary interrupt as described in Section 26. The secondary interrupt bit is defined in Table 66.

The secondary interrupt can be masked. When the mask bit is set, the corresponding interrupt event is masked and does not trigger a TEMP_INT interrupt. The secondary interrupt bit in R16401 (4011h) is valid regardless of whether the mask bit is set. The secondary interrupt is masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	1	TEMP_THW_CINT	Thermal Warning interrupt (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.
R16410 (4019h) Interrupt Status 1 Mask	1	IM_TEMP_THW_CINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 66 Thermal Interrupts

23.2.3 GPIO INTERRUPTS

The primary GP_INT interrupt comprises sixteen secondary interrupts as described in Section 21.4. The secondary interrupt bits are defined in Table 67.

Each of the secondary interrupts can be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a GP_INT interrupt. The secondary interrupt bits in R16405 (4015h) are valid regardless of whether the mask bit is set. The secondary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16405 (4015h) Interrupt Status 5	15:0	GP _n _EINT	GPIO interrupt. (Trigger is controlled by GP _n _INT_MODE) Note: Cleared when a '1' is written.
R16413 (401Dh) Interrupt Status 5 Mask	15:0	IM_GP _n _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
Note: <i>n</i> is a number between 1 and 12 that identifies the individual GPIO.			

Table 67 GPIO Interrupts

23.2.4 ON PIN INTERRUPTS

The primary ON_PIN_INT interrupt comprises a single secondary interrupt as described in Section 11.6. The secondary interrupt bit is defined in Table 68.

The secondary interrupt can be masked. When the mask bit is set, the corresponding interrupt event is masked and does not trigger an ON_PIN_INT interrupt. The secondary interrupt bit in R16401 (4011h) is valid regardless of whether the mask bit is set. The secondary interrupt is masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	12	ON_PIN_CINT	ON pin interrupt. (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	12	IM_ON_PIN_CINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 68 ON Pin Interrupt

23.2.5 WATCHDOG INTERRUPTS

The primary WDOG_INT interrupt comprises a single secondary interrupt as described in Section 25. The secondary interrupt bit is defined in Table 69.

The secondary interrupt can be masked. When the mask bit is set, the corresponding interrupt event is masked and does not trigger a WDOG_INT interrupt. The secondary interrupt bit in R16401 (4011h) is valid regardless of whether the mask bit is set. The secondary interrupt is masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	11	WDOG_TO_EINT	Watchdog timeout interrupt. (Rising Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	11	IM_WDOG_TO_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 69 Watchdog Timer Interrupts

23.2.6 AUXADC INTERRUPTS

The primary AUXADC_INT interrupt comprises five secondary interrupts as described in Section 18.5. The secondary interrupt bits are defined in Table 70.

Each of the secondary interrupts can be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a AUXADC_INT interrupt. The secondary interrupt bits in R16401 (4011h) are valid regardless of whether the mask bit is set. The secondary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	8	AUXADC_DATA_EINT	AUXADC Data Ready interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	7:4	AUXADC_DCOMP n _EINT	AUXADC Digital Comparator n interrupt (Trigger is controlled by DCOMP n _GT) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	8	IM_AUXADC_DATA_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	7:4	IM_AUXADC_DCOMP n _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Note: n is a number between 1 and 4 that identifies the individual Comparator.

Table 70 AUXADC Interrupts

23.2.7 POWER PATH MANAGEMENT INTERRUPTS

The primary PPM_INT interrupt comprises a single secondary interrupt as described in Section 17.2. The secondary interrupt bit is defined in Table 71.

The secondary interrupt can be masked. When the mask bit is set, the corresponding interrupt event is masked and does not trigger a PPM_INT interrupt. The secondary interrupt bit in R16401 (4011h) are valid regardless of whether the mask bit is set. The secondary interrupt is masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	15	PPM_SYSLO_EINT	Power Path SYSLO interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	15	IM_PPM_SYSLO_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 71 Power Path Management Interrupts

23.2.8 REAL TIME CLOCK AND CRYSTAL OSCILLATOR INTERRUPTS

The primary RTC_INT interrupt comprises four secondary interrupts as described in Section 20.3. The secondary interrupt bits are defined in Table 72.

Each of the secondary interrupts can be masked except for XTAL_TAMPER_EINT, which cannot be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a RTC_INT interrupt. The secondary interrupt bits in R16401 (4011h) and R16404 (4014h) are valid regardless of whether the mask bit is set.

The secondary interrupts are all masked by default, except for XTAL_TAMPER_EINT, which cannot be masked.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	3	RTC_PER_EINT	RTC Periodic interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	2	RTC_ALM_EINT	RTC Alarm interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16404 (4014h) Interrupt Status 4	7	XTAL_START_EINT	Crystal Oscillator Start Failure interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	6	XTAL_TAMPER_EINT	Crystal Oscillator Tamper interrupt (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	3	IM_RTC_PER_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	2	IM_RTC_ALM_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
R16412 (401Ch) Interrupt Status 4 Mask	7	IM_XTAL_START_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 72 Real Time Clock (RTC) and Crystal Oscillator (XTAL) Interrupts

23.2.9 OTP MEMORY INTERRUPTS

The primary OTP_INT interrupt comprises two secondary interrupts as described in Section 14.5. The secondary interrupt bits are defined in Table 73.

Each of the secondary interrupts can be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a OTP_INT interrupt. The secondary interrupt bits in R16402 (4012h) are valid regardless of whether the mask bit is set. The secondary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16402 (4012h) Interrupt Status 2	5	OTP_CMD_END_EINT	OTP / ICE Command End interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	4	OTP_ERR_EINT	OTP / ICE Command Fail interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16410 (401Ah) Interrupt Status 2 Mask	5	IM_OTP_CMD_END_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	4	IM_OTP_ERR_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 73 OTP Memory Interrupts

23.2.10 HIGH CURRENT INTERRUPTS

The primary HC_INT interrupt comprises two secondary interrupts as described in Section 15.12. The secondary interrupt bits are defined in Table 74.

Each of the secondary interrupts can be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a HC_INT interrupt. The secondary interrupt bits in R16404 (4014h) are valid regardless of whether the mask bit is set. The secondary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16404 (4014h) Interrupt Status 4	9	HC_DC2_EINT	DC-DC2 High Current interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
	8	HC_DC1_EINT	DC-DC1 High Current interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16412 (401Ch) Interrupt Status 4 Mask	9	IM_HC_DC2_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
	8	IM_HC_DC1_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 74 Overcurrent Interrupts

23.2.11 UNDERVOLTAGE INTERRUPTS

The primary UV_INT interrupt comprises fourteen secondary interrupts as described in Section 15.12). The secondary interrupt bits are defined in Table 75.

Each of the secondary interrupts can be masked. When a mask bit is set, the corresponding interrupt event is masked and does not trigger a UV_INT interrupt. The secondary interrupt bits in R16403 (4013h) and R16404 (4014h) are valid regardless of whether the mask bit is set. The secondary interrupts are all masked by default.

ADDRESS	BIT	LABEL	DESCRIPTION
R16403 (4013h) Interrupt Status 3	9:0	UV_LDO _n _EINT	LDO _n Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16404 (4014h) Interrupt Status 4	3:0	UV_DC _m _EINT	DC-DC _m Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.
R16411 (401Bh) Interrupt Status 3 Mask	9:0	IM_UV_LDO _n _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
R16412 (401Ch) Interrupt Status 4 Mask	3:0	IM_UV_DC _m _EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)
Notes: 1. <i>n</i> is a number between 1 and 10 that identifies the individual LDO Regulator (LDO1-LDO10). 2. <i>m</i> is a number between 1 and 4 that identifies the individual DC-DC Converter (DC1-DC4).			

Table 75 Undervoltage Interrupts

24 RESETS AND SUPPLY VOLTAGE MONITORING

24.1 RESETS

The WM8326 provides hardware and software monitoring functions as inputs to a Reset management system. These functions enable the device to take appropriate action when power supplies are critically low or if a hardware or software fault condition is detected.

There are different levels of Resets, providing different response mechanisms according to the condition that caused the Reset event. Where applicable, the WM8326 will automatically return to the ON state and resume normal operation as quickly as possible following a Reset.

A System Reset occurs in the event of a Power Sequence Failure, Device overtemperature, PVDD undervoltage, Software 'OFF' request or VPMIC (LDO12) undervoltage condition. Under these conditions, the WM8326 asserts the **RESET** pin and transitions to the OFF state. In the case of VPMIC undervoltage, the WM8326 enters the BACKUP state. The contents of the Register map are not reset under System Reset conditions.

A Device Reset occurs in the event of a Watchdog Timeout, Hardware Reset request or Converter (LDO or DC-DC) Undervoltage condition. Under these conditions, the WM8326 asserts the **RESET** pin and transitions to the OFF state. The contents of the Register map are cleared to default values, except for the RTC and software scratch registers, which are maintained. The WM8326 will automatically return to the ON state after performing the Device Reset.

A Software Reset occurs when any value is written to Register 0000h, as described in Section 12.5. In this event, the WM8326 asserts the **RESET** pin and transitions to the OFF state. The Register map contents may or may not be affected, depending on the value of the SW_RESET_CFG field. See Section 24.3 for further details of Software Reset configuration. The WM8326 will automatically return to the ON state after performing the Software Reset.

A Power-On Reset occurs when the supply voltage is less than the Power-On Reset threshold, as described in Section 24.4. In this event, the WM8326 is forced into the NO POWER state, as described in Section 11.2. All the contents of the Register map are lost in the NO POWER state.

A summary of the WM8326 Resets is contained in Table 76 .

RESET TYPE	RESET CONDITION	DESCRIPTION	RESPONSE	AUTOMATIC RECOVERY
System Reset	Power Sequence Failure	DC Converters, LDOs or CLKOUT circuits have failed to start up within the permitted time. See Section 11.3.	Assert RESET pin. Select OFF state.	No
	Device overtemperature	An overtemperature condition has been detected. See Section 26.	If the Reset Condition is VPMIC (LDO12) undervoltage, then the WM8326 enters the BACKUP state.	No
	PVDD undervoltage (1)	PVDD is less than the user-selectable threshold SYSLO_THR and SYSLO_ERR_ACT is configured to select OFF in this condition. See Section 24.4.		No
	PVDD undervoltage (2)	PVDD is less than the SHUTDOWN voltage. See Section 24.4.		No
	Software OFF request	OFF has been commanded by writing CHIP_ON = 0. See Section 11.3		No
	VPMIC (LDO12) undervoltage	The WM8326 supply voltage is less than the System Reset threshold. See Section 24.4.		No
Device Reset	Watchdog timeout	Watchdog timer has expired and the selected response is to generate a Device Reset. See Section 25.	Assert RESET pin. Shutdown and restart the WM8326. Reset Register map (Note the RTC and software scratch registers are not reset.)	Yes
	Hardware Reset	The RESET pin has been pulled low by an external source. See Section 24.2.		Yes
	Converter (LDO or DC-DC) Undervoltage	An undervoltage condition has been detected and the selected response is "Shut down system (Device Reset)" See Section 15.		Yes
Software Reset	Software Reset	Software Reset has been commanded by writing to Register 0000h. See Section 12.5.	Assert RESET pin. Shutdown and restart the WM8326. See Section 24.3 for configurable options regarding the Register Map contents.	Yes
Power On Reset	Power On Reset	The WM8326 supply voltage is less than the Power-On Reset (POR) threshold. See Section 24.4.	The WM8326 is in the NO POWER state. All register contents are lost.	No

Table 76 Resets Summary

In the cases where Automatic Recovery is supported (as noted in Table 76), the WM8326 will re-start the WM8326 following the Reset, and return the device to the ON state. The particular Reset condition which caused the return to the ON state will be indicated in the "ON Source" register - see Section 11.3.

Note that, if a Watchdog timeout or Converter undervoltage fault persists, a maximum of 6 Device Resets will be attempted to initiate the start-up sequence. Similarly, a maximum of 6 Software Resets is permitted. If these limits are exceeded, the WM8326 will remain in the OFF state until the next valid ON state transition event occurs.

The WM8326 asserts the **RESET** low as soon as the device begins the shutdown sequence. **RESET** is held low for the duration of the shutdown sequence and is held low in the OFF state. In the cases where Automatic Recovery is supported, **RESET** is automatically cleared (high) after successful completion of the startup sequence. The duration of the **RESET** low period after the startup sequence has completed is governed by the RST_DUR register field described in Section 11.7.

24.2 HARDWARE RESET

A Hardware Reset is triggered when an external source pulls the $\overline{\text{RESET}}$ pin low. Under this condition, the WM8326 transitions to the OFF state. The contents of the Register map are cleared to default values, except for the RTC and software scratch registers, which are maintained. The WM8326 will then automatically schedule an ON state transition to resume normal operation.

If the external source continues to pull the $\overline{\text{RESET}}$ pin low, then the WM8326 cannot fully complete the ON state transition following the Hardware Reset. In this case, the WM8326 will mask the external reset for up to 32 seconds. If the $\overline{\text{RESET}}$ pin is released (ie. it returns to logic '1') during this time, then the ON state transition is completed and the Hardware Reset input is valid again from this point. If the $\overline{\text{RESET}}$ pin is not released, then the WM8326 will force an OFF condition on expiry of the 32 seconds timeout. Recovery from this forced OFF condition cannot occur until the external reset condition is de-asserted, followed by a valid ON event. If an ON event occurs before the external reset is de-asserted, then start-up will be attempted, but the transition will be unsuccessful, causing a return to the OFF state.

It is possible to mask the $\overline{\text{RESET}}$ pin input in the SLEEP state by setting the RST_SLP_MSK register bit as described in Section 11.7.

24.3 SOFTWARE RESET

A Software Reset is triggered by writing to Register 0000h, as described in Section 12.5. In this event, the WM8326 asserts the $\overline{\text{RESET}}$ pin and transitions to the OFF state. If the Reset occurred in the ON state, then the WM8326 will automatically return to the ON state following the Reset.

The SWRST_DLY register field determines whether a time delay is applied between the Software Reset command and the resultant shutdown and start-up sequences. When the SWRST_DLY bit is set, the programmable time delay PWRSTATE_DLY is applied before commencing the shutdown sequence.

The timing of the Software Reset is illustrated in Figure 25. See Section 11.3 for a definition of the PWRSTATE_DLY register.

The SW_RESET_CFG register field determines if the Register Map is reset under a Software Reset condition.

Note that the SW_RESET_CFG control register is locked by the WM8326 User Key. This register can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16387 (4003h) Power State	9	SWRST_DLY	0	Software Reset Delay 0 = No delay 1 = Software Reset is delayed by PWRSTATE_DLY following the Software Reset command
R16390 (4006h) Reset Control	10	SW_RESET_CFG	1	Software Reset Configuration. Selects whether the register map is reset to default values when Software Reset occurs. 0 = All registers except RTC and Software Scratch registers are reset by Software Reset 1 = Register Map is not affected by Software Reset <i>Protected by user key</i>

Table 77 Software Reset Configuration

The timing details of the Software Reset are illustrated in Figure 25.

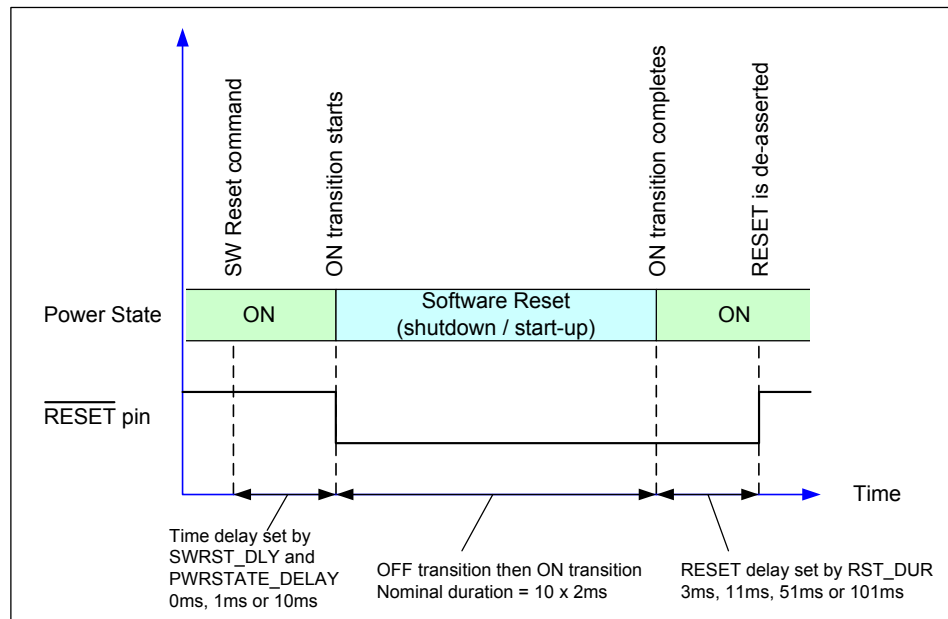


Figure 25 Software Reset Timing

24.4 SUPPLY VOLTAGE MONITORING

The WM8326 includes a number of mechanisms to prevent the system from starting up, or to force it to shut down, when the power sources are critically low.

The internal regulator LDO12 is powered from an internal domain equivalent to PVDD and generates an internal supply (VPMIC) to support various “always-on” functions. In the absence of the PVDD supply, LDO12 can be powered from a backup battery. (Note that PVDD is not maintained by the backup battery.) The VPMIC monitoring function controls the Power-On Reset circuit, which sets the threshold below which the WM8326 cannot operate.

The operation of the VPMIC monitoring circuit is illustrated in Figure 26. The internal signal $\overline{\text{PORRST}}$ is governed by the V_{POR} thresholds. These determine when the WM8326 is kept in the NO POWER state. The internal signal $\overline{\text{PMICRST}}$ is governed by the V_{RES} thresholds. These determine when the WM8326 is kept in the BACKUP state.

The VPMIC monitoring thresholds illustrated in Figure 26 are fixed. The voltage levels are defined in the Electrical Characteristics - see Section 7.3.

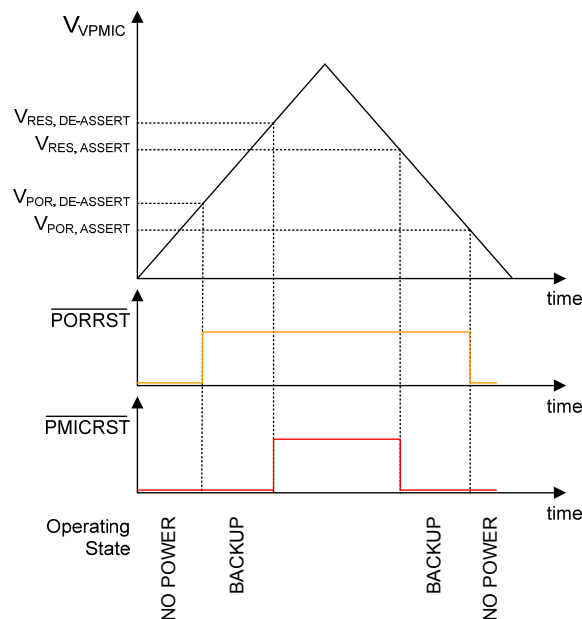


Figure 26 VPMIC Monitoring

The operation of the PVDD monitoring circuit is illustrated in Figure 27. The V_{SHUTDOWN} threshold is the voltage below which the WM8326 forces an OFF transition. This threshold voltage is fixed and is defined in the Electrical Characteristics - see Section 7.3.

The V_{SYSOK} threshold is the level at which the internal signal SYSOK is asserted. Any ON request will be inhibited if SYSOK is not set. The V_{SYSOK} threshold can be set using the SYSOK_THR register field in accordance with the minimum voltage requirements of the application. Note that a hysteresis margin is added to the SYSOK_THR setting; see Section 7.3 for details.

The V_{SYSLO} threshold is the level at which the internal signal SYSLO is asserted. This indicates a PVDD undervoltage condition, at which a selectable response can be initiated. The V_{SYSLO} threshold can be set using the SYSLO_THR register field. The action taken under this undervoltage condition is selected using the SYSLO_ERR_ACT register field, as defined in Table 78. An Interrupt event is associated with the SYSLO condition - see Section 17.2.

The SYSLO status can be read from the SYSLO_STS register bit. This bit is asserted when PVDD is below the SYSLO threshold.

The WM8326 can also indicate the status of the SYSOK signal via a GPIO pin configured as a “PVDD Good” output (see Section 21). A GPIO pin configured as “PVDD Good” output will be asserted when the PVDD is above the SYSOK threshold.

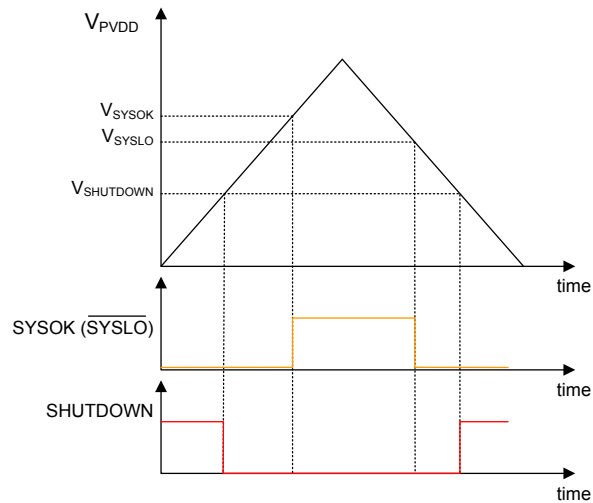


Figure 27 PVDD Monitoring

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16385 (4001h) PVDD Control	15:14	SYSLO_ERR_ ACT	00	SYSLO Error Action Selects the action taken when SYSLO is asserted 00 = Interrupt 01 = WAKE transition 10 = Reserved 11 = OFF transition
	11	SYSLO_STS	0	SYSLO Status 0 = Normal 1 = PVDD is below SYSLO threshold
	6:4	SYSLO_THR [2:0]	010	SYSLO threshold (falling PVDD) This is the falling PVDD voltage at which SYSLO will be asserted 000 = 2.8V 001 = 2.9V ... 111 = 3.5V
	2:0	SYSOK_THR [2:0]	101	SYSOK threshold (rising PVDD) This is the rising PVDD voltage at which SYSOK will be asserted 000 = 2.8V 001 = 2.9V ... 111 = 3.5V Note that the SYSOK hysteresis margin is added to these threshold levels.

Table 78 PVDD Monitoring Control

25 WATCHDOG TIMER

The WM8326 includes a Watchdog Timer designed to detect a possible software fault condition where the host processor has locked up. The Watchdog Timer is a free-running counter driven by the internal RC oscillator.

The Watchdog Timer is enabled by default; it can be enabled or disabled by writing to the WDOG_ENA register bit. The Watchdog behaviour in SLEEP is configurable; it can either be set to continue as normal or to be disabled. The Watchdog behaviour in SLEEP is determined by the WDOG_SLPENA bit.

The watchdog timer duration is set using WDOG_TO. The watchdog timer can be halted for debug purposes using the WDOG_DEBUG bit.

The Watchdog reset source is selectable between Software and Hardware triggers. (Note that the de-selected reset source has no effect.) If the Watchdog is not reset within a programmable timeout period, this is interpreted by the WM8326 as a fault condition. The Watchdog Timer then either triggers a Device Reset, or issues a WAKE request or raises an Interrupt. This primary action is determined by the WDOG_PRIMACT register field.

If the Watchdog is not reset within a further timeout period of the Watchdog counter, a secondary action is triggered. The secondary action taken at this point is determined by the WDOG_SECACT register field.

The Watchdog reset source is selected using the WDOG_RST_SRC register bit. When Software WDOG reset source is selected, the Watchdog is reset by writing a '1' to the WDOG_RESET field. When Hardware WDOG reset source is selected, the Watchdog is reset by toggling a GPIO pin that has been configured as a Watchdog Reset Input (see Section 21).

If a Device Reset is triggered by the watchdog timeout, the WM8326 asserts the $\overline{\text{RESET}}$ pin, resets the internal control registers (excluding the RTC) and initiates a start-up sequence. Note that, following a Device Reset, the action taken on subsequent timeout of the Watchdog Timer will be determined by the WDOG_PRIMACT register. If the watchdog timeout fault persists, then a maximum of 6 Device Reset attempts will be made. See Section 24. If the watchdog timeout occurs more than 6 times, the WM8326 will remain in the OFF state until the next valid ON state transition event occurs.

Note that the Watchdog control registers are locked by the WM8326 User Key. These registers can only be changed by writing the appropriate code to the Security register, as described in Section 12.4.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16388 (4004h) Watchdog	15	WDOG_ENA	1	Watchdog Timer Enable 0 = Disabled 1 = Enabled (enables the watchdog; does not reset it) <i>Protected by user key</i>
	14	WDOG_DEBUG	0	Watchdog Pause 0 = Disabled 1 = Enabled (halts the Watchdog timer for system debugging) <i>Protected by user key</i>
	13	WDOG_RST_SRC	1	Watchdog Reset Source 0 = Hardware only 1 = Software only <i>Protected by user key</i>
	12	WDOG_SLPENA	0	Watchdog SLEEP Enable 0 = Disabled 1 = Controlled by WDOG_ENA <i>Protected by user key</i>
	11	WDOG_RESET	0	Watchdog Software Reset 0 = Normal 1 = Watchdog Reset (resets the watchdog, if WDOG_RST_SRC = 1) <i>Protected by user key</i>

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	9:8	WDOG_SECACT	10	Secondary action of Watchdog timeout (taken after 2 timeout periods) 00 = No action 01 = Interrupt 10 = Device Reset 11 = WAKE transition <i>Protected by user key</i>
	5:4	WDOG_PRIMARYCT	01	Primary action of Watchdog timeout 00 = No action 01 = Interrupt 10 = Device Reset 11 = WAKE transition <i>Protected by user key</i>
	2:0	WDOG_TO [2:0]	111	Watchdog timeout period 000 = 0.256s 001 = 0.512s 010 = 1.024s 011 = 2.048s 100 = 4.096s 101 = 8.192s 110 = 16.384s 111 = 32.768s <i>Protected by user key</i>

Table 79 Controlling the Watchdog Timer

The Watchdog timeout interrupt event is indicated by the WDOG_TO_EINT register field. This secondary interrupt triggers a primary Watchdog Interrupt, WDOG_INT (see Section 23). This can be masked by setting the mask bit as described in Table 80.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	11	WDOG_TO_EINT	Watchdog timeout interrupt. (Rising Edge triggered) Note: Cleared when a '1' is written.
R16409 (4019h) Interrupt Status 1 Mask	11	IM_WDOG_TO_EINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 80 Watchdog Timer Interrupts

26 TEMPERATURE SENSING

The WM8326 provides temperature monitoring as status information and also for self-protection of the device. Temperature monitoring is always enabled in the ON and SLEEP states.

The thermal warning temperature can be set using the THW_TEMP register field. The thermal warning hysteresis ensures that the THW_TEMP is not reset until the device temperature has dropped below the threshold by a suitable margin. The extent of the hysteresis can be selected using the THW_HYST register field.

The Thermal Warning condition can be read using the THW_STS register bit. An overtemperature condition causes the thermal warning interrupt (TEMP_THW_CINT) to be set. The thermal warning interrupt is also set when the overtemperature condition clears, ie. when the device has returned to its normal operating limits.

The thermal shutdown temperature is set at a fixed level. If a thermal shutdown condition is detected whilst in the ON or SLEEP states, then a System Reset is triggered, as described in Section 24.1, forcing a transition to the OFF state.

The temperature sensing circuit is configured and monitored using the register fields described in Table 81.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16386 (4002h)	3	THW_HYST	1	Thermal Warning hysteresis 0 = 8 degrees C 1 = 16 degrees C
	1:0	THW_TEMP [1:0]	10	Thermal Warning temperature 00 = 90 degrees C 01 = 100 degrees C 10 = 110 degrees C 11 = 120 degrees C
R16397 (400Dh)	15	THW_STS	0	Thermal Warning status 0 = Normal 1 = Overtemperature Warning (warning temperature is set by THW_TEMP)

Table 81 Temperature Sensing Control

The thermal warning interrupt event is indicated by the TEMP_THW_CINT register field. This secondary interrupt triggers a primary Thermal Interrupt, TEMP_INT (see Section 23). This can be masked by setting the mask bit as described in Table 82.

ADDRESS	BIT	LABEL	DESCRIPTION
R16401 (4011h) Interrupt Status 1	1	TEMP_THW_CINT	Thermal Warning interrupt (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.
R16410 (4019h) Interrupt Status 1 Mask	1	IM_TEMP_THW_CINT	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)

Table 82 Thermal Interrupts

27 VOLTAGE AND CURRENT REFERENCES

27.1 VOLTAGE REFERENCE (VREF)

The main voltage reference generated by the WM8326 is bonded to the VREFC pin. The accuracy of this reference is optimised by factory-set trim registers.

The voltage reference (VREF) requires an external decoupling capacitor; a 100nF X5R capacitor is recommended, as noted in Section 30.2. Omitting this capacitor will result in increased noise on the voltage reference; this will particularly affect the analogue LDOs.

The voltage reference circuit includes a low-power mode, which enables power consumption to be minimised where appropriate. The low-power reference mode may lead to increased noise on the voltage reference; this mode should only be selected when minimum power consumption is more important than voltage stability. Note that the Low Power Reference mode is not supported when the Auxiliary ADC function is enabled.

The Low Power Reference mode is enabled when REF_LP register is set. The Low Power Reference mode should only be enabled when the Auxiliary ADC is disabled. Enabling the Low Power Reference mode will lead to a malfunction of the Auxiliary ADC function.

ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16387 (4003h)	12	REF_LP	0	Low Power Voltage Reference Control 0 = Normal 1 = Low Power Reference Mode select Note that Low Power Reference Mode is only supported when the Auxiliary ADC is disabled.

Table 83 Low Power Voltage Reference Control

27.2 CURRENT REFERENCE (IREF)

The Power Management circuits of the WM8326 use an integrated current reference.

This current reference (IREF) requires the connection of an external resistor to the IREFR pin; a 100k Ω (1%) resistor is recommended, as noted in Section 30.2. The WM8326 will malfunction if this resistor is omitted.

28 REGISTER MAP OVERVIEW

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
0	0000	Reset ID																	0000_0000_0000_0000
1	0001	Revision																	0000_0000_0000_0000
2	0002	Reserved																	0000_0000_0000_0000
3	0003	Reserved																	0000_0000_0000_0000
4	0004	Reserved																	0000_0000_0000_0000
5	0005	Reserved																	0000_0000_0000_0000
6	0006	Reserved																	0000_0000_0000_0000
7	0007	Reserved																	0000_0000_0000_0000
16384	4000	Parent ID																	0110_0010_0100_0110
16385	4001	PVDD Control																	0000_0000_0010_0101
16386	4002	Thermal Monitoring																	0000_0000_0000_1010
16387	4003	Power State																	0000_1000_0000_0000
16388	4004	Watchdog																	1010_P010_0001_0111
16389	4005	ON Pin Control																	0000_0001_0000_0000
16390	4006	Reset Control																	1000_0100_0111_0011
16391	4007	Control Interface																	0000_0000_0000_0100
16392	4008	Security Key																	0000_0000_0000_0000
16393	4009	Software Scratch																	0000_0000_0000_0000
16394	400A	OTP Control																	0010_0000_0000_0000
16395	400B	Security Key 2																	0000_0000_0000_0000
16396	400C	GPIO Level																	0000_0000_0000_0000
16397	400D	System Status																	0000_0000_0000_0000
16398	400E	ON Source																	0000_0000_0000_0000
16399	400F	OFF Source																	0000_0000_0000_0000
16400	4010	System Interrupts																	PPPP_PP0P_PP0P_PP0P
16401	4011	Interrupt Status 1																	PP0P_PP0P_PP0P_PP0P
16402	4012	Interrupt Status 2																	0000_0000_00P0_0PPP
16403	4013	Interrupt Status 3																	0000_00P0_PPPP_PPPP
16404	4014	Interrupt Status 4																	0000_00P0_PP00_PPPP
16405	4015	Interrupt Status 5																	0000_PPPP_PPPP_PPPP
16406	4016	Reserved																	0000_0000_0000_0000
16407	4017	IRQ Config																	0000_0000_0000_0010

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
16408	4018	System Interrupts Mask	IM_PS_INT	IM_TEMP_INT	IM_GP_INT	IM_ON_PRL_INT	IM_WDOG_INT	0	0	IM_AUXAD_C_INT	IM_PRL_INT	0	IM_RTC_INT	IM_OTP_INT	1	0	IM_HC_INT	IM_UV_INT	1111_1001_1011_1011
16409	4019	Interrupt Status 1 Mask	IM_PRL_SY_SLO_INT	0	0	IM_ON_PRL_CNT	IM_WDOG_T0_INT	0	0	IM_AUXAD_C_DATA_EI	IM_AUXAD_C_DCOMP4_INT	IM_AUXAD_C_DCOMP3_INT	IM_RTC_FEL_INT	IM_OTP_ERR_INT	0	IM_RTC_FEL_INT	IM_TEMP_T	0	1001_1001_1111_1110
16410	401A	Interrupt Status 2 Mask	0	0	0	0	0	0	0	0	0	0	IM_OTP_CM_D_END_INT	IM_OTP_ERR_INT	0	IM_PS_FOR_INT	IM_PS_SLE	IM_PS_ON	0000_0000_0011_0111
16411	401B	Interrupt Status 3 Mask	0	0	0	0	0	0	IM_UV_LDO_10_INT	IM_UV_LDO_9_INT	IM_UV_LDO_8_INT	IM_UV_LDO_7_INT	IM_UV_LDO_6_INT	IM_UV_LDO_5_INT	IM_UV_LDO_4_INT	IM_UV_LDO_3_INT	IM_UV_LDO_2_INT	IM_UV_LDO_1_INT	0000_0011_1111_1111
16412	401C	Interrupt Status 4 Mask	0	0	0	0	0	0	IM_HC_DC2_INT	IM_HC_DC1_TART_INT	IM_XTAL_S_INT	0	0	0	IM_UV_DC3_INT	IM_UV_DC2_INT	IM_UV_DC1_INT	0000_0011_1000_1111	
16413	401D	Interrupt Status 5 Mask	0	0	0	0	IM_GP2_B	IM_GP1_TNT	IM_GP0_B	IM_GP3_B	IM_GP8_B	IM_GP7_TNT	IM_GP6_TNT	IM_GP5_B	IM_GP4_B	IM_GP3_B	IM_GP2_B	IM_GP1_TNT	0000_1111_1111_1111
16414	401E	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16415	401F	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16416	4020	RTC Write Counter	RTC_WR_CNT[15:0]																0000_0000_0000_0000
16417	4021	RTC Time 1	RTC_TIME[31:16]																0000_0000_0000_0000
16418	4022	RTC Time 2	RTC_TIME[15:0]																0000_0000_0000_0000
16419	4023	RTC Alarm 1	RTC_ALM[31:16]																0000_0000_0000_0000
16420	4024	RTC Alarm 2	RTC_ALM[15:0]																0000_0000_0000_0000
16421	4025	RTC Control	RTC_VALID	RTC_SYNC_BUSY	0	0	0	RTC_ALM_BNA	0	0	0	RTC_INT_FREQ[2:0]		RTC_TRIM[9:0]		0	0	0	0000_0000_0000_0000
16422	4026	RTC Trim	0	0	0	0	0	0	RTC_TRIM[9:0]										0000_0000_0000_0000
16423	4027	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16424	4028	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16425	4029	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16426	402A	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16427	402B	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16428	402C	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16429	402D	AuxADC Data	AUX_DATA[11:0]																0000_0000_0000_0000
16430	402E	AuxADC Control	AUX_ENA	AUX_OVT_BNA	0	AUX_SURENA	0	0	0	0	0	AUX_DATA[11:0]		AUX_RATES[0]		AUX_GRO[12:SEL]		AUX_GRO[0:SEL]	0000_0000_0000_0000
16431	402F	AuxADC Source	0	0	0	0	0	0	0	0	0	AUX_PVDD_SEL	0	AUX_CHIP_TEMP_SEL	0	DCOMP3_EN	DCOMP2_EN	DCOMP1_EN	0000_0000_0000_0000
16432	4030	Comparator Control	0	0	0	0	DCOMP4_STS	DCOMP3_STS	DCOMP2_STS	DCOMP1_STS	0	0	0	0	0	A	A	A	0000_0000_0000_0000
16433	4031	Comparator 1	DCOMP1_SRC[2:0]		DCOMP1_GT		DCOMP1_THR[11:0]		DCOMP1_THR[11:0]		DCOMP1_THR[11:0]		DCOMP1_THR[11:0]		DCOMP1_THR[11:0]		DCOMP1_THR[11:0]		0000_0000_0000_0000
16434	4032	Comparator 2	DCOMP2_SRC[2:0]		DCOMP2_GT		DCOMP2_THR[11:0]		DCOMP2_THR[11:0]		DCOMP2_THR[11:0]		DCOMP2_THR[11:0]		DCOMP2_THR[11:0]		DCOMP2_THR[11:0]		0000_0000_0000_0000
16435	4033	Comparator 3	DCOMP3_SRC[2:0]		DCOMP3_GT		DCOMP3_THR[11:0]		DCOMP3_THR[11:0]		DCOMP3_THR[11:0]		DCOMP3_THR[11:0]		DCOMP3_THR[11:0]		DCOMP3_THR[11:0]		0000_0000_0000_0000
16436	4034	Comparator 4	DCOMP4_SRC[2:0]		DCOMP4_GT		DCOMP4_THR[11:0]		DCOMP4_THR[11:0]		DCOMP4_THR[11:0]		DCOMP4_THR[11:0]		DCOMP4_THR[11:0]		DCOMP4_THR[11:0]		0000_0000_0000_0000
16437	4035	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16438	4036	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16439	4037	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
16440	4038	GPIO1 Control	GPIO1_DIR	GPIO1_PULL[1:0]	GPIO1_INT_M_ODE	GPIO1_PWR_DOM	GPIO1_POL	GPIO1_OD	0	GPIO1_ENA	0	0	0	0	GPIO1_FN[3:0]			0	1010_0100_0000_0000
16441	4039	GPIO2 Control	GPIO2_DIR	GPIO2_PULL[1:0]	GPIO2_INT_M_ODE	GPIO2_PWR_DOM	GPIO2_POL	GPIO2_OD	0	GPIO2_ENA	0	0	0	0	GPIO2_FN[3:0]			0	1010_0100_0000_0000
16442	403A	GPIO3 Control	GPIO3_DIR	GPIO3_PULL[1:0]	GPIO3_INT_M_ODE	GPIO3_PWR_DOM	GPIO3_POL	GPIO3_OD	0	GPIO3_ENA	0	0	0	0	GPIO3_FN[3:0]			0	1010_0100_0000_0000
16443	403B	GPIO4 Control	GPIO4_DIR	GPIO4_PULL[1:0]	GPIO4_INT_M_ODE	GPIO4_PWR_DOM	GPIO4_POL	GPIO4_OD	0	GPIO4_ENA	0	0	0	0	GPIO4_FN[3:0]			0	1010_0100_0000_0000
16444	403C	GPIO5 Control	GPIO5_DIR	GPIO5_PULL[1:0]	GPIO5_INT_M_ODE	GPIO5_PWR_DOM	GPIO5_POL	GPIO5_OD	0	GPIO5_ENA	0	0	0	0	GPIO5_FN[3:0]			0	1010_0100_0000_0000
16445	403D	GPIO6 Control	GPIO6_DIR	GPIO6_PULL[1:0]	GPIO6_INT_M_ODE	GPIO6_PWR_DOM	GPIO6_POL	GPIO6_OD	0	GPIO6_ENA	0	0	0	0	GPIO6_FN[3:0]			0	1010_0100_0000_0000
16446	403E	GPIO7 Control	GPIO7_DIR	GPIO7_PULL[1:0]	GPIO7_INT_M_ODE	GPIO7_PWR_DOM	GPIO7_POL	GPIO7_OD	0	GPIO7_ENA	0	0	0	0	GPIO7_FN[3:0]			0	1010_0100_0000_0000
16447	403F	GPIO8 Control	GPIO8_DIR	GPIO8_PULL[1:0]	GPIO8_INT_M_ODE	GPIO8_PWR_DOM	GPIO8_POL	GPIO8_OD	0	GPIO8_ENA	0	0	0	0	GPIO8_FN[3:0]			0	1010_0100_0000_0000
16448	4040	GPIO9 Control	GPIO9_DIR	GPIO9_PULL[1:0]	GPIO9_INT_M_ODE	GPIO9_PWR_DOM	GPIO9_POL	GPIO9_OD	0	GPIO9_ENA	0	0	0	0	GPIO9_FN[3:0]			0	1010_0100_0000_0000
16449	4041	GPIO10 Control	GPIO10_DIR	GPIO10_PULL[1:0]	GPIO10_INT_MODE	GPIO10_PWR_DOM	GPIO10_POL	GPIO10_OD	0	GPIO10_ENA	0	0	0	0	GPIO10_FN[3:0]			0	1010_0100_0000_0000
16450	4042	GPIO11 Control	GPIO11_DIR	GPIO11_PULL[1:0]	GPIO11_INT_MODE	GPIO11_PWR_DOM	GPIO11_POL	GPIO11_OD	0	GPIO11_ENA	0	0	0	0	GPIO11_FN[3:0]			0	1010_0100_0000_0000
16451	4043	GPIO12 Control	GPIO12_DIR	GPIO12_PULL[1:0]	GPIO12_INT_MODE	GPIO12_PWR_DOM	GPIO12_POL	GPIO12_OD	0	GPIO12_ENA	0	0	0	0	GPIO12_FN[3:0]			0	1010_0100_0000_0000
16452	4044	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16453	4045	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16454	4046	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16455	4047	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16456	4048	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0001
16457	4049	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0110_0000_0010
16458	404A	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16459	404B	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16460	404C	Status LED 1	LED1_SRQ[1:0]	0	0	0	0	0	LED1_MODE[1:0]	0	0	LED1_SEQ_LEN[1:0]	LED1_DUR[1:0]	LED1_DUTY_CYC[1:0]					1100_0000_0010_0110
16461	404D	Status LED 2	LED2_SRQ[1:0]	0	0	0	0	0	LED2_MODE[1:0]	0	0	LED2_SEQ_LEN[1:0]	LED2_DUR[1:0]	LED2_DUTY_CYC[1:0]					1100_0000_0010_0110
16462	404E	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16463	404F	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16464	4050	DDCC Enable	0	0	0	0	0	0	0	0	EF2_ENA	EF2_ENA	0	0	DC4_ENA	DC3_ENA	DC2_ENA	DC1_ENA	0000_0000_UUUU_UUUU
16465	4051	LDO Enable	0	0	0	0	0	0	LD010_ENA	LD09_ENA	LD08_ENA	LD07_ENA	LD06_ENA	LD05_ENA	LD04_ENA	LD03_ENA	LD02_ENA	LD01_ENA	0000_0000_UUUU_UUUU
16466	4052	DDCC Status	0	0	0	0	0	0	0	0	EF2_STS	EF2_STS	0	0	DC4_STS	DC3_STS	DC2_STS	DC1_STS	0000_0000_0000_0000
16467	4053	LDO Status	0	0	0	0	0	LD011_STS	LD010_STS	LD09_STS	LD08_STS	LD07_STS	LD06_STS	LD05_STS	LD04_STS	LD03_STS	LD02_STS	LD01_STS	0000_0000_0000_0000
16468	4054	DDCC UV Status	0	0	DC2_OV_S	DC1_OV_S	0	0	DC2_HC_STS	DC1_HC_STS	0	0	0	0	DC4_UV_S	DC3_UV_S	DC2_UV_S	DC1_UV_S	0000_0000_0000_0000
16469	4055	LDO UV Status	INTLDO_UV_STS	0	0	0	0	0	LD010_UV_STS	LD09_UV_STS	LD08_UV_STS	LD07_UV_STS	LD06_UV_STS	LD05_UV_STS	LD04_UV_STS	LD03_UV_STS	LD02_UV_STS	LD01_UV_STS	0000_0000_0000_0000
16470	4056	DC1 Control 1	DC1_RATE[1:0]	0	0	DC1_FHAS	0	0	DC1_FREQ[1:0]	0	DC1_FLT	0	0	DC1_SOFT_START[1:0]	0	0	DC1_CAP[1:0]	0	1000_0000_0000_0000
16471	4057	DC1 Control 2	DC1_ERR_ACT[1:0]	0	0	DC1_HWC_SEL	DC1_HWC_SRQ[1:0]	DC1_HWC_V	DC1_HWC_MODE[1:0]	0	0	DC1_HC_THR[2:0]	0	0	0	0	DC1_FAST_DRV	DC1_HC_IN_D_ENA	0000_0011_0000_0000

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
16472	4058	DC1 ON Config	DC1_ON_SLOT[2:0]			0	0	0	DC1_ON_MODE[1:0]		0				DC1_ON_VSEL[6:2]		DC1_ON_VSEL[1:0]		0000_0001_0000_0000
16473	4059	DC1 SLEEP Control	DC1_SLP_SLOT[2:0]			0	0	0	DC1_SLP_MODE[1:0]		0				DC1_SLP_VSEL[6:0]				0000_0011_0000_0000
16474	405A	DC1 DVS Control	0	0	0	DC1_DVS_SRC[1:0]		0	0	0	0				DC1_DVS_VSEL[6:0]				0000_0000_0000_0000
16475	405B	DC2 Control 1	DC2_RATE[1:0]	0	0	DC2_PHASE	0	0	DC2_FREQ[1:0]		DC2_FLT	0		DC2_SOFT_START[1:0]	0	0	DC2_CAP[1:0]		1001_0000_0000_0000
16476	405C	DC2 Control 2	DC2_ERR_ACT[1:0]	0	0	DC2_HWC_SRC[1:0]		DC2_HWC_VSEL	DC2_HWC_MODE[1:0]		0		DC2_HC_THR[2:0]		0	0	DC2_FAST_DRV	DC2_HC_IN_D_BNA	0000_0011_0000_0000
16477	405D	DC2 ON Config	DC2_ON_SLOT[2:0]			0	0	0	DC2_ON_MODE[1:0]		0				DC2_ON_VSEL[6:2]		DC2_ON_VSEL[1:0]		0000_0001_0000_0000
16478	405E	DC2 SLEEP Control	DC2_SLP_SLOT[2:0]			0	0	0	DC2_SLP_MODE[1:0]		0				DC2_SLP_VSEL[6:0]				0000_0011_0000_0000
16479	405F	DC2 DVS Control	0	0	0	DC2_DVS_SRC[1:0]		0	0	0	0			DC3_SOFT_START[1:0]	DC3_STNBY_LIM[1:0]		DC3_CAP[1:0]		0000_0000_0000_0000
16480	4060	DC3 Control 1	0	0	0	DC3_PHASE	0	0	0	0	DC3_FLT	0	0	0	0	0	0	0	0000_0000_0001_0100
16481	4061	DC3 Control 2	DC3_ERR_ACT[1:0]	0	0	DC3_HWC_SRC[1:0]		DC3_HWC_VSEL	DC3_HWC_MODE[1:0]		DC3_OVP	0	0	0	0	0	0	0	0000_0011_0000_0000
16482	4062	DC3 ON Config	DC3_ON_SLOT[2:0]			0	0	0	DC3_ON_MODE[1:0]		0				DC3_ON_VSEL[6:2]		DC3_ON_VSEL[1:0]		0000_0001_0000_0000
16483	4063	DC3 SLEEP Control	DC3_SLP_SLOT[2:0]			0	0	0	DC3_SLP_MODE[1:0]		0				DC3_SLP_VSEL[6:0]				0000_0011_0000_0000
16484	4064	DC4 Control 1	0	0	DC4_SLV	DC4_PHASE	0	0	0	0	DC4_FLT	0		DC4_SOFT_START[1:0]	DC4_STNBY_LIM[1:0]		DC4_CAP[1:0]		0000_0000_0001_0100
16485	4065	DC4 Control 2	DC4_ERR_ACT[1:0]	0	0	DC4_HWC_SRC[1:0]		DC4_HWC_VSEL	DC4_HWC_MODE[1:0]		DC4_OVP	0	0	0	0	0	0	0	0000_0011_0000_0000
16486	4066	DC4 ON Config	DC4_ON_SLOT[2:0]			0	0	0	DC4_ON_MODE[1:0]		0				DC4_ON_VSEL[6:2]		DC4_ON_VSEL[1:0]		0000_0001_0000_0000
16487	4067	DC4 SLEEP Control	DC4_SLP_SLOT[2:0]			0	0	0	DC4_SLP_MODE[1:0]		0				DC4_SLP_VSEL[6:0]				0000_0011_0000_0000
16488	4068	LD01 Control	LD01_ERR_ACT[1:0]	0	0	LD01_HWC_SRC[1:0]		LD01_HWC_VSEL	LD01_HWC_MODE[1:0]		LD01_FLT	LD01_SWI	0	0	0	0	0	LD01_LP_M_ODE	0000_0010_0000_0000
16489	4069	LD01 ON Control	LD01_ON_SLOT[2:0]			0	0	0	LD01_ON_MODE		0	0	0	0	LD01_ON_VSEL[4:0]				0000_0000_0000_0000
16490	406A	LD01 SLEEP Control	LD01_SLP_SLOT[2:0]			0	0	0	LD01_SLP_MODE		0	0	0	0	LD01_SLP_VSEL[4:0]				0000_0001_0000_0000
16491	406B	LD02 Control	LD02_ERR_ACT[1:0]	0	0	LD02_HWC_SRC[1:0]		LD02_HWC_VSEL	LD02_HWC_MODE[1:0]		LD02_FLT	LD02_SWI	0	0	0	0	0	LD02_LP_M_ODE	0000_0010_0000_0000
16492	406C	LD02 ON Control	LD02_ON_SLOT[2:0]			0	0	0	LD02_ON_MODE		0	0	0	0	LD02_ON_VSEL[4:0]				0000_0000_0000_0000
16493	406D	LD02 SLEEP Control	LD02_SLP_SLOT[2:0]			0	0	0	LD02_SLP_MODE		0	0	0	0	LD02_SLP_VSEL[4:0]				0000_0001_0000_0000
16494	406E	LD03 Control	LD03_ERR_ACT[1:0]	0	0	LD03_HWC_SRC[1:0]		LD03_HWC_VSEL	LD03_HWC_MODE[1:0]		LD03_FLT	LD03_SWI	0	0	0	0	0	LD03_LP_M_ODE	0000_0010_0000_0000
16495	406F	LD03 ON Control	LD03_ON_SLOT[2:0]			0	0	0	LD03_ON_MODE		0	0	0	0	LD03_ON_VSEL[4:0]				0000_0000_0000_0000
16496	4070	LD03 SLEEP Control	LD03_SLP_SLOT[2:0]			0	0	0	LD03_SLP_MODE		0	0	0	0	LD03_SLP_VSEL[4:0]				0000_0001_0000_0000
16497	4071	LD04 Control	LD04_ERR_ACT[1:0]	0	0	LD04_HWC_SRC[1:0]		LD04_HWC_VSEL	LD04_HWC_MODE[1:0]		LD04_FLT	LD04_SWI	0	0	0	0	0	LD04_LP_M_ODE	0000_0010_0000_0000
16498	4072	LD04 ON Control	LD04_ON_SLOT[2:0]			0	0	0	LD04_ON_MODE		0	0	0	0	LD04_ON_VSEL[4:0]				0000_0000_0000_0000
16499	4073	LD04 SLEEP Control	LD04_SLP_SLOT[2:0]			0	0	0	LD04_SLP_MODE		0	0	0	0	LD04_SLP_VSEL[4:0]				0000_0001_0000_0000
16500	4074	LD05 Control	LD05_ERR_ACT[1:0]	0	0	LD05_HWC_SRC[1:0]		LD05_HWC_VSEL	LD05_HWC_MODE[1:0]		LD05_FLT	LD05_SWI	0	0	0	0	0	LD05_LP_M_ODE	0000_0010_0000_0000
16501	4075	LD05 ON Control	LD05_ON_SLOT[2:0]			0	0	0	LD05_ON_MODE		0	0	0	0	LD05_ON_VSEL[4:0]				0000_0000_0000_0000
16502	4076	LD05 SLEEP Control	LD05_SLP_SLOT[2:0]			0	0	0	LD05_SLP_MODE		0	0	0	0	LD05_SLP_VSEL[4:0]				0000_0001_0000_0000
16503	4077	LD06 Control	LD06_ERR_ACT[1:0]	0	0	LD06_HWC_SRC[1:0]		LD06_HWC_VSEL	LD06_HWC_MODE[1:0]		LD06_FLT	LD06_SWI	0	0	0	0	0	LD06_LP_M_ODE	0000_0010_0000_0000

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
16504	4078	LD06 ON Control	LD06_ON_SLOT[2:0]			0	0	0	0	LD06_ON_MODE	0	0	0		LD06_ON_VSEL[4:0]			0	0000_0000_0000_0000
16505	4079	LD06 SLEEP Control	LD06_SLP_SLOT[2:0]			0	0	0	0	LD06_SLP_MODE	0	0	0		LD06_SLP_VSEL[4:0]			0	0000_0001_0000_0000
16506	407A	LD07 Control	LD07_ERR_ACT[1:0]	0		LD07_HWC_SRC[1:0]	LD07_HWC_SLOT[2:0]	LD07_HWC_VSEL	LD07_HWC_MODE[1:0]	LD07_FLT	LD07_SWI	0	0	0	0	0	0	0	0000_0010_0000_0000
16507	407B	LD07 ON Control	LD07_ON_SLOT[2:0]			0	0	0	0	LD07_ON_MODE	0	0	0		LD07_ON_VSEL[4:0]			0	0000_0000_0000_0000
16508	407C	LD07 SLEEP Control	LD07_SLP_SLOT[2:0]			0	0	0	0	LD07_SLP_MODE	0	0	0		LD07_SLP_VSEL[4:0]			0	0000_0001_0000_0000
16509	407D	LD08 Control	LD08_ERR_ACT[1:0]	0		LD08_HWC_SRC[1:0]	LD08_HWC_SLOT[2:0]	LD08_HWC_VSEL	LD08_HWC_MODE[1:0]	LD08_FLT	LD08_SWI	0	0	0	0	0	0	0	0000_0010_0000_0000
16510	407E	LD08 ON Control	LD08_ON_SLOT[2:0]			0	0	0	0	LD08_ON_MODE	0	0	0		LD08_ON_VSEL[4:0]			0	0000_0000_0000_0000
16511	407F	LD08 SLEEP Control	LD08_SLP_SLOT[2:0]			0	0	0	0	LD08_SLP_MODE	0	0	0		LD08_SLP_VSEL[4:0]			0	0000_0001_0000_0000
16512	4080	LD09 Control	LD09_ERR_ACT[1:0]	0		LD09_HWC_SRC[1:0]	LD09_HWC_SLOT[2:0]	LD09_HWC_VSEL	LD09_HWC_MODE[1:0]	LD09_FLT	LD09_SWI	0	0	0	0	0	0	0	0000_0010_0000_0000
16513	4081	LD09 ON Control	LD09_ON_SLOT[2:0]			0	0	0	0	LD09_ON_MODE	0	0	0		LD09_ON_VSEL[4:0]			0	0000_0000_0000_0000
16514	4082	LD09 SLEEP Control	LD09_SLP_SLOT[2:0]			0	0	0	0	LD09_SLP_MODE	0	0	0		LD09_SLP_VSEL[4:0]			0	0000_0001_0000_0000
16515	4083	LD010 Control	LD010_ERR_ACT[1:0]	0		LD010_HWC_SRC[1:0]	LD010_HWC_SLOT[2:0]	LD010_HWC_VSEL	LD010_HWC_MODE[1:0]	LD010_FLT	LD010_SWI	0	0	0	0	0	0	0	0000_0010_0000_0000
16516	4084	LD010 ON Control	LD010_ON_SLOT[2:0]			0	0	0	0	LD010_ON_MODE	0	0	0		LD010_ON_VSEL[4:0]			0	0000_0000_0000_0000
16517	4085	LD010 SLEEP Control	LD010_SLP_SLOT[2:0]			0	0	0	0	LD010_SLP_MODE	0	0	0		LD010_SLP_VSEL[4:0]			0	0000_0001_0000_0000
16518	4086	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16519	4087	LD011 ON Control	LD011_ON_SLOT[2:0]			LD011_FRC_ENA	0	0	0	LD011_VSE_L_SRC	0	0	0		LD011_ON_VSEL[3:0]			0	0000_0000_0000_0000
16520	4088	LD011 SLEEP Control	LD011_SLP_SLOT[2:0]			0	0	0	0	0	0	0	0		LD011_SLP_VSEL[3:0]			0	0000_0000_0000_0000
16521	4089	EPE1 Control	EPE1_ON_SLOT[2:0]			EPE1_HWC_SRC[1:0]	0	0	0	EPE1_HWC_ENA	EPE1_SLP_SLOT[2:0]	0	0	0	0	0	0	0	0000_0000_0000_0000
16522	408A	EPE2 Control	EPE2_ON_SLOT[2:0]			EPE2_HWC_SRC[1:0]	0	0	0	EPE2_HWC_ENA	EPE2_SLP_SLOT[2:0]	0	0	0	0	0	0	0	0000_0000_0000_0000
16523	408B	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16524	408C	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16525	408D	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16526	408E	Power Good Source 1	0	0	0	0	0	0	0	0	0	0	0	0	DC4_OK	DC3_OK	DC2_OK	DC1_OK	0000_0000_0000_0111
16527	408F	Power Good Source 2	0	0	0	0	0	0	0	LD09_OK	LD08_OK	LD07_OK	LD06_OK	LD05_OK	LD04_OK	LD03_OK	LD02_OK	LD01_OK	0000_0011_1111_1111
16528	4090	Clock Control 1	CLKOUT_ENA	0	CLKOUT_O_D	0	0	CLKOUT_SLOT[2:0]	0	0	0	CLKOUT_SLP_SLOT[2:0]	0	0	0	0	0	0	0000_0000_0000_0000
16529	4091	Clock Control 2	XTAL_INH	0	XTAL_ENA	XTAL_BKUP_ENA	0	0	0	0	0	0	0	0	0	0	0	0	0001_0000_0000_0000
16530	4092	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16531	4093	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16532	4094	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16533	4095	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16534	4096	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
16535	4097	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
30720	7800	Unique ID1								UNIQUE_ID[127:112]								0	000_0000_0000_0000
30721	7801	Unique ID2								UNIQUE_ID[111:96]									000_0000_0000_0000
30722	7802	Unique ID3								UNIQUE_ID[95:80]									000_0000_0000_0000
30723	7803	Unique ID4								UNIQUE_ID[79:64]									000_0000_0000_0000
30724	7804	Unique ID5								UNIQUE_ID[63:48]									000_0000_0000_0000
30725	7805	Unique ID6								UNIQUE_ID[47:32]									000_0000_0000_0000
30726	7806	Unique ID7								UNIQUE_ID[31:16]									000_0000_0000_0000
30727	7807	Unique ID8								UNIQUE_ID[15:0]									000_0000_0000_0000
30728	7808	Factory OTP ID	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30729	7809	Factory OTP1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30730	780A	Factory OTP 2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30731	780B	Factory OTP 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30732	780C	Factory OTP 4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30733	780D	Factory OTP 5	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30734	780E	Factory OTP 6	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30735	780F	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	000_0000_0000_0000
30736	7810	Customer OTPID	OTP_AUTO_PROG								OTP_CUST_ID[13:0]							OTP_CUST_FINAL	000_0000_0000_0000
30737	7811	DC1 OTP Control		DC2_ON_SLOT[2:0]				DC2_ON_VSEL[6:2]				DC1_ON_SLOT[2:0]			DC1_ON_VSEL[6:2]				000_0000_0000_0000
30738	7812	DC2 OTP Control		DC3_ON_SLOT[2:0]				DC4_ON_VSEL[6:2]				DC3_ON_SLOT[2:0]			DC3_ON_VSEL[6:2]				000_0000_0000_0000
30739	7813	DC3 OTP Control	DC4_PHASE	DC3_PHASE	DC2_PHASE			DC4_CAP1[1:0]				DC2_CAP1[1:0]			DC1_CAP1[1:0]		DC1_FREQ[1:0]		0010_0000_0000_0000
30740	7814	LD01/2 OTP Control		LD02_ON_SLOT[2:0]				LD02_ON_VSEL[4:0]				LD01_ON_SLOT[2:0]			LD01_ON_VSEL[4:0]				000_0000_0000_0000
30741	7815	LD03/4 OTP Control		LD04_ON_SLOT[2:0]				LD04_ON_VSEL[4:0]				LD03_ON_SLOT[2:0]			LD03_ON_VSEL[4:0]				000_0000_0000_0000
30742	7816	LD05/6 OTP Control		LD06_ON_SLOT[2:0]				LD06_ON_VSEL[4:0]				LD05_ON_SLOT[2:0]			LD05_ON_VSEL[4:0]				000_0000_0000_0000
30743	7817	LD07/8 OTP Control		LD08_ON_SLOT[2:0]				LD08_ON_VSEL[4:0]				LD07_ON_SLOT[2:0]			LD07_ON_VSEL[4:0]				000_0000_0000_0000
30744	7818	LD09/10 OTP Control		LD010_ON_SLOT[2:0]				LD010_ON_VSEL[4:0]				LD09_ON_SLOT[2:0]			LD09_ON_VSEL[4:0]				000_0000_0000_0000
30745	7819	LD011/EPE Control		LD011_ON_SLOT[2:0]		0		LD011_ON_VSEL[3:0]				EPEF_ON_SLOT[2:0]			EPEF_ON_SLOT[2:0]	0	DC4_SLV		000_0000_0000_0000
30746	781A	GPIO1 OTP Control	GPIO_DIR	GPIO_PULL[1:0]		GPIO_INT[1:0] ODE		GPIO_POL		GPIO_OD		GPIO_FNR[3:0]			XTAL_BVA	XTAL_INH	0		1010_0100_0000_0000
30747	781B	GPIO2 OTP Control	GPIO2_DIR	GPIO2_PULL[1:0]		GPIO2_INT[1:0] ODE		GPIO2_POL		GPIO2_OD		GPIO2_FNR[3:0]			CLKOUT_SLOT[2:0]		WDOG_ENA		1010_0100_0000_0001
30748	781C	GPIO3 OTP Control	GPIO3_DIR	GPIO3_PULL[1:0]		GPIO3_INT[1:0] ODE		GPIO3_POL		GPIO3_OD		GPIO3_FNR[3:0]			0	0	0	0	1010_0100_0000_0000
30749	781D	GPIO4 OTP Control	GPIO4_DIR	GPIO4_PULL[1:0]		GPIO4_INT[1:0] ODE		GPIO4_POL		GPIO4_OD		GPIO4_FNR[3:0]			LED7_SRCQ[1:0]		LED2_SRCQ[1:0]		1010_0100_0000_1111
30750	781E	GPIO5 OTP Control	GPIO5_DIR	GPIO5_PULL[1:0]		GPIO5_INT[1:0] ODE		GPIO5_POL		GPIO5_OD		GPIO5_FNR[3:0]			0	0	0	0	1010_0100_0000_0000
30751	781F	GPIO6 OTP Control	GPIO6_DIR	GPIO6_PULL[1:0]		GPIO6_INT[1:0] ODE		GPIO6_POL		GPIO6_OD		GPIO6_FNR[3:0]			SYSK_THR[2:0]		0		1010_0100_0000_1010

Dec Addr	Hex Addr	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Bin Default
30752	7820	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30753	7821	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30754	7822	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30755	7823	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30756	7824	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30757	7825	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30758	7826	Reserved	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000_0000_0000_0000
30759	7827	ICE CHECK DATA	ICE_VALID_DATA[15:0]																

29 REGISTER BITS BY ADDRESS

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R0 (00h) Reset ID	15:0	CHIP_ID [15:0]	0000_0000 _0000_000 0	Writing to this register causes a Software Reset. The register map contents may be reset, depending on SW_RESET_CFG. Reading from this register will indicate Chip ID.	

Register 00h Reset ID

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R1 (01h) Revision	15:8	PARENT_REV [7:0]	0000_0000	The revision number of the parent die	
	7:0	CHILD_REV [7:0]	0000_0000	The revision number of the child die (when present)	

Register 01h Revision

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16384 (4000h) Parent ID	15:0	PARENT_ID [15:0]	0110_0010 _0100_011 0	The ID of the parent die	

Register 4000h Parent ID

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16385 (4001h) PVDD Control	15:14	SYSLO_ERR_ACT [1:0]	00	SYSLO Error Action Selects the action taken when SYSLO is asserted 00 = Interrupt 01 = WAKE transition 10 = Reserved 11 = OFF transition	
	11	SYSLO_STS	0	SYSLO Status 0 = Normal 1 = PVDD is below SYSLO threshold	
	6:4	SYSLO_THR [2:0]	010	SYSLO threshold (falling PVDD) This is the falling PVDD voltage at which SYSLO will be asserted 000 = 2.8V 001 = 2.9V ... 111 = 3.5V	
	2:0	SYSOK_THR [2:0]	101	SYSOK threshold (rising PVDD) This is the rising PVDD voltage at which SYSOK will be asserted 000 = 2.8V 001 = 2.9V ... 111 = 3.5V Note that the SYSOK hysteresis margin is added to these threshold levels.	

Register 4001h PVDD Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16386 (4002h) Thermal Monitoring	3	THW_HYST	1	Thermal Warning hysteresis 0 = 8 degrees C 1 = 16 degrees C	
	1:0	THW_TEMP [1:0]	10	Thermal Warning temperature 00 = 90 degrees C 01 = 100 degrees C 10 = 110 degrees C 11 = 120 degrees C	

Register 4002h Thermal Monitoring

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16387 (4003h) Power State	15	CHIP_ON	0	Indicates whether the system is ON or OFF. 0 = OFF 1 = ON (or SLEEP) OFF can be commanded by writing CHIP_ON = 0. Note that writing CHIP_ON = 1 is not a valid 'ON' event, and will not trigger an ON transition.	
	14	CHIP_SLP	0	Indicates whether the system is in the SLEEP state. 0 = Not in SLEEP 1 = SLEEP WAKE can be commanded by writing CHIP_SLP = 0. SLEEP can be commanded by writing CHIP_SLP = 1.	
	12	REF_LP	0	Low Power Voltage Reference Control 0 = Normal 1 = Low Power Reference Mode select Note that Low Power Reference Mode is only supported when the Auxiliary ADC is disabled.	
	11:10	PWRSTATE_DLY [1:0]	10	Power State transition delay 00 = No delay 01 = No delay 10 = 1ms 11 = 10ms	
	9	SWRST_DLY	0	Software Reset Delay 0 = No delay 1 = Software Reset is delayed by PWRSTATE_DLY following the Software Reset command	

Register 4003h Power State

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16388 (4004h) Watchdog	15	WDOG_ENA	1	Watchdog Timer Enable 0 = Disabled 1 = Enabled (enables the watchdog; does not reset it) <i>Protected by security key.</i>	
	14	WDOG_DEBU G	0	Watchdog Pause 0 = Disabled 1 = Enabled (halts the Watchdog timer for system debugging) <i>Protected by security key.</i>	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	13	WDOG_RST_SRC	1	Watchdog Reset Source 0 = Hardware only 1 = Software only <i>Protected by security key.</i>	
	12	WDOG_SLPE NA	0	Watchdog SLEEP Enable 0 = Disabled 1 = Controlled by WDOG_ENA <i>Protected by security key.</i>	
	11	WDOG_RESET	0	Watchdog Software Reset 0 = Normal 1 = Watchdog Reset (resets the watchdog, if WDOG_RST_SRC = 1)	
	9:8	WDOG_SECACT [1:0]	10	Secondary action of Watchdog timeout (taken after 2 timeout periods) 00 = No action 01 = Interrupt 10 = Device Reset 11 = WAKE transition <i>Protected by security key.</i>	
	5:4	WDOG_PRIMA CT [1:0]	01	Primary action of Watchdog timeout 00 = No action 01 = Interrupt 10 = Device Reset 11 = WAKE transition <i>Protected by security key.</i>	
	2:0	WDOG_TO [2:0]	111	Watchdog timeout period 000 = 0.256s 001 = 0.512s 010 = 1.024s 011 = 2.048s 100 = 4.096s 101 = 8.192s 110 = 16.384s 111 = 32.768s <i>Protected by security key.</i>	

Register 4004h Watchdog

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16389 (4005h) ON Pin Control	9:8	ON_PIN_SECACT [1:0]	01	Secondary action of ON pin (taken after 1 timeout period) 00 = Interrupt 01 = ON request 10 = OFF request 11 = Reserved <i>Protected by security key.</i>	
	5:4	ON_PIN_PRIM ACT [1:0]	00	Primary action of ON pin 00 = Ignore 01 = ON request 10 = OFF request 11 = Reserved Note that an Interrupt is always raised.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				<i>Protected by security key.</i>	
	3	ON_PIN_STS	0	Current status of ON pin 0 = Asserted (logic 0) 1 = Not asserted (logic 1)	
	1:0	ON_PIN_TO [1:0]	00	ON pin timeout period 00 = 1s 01 = 2s 10 = 4s 11 = 8s <i>Protected by security key.</i>	

Register 4005h ON Pin Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16390 (4006h) Reset Control	15	RECONFIG_A T_ON	1	Selects if the bootstrap configuration data should be reloaded when an ON transition is scheduled 0 = Disabled 1 = Enabled <i>Protected by security key.</i>	
	10	SW_RESET_C FG	1	Software Reset Configuration. Selects whether the register map is reset to default values when Software Reset occurs. 0 = All registers except VPMIC domain and RTC are reset by Software Reset 1 = Register Map is not affected by Software Reset <i>Protected by security key.</i>	
	6	AUXRST_SLP ENA	1	Sets the output status of Auxiliary Reset (GPIO) function in SLEEP 0 = Auxiliary Reset not asserted 1 = Auxiliary Reset asserted <i>Protected by security key.</i>	
	5	RST_SLP_MS K	1	Masks the RESET pin input in SLEEP mode 0 = External RESET active in SLEEP 1 = External RESET masked in SLEEP <i>Protected by security key.</i>	
	4	RST_SLPENA	1	Sets the output status of RESET pin in SLEEP 0 = RESET high (not asserted) 1 = RESET low (asserted) <i>Protected by security key.</i>	
	1:0	RST_DUR [1:0]	11	Delay period for releasing RESET after ON or WAKE sequence 00 = 3ms 01 = 11ms 10 = 51ms 11 = 101ms <i>Protected by security key.</i>	

Register 4006h Reset Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16391 (4007h) Control Interface	2	AUTOINC	1	Enable Auto-Increment function 0 = Disabled 1 = Enabled	

Register 4007h Control Interface

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16392 (4008h) Security Key	15:0	SECURITY [15:0]	0000_0000 _0000_000 0	Security Key A value of 9716h must be written to this register to access the user-keyed registers.	

Register 4008h Security Key

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16393 (4009h) Software Scratch	15:0	SW_SCRATCH [15:0]	0000_0000 _0000_000 0	Software Scratch Register for use by the host processor. Note that this register's contents are retained in the BACKUP power state.	

Register 4009h Software Scratch

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16394 (400Ah) OTP Control	15	OTP_PROG	0	Selects the PROGRAM device state. 0 = No action 1 = Select PROGRAM mode Note that, after PROGRAM mode has been selected, the chip will remain in PROGRAM mode until a Device Reset. <i>Protected by security key.</i>	
	13	OTP_MEM	1	Selects ICE or OTP memory for Program commands. 0 = ICE 1 = OTP <i>Protected by security key.</i>	
	11	OTP_FINAL	0	Selects the FINALISE command, preventing further OTP programming. 0 = No action 1 = Finalise Command <i>Protected by security key.</i>	
	10	OTP_VERIFY	0	Selects the VERIFY command for the selected OTP memory page(s). 0 = No action 1 = Verify Command <i>Protected by security key.</i>	
	9	OTP_WRITE	0	Selects WRITE command for the selected OTP memory page(s). 0 = No action 1 = Write Command <i>Protected by security key.</i>	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	8	OTP_READ	0	Selects READ command for the selected memory page(s). 0 = No action 1 = Read Command <i>Protected by security key.</i>	
	7:6	OTP_READ_LVL [1:0]	00	Selects the Margin Level for READ or VERIFY OTP commands. 00 = Normal 01 = Reserved 10 = Margin 1 11 = Margin 2 <i>Protected by security key.</i>	
	5	OTP_BULK	0	Selects the number of memory pages for ICE / OTP commands. 0 = Single Page 1 = All Pages	
	1:0	OTP_PAGE [1:0]	00	Selects the single memory page for ICE / OTP commands (when OTP_BULK=0). If OTP is selected (OTP_MEM = 1): 00 = Page 0 01 = Page 1 10 = Page 2 11 = Page 3 If ICE is selected (OTP_MEM = 0): 00 = Page 2 01 = Page 3 10 = Page 4 11 = Reserved	

Register 400Ah OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16396 (400Ch) GPIO Level	11	GP12_LVL	0	GPIO12 level. When GP12_FN = 0h and GP12_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP12_POL is 0, the register contains the opposite logic level to the external pin.	
	10	GP11_LVL	0	GPIO11 level. When GP11_FN = 0h and GP11_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP11_POL is 0, the register contains the opposite logic level to the external pin.	
	9	GP10_LVL	0	GPIO10 level. When GP10_FN = 0h and GP10_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP10_POL is 0, the register contains the opposite logic level to the external pin.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	8	GP9_LVL	0	GPIO9 level. When GP9_FN = 0h and GP9_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP9_POL is 0, the register contains the opposite logic level to the external pin.	
	7	GP8_LVL	0	GPIO8 level. When GP8_FN = 0h and GP8_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP8_POL is 0, the register contains the opposite logic level to the external pin.	
	6	GP7_LVL	0	GPIO7 level. When GP7_FN = 0h and GP7_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP7_POL is 0, the register contains the opposite logic level to the external pin.	
	5	GP6_LVL	0	GPIO6 level. When GP6_FN = 0h and GP6_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP6_POL is 0, the register contains the opposite logic level to the external pin.	
	4	GP5_LVL	0	GPIO5 level. When GP5_FN = 0h and GP5_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP5_POL is 0, the register contains the opposite logic level to the external pin.	
	3	GP4_LVL	0	GPIO4 level. When GP4_FN = 0h and GP4_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP4_POL is 0, the register contains the opposite logic level to the external pin.	
	2	GP3_LVL	0	GPIO3 level. When GP3_FN = 0h and GP3_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP3_POL is 0, the register contains the opposite logic level to the external pin.	
	1	GP2_LVL	0	GPIO2 level. When GP2_FN = 0h and GP2_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP2_POL is 0, the register contains the opposite logic level to the external pin.	
	0	GP1_LVL	0	GPIO1 level. When GP1_FN = 0h and GP1_DIR = 0, write to this bit to set a GPIO output. Read from this bit to read GPIO input level. When GP1_POL is 0, the register contains the opposite logic level to the external pin.	

Register 400Ch GPIO Level

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16397 (400Dh) System Status	15	THW_STS	0	Thermal Warning status 0 = Normal 1 = Overtemperature Warning (warning temperature is set by THW_TEMP)	
	7	XTAL_OK	0	Crystal Oscillator Status 0 = Disabled or in start-up phase 1 = Enabled and verified	
	4:0	MAIN_STATE [4:0]	0_0000	Main State Machine condition 0_0000 = OFF 0_0001 = ON_CHK 0_0010 = OTP_DN 0_0011 = READ_OTP 0_0100 = READ_ICE 0_0101 = ICE_DN 0_0110 = BGDELAY 0_0111 = HYST 0_1000 = S_PRG_RD_OTP 0_1001 = S_PRG_OTP_DN 0_1010 = PWRDN1 0_1011 = PROGRAM 0_1100 = PROG_DN 0_1101 = PROG_OTP 0_1110 = VFY_OTP 0_1111 = VFY_DN 1_0000 = SD_RD_OTP 1_0001 = UNUSED 1_0010 = ICE_FAIL 1_0011 = SHUTDOWN 1_0100 = STARTFAIL 1_0101 = STARTUP 1_0110 = PREACTIVE 1_0111 = XTAL_CHK 1_1000 = PWRDN2 1_1001 = SHUT_DLY 1_1010 = RESET 1_1011 = RESET_DLY 1_1100 = SLEEP 1_1101 = SLEEP_DLY 1_1110 = CHK_RST 1_1111 = ACTIVE (ON)	

Register 400Dh System Status

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16398 (400Eh) ON Source	15	ON_TRANS	0	Most recent ON/WAKE event type 0 = WAKE transition 1 = ON transition <i>Reset by state machine.</i>	
	11	ON_GPIO	0	Most recent ON/WAKE event type 0 = Not caused by GPIO input 1 = Caused by GPIO input	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				<i>Reset by state machine.</i>	
	10	ON_SYSLO	0	Most recent WAKE event type 0 = Not caused by PVDD 1 = Caused by SYSLO threshold. Note that the SYSLO threshold cannot trigger an ON event. <i>Reset by state machine.</i>	
	7	ON_WDOG_T O	0	Most recent WAKE event type 0 = Not caused by Watchdog timer 1 = Caused by Watchdog timer <i>Reset by state machine.</i>	
	6	ON_SW_REQ	0	Most recent WAKE event type 0 = Not caused by software WAKE 1 = Caused by software WAKE command (CHIP_SLP = 0) <i>Reset by state machine.</i>	
	5	ON_RTC_ALM	0	Most recent ON/WAKE event type 0 = Not caused by RTC Alarm 1 = Caused by RTC Alarm <i>Reset by state machine.</i>	
	4	ON_ON_PIN	0	Most recent ON/WAKE event type 0 = Not caused by the ON pin 1 = Caused by the ON pin <i>Reset by state machine.</i>	
	3	RESET_CNV_ UV	0	Most recent ON event type 0 = Not caused by undervoltage 1 = Caused by a Device Reset due to a Converter (LDO or DC-DC) undervoltage condition <i>Reset by state machine.</i>	
	2	RESET_SW	0	Most recent ON event type 0 = Not caused by Software Reset 1 = Caused by Software Reset <i>Reset by state machine.</i>	
	1	RESET_HW	0	Most recent ON event type 0 = Not caused by Hardware Reset 1 = Caused by Hardware Reset <i>Reset by state machine.</i>	
	0	RESET_WDO G	0	Most recent ON event type 0 = Not caused by the Watchdog 1 = Caused by a Device Reset triggered by the Watchdog timer <i>Reset by state machine.</i>	

Register 400Eh ON Source

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16399 (400Fh) OFF Source	13	OFF_INTLDO_ ERR	0	Most recent OFF event type 0 = Not caused by LDO13 Error condition 1 = Caused by LDO13 Error condition <i>Reset by state machine.</i>	
	12	OFF_PWR_SE Q	0	Most recent OFF event type 0 = Not caused by Power Sequence Failure 1 = Caused by a Power Sequence Failure	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				<i>Reset by state machine.</i>	
	11	OFF_GPIO	0	Most recent OFF event type 0 = Not caused by GPIO input 1 = Caused by GPIO input <i>Reset by state machine.</i>	
	10	OFF_PVDD	0	Most recent OFF event type 0 = Not caused by PVDD 1 = Caused by the SYSLO or SHUTDOWN threshold <i>Reset by state machine.</i>	
	9	OFF_THERR	0	Most recent OFF event type 0 = Not caused by temperature 1 = Caused by over-temperature <i>Reset by state machine.</i>	
	6	OFF_SW_REQ	0	Most recent OFF event type 0 = Not caused by software OFF 1 = Caused by software OFF command (CHIP_ON = 0) <i>Reset by state machine.</i>	
	4	OFF_ON_PIN	0	Most recent OFF event type 0 = Not caused by the ON pin 1 = Caused by the ON pin <i>Reset by state machine.</i>	

Register 400Fh OFF Source

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16400 (4010h) System Interrupts	15	PS_INT	0	Power State primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	14	TEMP_INT	0	Thermal primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	13	GP_INT	0	GPIO primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	12	ON_PIN_INT	0	ON Pin primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	11	WDOG_INT	0	Watchdog primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	8	AUXADC_INT	0	AUXADC primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	7	PPM_INT	0	Power Path Management primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	5	RTC_INT	0	Real Time Clock and Crystal Oscillator primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	4	OTP_INT	0	OTP Memory primary interrupt 0 = No interrupt	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				1 = Interrupt is asserted	
	1	HC_INT	0	High Current primary interrupt 0 = No interrupt 1 = Interrupt is asserted	
	0	UV_INT	0	Undervoltage primary interrupt 0 = No interrupt 1 = Interrupt is asserted	

Register 4010h System Interrupts

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16401 (4011h) Interrupt Status 1	15	PPM_SYSLO_EINT	0	Power Path SYSLO interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	12	ON_PIN_CINT	0	ON pin interrupt. (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.	
	11	WDOG_TO_EINT	0	Watchdog timeout interrupt. (Rising Edge triggered) Note: Cleared when a '1' is written.	
	8	AUXADC_DATA_EINT	0	AUXADC Data Ready interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	7	AUXADC_DCOMP4_EINT	0	AUXADC Digital Comparator 4 interrupt (Trigger is controlled by DCMP4_GT) Note: Cleared when a '1' is written.	
	6	AUXADC_DCOMP3_EINT	0	AUXADC Digital Comparator 3 interrupt (Trigger is controlled by DCMP3_GT) Note: Cleared when a '1' is written.	
	5	AUXADC_DCOMP2_EINT	0	AUXADC Digital Comparator 2 interrupt (Trigger is controlled by DCMP2_GT) Note: Cleared when a '1' is written.	
	4	AUXADC_DCOMP1_EINT	0	AUXADC Digital Comparator 1 interrupt (Trigger is controlled by DCMP1_GT) Note: Cleared when a '1' is written.	
	3	RTC_PERIODIC_INT	0	RTC Periodic interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	2	RTC_ALARM_INT	0	RTC Alarm interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	1	TEMP_THW_CINT	0	Thermal Warning interrupt (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.	

Register 4011h Interrupt Status 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16402 (4012h) Interrupt Status 2	5	OTP_CMD_EN D_EINT	0	OTP / ICE Command End interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	4	OTP_ERR_EIN T	0	OTP / ICE Command Fail interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	2	PS_POR_EINT	0	Power On Reset interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	1	PS_SLEEP_O FF_EINT	0	SLEEP or OFF interrupt (Power state transition to SLEEP or OFF states) (Rising Edge triggered) Note: Cleared when a '1' is written.	
	0	PS_ON_WAKE _EINT	0	ON or WAKE interrupt (Power state transition to ON state) (Rising Edge triggered) Note: Cleared when a '1' is written.	

Register 4012h Interrupt Status 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16403 (4013h) Interrupt Status 3	9	UV_LDO10_EI NT	0	LDO10 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	8	UV_LDO9_EIN T	0	LDO9 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	7	UV_LDO8_EIN T	0	LDO8 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	6	UV_LDO7_EIN T	0	LDO7 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	5	UV_LDO6_EIN T	0	LDO6 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	4	UV_LDO5_EIN T	0	LDO5 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	3	UV_LDO4_EIN T	0	LDO4 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	2	UV_LDO3_EIN T	0	LDO3 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	1	UV_LDO2_EIN T	0	LDO2 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	0	UV_LDO1_EIN T	0	LDO1 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	

Register 4013h Interrupt Status 3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16404 (4014h) Interrupt Status 4	9	HC_DC2_EINT	0	DC-DC2 High current interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	8	HC_DC1_EINT	0	DC-DC1 High current interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	7	XTAL_START_EINT	0	Crystal Oscillator Start Failure interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	6	XTAL_TAMPER_EINT	0	Crystal Oscillator Tamper interrupt (Rising and Falling Edge triggered) Note: Cleared when a '1' is written.	
	3	UV_DC4_EINT	0	DC-DC4 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	2	UV_DC3_EINT	0	DC-DC3 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	1	UV_DC2_EINT	0	DC-DC2 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	
	0	UV_DC1_EINT	0	DC-DC1 Undervoltage interrupt (Rising Edge triggered) Note: Cleared when a '1' is written.	

Register 4014h Interrupt Status 4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16405 (4015h) Interrupt Status 5	11	GP12_EINT	0	GPIO12 interrupt. (Trigger is controlled by GP12_INT_MODE) Note: Cleared when a '1' is written.	
	10	GP11_EINT	0	GPIO11 interrupt. (Trigger is controlled by GP11_INT_MODE) Note: Cleared when a '1' is written.	
	9	GP10_EINT	0	GPIO10 interrupt. (Trigger is controlled by GP10_INT_MODE) Note: Cleared when a '1' is written.	
	8	GP9_EINT	0	GPIO9 interrupt. (Trigger is controlled by GP9_INT_MODE) Note: Cleared when a '1' is written.	
	7	GP8_EINT	0	GPIO8 interrupt. (Trigger is controlled by GP8_INT_MODE) Note: Cleared when a '1' is written.	
	6	GP7_EINT	0	GPIO7 interrupt. (Trigger is controlled by GP7_INT_MODE) Note: Cleared when a '1' is written.	
	5	GP6_EINT	0	GPIO6 interrupt. (Trigger is controlled by GP6_INT_MODE) Note: Cleared when a '1' is written.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4	GP5_EINT	0	GPIO5 interrupt. (Trigger is controlled by GP5_INT_MODE) Note: Cleared when a '1' is written.	
	3	GP4_EINT	0	GPIO4 interrupt. (Trigger is controlled by GP4_INT_MODE) Note: Cleared when a '1' is written.	
	2	GP3_EINT	0	GPIO3 interrupt. (Trigger is controlled by GP3_INT_MODE) Note: Cleared when a '1' is written.	
	1	GP2_EINT	0	GPIO2 interrupt. (Trigger is controlled by GP2_INT_MODE) Note: Cleared when a '1' is written.	
	0	GP1_EINT	0	GPIO1 interrupt. (Trigger is controlled by GP1_INT_MODE) Note: Cleared when a '1' is written.	

Register 4015h Interrupt Status 5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16407 (4017h) IRQ Config	1	IRQ_OD	1	IRQ pin configuration 0 = CMOS 1 = Open Drain (integrated pull-up)	
	0	IM_IRQ	0	IRQ pin output mask 0 = Normal 1 = IRQ output is masked	

Register 4017h IRQ Config

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16408 (4018h) System Interrupts Mask	15	IM_PS_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	14	IM_TEMP_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	13	IM_GP_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	12	IM_ON_PIN_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	11	IM_WDOG_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	8	IM_AUXADC_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	7	IM_PPM_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	5	IM_RTC_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	4	IM_OTP_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	1	IM_HC_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	0	IM_UV_INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

Register 4018h System Interrupts Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16409 (4019h) Interrupt Status 1 Mask	15	IM_PPM_SYSL O_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	12	IM_ON_PIN_C INT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	11	IM_WDOG_TO _EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	8	IM_AUXADC_ DATA_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	7	IM_AUXADC_ DCOMP4_EIN T	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	6	IM_AUXADC_ DCOMP3_EIN T	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				Default value is 1 (masked)	
	5	IM_AUXADC_DCOMP2_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	4	IM_AUXADC_DCOMP1_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	3	IM_RTC_PER_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	2	IM_RTC_ALM_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	1	IM_TEMP_THW_CINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

Register 4019h Interrupt Status 1 Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16410 (401Ah) Interrupt Status 2 Mask	5	IM_OTP_CMD_END_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	4	IM_OTP_ERR_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	2	IM_PS_POR_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	1	IM_PS_SLEEP_OFF_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	0	IM_PS_ON_WAKE_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

Register 401Ah Interrupt Status 2 Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16411 (401Bh) Interrupt Status 3 Mask	9	IM_UV_LDO10_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	8	IM_UV_LDO9_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	7	IM_UV_LDO8_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	6	IM_UV_LDO7_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	5	IM_UV_LDO6_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	4	IM_UV_LDO5_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	3	IM_UV_LDO4_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	2	IM_UV_LDO3_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	1	IM_UV_LDO2_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	0	IM_UV_LDO1_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

Register 401Bh Interrupt Status 3 Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16412 (401Ch) Interrupt Status 4 Mask	9	IM_HC_DC2_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	8	IM_HC_DC1_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				Default value is 1 (masked)	
	7	IM_XTAL_START_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	3	IM_UV_DC4_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	2	IM_UV_DC3_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	1	IM_UV_DC2_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	0	IM_UV_DC1_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

Register 401Ch Interrupt Status 4 Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16413 (401Dh) Interrupt Status 5 Mask	11	IM_GP12_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	10	IM_GP11_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	9	IM_GP10_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	8	IM_GP9_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	7	IM_GP8_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	6	IM_GP7_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	5	IM_GP6_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				Default value is 1 (masked)	
	4	IM_GP5_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	3	IM_GP4_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	2	IM_GP3_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	1	IM_GP2_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	
	0	IM_GP1_EINT	1	Interrupt mask. 0 = Do not mask interrupt. 1 = Mask interrupt. Default value is 1 (masked)	

Register 401Dh Interrupt Status 5 Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16416 (4020h) RTC Write Counter	15:0	RTC_WR_CNT [15:0]	0000_0000 _0000_000 0	RTC Write Counter. This random number is updated on every write to the RTC_TIME registers.	

Register 4020h RTC Write Counter

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16417 (4021h) RTC Time 1	15:0	RTC_TIME [15:0]	0000_0000 _0000_000 0	RTC Seconds counter (MSW) RTC_TIME increments by 1 every second. This is the 16 MSBs.	

Register 4021h RTC Time 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16418 (4022h) RTC Time 2	15:0	RTC_TIME [15:0]	0000_0000 _0000_000 0	RTC Seconds counter (LSW) RTC_TIME increments by 1 every second. This is the 16 LSBs.	

Register 4022h RTC Time 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16419 (4023h) RTC Alarm 1	15:0	RTC_ALM [15:0]	0000_0000 _0000_000 0	RTC Alarm time (MSW) 16 MSBs of RTC_ALM	

Register 4023h RTC Alarm 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16420 (4024h) RTC Alarm 2	15:0	RTC_ALM [15:0]	0000_0000 _0000_000 0	RTC Alarm time (LSW) 16 LSBs of RTC_ALM	

Register 4024h RTC Alarm 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16421 (4025h) RTC Control	15	RTC_VALID	0	RTC Valid status 0 = RTC_TIME has not been set since Power On Reset 1 = RTC_TIME has been written to since Power On Reset	
	14	RTC_SYNC_B USY	0	RTC Busy status 0 = Normal 1 = Busy The RTC registers should not be written to when RTC_SYNC_BUSY = 1.	
	10	RTC_ALM_EN A	0	RTC Alarm Enable 0 = Disabled 1 = Enabled	
	6:4	RTC_PINT_FR EQ [2:0]	000	RTC Periodic Interrupt timeout period 000 = Disabled 001 = 2s 010 = 4s 011 = 8s 100 = 16s 101 = 32s 110 = 64s 111 = 128s	

Register 4025h RTC Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16422 (4026h) RTC Trim	9:0	RTC_TRIM [9:0]	00_0000_0 000	RTC frequency trim. Value is a 10bit fixed point <4,6> 2's complement number. MSB Scaling = -8Hz. The register indicates the error (in Hz) with respect to the ideal 32768Hz) of the input crystal frequency. <i>Protected by security key.</i>	

Register 4026h RTC Trim

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16429 (402Dh) AuxADC Data	15:12	AUX_DATA_S RC [3:0]	0000	AUXADC Data Source 1 = GPIO10 2 = GPIO11 3 = GPIO12 5 = Chip Temperature 7 = PVDD voltage All other values are Reserved	
	11:0	AUX_DATA [11:0]	0000_0000 _0000	AUXADC Measurement Data Voltage (mV) = AUX_DATA x 1.465 ChipTemp (°C) = (498 - AUX_DATA) / 1.09	

Register 402Dh AuxADC Data

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16430 (402Eh) AuxADC Control	15	AUX_ENA	0	AUXADC Enable 0 = Disabled 1 = Enabled Note - this bit is reset to 0 when the OFF power state is entered.	
	14	AUX_CVT_EN A	0	AUXADC Conversion Enable 0 = Disabled 1 = Enabled In automatic mode, conversions are enabled by setting this bit. In manual mode (AUX_RATE = 0), setting this bit will initiate a conversion; the bit is reset automatically after each conversion.	
	12	AUX_SLPENA	0	AUXADC SLEEP Enable 0 = Disabled 1 = Controlled by AUX_ENA	
	5:0	AUX_RATE [5:0]	00_0000	AUXADC Conversion Rate 0 = Manual 1 = 2 samples/s 2 = 4 samples/s 3 = 6 samples/s ... 31 = 62 samples/s 32 = Reserved 33 = 16 samples/s 34 = 32 samples/s 35 = 48 samples/s ... 63 = 496 samples/s	

Register 402Eh AuxADC Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16431 (402Fh) AuxADC Source	6	AUX_PVDD_SEL	0	AUXADC PVDD input select 0 = Disable PVDD measurement 1 = Enable PVDD measurement	
	4	AUX_CHIP_TEMP_SEL	0	AUXADC Chip Temp input select 0 = Disable Chip Temp measurement 1 = Enable Chip Temp measurement	
	2	AUX_GPIO12_SEL	0	AUXADC GPIO12 input select 0 = Disable GPIO12 measurement 1 = Enable GPIO12 measurement	
	1	AUX_GPIO11_SEL	0	AUXADC GPIO11 input select 0 = Disable GPIO11 measurement 1 = Enable GPIO11 measurement	
	0	AUX_GPIO10_SEL	0	AUXADC GPIO10 input select 0 = Disable GPIO10 measurement 1 = Enable GPIO10 measurement	

Register 402Fh AuxADC Source

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16432 (4030h) Comparator Control	11	DCOMP4_STS	0	Digital Comparator 4 status 0 = Comparator 4 threshold not detected 1 = Comparator 4 threshold detected (Trigger is controlled by DCMP4_GT)	
	10	DCOMP3_STS	0	Digital Comparator 3 status 0 = Comparator 3 threshold not detected 1 = Comparator 3 threshold detected (Trigger is controlled by DCMP3_GT)	
	9	DCOMP2_STS	0	Digital Comparator 2 status 0 = Comparator 2 threshold not detected 1 = Comparator 2 threshold detected (Trigger is controlled by DCMP2_GT)	
	8	DCOMP1_STS	0	Digital Comparator 1 status 0 = Comparator 1 threshold not detected 1 = Comparator 1 threshold detected (Trigger is controlled by DCMP1_GT)	
	3	DCMP4_ENA	0	Digital Comparator 4 Enable 0 = Disabled 1 = Enabled	
	2	DCMP3_ENA	0	Digital Comparator 3 Enable 0 = Disabled 1 = Enabled	
	1	DCMP2_ENA	0	Digital Comparator 2 Enable 0 = Disabled 1 = Enabled	
	0	DCMP1_ENA	0	Digital Comparator 1 Enable 0 = Disabled 1 = Enabled	

Register 4030h Comparator Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16433 (4031h) Comparator 1	15:13	DCMP1_SRC [2:0]	000	Digital Comparator 1 source select 0 = Reserved 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage	
	12	DCMP1_GT	0	Digital Comparator 1 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold	
	11:0	DCMP1_THR [11:0]	0000_0000_0000	Digital Comparator 1 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)	

Register 4031h Comparator 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16434 (4032h) Comparator 2	15:13	DCMP2_SRC [2:0]	000	Digital Comparator 2 source select 0 = Reserved 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage	
	12	DCMP2_GT	0	Digital Comparator 2 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold	
	11:0	DCMP2_THR [11:0]	0000_0000_0000	Digital Comparator 2 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)	

Register 4032h Comparator 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16435 (4033h) Comparator 3	15:13	DCMP3_SRC [2:0]	000	Digital Comparator 3 source select 0 = Reserved 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage	
	12	DCMP3_GT	0	Digital Comparator 3 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	11:0	DCMP3_THR [11:0]	0000_0000_0000	Digital Comparator 3 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)	

Register 4033h Comparator 3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16436 (4034h) Comparator 4	15:13	DCMP4_SRC [2:0]	000	Digital Comparator 4 source select 0 = Backup Battery voltage 1 = GPIO10 2 = GPIO11 3 = GPIO12 4 = Reserved 5 = Chip Temperature 6 = Reserved 7 = PVDD voltage	
	12	DCMP4_GT	0	Digital Comparator 4 interrupt control 0 = interrupt when less than threshold 1 = interrupt when greater than or equal to threshold	
	11:0	DCMP4_THR [11:0]	0000_0000_0000	Digital Comparator 4 threshold (12-bit unsigned binary number; coding is the same as AUX_DATA)	

Register 4034h Comparator 4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16440 (4038h) GPIO1 Control	15	GP1_DIR	1	GPIO1 pin direction 0 = Output 1 = Input	
	14:13	GP1_PULL [1:0]	01	GPIO1 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP1_INT_MODE	0	GPIO1 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP1_POL=1) or falling edge triggered (if GP1_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP1_PWR_DOMAIN	0	GPIO1 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP1_POL	1	GPIO1 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP1_OD	0	GPIO1 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP1_ENA	0	GPIO1 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	3:0	GP1_FN [3:0]	0000	GPIO1 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 4038h GPIO1 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16441 (4039h) GPIO2 Control	15	GP2_DIR	1	GPIO2 pin direction 0 = Output 1 = Input	
	14:13	GP2_PULL [1:0]	01	GPIO2 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP2_INT_MODE	0	GPIO2 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP2_POL=1) or falling edge triggered (if GP2_POL=0) 1 = GPIO interrupt is triggered on rising and falling	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				edges	
	11	GP2_PWR_DOMAIN	0	GPIO2 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP2_POL	1	GPIO2 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP2_OD	0	GPIO2 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP2_ENA	0	GPIO2 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP2_FN [3:0]	0000	GPIO2 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 4039h GPIO2 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16442 (403Ah) GPIO3 Control	15	GP3_DIR	1	GPIO3 pin direction 0 = Output 1 = Input	
	14:13	GP3_PULL [1:0]	01	GPIO3 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP3_INT_MODE	0	GPIO3 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP3_POL=1) or falling edge triggered (if GP3_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP3_PWR_DOMAIN	0	GPIO3 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP3_POL	1	GPIO3 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP3_OD	0	GPIO3 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP3_ENA	0	GPIO3 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP3_FN [3:0]	0000	GPIO3 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 403Ah GPIO3 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16443 (403Bh) GPIO4 Control	15	GP4_DIR	1	GPIO4 pin direction 0 = Output 1 = Input	
	14:13	GP4_PULL [1:0]	01	GPIO4 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP4_INT_MODE	0	GPIO4 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP4_POL=1) or falling edge triggered (if GP4_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP4_PWR_DOMAIN	0	GPIO4 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP4_POL	1	GPIO4 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP4_OD	0	GPIO4 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP4_ENA	0	GPIO4 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP4_FN [3:0]	0000	GPIO4 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 403Bh GPIO4 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16444 (403Ch) GPIO5 Control	15	GP5_DIR	1	GPIO5 pin direction 0 = Output 1 = Input	
	14:13	GP5_PULL [1:0]	01	GPIO5 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP5_INT_MODE	0	GPIO5 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP5_POL=1) or falling edge triggered (if GP5_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP5_PWR_DOMAIN	0	GPIO5 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP5_POL	1	GPIO5 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP5_OD	0	GPIO5 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP5_ENA	0	GPIO5 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP5_FN [3:0]	0000	GPIO5 Pin Function Input functions:	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 403Ch GPIO5 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16445 (403Dh) GPIO6 Control	15	GP6_DIR	1	GPIO6 pin direction 0 = Output 1 = Input	
	14:13	GP6_PULL [1:0]	01	GPIO6 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP6_INT_MOD E	0	GPIO6 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP6_POL=1) or falling edge triggered (if GP6_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	11	GP6_PWR_DOM	0	GPIO6 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP6_POL	1	GPIO6 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP6_OD	0	GPIO6 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP6_ENA	0	GPIO6 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP6_FN [3:0]	0000	GPIO6 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 403Dh GPIO6 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16446 (403Eh) GPIO7 Control	15	GP7_DIR	1	GPIO7 pin direction 0 = Output 1 = Input	
	14:13	GP7_PULL [1:0]	01	GPIO7 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP7_INT_MODE	0	GPIO7 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP7_POL=1) or falling edge triggered (if GP7_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP7_PWR_DOMAIN	0	GPIO7 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP7_POL	1	GPIO7 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP7_OD	0	GPIO7 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP7_ENA	0	GPIO7 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP7_FN [3:0]	0000	GPIO7 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 403Eh GPIO7 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16447 (403Fh) GPIO8 Control	15	GP8_DIR	1	GPIO8 pin direction 0 = Output 1 = Input	
	14:13	GP8_PULL [1:0]	01	GPIO8 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP8_INT_MODE	0	GPIO8 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP8_POL=1) or falling edge triggered (if GP8_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP8_PWR_DOMAIN	0	GPIO8 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP8_POL	1	GPIO8 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP8_OD	0	GPIO8 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP8_ENA	0	GPIO8 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP8_FN [3:0]	0000	GPIO8 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 403Fh GPIO8 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16448 (4040h) GPIO9 Control	15	GP9_DIR	1	GPIO9 pin direction 0 = Output 1 = Input	
	14:13	GP9_PULL [1:0]	01	GPIO9 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP9_INT_MODE	0	GPIO9 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP9_POL=1) or falling edge triggered (if GP9_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP9_PWR_DOMAIN	0	GPIO9 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP9_POL	1	GPIO9 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP9_OD	0	GPIO9 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP9_ENA	0	GPIO9 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP9_FN [3:0]	0000	GPIO9 Pin Function Input functions:	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 4040h GPIO9 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16449 (4041h) GPIO10 Control	15	GP10_DIR	1	GPIO10 pin direction 0 = Output 1 = Input	
	14:13	GP10_PULL [1:0]	01	GPIO10 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP10_INT_MODE	0	GPIO10 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP10_POL=1) or falling edge triggered (if GP10_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	11	GP10_PWR_DOM	0	GPIO10 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP10_POL	1	GPIO10 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP10_OD	0	GPIO10 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP10_ENA	0	GPIO10 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP10_FN [3:0]	0000	GPIO10 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 4041h GPIO10 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16450 (4042h) GPIO11 Control	15	GP11_DIR	1	GPIO11 pin direction 0 = Output 1 = Input	
	14:13	GP11_PULL [1:0]	01	GPIO11 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP11_INT_MODE	0	GPIO11 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP11_POL=1) or falling edge triggered (if GP11_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP11_PWR_DOMAIN	0	GPIO11 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP11_POL	1	GPIO11 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP11_OD	0	GPIO11 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP11_ENA	0	GPIO11 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP11_FN [3:0]	0000	GPIO11 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 4042h GPIO11 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16451 (4043h) GPIO12 Control	15	GP12_DIR	1	GPIO12 pin direction 0 = Output 1 = Input	
	14:13	GP12_PULL [1:0]	01	GPIO12 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP12_INT_MODE	0	GPIO12 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP12_POL=1) or falling edge triggered (if GP12_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP12_PWR_DOMAIN	0	GPIO12 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP12_POL	1	GPIO12 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP12_OD	0	GPIO12 Output pin configuration 0 = CMOS 1 = Open Drain	
	7	GP12_ENA	0	GPIO12 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	3:0	GP12_FN [3:0]	0000	GPIO12 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 4043h GPIO12 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16460 (404Ch) Status LED 1	15:14	LED1_SRC [1:0]	11	LED1 Source (Selects the LED1 function.) 00 = Off 01 = Power State Status 10 = Reserved 11 = Manual Mode Note - LED1 also indicates completion of OTP Auto Program	
	9:8	LED1_MODE [1:0]	00	LED1 Mode (Controls LED1 in Manual Mode only.) 00 = Off 01 = Constant 10 = Continuous Pulsed 11 = Pulsed Sequence	
	5:4	LED1_SEQ_LEN [1:0]	10	LED1 Pulse Sequence Length (when LED1_MODE = Pulsed Sequence) 00 = 1 pulse 01 = 2 pulses 10 = 4 pulses 11 = 7 pulses	
	3:2	LED1_DUR [1:0]	01	LED1 On time (when LED1_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1 second 01 = 250ms 10 = 125ms 11 = 62.5ms	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	1:0	LED1_DUTY_CYC [1:0]	10	LED1 Duty Cycle (On:Off ratio) (when LED1_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1:1 (50% on) 01 = 1:2 (33.3% on) 10 = 1:3 (25% on) 11 = 1:7 (12.5% on)	

Register 404Ch Status LED 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16461 (404Dh) Status LED 2	15:14	LED2_SRC [1:0]	11	LED2 Source (Selects the LED2 function.) 00 = Off 01 = Power State Status 10 = Reserved 11 = Manual Mode Note - LED2 also indicates an OTP Auto Program Error condition	
	9:8	LED2_MODE [1:0]	00	LED2 Mode (Controls LED2 in Manual Mode only.) 00 = Off 01 = Constant 10 = Continuous Pulsed 11 = Pulsed Sequence	
	5:4	LED2_SEQ_LENGTH [1:0]	10	LED2 Pulse Sequence Length (when LED2_MODE = Pulsed Sequence) 00 = 1 pulse 01 = 2 pulses 10 = 4 pulses 11 = 7 pulses	
	3:2	LED2_DUR [1:0]	01	LED2 On time (when LED2_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1 second 01 = 250ms 10 = 125ms 11 = 62.5ms	
	1:0	LED2_DUTY_CYC [1:0]	10	LED2 Duty Cycle (On:Off ratio) (when LED2_MODE = Continuous Pulsed or Pulsed Sequence) 00 = 1:1 (50% on) 01 = 1:2 (33.3% on) 10 = 1:3 (25% on) 11 = 1:7 (12.5% on)	

Register 404Dh Status LED 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16464 (4050h) DCDC Enable	7	EPE2_ENA	0	EPE2 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in EPE2_STS)	
	6	EPE1_ENA	0	EPE1 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in EPE1_STS)	
	3	DC4_ENA	0	DC-DC4 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in DC4_STS)	
	2	DC3_ENA	0	DC-DC3 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in DC3_STS)	
	1	DC2_ENA	0	DC-DC2 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in DC2_STS)	
	0	DC1_ENA	0	DC_DC1 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in DC1_STS)	

Register 4050h DCDC Enable

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16465 (4051h) LDO Enable	10	LDO11_ENA	0	LDO11 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO11_STS)	
	9	LDO10_ENA	0	LDO10 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO10_STS)	
	8	LDO9_ENA	0	LDO9 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO9_STS)	
	7	LDO8_ENA	0	LDO8 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO8_STS)	
	6	LDO7_ENA	0	LDO7 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO7_STS)	
	5	LDO6_ENA	0	LDO6 Enable request 0 = Disabled 1 = Enabled	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				(Note that the actual status is indicated in LDO6_STS)	
	4	LDO5_ENA	0	LDO5 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO5_STS)	
	3	LDO4_ENA	0	LDO4 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO4_STS)	
	2	LDO3_ENA	0	LDO3 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO3_STS)	
	1	LDO2_ENA	0	LDO2 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO2_STS)	
	0	LDO1_ENA	0	LDO1 Enable request 0 = Disabled 1 = Enabled (Note that the actual status is indicated in LDO1_STS)	

Register 4051h LDO Enable

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16466 (4052h) DCDC Status	7	EPE2_STS	0	EPE2 Status 0 = Disabled 1 = Enabled	
	6	EPE1_STS	0	EPE1 Status 0 = Disabled 1 = Enabled	
	3	DC4_STS	0	DC-DC4 Status 0 = Disabled 1 = Enabled	
	2	DC3_STS	0	DC-DC3 Status 0 = Disabled 1 = Enabled	
	1	DC2_STS	0	DC-DC2 Status 0 = Disabled 1 = Enabled	
	0	DC1_STS	0	DC-DC1 Status 0 = Disabled 1 = Enabled	

Register 4052h DCDC Status

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16467 (4053h) LDO Status	10	LDO11_STS	0	LDO11 Status 0 = Disabled 1 = Enabled	
	9	LDO10_STS	0	LDO10 Status 0 = Disabled 1 = Enabled	
	8	LDO9_STS	0	LDO9 Status 0 = Disabled 1 = Enabled	
	7	LDO8_STS	0	LDO8 Status 0 = Disabled 1 = Enabled	
	6	LDO7_STS	0	LDO7 Status 0 = Disabled 1 = Enabled	
	5	LDO6_STS	0	LDO6 Status 0 = Disabled 1 = Enabled	
	4	LDO5_STS	0	LDO5 Status 0 = Disabled 1 = Enabled	
	3	LDO4_STS	0	LDO4 Status 0 = Disabled 1 = Enabled	
	2	LDO3_STS	0	LDO3 Status 0 = Disabled 1 = Enabled	
	1	LDO2_STS	0	LDO2 Status 0 = Disabled 1 = Enabled	
	0	LDO1_STS	0	LDO1 Status 0 = Disabled 1 = Enabled	

Register 4053h LDO Status

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16468 (4054h) DCDC UV Status	13	DC2_OV_STS	0	DC-DC2 Overvoltage Status 0 = Normal 1 = Overvoltage	
	12	DC1_OV_STS	0	DC-DC1 Overvoltage Status 0 = Normal 1 = Overvoltage	
	9	DC2_HC_STS	0	DC-DC2 High Current Status 0 = Normal 1 = High Current	
	8	DC1_HC_STS	0	DC-DC1 High Current Status 0 = Normal 1 = High Current	
	3	DC4_UV_STS	0	DC-DC4 Undervoltage Status 0 = Normal	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				1 = Undervoltage	
	2	DC3_UV_STS	0	DC-DC3 Undervoltage Status 0 = Normal 1 = Undervoltage	
	1	DC2_UV_STS	0	DC-DC2 Undervoltage Status 0 = Normal 1 = Undervoltage	
	0	DC1_UV_STS	0	DC-DC1 Undervoltage Status 0 = Normal 1 = Undervoltage	

Register 4054h DCDC UV Status

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16469 (4055h) LDO UV Status	15	INTLDO_UV_STS	0	LDO13 (Internal LDO) Undervoltage Status 0 = Normal 1 = Undervoltage	
	9	LDO10_UV_STS	0	LDO10 Undervoltage Status 0 = Normal 1 = Undervoltage	
	8	LDO9_UV_STS	0	LDO9 Undervoltage Status 0 = Normal 1 = Undervoltage	
	7	LDO8_UV_STS	0	LDO8 Undervoltage Status 0 = Normal 1 = Undervoltage	
	6	LDO7_UV_STS	0	LDO7 Undervoltage Status 0 = Normal 1 = Undervoltage	
	5	LDO6_UV_STS	0	LDO6 Undervoltage Status 0 = Normal 1 = Undervoltage	
	4	LDO5_UV_STS	0	LDO5 Undervoltage Status 0 = Normal 1 = Undervoltage	
	3	LDO4_UV_STS	0	LDO4 Undervoltage Status 0 = Normal 1 = Undervoltage	
	2	LDO3_UV_STS	0	LDO3 Undervoltage Status 0 = Normal 1 = Undervoltage	
	1	LDO2_UV_STS	0	LDO2 Undervoltage Status 0 = Normal 1 = Undervoltage	
	0	LDO1_UV_STS	0	LDO1 Undervoltage Status 0 = Normal 1 = Undervoltage	

Register 4055h LDO UV Status

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16470 (4056h) DC1 Control 1	15:14	DC1_RATE [1:0]	10	DC-DC1 Voltage Ramp rate 00 = 1 step every 32us 01 = 1 step every 16us 10 = 1 step every 8us 11 = Immediate voltage change	
	12	DC1_PHASE	0	DC-DC1 Clock Phase Control 0 = Normal 1 = Inverted	
	9:8	DC1_FREQ [1:0]	00	DC-DC1 Switching Frequency 00 = Reserved 01 = 2.0MHz (2.2uH output inductor) 10 = 4.0MHz (1uH output inductor) 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	7	DC1_FLT	0	DC-DC1 Output float 0 = DC-DC1 output discharged when disabled 1 = DC-DC1 output floating when disabled	
	5:4	DC1_SOFT_START [1:0]	00	DC-DC1 Soft-Start Control (Duration in each of the 8 startup current limiting steps.) 00 = 32us steps 01 = 64us steps 10 = 128us steps 11 = 256us steps	
	1:0	DC1_CAP [1:0]	00	DC-DC1 Output Capacitor 00 = Reserved 01 = Reserved 10 = 22uF to 47uF 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	

Register 4056h DC1 Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16471 (4057h) DC1 Control 2	15:14	DC1_ERR_ACTION [1:0]	00	DC-DC1 Error Action (Undervoltage) 00 = Ignore 01 = Shut down converter 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	DC1_HWC_SOURCE [1:0]	00	DC-DC1 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	DC1_HWC_VSEL	0	DC-DC1 Hardware Control Voltage select 0 = Set by DC1_ON_VSEL 1 = Set by DC1_SLP_VSEL	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	9:8	DC1_HWC_MODE [1:0]	11	DC-DC1 Hardware Control Operating Mode 00 = Forced Continuous Conduction Mode 01 = Disabled 10 = LDO Mode 11 = Hysteretic Mode	
	6:4	DC1_HC_THR [2:0]	000	DC-DC1 High Current threshold 000 = 250mA 001 = 500mA 010 = 750mA 011 = 1000mA 100 = 1250mA 101 = 1500mA 110 = 1750mA 111 = 2000mA	
	0	DC1_HC_IND_ENA	0	DC-DC1 High Current detect enable 0 = Disabled 1 = Enabled	

Register 4057h DC1 Control 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16472 (4058h) DC1 ON Config	15:13	DC1_ON_SLOT [2:0]	000	DC-DC1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	9:8	DC1_ON_MODE [1:0]	01	DC-DC1 ON Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:2	DC1_ON_VSEL [6:2]	0_0000	DC-DC1 ON Voltage select DC1_ON_VSEL [6:0] selects the DC-DC1 output voltage from 0.6V to 1.8V in 12.5mV steps. DC1_ON_VSEL [6:2] also exist in ICE/OTP memory, controlling the voltage in 50mV steps. DC1_ON_VSEL [6:0] is coded as follows: 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	1:0	DC1_ON_VSEL [1:0]	00	DC-DC1 ON Voltage select DC1_ON_VSEL [6:0] selects the DC-DC1 output voltage from 0.6V to 1.8V in 12.5mV steps. See DC1_ON_VSEL [6:2] for definition.	

Register 4058h DC1 ON Config

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16473 (4059h) DC1 SLEEP Control	15:13	DC1_SLP_SLOT [2:0]	000	DC-DC1 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If DC-DC1 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the converter enters its SLEEP condition.	
	9:8	DC1_SLP_MODE [1:0]	11	DC-DC1 SLEEP Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:0	DC1_SLP_VSEL [6:0]	000_0000	DC-DC1 SLEEP Voltage select 0.6V to 1.8V in 12.5mV steps 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	

Register 4059h DC1 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16474 (405Ah) DC1 DVS Control	12:11	DC1_DVS_SRC [1:0]	00	DC-DC1 DVS Control Source 00 = Disabled 01 = Enabled 10 = Controlled by Hardware DVS1 11 = Controlled by Hardware DVS2	
	6:0	DC1_DVS_VSEL [6:0]	000_0000	DC-DC1 DVS Voltage select 0.6V to 1.8V in 12.5mV steps 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	

Register 405Ah DC1 DVS Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16475 (405Bh) DC2 Control 1	15:14	DC2_RATE [1:0]	10	DC-DC2 Voltage Ramp rate 00 = 1 step every 32us 01 = 1 step every 16us 10 = 1 step every 8us 11 = Immediate voltage change	
	12	DC2_PHASE	1	DC-DC2 Clock Phase Control 0 = Normal 1 = Inverted	
	9:8	DC2_FREQ [1:0]	00	DC-DC2 Switching Frequency 00 = Reserved 01 = 2.0MHz (2.2uH output inductor) 10 = 4.0MHz (1uH output inductor) 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	7	DC2_FLT	0	DC-DC2 Output float 0 = DC-DC2 output discharged when disabled 1 = DC-DC2 output floating when disabled	
	5:4	DC2_SOFT_START [1:0]	00	DC-DC2 Soft-Start Control (Duration in each of the 8 startup current limiting steps.) 00 = 32us steps 01 = 64us steps 10 = 128us steps 11 = 256us steps	
	1:0	DC2_CAP [1:0]	00	DC-DC2 Output Capacitor 00 = Reserved 01 = Reserved 10 = 22uF to 47uF 11 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	

Register 405Bh DC2 Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16476 (405Ch) DC2 Control 2	15:14	DC2_ERR_ACT [1:0]	00	DC-DC2 Error Action (Undervoltage) 00 = Ignore 01 = Shut down converter 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	DC2_HWC_SRC [1:0]	00	DC-DC2 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	DC2_HWC_VSEL	0	DC-DC2 Hardware Control Voltage select 0 = Set by DC2_ON_VSEL 1 = Set by DC2_SLP_VSEL	
	9:8	DC2_HWC_MODE [1:0]	11	DC-DC2 Hardware Control Operating Mode 00 = Forced Continuous Conduction Mode 01 = Disabled 10 = LDO Mode 11 = Hysteretic Mode	
	6:4	DC2_HC_THR [2:0]	000	DC-DC2 High Current threshold 000 = 250mA 001 = 500mA 010 = 750mA 011 = 1000mA 100 = 1250mA 101 = 1500mA 110 = 1750mA 111 = 2000mA	
	0	DC2_HC_IND_ENA	0	DC-DC2 High Current detect enable 0 = Disabled 1 = Enabled	

Register 405Ch DC2 Control 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16477 (405Dh) DC2 ON Config	15:13	DC2_ON_SLOT [2:0]	000	DC-DC2 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	9:8	DC2_ON_MODE [1:0]	01	DC-DC2 ON Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:2	DC2_ON_VSEL [6:2]	0_0000	DC-DC2 ON Voltage select DC2_ON_VSEL [6:0] selects the DC-DC2 output voltage from 0.6V to 1.8V in 12.5mV steps. DC2_ON_VSEL [6:2] also exist in ICE/OTP memory, controlling the voltage in 50mV steps. DC2_ON_VSEL [6:0] is coded as follows: 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	
	1:0	DC2_ON_VSEL [1:0]	00	DC-DC2 ON Voltage select DC2_ON_VSEL [6:0] selects the DC-DC2 output voltage from 0.6V to 1.8V in 12.5mV steps. See DC2_ON_VSEL [6:2] for definition.	

Register 405Dh DC2 ON Config

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16478 (405Eh) DC2 SLEEP Control	15:13	DC2_SLP_SLOT [2:0]	000	DC-DC2 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If DC-DC2 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the converter enters its SLEEP condition.	
	9:8	DC2_SLP_MODE [1:0]	11	DC-DC2 SLEEP Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:0	DC2_SLP_VOLTAGE [6:0]	000_0000	DC-DC2 SLEEP Voltage select 0.6V to 1.8V in 12.5mV steps 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	

Register 405Eh DC2 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16479 (405Fh) DC2 DVS Control	12:11	DC2_DVS_SOURCE [1:0]	00	DC-DC2 DVS Control Source 00 = Disabled 01 = Enabled 10 = Controlled by Hardware DVS1 11 = Controlled by Hardware DVS2	
	6:0	DC2_DVS_VOLTAGE [6:0]	000_0000	DC-DC2 DVS Voltage select 0.6V to 1.8V in 12.5mV steps 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	

Register 405Fh DC2 DVS Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16480 (4060h) DC3 Control 1	12	DC3_PHASE	0	DC-DC3 Clock Phase Control 0 = Normal 1 = Inverted	
	7	DC3_FLT	0	DC-DC3 Output float 0 = DC-DC3 output discharged when disabled 1 = DC-DC3 output floating when disabled	
	5:4	DC3_SOFT_START [1:0]	01	DC-DC3 Soft-Start Control (Duration in each of the 3 intermediate startup current limiting steps.) 00 = Immediate start-up 01 = 512us steps 10 = 4.096ms steps 11 = 32.768ms steps	
	3:2	DC3_STNBY_LIM [1:0]	01	DC-DC3 Current Limit Sets the maximum DC output current in Hysteretic Mode. 00 = 50mA 01 = 100mA 10 = 200mA 11 = 400mA <i>Protected by security key.</i>	
	1:0	DC3_CAP [1:0]	00	DC-DC3 Output Capacitor 00 = 10uF to 20uF 01 = 10uF to 20uF 10 = 22uF to 45uF 11 = 47uF to 100uF This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	

Register 4060h DC3 Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16481 (4061h) DC3 Control 2	15:14	DC3_ERR_ACTION [1:0]	00	DC-DC3 Error Action (Undervoltage) 00 = Ignore 01 = Shut down converter 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	DC3_HWC_SOURCE [1:0]	00	DC-DC3 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	10	DC3_HWC_VSEL	0	DC-DC3 Hardware Control Voltage select 0 = Set by DC3_ON_VSEL 1 = Set by DC3_SLP_VSEL	
	9:8	DC3_HWC_MODE [1:0]	11	DC-DC3 Hardware Control Operating Mode 00 = Forced Continuous Conduction Mode 01 = Disabled 10 = LDO Mode 11 = Hysteretic Mode	
	7	DC3_OVP	0	DC-DC3 Overvoltage Protection 0 = Disabled 1 = Enabled	

Register 4061h DC3 Control 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16482 (4062h) DC3 ON Config	15:13	DC3_ON_SLOT [2:0]	000	DC-DC3 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	9:8	DC3_ON_MODE [1:0]	01	DC-DC3 ON Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:2	DC3_ON_VSEL [6:2]	0_0000	DC-DC3 ON Voltage select DC3_ON_VSEL [6:0] selects the DC-DC3 output voltage from 0.85V to 3.4V in 25mV steps. DC3_ON_VSEL [6:2] also exist in ICE/OTP memory, controlling the voltage in 100mV steps. DC3_ON_VSEL [6:0] is coded as follows: 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V	
	1:0	DC3_ON_VSEL [1:0]	00	DC-DC3 ON Voltage select DC3_ON_VSEL [6:0] selects the DC-DC3 output voltage from 0.85V to 3.4V in 25mV steps. See DC3_ON_VSEL [6:2] for definition.	

Register 4062h DC3 ON Config

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16483 (4063h) DC3 SLEEP Control	15:13	DC3_SLP_SLOT [2:0]	000	DC-DC3 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If DC-DC3 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the converter enters its SLEEP condition.	
	9:8	DC3_SLP_MODE [1:0]	11	DC-DC3 SLEEP Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:0	DC3_SLP_VOLTAGE [6:0]	000_0000	DC-DC3 SLEEP Voltage select 0.85V to 3.4V in 25mV steps 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V	

Register 4063h DC3 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16484 (4064h) DC4 Control 1	13	DC4_SLV	0	DC-DC4 Slave Mode select 0 = Disabled 1 = Enabled DC4_SLV = 1, then DC-DC4 is a slave to DC-DC3, and both converters are controlled by the DC-DC3 registers. This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	12	DC4_PHASE	0	DC-DC4 Clock Phase Control 0 = Normal 1 = Inverted	
	7	DC4_FLT	0	DC-DC4 Output float 0 = DC-DC4 output discharged when disabled 1 = DC-DC4 output floating when disabled	
	5:4	DC4_SOFT_START [1:0]	01	DC-DC4 Soft-Start Control (Duration in each of the 3 intermediate startup current limiting steps.) 00 = Immediate start-up 01 = 512us steps 10 = 4.096ms steps	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				11 = 32.768ms steps	
	3:2	DC4_STNBY_LIM [1:0]	01	DC-DC4 Current Limit Sets the maximum DC output current in Hysteretic Mode. 00 = 50mA 01 = 100mA 10 = 200mA 11 = 400mA <i>Protected by security key.</i>	
	1:0	DC4_CAP [1:0]	00	DC-DC4 Output Capacitor 00 = 10uF to 20uF 01 = 10uF to 20uF 10 = 22uF to 45uF 11 = 47uF to 100uF This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	

Register 4064h DC4 Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16485 (4065h) DC4 Control 2	15:14	DC4_ERR_ACT [1:0]	00	DC-DC4 Error Action (Undervoltage) 00 = Ignore 01 = Shut down converter 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	DC4_HWC_SRC [1:0]	00	DC-DC4 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	DC4_HWC_VSEL	0	DC-DC4 Hardware Control Voltage select 0 = Set by DC4_ON_VSEL 1 = Set by DC4_SLP_VSEL	
	9:8	DC4_HWC_MODE [1:0]	11	DC-DC4 Hardware Control Operating Mode 00 = Forced Continuous Conduction Mode 01 = Disabled 10 = LDO Mode 11 = Hysteretic Mode	
	7	DC4_OVP	0	DC-DC4 Overvoltage Protection 0 = Disabled 1 = Enabled	

Register 4065h DC4 Control 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16486 (4066h) DC4 ON Config	15:13	DC4_ON_SLO T [2:0]	000	DC-DC4 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	9:8	DC4_ON_MOD E [1:0]	01	DC-DC4 ON Operating Mode 00 = Forced Continuous Conduction Mode 01 = Auto Mode (Continuous / Discontinuous Conduction with Pulse-Skipping) 10 = LDO Mode 11 = Hysteretic Mode	
	6:2	DC4_ON_VSEL L [6:2]	0_0000	DC-DC4 ON Voltage select DC4_ON_VSEL [6:0] selects the DC-DC4 output voltage from 0.85V to 3.4V in 25mV steps. DC4_ON_VSEL [6:2] also exist in ICE/OTP memory, controlling the voltage in 100mV steps. DC4_ON_VSEL [6:0] is coded as follows: 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V	
	1:0	DC4_ON_VSEL L [1:0]	00	DC-DC4 ON Voltage select DC4_ON_VSEL [6:0] selects the DC-DC4 output voltage from 0.85V to 3.4V in 25mV steps. See DC4_ON_VSEL [6:2] for definition.	

Register 4066h DC4 ON Config

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16487 (4067h) DC4 SLEEP Control	15:13	DC4_SLP_SLO T [2:0]	000	DC-DC4 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If DC-DC4 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the converter enters its SLEEP condition.	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	9:8	DC4_SLP_MODE [1:0]	11	DC-DC4 SLEEP Operating Mode 00 = Forced Continuous Conduction Mode 01 = Continuous / Discontinuous Conduction with Pulse-Skipping 10 = LDO Mode 11 = Hysteretic Mode	
	6:0	DC4_SLP_VSEL [6:0]	000_0000	DC-DC4 SLEEP Voltage select 0.85V to 3.4V in 25mV steps 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V	

Register 4067h DC4 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16488 (4068h) LDO1 Control	15:14	LDO1_ERR_ACT [1:0]	00	LDO1 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO1_HWC_SRC [1:0]	00	LDO1 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO1_HWC_VSEL	0	LDO1 Hardware Control Voltage select 0 = Set by LDO1_ON_VSEL 1 = Set by LDO1_SLP_VSEL	
	9:8	LDO1_HWC_MODE [1:0]	10	LDO1 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO1_ON_MODE	
	7	LDO1_FLT	0	LDO1 Output float 0 = LDO1 output discharged when disabled 1 = LDO1 output floating when disabled	
	6	LDO1_SWI	0	LDO1 Switch Mode 0 = LDO mode 1 = Switch mode	
	0	LDO1_LP_MODE	0	LDO1 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.	

Register 4068h LDO1 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16489 (4069h) LDO1 ON Control	15:13	LDO1_ON_SLOT [2:0]	000	LDO1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO1_ON_MODE	0	LDO1 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO1_ON_VOLTAGE_SELECT [4:0]	0_0000	LDO1 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4069h LDO1 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16490 (406Ah) LDO1 SLEEP Control	15:13	LDO1_SLP_SLOT [2:0]	000	LDO1 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO1 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO1_SLP_MODE	1	LDO1 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO1_SLP_VOLTAGE_SELECT [4:0]	0_0000	LDO1 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ...	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 406Ah LDO1 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16491 (406Bh) LDO2 Control	15:14	LDO2_ERR_A CT [1:0]	00	LDO2 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO2_HWC_S RC [1:0]	00	LDO2 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO2_HWC_V SEL	0	LDO2 Hardware Control Voltage select 0 = Set by LDO2_ON_VSEL 1 = Set by LDO2_SLP_VSEL	
	9:8	LDO2_HWC_M ODE [1:0]	10	LDO2 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO2_ON_MODE	
	7	LDO2_FLT	0	LDO2 Output float 0 = LDO2 output discharged when disabled 1 = LDO2 output floating when disabled	
	6	LDO2_SWI	0	LDO2 Switch Mode 0 = LDO mode 1 = Switch mode	
	0	LDO2_LP_MO DE	0	LDO2 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.	

Register 406Bh LDO2 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16492 (406Ch) LDO2 ON Control	15:13	LDO2_ON_SLOT [2:0]	000	LDO2 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO2_ON_MODE	0	LDO2 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO2_ON_VOLTAGE [4:0]	0_0000	LDO2 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 406Ch LDO2 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16493 (406Dh) LDO2 SLEEP Control	15:13	LDO2_SLP_SLOT [2:0]	000	LDO2 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO2 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO2_SLP_MODE	1	LDO2 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO2_SLP_VSEL [4:0]	0_0000	LDO2 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 406Dh LDO2 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16494 (406Eh) LDO3 Control	15:14	LDO3_ERR_ACT [1:0]	00	LDO3 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO3_HWC_SRC [1:0]	00	LDO3 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO3_HWC_VSEL	0	LDO3 Hardware Control Voltage select 0 = Set by LDO3_ON_VSEL 1 = Set by LDO3_SLP_VSEL	
	9:8	LDO3_HWC_MODE [1:0]	10	LDO3 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO3_ON_MODE	
	7	LDO3_FLT	0	LDO3 Output float 0 = LDO3 output discharged when disabled 1 = LDO3 output floating when disabled	
	6	LDO3_SWI	0	LDO3 Switch Mode 0 = LDO mode 1 = Switch mode	
	0	LDO3_LP_MODE	0	LDO3 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.	

Register 406Eh LDO3 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16495 (406Fh) LDO3 ON Control	15:13	LDO3_ON_SLOT [2:0]	000	LDO3 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO3_ON_MODE	0	LDO3 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO3_ON_VOLTAGE [4:0]	0_0000	LDO3 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 406Fh LDO3 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16496 (4070h) LDO3 SLEEP Control	15:13	LDO3_SLP_SLOT [2:0]	000	LDO3 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO3 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO3_SLP_MODE	1	LDO3 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO3_SLP_VSEL [4:0]	0_0000	LDO3 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4070h LDO3 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16497 (4071h) LDO4 Control	15:14	LDO4_ERR_ACT [1:0]	00	LDO4 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO4_HWC_SRC [1:0]	00	LDO4 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO4_HWC_VSEL	0	LDO4 Hardware Control Voltage select 0 = Set by LDO4_ON_VSEL 1 = Set by LDO4_SLP_VSEL	
	9:8	LDO4_HWC_MODE [1:0]	10	LDO4 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO4_ON_MODE	
	7	LDO4_FLT	0	LDO4 Output float 0 = LDO4 output discharged when disabled 1 = LDO4 output floating when disabled	
	6	LDO4_SWI	0	LDO4 Switch Mode 0 = LDO mode 1 = Switch mode	
	0	LDO4_LP_MODE	0	LDO4 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.	

Register 4071h LDO4 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16498 (4072h) LDO4 ON Control	15:13	LDO4_ON_SLOT [2:0]	000	LDO4 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO4_ON_MODE	0	LDO4 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO4_ON_VOLTAGE [4:0]	0_0000	LDO4 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4072h LDO4 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16499 (4073h) LDO4 SLEEP Control	15:13	LDO4_SLP_SLOT [2:0]	000	LDO4 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO4 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO4_SLP_MODE	1	LDO4 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO4_SLP_VSEL [4:0]	0_0000	LDO4 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4073h LDO4 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16500 (4074h) LDO5 Control	15:14	LDO5_ERR_ACT [1:0]	00	LDO5 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO5_HWC_SRC [1:0]	00	LDO5 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO5_HWC_VSEL	0	LDO5 Hardware Control Voltage select 0 = Set by LDO5_ON_VSEL 1 = Set by LDO5_SLP_VSEL	
	9:8	LDO5_HWC_MODE [1:0]	10	LDO5 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO5_ON_MODE	
	7	LDO5_FLT	0	LDO5 Output float 0 = LDO5 output discharged when disabled 1 = LDO5 output floating when disabled	
	6	LDO5_SWI	0	LDO5 Switch Mode 0 = LDO mode 1 = Switch mode	
	0	LDO5_LP_MODE	0	LDO5 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.	

Register 4074h LDO5 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16501 (4075h) LDO5 ON Control	15:13	LDO5_ON_SLOT [2:0]	000	LDO5 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO5_ON_MODE	0	LDO5 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO5_ON_VOLTAGE [4:0]	0_0000	LDO5 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4075h LDO5 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16502 (4076h) LDO5 SLEEP Control	15:13	LDO5_SLP_SLOT [2:0]	000	LDO5 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO5 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO5_SLP_MODE	1	LDO5 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO5_SLP_VSEL [4:0]	0_0000	LDO5 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4076h LDO5 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16503 (4077h) LDO6 Control	15:14	LDO6_ERR_ACT [1:0]	00	LDO6 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO6_HWC_SRC [1:0]	00	LDO6 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO6_HWC_VSEL	0	LDO6 Hardware Control Voltage select 0 = Set by LDO6_ON_VSEL 1 = Set by LDO6_SLP_VSEL	
	9:8	LDO6_HWC_MODE [1:0]	10	LDO6 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO6_ON_MODE	
	7	LDO6_FLT	0	LDO6 Output float 0 = LDO6 output discharged when disabled 1 = LDO6 output floating when disabled	
	6	LDO6_SWI	0	LDO6 Switch Mode 0 = LDO mode 1 = Switch mode	
	0	LDO6_LP_MODE	0	LDO6 Low Power Mode Select 0 = 50mA (reduced quiescent current) 1 = 20mA (minimum quiescent current) Selects which Low Power mode is used in ON, SLEEP, or under HWC modes.	

Register 4077h LDO6 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16504 (4078h) LDO6 ON Control	15:13	LDO6_ON_SLOT [2:0]	000	LDO6 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO6_ON_MODE	0	LDO6 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO6_ON_VOLTAGE [4:0]	0_0000	LDO6 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4078h LDO6 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16505 (4079h) LDO6 SLEEP Control	15:13	LDO6_SLP_SLOT [2:0]	000	LDO6 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO6 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO6_SLP_MODE	1	LDO6 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO6_SLP_VSEL [4:0]	0_0000	LDO6 SLEEP Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 4079h LDO6 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16506 (407Ah) LDO7 Control	15:14	LDO7_ERR_ACT [1:0]	00	LDO7 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO7_HWC_SRC [1:0]	00	LDO7 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO7_HWC_VSEL	0	LDO7 Hardware Control Voltage select 0 = Set by LDO7_ON_VSEL 1 = Set by LDO7_SLP_VSEL	
	9:8	LDO7_HWC_MODE [1:0]	10	LDO7 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO7_ON_MODE	
	7	LDO7_FLT	0	LDO7 Output float 0 = LDO7 output discharged when disabled 1 = LDO7 output floating when disabled	
	6	LDO7_SWI	0	LDO7 Switch Mode 0 = LDO mode 1 = Switch mode	

Register 407Ah LDO7 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16507 (407Bh) LDO7 ON Control	15:13	LDO7_ON_SLOT [2:0]	000	LDO7 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO7_ON_MODE	0	LDO7 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO7_ON_VOLTAGE [4:0]	0_0000	LDO7 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 407Bh LDO7 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16508 (407Ch) LDO7 SLEEP Control	15:13	LDO7_SLP_SLOT [2:0]	000	LDO7 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO7 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO7_SLP_MODE	1	LDO7 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO7_SLP_VSEL [4:0]	0_0000	LDO7 SLEEP Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 407Ch LDO7 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16509 (407Dh) LDO8 Control	15:14	LDO8_ERR_ACT [1:0]	00	LDO8 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO8_HWC_SRC [1:0]	00	LDO8 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO8_HWC_VSEL	0	LDO8 Hardware Control Voltage select 0 = Set by LDO8_ON_VSEL 1 = Set by LDO8_SLP_VSEL	
	9:8	LDO8_HWC_MODE [1:0]	10	LDO8 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO8_ON_MODE	
	7	LDO8_FLT	0	LDO8 Output float 0 = LDO8 output discharged when disabled 1 = LDO8 output floating when disabled	
	6	LDO8_SWI	0	LDO8 Switch Mode 0 = LDO mode 1 = Switch mode	

Register 407Dh LDO8 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16510 (407Eh) LDO8 ON Control	15:13	LDO8_ON_SLOT [2:0]	000	LDO8 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO8_ON_MODE	0	LDO8 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO8_ON_VOLTAGE [4:0]	0_0000	LDO8 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 407Eh LDO8 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16511 (407Fh) LDO8 SLEEP Control	15:13	LDO8_SLP_SLOT [2:0]	000	LDO8 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO8 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO8_SLP_MODE	1	LDO8 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO8_SLP_VSEL [4:0]	0_0000	LDO8 SLEEP Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 407Fh LDO8 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16512 (4080h) LDO9 Control	15:14	LDO9_ERR_ACT [1:0]	00	LDO9 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO9_HWC_SRC [1:0]	00	LDO9 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO9_HWC_VSEL	0	LDO9 Hardware Control Voltage select 0 = Set by LDO9_ON_VSEL 1 = Set by LDO9_SLP_VSEL	
	9:8	LDO9_HWC_MODE [1:0]	10	LDO9 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO9_ON_MODE	
	7	LDO9_FLT	0	LDO9 Output float 0 = LDO9 output discharged when disabled 1 = LDO9 output floating when disabled	
	6	LDO9_SWI	0	LDO9 Switch Mode 0 = LDO mode 1 = Switch mode	

Register 4080h LDO9 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16513 (4081h) LDO9 ON Control	15:13	LDO9_ON_SLOT [2:0]	000	LDO9 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO9_ON_MODE	0	LDO9 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO9_ON_VOLTAGE [4:0]	0_0000	LDO9 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 4081h LDO9 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16514 (4082h) LDO9 SLEEP Control	15:13	LDO9_SLP_SLOT [2:0]	000	LDO9 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO9 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO9_SLP_MODE	1	LDO9 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO9_SLP_VSEL [4:0]	0_0000	LDO9 SLEEP Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 4082h LDO9 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16515 (4083h) LDO10 Control	15:14	LDO10_ERR_ACT [1:0]	00	LDO10 Error Action (Undervoltage) 00 = Ignore 01 = Shut down regulator 10 = Shut down system (Device Reset) 11 = Reserved Note that an Interrupt is always raised.	
	12:11	LDO10_HWC_SRC [1:0]	00	LDO10 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	10	LDO10_HWC_VSEL	0	LDO10 Hardware Control Voltage select 0 = Set by LDO10_ON_VSEL 1 = Set by LDO10_SLP_VSEL	
	9:8	LDO10_HWC_MODE [1:0]	10	LDO10 Hardware Control Operating Mode 00 = Low Power mode 01 = Turn converter off 10 = Low Power mode 11 = Set by LDO10_ON_MODE	
	7	LDO10_FLT	0	LDO10 Output float 0 = LDO10 output discharged when disabled 1 = LDO10 output floating when disabled	
	6	LDO10_SWI	0	LDO10 Switch Mode 0 = LDO mode 1 = Switch mode	

Register 4083h LDO10 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16516 (4084h) LDO10 ON Control	15:13	LDO10_ON_SLOT [2:0]	000	LDO10 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	8	LDO10_ON_MODE	0	LDO10 ON Operating Mode 0 = Normal mode 1 = Low Power mode	
	4:0	LDO10_ON_VOLTAGE_SEL [4:0]	0_0000	LDO10 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 4084h LDO10 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16517 (4085h) LDO10 SLEEP Control	15:13	LDO10_SLP_SLOT [2:0]	000	LDO10 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO10 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	8	LDO10_SLP_MODE	1	LDO10 SLEEP Operating Mode 0 = Normal mode 1 = Low Power mode	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	4:0	LDO10_SLP_VSEL [4:0]	0_0000	LDO10 SLEEP Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 4085h LDO10 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16519 (4087h) LDO11 ON Control	15:13	LDO11_ON_SLOT [2:0]	000	LDO11 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12	LDO11_FRCENA	0	LDO11 Force Enable (allows LDO11 to be enabled at all times in the OFF, ON and SLEEP states) 0 = Disabled 1 = Enabled	
	7	LDO11_VSEL_SRC	0	LDO11 Voltage Select source 0 = Normal (LDO11 settings) 1 = Same as DC-DC Converter 1	
	3:0	LDO11_ON_VSEL [3:0]	0000	LDO11 ON Voltage select 0.80V to 1.55V in 50mV steps 0h = 0.80V 1h = 0.85V 2h = 0.90V ... Eh = 1.50V Fh = 1.55V	

Register 4087h LDO11 ON Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16520 (4088h) LDO11 SLEEP Control	15:13	LDO11_SLP_SLOT [2:0]	000	LDO11 SLEEP Slot select 000 = SLEEP voltage / operating mode transition in Timeslot 5 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = SLEEP voltage / operating mode transition in Timeslot 3 111 = SLEEP voltage / operating mode transition in Timeslot 1 If LDO11 is assigned to a Hardware Enable Input, then codes 001-101 select in which timeslot the regulator enters its SLEEP condition.	
	3:0	LDO11_SLP_VSEL [3:0]	0000	LDO11 SLEEP Voltage select 0.80V to 1.55V in 50mV steps 0h = 0.80V 1h = 0.85V 2h = 0.90V ... Eh = 1.50V Fh = 1.55V	

Register 4088h LDO11 SLEEP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16521 (4089h) EPE1 Control	15:13	EPE1_ON_SLOT [2:0]	000	EPE1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:11	EPE1_HWC_SRC [1:0]	00	EPE1 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	8	EPE1_HWCEN A	0	EPE1 Hardware Control Enable 0 = EPE1 is controlled by EPE1_ENA (Hardware Control input(s) are ignored) 1 = EPE1 is controlled by HWC inputs (Hardware Control input(s) force EPE1 to be de-asserted)	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	7:5	EPE1_SLP_SL OT [2:0]	000	EPE1 SLEEP Slot select 000 = No action 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = No action 111 = No action	

Register 4089h EPE1 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16522 (408Ah) EPE2 Control	15:13	EPE2_ON_SL OT [2:0]	000	EPE2 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:11	EPE2_HWC_S RC [1:0]	00	EPE2 Hardware Control Source 00 = Disabled 01 = Hardware Control 1 10 = Hardware Control 2 11 = Hardware Control 1 or 2	
	8	EPE2_HWCEN A	0	EPE2 Hardware Control Enable 0 = EPE2 is controlled by EPE2_ENA (Hardware Control input(s) are ignored) 1 = EPE2 is controlled by HWC inputs (Hardware Control input(s) force EPE2 to be de-asserted)	
	7:5	EPE2_SLP_SL OT [2:0]	000	EPE2 SLEEP Slot select 000 = No action 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = No action 111 = No action	

Register 408Ah EPE2 Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16526 (408Eh) Power Good Source 1	3	DC4_OK	0	DC-DC4 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	2	DC3_OK	1	DC-DC3 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	1	DC2_OK	1	DC-DC2 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	0	DC1_OK	1	DC-DC1 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	

Register 408Eh Power Good Source 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16527 (408Fh) Power Good Source 2	9	LDO10_OK	1	LDO10 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	8	LDO9_OK	1	LDO9 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	7	LDO8_OK	1	LDO8 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	6	LDO7_OK	1	LDO7 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	5	LDO6_OK	1	LDO6 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	4	LDO5_OK	1	LDO5 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	3	LDO4_OK	1	LDO4 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	2	LDO3_OK	1	LDO3 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	1	LDO2_OK	1	LDO2 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	
	0	LDO1_OK	1	LDO1 status selected as an input to PWR_GOOD 0 = Disabled 1 = Enabled	

Register 408Fh Power Good Source 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16528 (4090h) Clock Control 1	15	CLKOUT_ENA	0	CLKOUT output enable 0 = Disabled 1 = Enabled <i>Protected by security key.</i>	
	13	CLKOUT_OD	0	CLKOUT pin configuration 0 = CMOS 1 = Open Drain	
	10:8	CLKOUT_SLOT [2:0]	000	CLKOUT output enable ON slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Do not enable 111 = Do not enable	
	6:4	CLKOUT_SLEEP_SLOT [2:0]	000	CLKOUT output SLEEP slot select 000 = Controlled by CLKOUT_ENA 001 = Disable in Timeslot 5 010 = Disable in Timeslot 4 011 = Disable in Timeslot 3 100 = Disable in Timeslot 2 101 = Disable in Timeslot 1 110 = Controlled by CLKOUT_ENA 111 = Controlled by CLKOUT_ENA	

Register 4090h Clock Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R16529 (4091h) Clock Control 2	15	XTAL_INH	0	Crystal Start-Up Inhibit 0 = Disabled 1 = Enabled When XTAL_INH=0, the internal RC oscillator will provide CLKOUT until the crystal oscillator is valid. When XTAL_INH=1, the 'ON' transition is inhibited until the crystal oscillator is valid.	
	13	XTAL_ENA	0	Crystal Oscillator Enable 0 = Disabled at all times 1 = Enabled in OFF, ON, SLEEP states (Note that the BACKUP behaviour is determined by XTAL_BKUPENA.) This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	12	XTAL_BKUPENA	1	Selects the RTC and 32.768kHz oscillator in BACKUP state 0 = RTC unlocked in BACKUP 1 = RTC maintained in BACKUP (Note that XTAL_ENA must also be set if the RTC is to be maintained in BACKUP)	

Register 4091h Clock Control 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30720 (7800h) Unique ID 1	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 7	

Register 7800h Unique ID 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30721 (7801h) Unique ID 2	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 6	

Register 7801h Unique ID 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30722 (7802h) Unique ID 3	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 5	

Register 7802h Unique ID 3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30723 (7803h) Unique ID 4	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 4	

Register 7803h Unique ID 4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30724 (7804h) Unique ID 5	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 3	

Register 7804h Unique ID 5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30725 (7805h) Unique ID 6	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 2	

Register 7805h Unique ID 6

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30726 (7806h) Unique ID 7	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 1	

Register 7806h Unique ID 7

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30727 (7807h) Unique ID 8	15:0	UNIQUE_ID [15:0]	0000_0000 _0000_000 0	Unique ID, Word 0	

Register 7807h Unique ID 8

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30736 (7810h) Customer OTP ID	15	OTP_AUTO_P ROG	0	If this bit is set when bootstrap data is loaded from ICE (in development mode), then the ICE contents will be programmed in the OTP.	
	14:1	OTP_CUST_ID [13:0]	00_0000_0 000_0000	This field is checked when an 'ON' transition is requested. A non-zero value is used to confirm valid data.	
	0	OTP_CUST_FI NAL	0	If OTP_CUST_FINAL is set in the OTP and also set in the DCRW, then no further Writes are possible to the OTP.	

Register 7810h Customer OTP ID

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30737 (7811h) DC1 OTP Control	15:13	DC2_ON_SLO T [2:0]	000	DC-DC2 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	DC2_ON_VSE L [6:2]	0_0000	DC-DC2 ON Voltage select DC2_ON_VSEL [6:0] selects the DC-DC2 output voltage from 0.6V to 1.8V in 12.5mV steps. DC2_ON_VSEL [6:2] controls the voltage in 50mV steps. DC2_ON_VSEL [6:0] is coded as follows: 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	
	7:5	DC1_ON_SLO T [2:0]	000	DC-DC1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	DC1_ON_VSEL [6:2]	0_0000	DC-DC1 ON Voltage select DC1_ON_VSEL [6:0] selects the DC-DC1 output voltage from 0.6V to 1.8V in 12.5mV steps. DC1_ON_VSEL [6:2] controls the voltage in 50mV steps. DC1_ON_VSEL [6:0] is coded as follows: 00h to 08h = 0.6V 09h = 0.6125V ... 48h = 1.4V (see note) ... 67h = 1.7875V 68h to 7Fh = 1.8V Note - Maximum output voltage selection in 4MHz switching mode is 48h (1.4V).	

Register 7811h DC1 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30738 (7812h) DC2 OTP Control	15:13	DC4_ON_SLOT [2:0]	000	DC-DC4 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	DC4_ON_VSEL [6:2]	0_0000	DC-DC4 ON Voltage select DC4_ON_VSEL [6:0] selects the DC-DC3 output voltage from 0.85V to 3.4V in 25mV steps. DC4_ON_VSEL [6:2] controls the voltage in 100mV steps. DC4_ON_VSEL [6:0] is coded as follows: 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V	
	7:5	DC3_ON_SLOT [2:0]	000	DC-DC3 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	DC3_ON_VSEL [6:2]	0_0000	DC-DC3 ON Voltage select DC3_ON_VSEL [6:0] selects the DC-DC3 output voltage from 0.85V to 3.4V in 25mV steps. DC3_ON_VSEL [6:2] controls the voltage in 100mV steps. DC3_ON_VSEL [6:0] is coded as follows: 00h = 0.85V 01h = 0.875V ... 65h = 3.375V 66h to 7Fh = 3.4V	

Register 7812h DC2 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30739 (7813h) DC3 OTP Control	15	DC4_PHASE	0	DC-DC4 Clock Phase Control 0 = Normal 1 = Inverted	
	14	DC3_PHASE	0	DC-DC3 Clock Phase Control 0 = Normal 1 = Inverted	
	13	DC2_PHASE	1	DC-DC2 Clock Phase Control 0 = Normal 1 = Inverted	
	12	DC1_PHASE	0	DC-DC1 Clock Phase Control 0 = Normal 1 = Inverted	
	11:10	DC4_CAP [1:0]	00	DC-DC4 Output Capacitor 00 = 10uF to 20uF 01 = 10uF to 20uF 10 = 22uF to 45uF 11 = 47uF to 100uF This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	9:8	DC3_CAP [1:0]	00	DC-DC3 Output Capacitor 00 = 10uF to 20uF 01 = 10uF to 20uF 10 = 22uF to 45uF 11 = 47uF to 100uF This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	7:6	DC2_CAP [1:0]	00	DC-DC2 Output Capacitor 00 = Reserved 01 = Reserved 10 = 22uF to 47uF 11 = Reserved This field can only be written to by loading configuration	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				settings from OTP/ICE. In all other cases, this field is Read Only.	
	5:4	DC1_CAP [1:0]	00	DC-DC1 Output Capacitor 00 = Reserved 01 = Reserved 10 = 22uF to 47uF 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	3:2	DC2_FREQ [1:0]	00	DC-DC2 Switching Frequency 00 = Reserved 01 = 2.0MHz (2.2uH output inductor) 10 = 4.0MHz (1uH output inductor) 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	1:0	DC1_FREQ [1:0]	00	DC-DC1 Switching Frequency 00 = Reserved 01 = 2.0MHz (2.2uH output inductor) 10 = 4.0MHz (1uH output inductor) 11 = Reserved This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	

Register 7813h DC3 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30740 (7814h) LDO1/2 OTP Control	15:13	LDO2_ON_SL OT [2:0]	000	LDO2 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	LDO2_ON_VS EL [4:0]	0_0000	LDO2 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	
	7:5	LDO1_ON_SL OT [2:0]	000	LDO1 ON Slot select 000 = Do not enable	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	LDO1_ON_VSEL [4:0]	0_0000	LDO1 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 7814h LDO1/2 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30741 (7815h) LDO3/4 OTP Control	15:13	LDO4_ON_SL OT [2:0]	000	LDO4 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	LDO4_ON_VS EL [4:0]	0_0000	LDO4 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	
	7:5	LDO3_ON_SL OT [2:0]	000	LDO3 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	LDO3_ON_VS EL [4:0]	0_0000	LDO3 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 7815h LDO3/4 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30742 (7816h) LDO5/6 OTP Control	15:13	LDO6_ON_SL OT [2:0]	000	LDO6 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	LDO6_ON_VS EL [4:0]	0_0000	LDO6 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	
	7:5	LDO5_ON_SL OT [2:0]	000	LDO5 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	LDO5_ON_VS EL [4:0]	0_0000	LDO5 ON Voltage select 0.9V to 1.6V in 50mV steps 1.7V to 3.3V in 100mV steps 00h = 0.90V 01h = 0.95V ... 0Eh = 1.60V 0Fh = 1.70V ... 1Eh = 3.20V 1Fh = 3.30V	

Register 7816h LDO5/6 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30743 (7817h) LDO7/8 OTP Control	15:13	LDO8_ON_SL OT [2:0]	000	LDO8 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	LDO8_ON_VS EL [4:0]	0_0000	LDO8 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	
	7:5	LDO7_ON_SL OT [2:0]	000	LDO7 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	LDO7_ON_VS EL [4:0]	0_0000	LDO7 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 7817h LDO7/8 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30744 (7818h) LDO9/10 OTP Control	15:13	LDO10_ON_SL OT [2:0]	000	LDO10 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	12:8	LDO10_ON_V SEL [4:0]	0_0000	LDO10 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	
	7:5	LDO9_ON_SL OT [2:0]	000	LDO9 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:0	LDO9_ON_VS EL [4:0]	0_0000	LDO9 ON Voltage select 1.0V to 1.6V in 50mV steps 1.7V to 3.5V in 100mV steps 00h = 1.00V 01h = 1.05V 02h = 1.10V ... 0Ch = 1.60V 0Dh = 1.70V ... 1Eh = 3.40V 1Fh = 3.50V	

Register 7818h LDO9/10 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30745 (7819h) LDO11/EPE Control	15:13	LDO11_ON_SLOT [2:0]	000	LDO11 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	11:8	LDO11_ON_VOLTAGE_SEL [3:0]	0000	LDO11 ON Voltage select 0.80V to 1.55V in 50mV steps 0h = 0.80V 1h = 0.85V 2h = 0.90V ... Eh = 1.50V Fh = 1.55V	
	7:5	EPE2_ON_SLOT [2:0]	000	EPE2 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	4:2	EPE1_ON_SLOT [2:0]	000	EPE1 ON Slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Controlled by Hardware Enable 1 111 = Controlled by Hardware Enable 2	
	0	DC4_SLV	0	DC-DC4 Slave Mode select 0 = Disabled 1 = Enabled DC4_SLV = 1, then DC-DC4 is a slave to DC-DC3, and both converters are controlled by the DC-DC3 registers. This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	

Register 7819h LDO11/EPE Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30746 (781Ah) GPIO1 OTP Control	15	GP1_DIR	1	GPIO1 pin direction 0 = Output 1 = Input	
	14:13	GP1_PULL [1:0]	01	GPIO1 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP1_INT_MODE	0	GPIO1 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP1_POL=1) or falling edge triggered (if GP1_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP1_PWR_DOMAIN	0	GPIO1 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP1_POL	1	GPIO1 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP1_OD	0	GPIO1 Output pin configuration 0 = CMOS 1 = Open Drain	
	8	GP1_ENA	0	GPIO1 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	7:4	GP1_FN [3:0]	0000	GPIO1 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	
	2	XTAL_ENA	0	Crystal Oscillator Enable 0 = Disabled at all times 1 = Enabled in OFF, ON, SLEEP states (Note that the BACKUP behaviour is determined by XTAL_BKUPENA.) This field can only be written to by loading configuration settings from OTP/ICE. In all other cases, this field is Read Only.	
	1	XTAL_INH	0	Crystal Start-Up Inhibit 0 = Disabled 1 = Enabled When XTAL_INH=0, the internal RC oscillator will provide CLKOUT until the crystal oscillator is valid. When XTAL_INH=1, the 'ON' transition is inhibited until the crystal oscillator is valid.	

Register 781Ah GPIO1 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30747 (781Bh) GPIO2 OTP Control	15	GP2_DIR	1	GPIO2 pin direction 0 = Output 1 = Input	
	14:13	GP2_PULL [1:0]	01	GPIO2 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP2_INT_MODE	0	GPIO2 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP2_POL=1) or falling edge triggered (if GP2_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP2_PWR_DOMAIN	0	GPIO2 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP2_POL	1	GPIO2 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP2_OD	0	GPIO2 Output pin configuration 0 = CMOS 1 = Open Drain	
	8	GP2_ENA	0	GPIO2 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
	7:4	GP2_FN [3:0]	0000	GPIO2 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	
	3:1	CLKOUT_SLOT [2:0]	000	CLKOUT output enable ON slot select 000 = Do not enable 001 = Enable in Timeslot 1 010 = Enable in Timeslot 2 011 = Enable in Timeslot 3 100 = Enable in Timeslot 4 101 = Enable in Timeslot 5 110 = Do not enable 111 = Do not enable	
	0	WDOG_ENA	1	Watchdog Timer Enable 0 = Disabled 1 = Enabled (enables the watchdog; does not reset it) <i>Protected by security key.</i>	

Register 781Bh GPIO2 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30748 (781Ch) GPIO3 OTP Control	15	GP3_DIR	1	GPIO3 pin direction 0 = Output 1 = Input	
	14:13	GP3_PULL [1:0]	01	GPIO3 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP3_INT_MODE	0	GPIO3 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP3_POL=1) or falling edge triggered (if GP3_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP3_PWR_DOMAIN	0	GPIO3 Power Domain select 0 = DBVDD 1 = PMICVDD (LDO12)	
	10	GP3_POL	1	GPIO3 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP3_OD	0	GPIO3 Output pin configuration 0 = CMOS 1 = Open Drain	
	8	GP3_ENA	0	GPIO3 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	7:4	GP3_FN [3:0]	0000	GPIO3 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 781Ch GPIO3 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30749 (781Dh) GPIO4 OTP Control	15	GP4_DIR	1	GPIO4 pin direction 0 = Output 1 = Input	
	14:13	GP4_PULL [1:0]	01	GPIO4 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP4_INT_MODE	0	GPIO4 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP4_POL=1) or falling edge triggered (if GP4_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP4_PWR_DOMAIN	0	GPIO4 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP4_POL	1	GPIO4 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP4_OD	0	GPIO4 Output pin configuration 0 = CMOS 1 = Open Drain	
	8	GP4_ENA	0	GPIO4 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	7:4	GP4_FN [3:0]	0000	GPIO4 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	
	3:2	LED1_SRC [1:0]	11	LED1 Source (Selects the LED1 function.) 00 = Off 01 = Power State Status 10 = Reserved 11 = Manual Mode Note - LED1 also indicates completion of OTP Auto Program	
	1:0	LED2_SRC [1:0]	11	LED2 Source (Selects the LED2 function.) 00 = Off 01 = Power State Status 10 = Reserved 11 = Manual Mode Note - LED2 also indicates an OTP Auto Program Error condition	

Register 781Dh GPIO4 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30750 (781Eh) GPIO5 OTP Control	15	GP5_DIR	1	GPIO5 pin direction 0 = Output 1 = Input	
	14:13	GP5_PULL [1:0]	01	GPIO5 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP5_INT_MODE	0	GPIO5 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP5_POL=1) or falling edge triggered (if GP5_POL=0)	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP5_PWR_DOMAIN	0	GPIO5 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP5_POL	1	GPIO5 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP5_OD	0	GPIO5 Output pin configuration 0 = CMOS 1 = Open Drain	
	8	GP5_ENA	0	GPIO5 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	7:4	GP5_FN [3:0]	0000	GPIO5 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved 8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	

Register 781Eh GPIO5 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30751 (781Fh) GPIO6 OTP Control	15	GP6_DIR	1	GPIO6 pin direction 0 = Output 1 = Input	
	14:13	GP6_PULL [1:0]	01	GPIO6 Pull-Up / Pull-Down configuration 00 = No pull resistor 01 = Pull-down enabled 10 = Pull-up enabled 11 = Reserved	
	12	GP6_INT_MOD E	0	GPIO6 Interrupt Mode 0 = GPIO interrupt is rising edge triggered (if GP6_POL=1) or falling edge triggered (if GP6_POL=0) 1 = GPIO interrupt is triggered on rising and falling edges	
	11	GP6_PWR_DO M	0	GPIO6 Power Domain select 0 = DBVDD 1 = PVDD	
	10	GP6_POL	1	GPIO6 Polarity select 0 = Inverted (active low) 1 = Non-Inverted (active high)	
	9	GP6_OD	0	GPIO6 Output pin configuration 0 = CMOS 1 = Open Drain	
	8	GP6_ENA	0	GPIO6 Enable control 0 = GPIO pin is tri-stated 1 = Normal operation	
	7:4	GP6_FN [3:0]	0000	GPIO6 Pin Function Input functions: 0 = GPIO input (long de-bounce) 1 = GPIO input 2 = Power On/Off request 3 = Sleep/Wake request 4 = Sleep/Wake request (long de-bounce) 5 = Sleep request 6 = Power On request 7 = Watchdog Reset input 8 = DVS1 input 9 = DVS2 input 10 = HW Enable1 input 11 = HW Enable2 input 12 = HW Control1 input 13 = HW Control2 input 14 = HW Control1 input (long de-bounce) 15 = HW Control2 input (long de-bounce) Output functions: 0 = GPIO output 1 = 32.768kHz oscillator output 2 = ON state 3 = SLEEP state 4 = Power State Change 5 = Reserved 6 = Reserved 7 = Reserved	

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
				8 = DC-DC1 DVS Done 9 = DC-DC2 DVS Done 10 = External Power Enable1 11 = External Power Enable2 12 = System Supply Good (SYSOK) 13 = Converter Power Good (PWR_GOOD) 14 = External Power Clock (2MHz) 15 = Auxiliary Reset	
	3:1	SYSOK_THR [2:0]	101	SYSOK threshold (rising PVDD) This is the rising PVDD voltage at which SYSOK will be asserted 000 = 2.8V 001 = 2.9V ... 111 = 3.5V Note that the SYSOK hysteresis margin is added to these threshold levels.	

Register 781Fh GPIO6 OTP Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	REFER TO
R30759 (7827h) ICE CHECK DATA	15:0	ICE_VALID_DATA [15:0]	0000_0000_0000_0000	This field is checked in development mode when an 'ON' transition is requested. A value of A596h is required to confirm valid data.	

Register 7827h ICE CHECK DATA

30 APPLICATIONS INFORMATION

30.1 TYPICAL CONNECTIONS

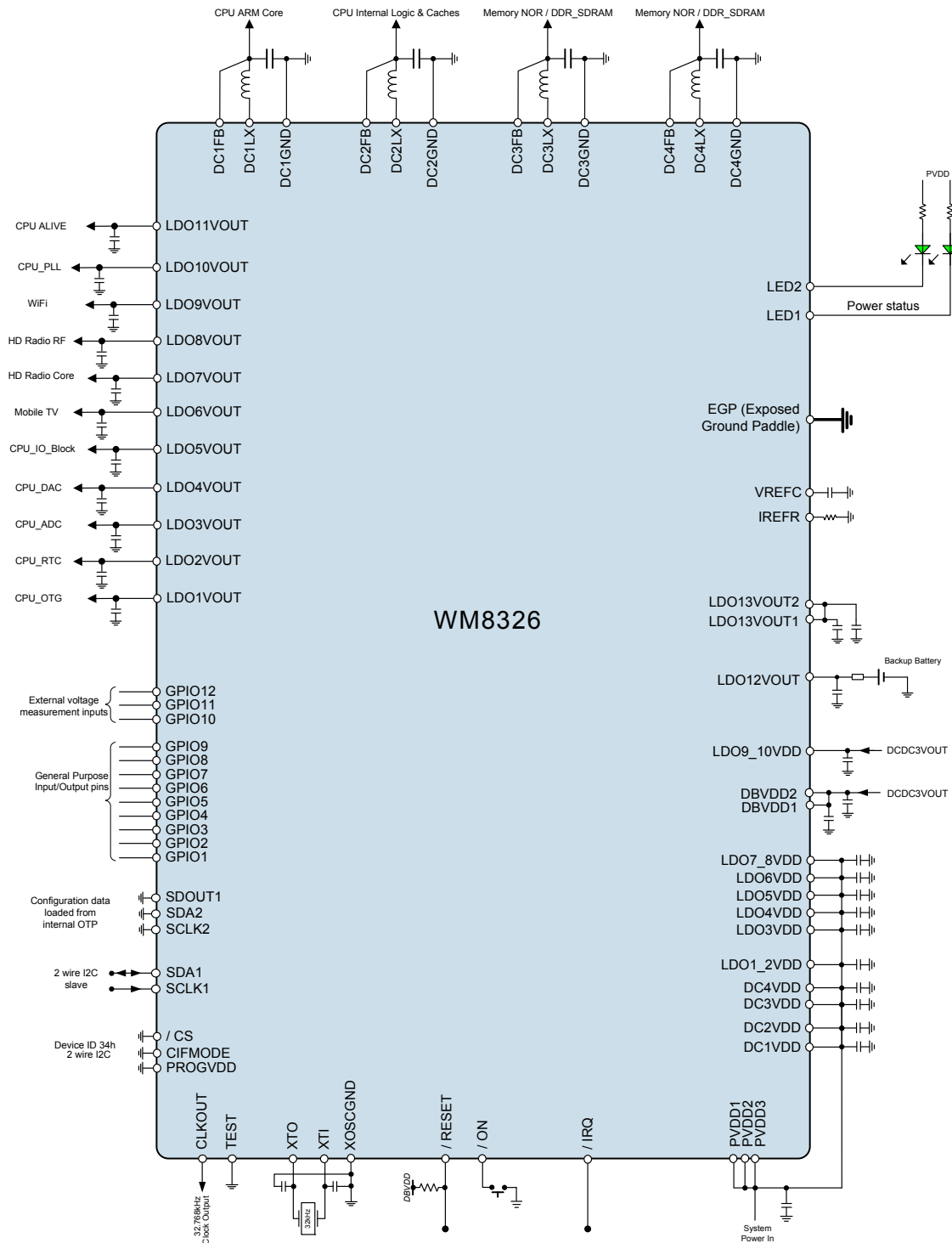


Figure 28 WM8326 Typical Connections Diagram

For detailed schematics, bill of materials and recommended external components refer to the WM8326 evaluation board users manual.

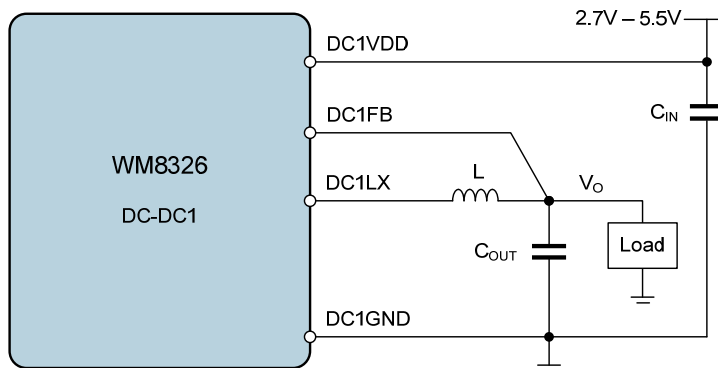
30.2 VOLTAGE AND CURRENT REFERENCE COMPONENTS

A decoupling capacitor is required between VREFC and GND; a 100nF X5R capacitor is recommended (available in 0201 package size).

A current reference resistor is required between IREFR and GND; a 100kΩ (1%) resistor is recommended.

30.3 DC-DC BUCK CONVERTER EXTERNAL COMPONENTS

The recommended connections to the DC-DC buck converters are illustrated in Figure 29.



Note: Equivalent circuit applies for DC-DC2, DC-DC3 and DC-DC4

Figure 29 DC-DC Buck Converter External Components

When selecting suitable capacitors, it is imperative that the effective capacitance is within the required limits at the applicable input/output voltage of the converter. It should be noted that some components' capacitance changes significantly depending on the DC voltage applied. Ceramic X7R or X5R types are recommended.

The choice of output capacitor varies depending on the required transient response. Larger values may be required for optimum performance under large load transient conditions. Smaller values may be sufficient for a steady load, or in applications without stringent requirements on output voltage accuracy during load transients.

For layout and size reasons, users may choose to implement large values of output capacitance by connecting two or more capacitors in parallel. To ensure stable operation, the DCm_CAP register fields must be set according to the output capacitance, as described in Section 15.6.

When selecting a suitable output inductor, the inductance value and the saturation current must be compatible with the operating conditions of the converter.

The magnitude of the inductor current ripple is dependant on the inductor value and can be determined by the following equation:

$$\Delta I_L = \frac{V_{OUT} \cdot (1 - (V_{OUT} / V_{IN}))}{L \cdot F_{SW}}$$

ΔI_L = Inductor ripple current
 V_{OUT} = Output voltage
 V_{IN} = Input voltage
 L = Inductance
 F_{SW} = Switching frequency

As a minimum requirement, the DC current rating should be equal to the maximum load current plus one half of the inductor current ripple:

$$I_{Lpeak} = I_{OUTmax} + (\Delta I_L / 2)$$

I_{Lpeak} = Inductor peak current
 I_{OUTmax} = Maximum load current
 ΔI_L = Inductor ripple current

To be suitable for the application, the chosen inductor must have a saturation current that is higher than the peak inductor current given by the above equation. To maximise the converter efficiency, the inductor should also have a low DC Resistance (DCR), resulting in minimum conduction losses. Care should also be taken to ensure that the component's inductance is valid at the applicable operating temperature.

The WM8326 incorporates a current-limit protection feature for all DC-DC Converter outputs. In order to achieve the benefit of this feature, the output inductor saturation current limit must be greater than or equal to the P-channel Current Limit for the applicable converter (see Section 7).

Wolfson recommends the following external components for use with DC-DC Converters 1 and 2.

The output inductor must be consistent with the DCm_FREQ register setting. The supported configurations are listed in Table 84. Note that for output voltages greater than 1.4V, the 2MHz mode must be used.

DCm_FREQ	SWITCHING FREQUENCY	OUTPUT INDUCTOR	COMMENTS
00	n/a	n/a	n/a
01	2MHz	2.2μH	Best efficiency
10	4MHz	1.0μH	Best transient performance
11	n/a	n/a	n/a

Table 84 Output Inductor Selection - DC-DC1, DC-DC2

The output capacitor must be consistent with the DCm_CAP register setting. For best performance, the 47μF component is recommended. For typical applications, the 22μF is suitable; this is the minimum recommended output capacitor value.

COMPONENT	VALUE	PART NUMBER	SIZE
L	1μH	Coilcraft XFL4020-102ME_	4 x 4 x 2.1mm
	2.2μH	TDK VLC5045-2R2N	5 x 5 x 4.5mm
	2.2μH	Coilcraft XAL4030-222ME_	4 x 4 x 3.1mm
C _{OUT}	47μF	MuRata GRM21BR60G476MEA1	0805
	22μF	MuRata GRM21BR60J226ME39	0805
C _{IN}	22μF	MuRata GRM21BR60J226ME39	0805

Table 85 Recommended External Components - DC-DC1, DC-DC2

Wolfson recommends the following external components for use with DC-DC Converters 3 and 4.

Note that the switching frequency of DC-DC3 and DC-DC4 is fixed at 2MHz and the output inductor must be 2.2μH in all cases.

The output capacitor must be consistent with the DCm_CAP register setting. For best performance, the 47μF component is recommended. For typical applications, the 22μF is suitable. The alternative values may be used for size or cost reasons if preferred.

COMPONENT	VALUE	PART NUMBER	SIZE
L	2.2 μ H	Coilcraft LPS3015-222ML	3 x 3 x 1.5mm
C _{OUT}	47 μ F	MuRata GRM21BR60G476MEA1	0805
	22 μ F	MuRata GRM21BR60J226ME39	0805
	10 μ F	MuRata GRM188R60J106ME84	0603
C _{IN}	4.7 μ F	MuRata GRM188R60J475ME84	0603

Table 86 Recommended External Components - DC-DC3, DC-DC4

30.3.1 DC-DC3 / DC-DC4 DUAL MODE

When DC-DC3 and DC-DC4 are operating in dual mode, the external component configuration for each converter is the same as previously noted for single converters. The output load connection points (V_O) are simply connected together as shown in Figure 30.

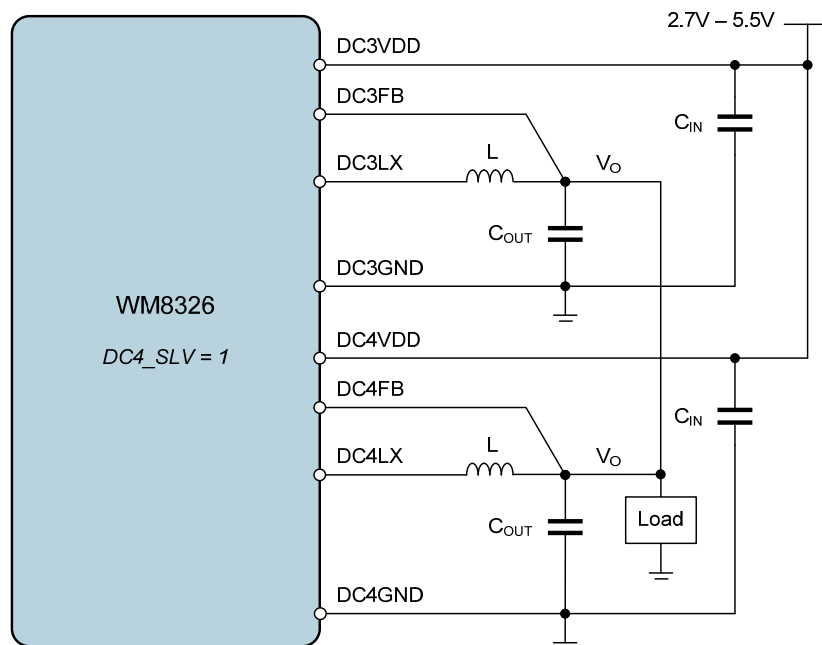


Figure 30 DC-DC3 / DC-DC4 Dual Mode Converter Connections

Wolfson recommends the following external components for use with DC-DC Converters 3 and 4 when operating in Dual Mode.

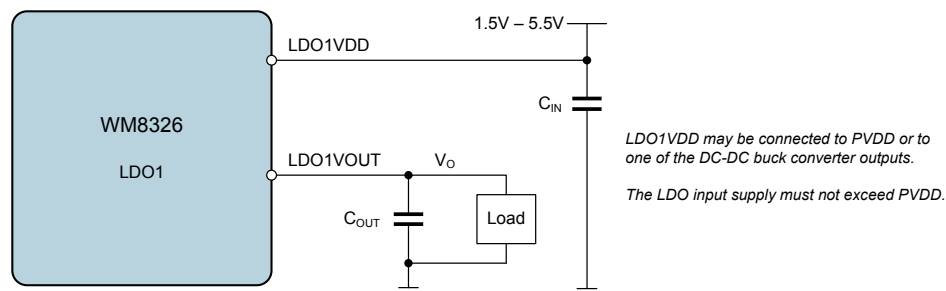
The output capacitor must be consistent with the DC_m_CAP register setting. For best performance, the 47 μ F component is recommended. For typical applications, the 22 μ F is suitable. The alternative values may be used for size or cost reasons if preferred.

COMPONENT	VALUE	PART NUMBER	SIZE
L	2.2 μ H	Coilcraft LPS3015-222ML_	3 x 3 x 1.5mm
C _{OUT}	47 μ F	MuRata GRM21BR60G476MEA1	0805
	22 μ F	MuRata GRM21BR60J226ME39	0805
	10 μ F	MuRata GRM188R60J106ME84	0603
C _{IN}	4.7 μ F	MuRata GRM188R60J475ME84	0603

Table 87 Recommended External Components - DC-DC3 / DC-DC4 Dual Mode

30.4 LDO REGULATOR EXTERNAL COMPONENTS

The recommended connections to the LDO Regulators are illustrated in Figure 31.



Note: Equivalent circuit applies for LDO2 through to LDO10.

Figure 31 LDO Regulators External Components

When selecting suitable capacitors, it is imperative that the effective capacitance is within the required limits at the applicable input/output voltage of the converter. Ceramic X7R or X5R types are recommended.

Wolfson recommends the following external components for use with LDO Regulators 1 to 6.

COMPONENT	VALUE	PART NUMBER	SIZE
C_{OUT}	2.2 μ F	Kemet C0402C225M9PAC	0402
C_{IN}	1.0 μ F	MuRata GRM155R61A105KE15	0402

Table 88 Recommended External Components - LDO1 to LDO6

Wolfson recommends the following external components for use with LDO Regulators 7 to 10. For these regulators, note that it is important that the output capacitance, C_{OUT} , does not exceed 4.7 μ F.

COMPONENT	VALUE	PART NUMBER	SIZE
C_{OUT}	1.0 μ F	MuRata GRM155R61A105KE15	0402
C_{IN}	1.0 μ F	MuRata GRM155R61A105KE15	0402

Table 89 Recommended External Components - LDO7 to LDO10

Wolfson recommends the following external components for use with LDO Regulators 11 to 13.

COMPONENT	VALUE	PART NUMBER	SIZE
C_{OUT} (LDO11)	0.1 μ F	MuRata GRM033R60J104KE19	0201
C_{OUT} (LDO12)	0.1 μ F	MuRata GRM033R60J104KE19	0201
C_{OUT} (LDO13)	2.2 μ F	Kemet C0402C225M9PAC	0402

Table 90 Recommended External Components - LDO11 to LDO13

30.5 PCB LAYOUT

Poor PCB layout will degrade the performance and be a contributory factor in EMI, ground bounce and resistive voltage losses. Poor regulation and instability can result.

Simple design rules can be implemented to negate these effects:

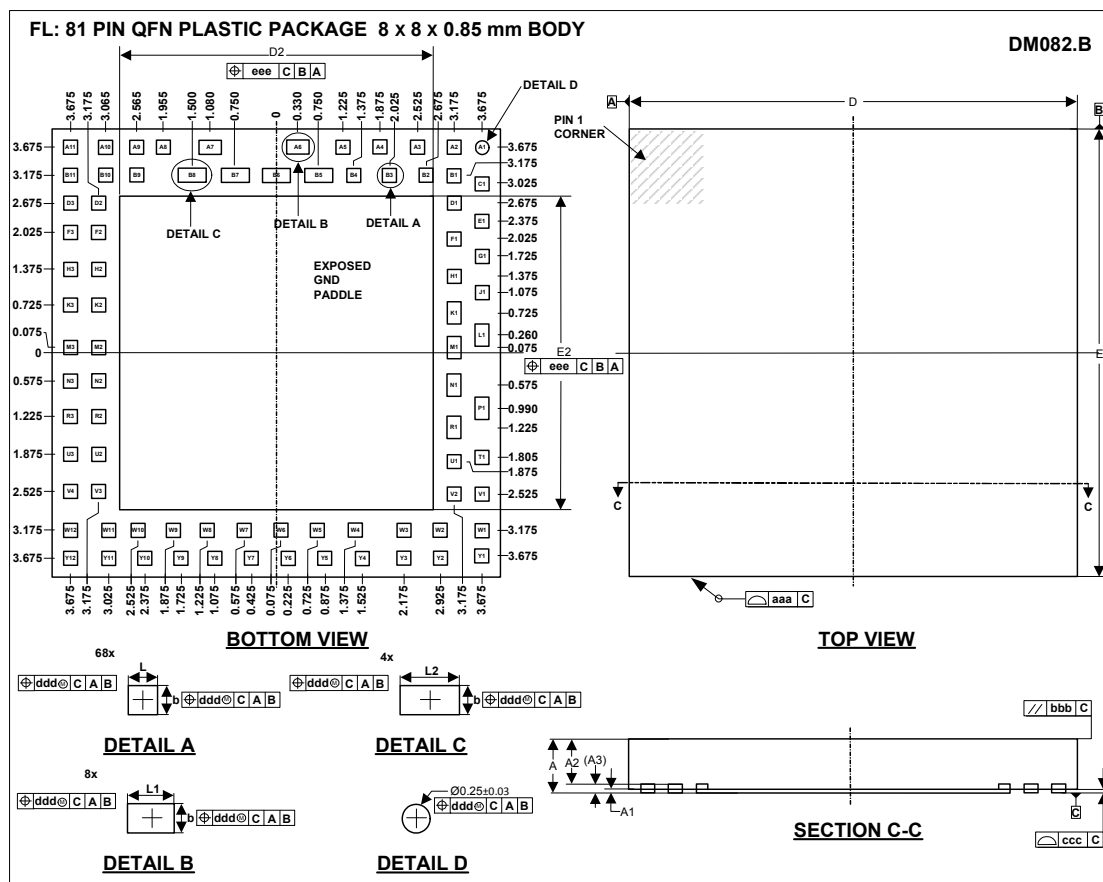
External input and output capacitors should be placed as close to the device as possible using short wide traces between the external power components. For the DC-DC Converters, the input capacitor placement takes priority on the DC-DC converters. (For the LDO Regulators, the placement of the input and output capacitors have equal priority.)

Route the DC-DC converter output voltage feedback as an independent connection to the top of the output capacitor to create a true sense of the output voltage, routing away from noisy signals such as the LX connection.

Use a local ground island for each individual DC-DC converter connected at a single point onto a fully flooded ground plane.

Current loop areas should be kept as small as possible with loop areas changing little during alternating switching cycles.

31 PACKAGE DIAGRAM



Symbols	Dimensions (mm)			NOTE
	MIN	NOM	MAX	
A	---	---	0.85	
A1	0.02	0.05	0.08	
A2	0.64	0.675	0.71	
A3	0.12	0.13	0.14	
b	0.22	0.25	0.28	
D		8 BSC		
D2	5.55	5.60	5.65	
E		8 BSC		
E2	5.55	5.60	5.65	
L	0.22	0.25	0.28	
L1	0.37	0.4	0.43	
L2	0.47	0.5	0.53	
Tolerances of Form and Position				
aaa		0.10		
bbb		0.20		
ccc		0.05		
ddd		0.08		
eee		0.10		
REF		JEDEC, MO-220		

NOTES:

- ALL DIMENSIONS ARE IN MILLIMETRES
- THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JESD 95-1 SPP-002.
- COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- THIS DRAWING IS SUBJECT TO CHANGE WITHOUT NOTICE.

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33 REVISION HISTORY

DATE	REV	DESCRIPTION OF CHANGES	CHANGED BY
October 2010	1.0	Initial version created.	PH
October 2010	1.0	CLKIN renamed as TEST	PH
26/01/2011	1.1	SDOUT1 description amended to Open Drain, with external pull-up required. Default value of PWRSTATE_DLY corrected. Alternative 2.2uH recommended inductor quoted for DC1, DC2. Undervoltage margin specified for all DC-DC converters. Overvoltage margin specified for DC-DC converters 1, 2. Chip Temperature (AUX_DATA) equation updated.	PH
07/03/11	1.1	Added notes that SLEEP > OFF is not a controlled transition; converters and regulators are disabled immediately. RESET pin description updated to note integrated pull-up. IRQ description updated to note pull-up in Open Drain mode. System Reset and Device Reset descriptions updated, consistent with the Summary Table. Recommended external pull-up resistances added in Pin Description. Internal pull-up / pull-down resistances added in Electrical Characteristics. Noted Active High (non-inverted) polarity for GPIO "Power On/Off request" function is not fully supported in development mode.	PH
	2.0	Noted maximum limit on Software Resets. Also clarification of the maximum number of Watchdog / Undervoltage Device Resets. Correction to DBVDD test conditions (Section 7.7). RTC_PINT_FREQ definition updated. DC-DC output inductor saturation limit recommendations added. SYSOK_THR register description updated. Quiescent current characteristics updated for DC-DC 1-4. DC1/2 output current rating reduced to 1250mA in 4MHz mode.	PH
15/09/11	2.0	Backup battery power updated; Charger control registers deleted. LDO11 output amended for LDO11_VSEL_SRC=1 and DC-DC1 disabled. OTP Register Map overview correction (GPn_TRI replaced with GPn_ENA).	PH
01/12/11	2.1	LDO11 maximum output current increased (only for PVDD $\geq$ 3.1V).	PH
01/02/12	2.1	Electrical Characteristics updated. DC3_STNBY_LIM, DC4_STNBY_LIM descriptions updated. SYSOK_THR description updated.	PH
07/03/12	3.0	Product status changed to Pre-Production.	PH
25/06/12	4.0	Product status changed to Production Data	JMacD