SCAS439D - JUNE 1994 - REVISED FEBRUARY 1999

- Free-Running CLKA and CLKB Can Be Asynchronous or Coincident
- Clocked FIFO Buffering Data From Port A to Port B
- Synchronous Read-Retransmit Capability
- Mailbox Register in Each Direction
- Programmable Almost-Full and Almost-Empty Flags
- Microprocessor Interface Control Logic
- Input-Ready and AF Flags Synchronized by CLKA

- Output-Ready and AE Flags Synchronized by CLKB
- Low-Power 0.8-μm Advanced CMOS Technology
- Supports Clock Frequencies up to 67 MHz
- Fast Access Times of 11 ns
- Pin-to-Pin Compatible With SN74ACT3631 and SN74ACT3641
- Package Options Include 120-Pin Thin Quad Flat (PCB) and 132-Pin Plastic Quad Flat (PQ) Packages

## description

The SN74ACT3651 is a high-speed, low-power, CMOS clocked FIFO memory that supports clock frequencies up to 67 MHz and has read access times as fast as 11 ns. The  $2048 \times 36$  dual-port SRAM FIFO buffers data from port A to port B. The FIFO memory has retransmit capability, which allows previously read data to be accessed again. The FIFO has flags to indicate empty and full conditions and two programmable flags (almost full and almost empty) to indicate when a selected number of words is stored in memory. Communication between each port takes place with two 36-bit mailbox registers. Each mailbox register has a flag that signals when new mail has been stored. Two or more devices are used in parallel to create wider data paths. Expansion is also possible in word depth.

The SN74ACT3651 is a clocked FIFO, which means each port employs a synchronous interface. All data transfers through a port are gated to the low-to-high transition of a continuous (free-running) port clock by enable signals. The continuous clocks for each port are independent of one another and can be asynchronous or coincident. The enables for each port are arranged to provide a simple interface between microprocessors and/or buses with synchronous control.

The input-ready (IR) flag and almost-full  $(\overline{AF})$  flag of the FIFO are two-stage synchronized to CLKA. The output-ready (OR) flag and almost-empty  $(\overline{AE})$  flag of the FIFO are two-stage synchronized to CLKB. Offset values for  $\overline{AF}$  and  $\overline{AE}$  are programmed from port A or through a serial input.

The SN74ACT3651 is characterized for operation from 0°C to 70°C.

For more information on this device family, see the following application reports:

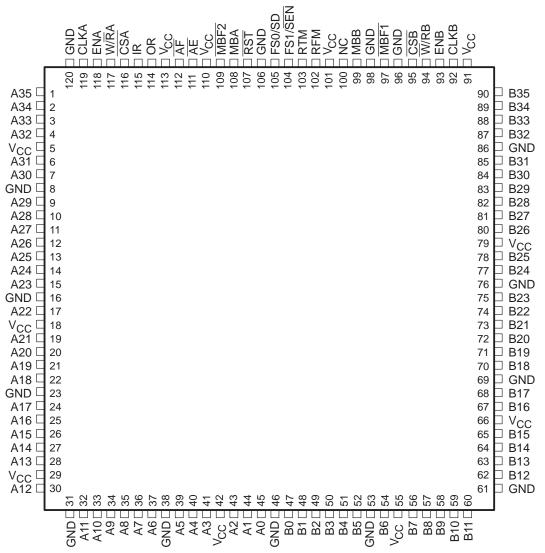
- FIFO Patented Synchronous Retransmit: Programmable DSP-Interface Application for FIR Filtering (literature number SCAA009)
- FIFO Mailbox-Bypass Registers: Using Bypass Registers to Initialize DMA Control (literature number SCAA007)
- Metastability Performance of Clocked FIFOs (literature number SCZA004)



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



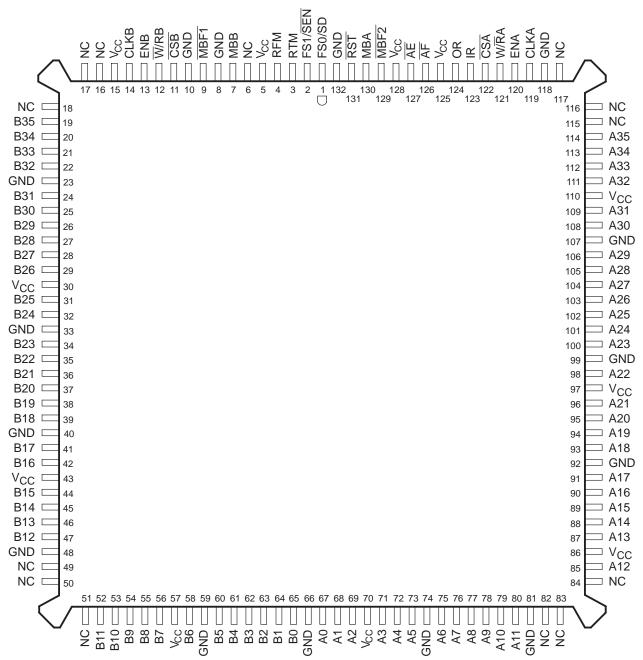
## PCB PACKAGE (TOP VIEW)



NC - No internal connection



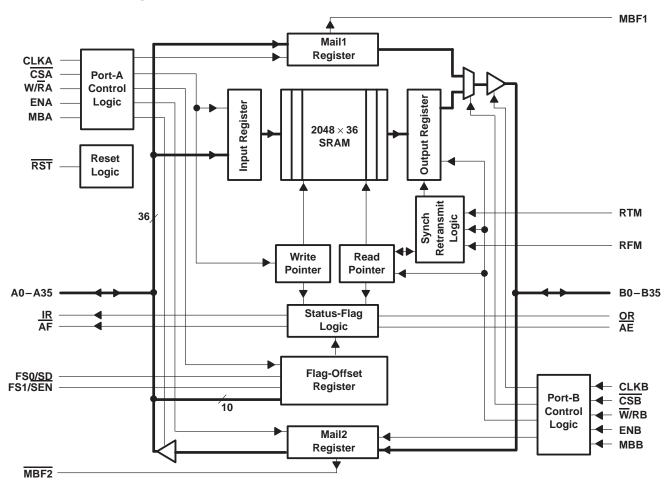




NC – No internal connection †Uses Yamaichi socket IC51-1324-828

# CLOCKED FIRST-IN, FIRST-OUT MEMORY SCAS439D – JUNE 1994 – REVISED FEBRUARY 1999

## functional block diagram





# CLOCKED FIRST-IN, FIRST-OUT MEMORY SCAS439D – JUNE 1994 – REVISED FEBRUARY 1999

## **Terminal Functions**

| TERMINAL<br>NAME   | I/O | DESCRIPTION  |
|--------------------|-----|--|
| A0-A35             | I/O | Port-A data. The 36-bit bidirectional data port for side A.  |
| ĀĒ                 | 0   | Almost-empty flag. Programmable flag synchronized to CLKB. AE is low when the number of words in the FIFO is less than or equal to the value in the almost-empty offset register (X).  |
| ĀF                 | 0   | Almost-full flag. Programmable flag synchronized to CLKA. AF is low when the number of empty locations in the FIFO is less than or equal to the value in the almost-full offset register (Y).  |
| B0-B35             | I/O | Port-B data. The 36-bit bidirectional data port for side B.  |
| CLKA               | I   | Port-A clock. CLKA is a continuous clock that synchronizes all data transfers through port A and can be asynchronous or coincident to CLKB. IR and AF are synchronous to the low-to-high transition of CLKA.   |
| CLKB               | ı   | Port-B clock. CLKB is a continuous clock that synchronizes all data transfers through port B and can be asynchronous or coincident to CLKA. OR and AE are synchronous to the low-to-high transition of CLKB.   |
| CSA                | ı   | Port-A chip select. CSA must be low to enable a low-to-high transition of CLKA to read or write data on port A. The A0-A35 outputs are in the high-impedance state when CSA is high.   |
| CSB                | I   | Port-B chip select. CSB must be low to enable a low-to-high transition of CLKB to read or write data on port B. The B0-B35 outputs are in the high-impedance state when CSB is high.   |
| ENA                | I   | Port-A master enable. ENA must be high to enable a low-to-high transition of CLKA to read or write data on port A.   |
| ENB                | I   | Port-B master enable. ENB must be high to enable a low-to-high transition of CLKB to read or write data on port B.   |
| FS1/SEN,<br>FS0/SD | ı   | Flag-offset select 1/serial enable, flag-offset select 0/serial data. FS1/SEN and FS0/SD are dual-purpose inputs used for flag-offset-register programming. During a device reset, FS1/SEN and FS0/SD select the flag-offset programming method. Three offset-register programming methods are available: automatically load one of two preset values, parallel load from port A, and serial load.  When serial load is selected for flag-offset-register programming, FS1/SEN is used as an enable synchronous to the |
|                    |     | low-to-high transition of CLKA. When FS1/SEN is low, a rising edge on CLKA loads the bit present on FS0/SD into the X-and Y-offset registers. The number of bit writes required to program the offset registers is 22. The first bit write stores the Y-register MSB and the last bit write stores the X-register LSB.   |
| IR                 | 0   | Input-ready flag. IR is synchronized to the low-to-high transition of CLKA. When IR is low, the FIFO is full and writes to its array are disabled. When the FIFO is in retransmit mode, IR indicates when the memory has been filled to the point of the retransmit data and prevents further writes. IR is set low during reset and is set high after reset.  |
| MBA                | ı   | Port-A mailbox select. A high level on MBA chooses a mailbox register for a port-A read or write operation.  |
| MBB                | ı   | Port-B mailbox select. A high level on MBB chooses a mailbox register for a port-B read or write operation. When the B0-B35 outputs are active, a high level on MBB selects data from the mail1 register for output and a low level selects FIFO data for output.  |
| MBF1               | 0   | Mail1 register flag. MBF1 is set low by the low-to-high transition of CLKA that writes data to the mail1 register. MBF1 is set high by a low-to-high transition of CLKB when a port-B read is selected and MBB is high. MBF1 is set high by a reset.   |
| MBF2               | 0   | Mail2 register flag. MBF2 is set low by the low-to-high transition of CLKB that writes data to the mail2 register. MBF2 is set high by a low-to-high transition of CLKA when a port-A read is selected and MBA is high. MBF2 is set high by a reset.   |
| OR                 | 0   | Output-ready flag. OR is synchronized to the low-to-high transition of CLKB. When OR is low, the FIFO is empty and reads are disabled. Ready data is present in the output register of the FIFO when OR is high. OR is forced low during the reset and goes high on the third low-to-high transition of CLKB after a word is loaded to empty memory.   |
| RFM                | ı   | Read from mark. When the FIFO is in retransmit mode, a high on RFM enables a low-to-high transition of CLKB to reset the read pointer to the beginning retransmit location and output the first selected retransmit data.  |
| RST                | I   | Reset. To reset the device, four low-to-high transitions of CLKA and four low-to-high transitions of CLKB must occur while RST is low. The low-to-high transition of RST latches the status of FS0 and FS1 for AF and AE offset selection.   |
| RTM                | I   | Retransmit mode. When RTM is high and valid data is present in the FIFO output register (OR is high), a low-to-high transition of CLKB selects the data for the beginning of a retransmit and puts the FIFO in retransmit mode. The selected word remains the initial retransmit point until a low-to-high transition of CLKB occurs while RTM is low, taking the FIFO out of retransmit mode.   |



SCAS439D - JUNE 1994 - REVISED FEBRUARY 1999

## **Terminal Functions (Continued)**

| TERMINAL<br>NAME | DESCRIPTION |   |
|------------------|-------------|---|
| W/RA             | Ι           | Port-A write/read select. A high on W/RA selects a write operation and a low selects a read operation on port A for a low-to-high transition of CLKA. The A0-A35 outputs are in the high-impedance state when W/RA is high. |
| W/RB             | 1           | Port-B write/read select. A low on W/RB selects a write operation and a high selects a read operation on port B for a low-to-high transition of CLKB. The B0-B35 outputs are in the high-impedance state when W/RB is low.  |

#### detailed description

#### reset

The SN74ACT3651 is reset by taking the reset ( $\overline{RST}$ ) input low for at least four port-A clock (CLKA) and four port-B clock (CLKB) low-to-high transitions. The reset input can switch asynchronously to the clocks. A reset initializes the memory-read and-write pointers and forces the IR flag low, the OR flag high, the  $\overline{AE}$  flag low, and the  $\overline{AF}$  flag high. Resetting the device also forces the mailbox flags ( $\overline{MBF1}$ ,  $\overline{MBF2}$ ) high. After a FIFO is reset, IR is set high after at least two clock cycles to begin normal operation. A FIFO must be reset after power up before data is written to its memory.

#### almost-empty flag and almost-full flag offset programming

Two registers in the SN74ACT3651 are used to hold the offset values for the  $\overline{AE}$  and  $\overline{AF}$  flags. The  $\overline{AE}$  flag offset register is labeled X, and the  $\overline{AF}$  flag offset register is labeled Y. The offset registers can be loaded with a value in three ways: one of two preset values is loaded into the offset registers, parallel load from port A, or serial load. The offset-register-programming mode is chosen by the flag select (FS1, FS0) inputs during a low-to-high transition on  $\overline{RST}$  (see Table 1).

**Table 1. Flag Programming** 

| FS1 | FS0 | RST      | X AND Y REGISTERS†        |
|-----|-----|----------|---------------------------|
| Н   | Н   | 1        | Serial load               |
| Н   | L   | 1        | 64                        |
| L   | Н   | 1        | 8                         |
| L   | L   | <b>↑</b> | Parallel load from port A |

<sup>&</sup>lt;sup>†</sup> X register holds the offset for  $\overline{AE}$ ; Y register holds the offset for  $\overline{AF}$ .

#### preset values

If a preset value of 8 or 64 is chosen by FS1 and FS0 at the time of an RST low-to-high transition according to Table 1, the preset value is automatically loaded into the X and Y registers. No other device initialization is necessary to begin normal operation, and the IR flag is set high after two low-to-high transitions on CLKA.

#### parallel load from port A

To program the X and Y registers from port A, the device is reset with FS0 and FS1 low during the low-to-high transition of  $\overline{RST}$ . After this reset is complete, the IR flag is set high after two low-to-high transitions on CLKA. The first two writes to the FIFO do not store data in its memory but load the offset registers in the order Y, X. Each offset register of the SN74ACT3651 uses port-A inputs (A10–A0). The highest number input is used as the most-significant bit of the binary number in each case. Each register value can be programmed from 1 to 2044. After both offset registers are programmed from port A, subsequent FIFO writes store data in the SRAM.



SCAS439D - JUNE 1994 - REVISED FEBRUARY 1999

#### serial load

To program the X and Y registers serially, the device is reset with FS0/SD and FS1/SEN high during the low-to-high transition of RST. After this reset is complete, the X-and Y-register values are loaded bitwise through FS0/SD on each low-to-high transition of CLKA that FS1/SEN is low. Twenty-two bit writes are needed to complete the programming. The first bit write stores the most-significant bit of the Y register and the last bit write stores the least-significant bit of the X register. Each register value can be programmed from 1 to 2044.

When the option is chosen to program the offset registers serially, the IR flag remains low until all register bits are written. The IR flag is set high by the low-to-high transition of CLKA after the last bit is loaded, to allow normal FIFO operation.

#### FIFO write/read operation

The state of the port-A data (A0-A35) outputs is controlled by the port-A chip select  $(\overline{CSA})$  and the port-A write/read select  $(W/\overline{R}A)$ . The A0-A35 outputs are in the high-impedance state when either  $\overline{CSA}$  or  $W/\overline{R}A$  is high. The A0-A35 outputs are active when both  $\overline{CSA}$  and  $W/\overline{R}A$  are low.

Data is loaded into the FIFO from the A0–A35 inputs on a low-to-high transition of CLKA when  $\overline{\text{CSA}}$  and the port-A mailbox select (MBA) are low, W/ $\overline{\text{R}}$ A, the port-A enable (ENA), and the IR flag are high (see Table 2). Writes to the FIFO are independent of any concurrent FIFO reads.

| CSA | W/RA | ENA | MBA | CLKA     | A0-A35 OUTPUTS          | PORT FUNCTION              |
|-----|------|-----|-----|----------|-------------------------|----------------------------|
| Н   | Х    | Х   | Х   | Х        | In high-impedance state | None                       |
| L   | Н    | L   | Х   | Х        | In high-impedance state | None                       |
| L   | Н    | Н   | L   | <b>↑</b> | In high-impedance state | FIFO write                 |
| L   | Н    | Н   | Н   | <b>↑</b> | In high-impedance state | Mail1 write                |
| L   | L    | L   | L   | Х        | Active, mail2 register  | None                       |
| L   | L    | Н   | L   | <b>↑</b> | Active, mail2 register  | None                       |
| L   | L    | L   | Н   | Х        | Active, mail2 register  | None                       |
| L   | L    | Н   | Н   | 1        | Active, mail2 register  | Mail2 read (set MBF2 high) |

**Table 2. Port-A Enable Function Table** 

The port-B control signals are identical to those of port A, with the exception that the port-B write/read select  $(\overline{W}/RB)$  is the inverse of the W/RA. The state of the port-B data (B0-B35) outputs is controlled by the port-B chip select  $(\overline{CSB})$  and  $\overline{W}/RB$ . The B0-B35 outputs are in the high-impedance state when either  $\overline{CSB}$  is high or  $\overline{W}/RB$  is low. The B0-B35 outputs are active when  $\overline{CSB}$  is low and  $\overline{W}/RB$  is high.

Data is read from the FIFO to its output register on a low-to-high transition of CLKB when  $\overline{\text{CSB}}$  and MBB are low,  $\overline{\text{W}}/\text{RB}$ , ENB, and the OR flag are high (see Table 3). Reads from the FIFO are independent of any concurrent FIFO writes.



SCAS439D – JUNE 1994 – REVISED FEBRUARY 1999

Table 3. Port-B Enable Function Table

| CSB | W/RB | ENB | MBB | CLKB     | B0-B35 OUTPUTS               | PORT FUNCTION              |
|-----|------|-----|-----|----------|------------------------------|----------------------------|
| Н   | Х    | Х   | Х   | Х        | In high-impedance state      | None                       |
| L   | L    | L   | Х   | Х        | In high-impedance state      | None                       |
| L   | L    | Н   | L   | <b>↑</b> | In high-impedance state      | None                       |
| L   | L    | Н   | Н   | <b>↑</b> | In high-impedance state      | Mail2 write                |
| L   | Н    | L   | L   | Х        | Active, FIFO output register | None                       |
| L   | Н    | Н   | L   | <b>↑</b> | Active, FIFO output register | FIFO read                  |
| L   | Н    | L   | Н   | Х        | Active, mail1 register       | None                       |
| L   | Н    | Н   | Н   | <b>↑</b> | Active, mail1 register       | Mail1 read (set MBF1 high) |

The setup- and hold-time constraints to the port clocks for the port-chip selects and write/read selects are only for enabling write and read operations and are not related to high-impedance control of the data outputs. If a port enable is low during a clock cycle, the port-chip select and write/read select can change states during the setup- and hold-time window of the cycle.

When OR is low, the next data word is sent to the FIFO output register automatically by the CLKB low-to-high transition that sets OR high. When OR is high, an available data word is clocked to the FIFO output register only when a FIFO read is selected by CSB, W/RB, ENB, and MBB.

#### synchronized FIFO flags

Each FIFO flag is synchronized to its port clock through at least two flip-flop stages. This is done to improve the flag's reliability by reducing the probability of metastable events on their outputs when CLKA and CLKB operate asynchronously with one another. OR and  $\overline{AE}$  are synchronized to CLKB. IR and  $\overline{AF}$  are synchronized to CLKA. Table 4 shows the relationship of each flag to the number of words stored in memory.

**Table 4. FIFO Flag Operation** 

| NUMBER OF WORDS IN          |    | RONIZED<br>CLKB | SYNCHRONIZED<br>TO CLKA |    |  |
|-----------------------------|----|-----------------|-------------------------|----|--|
| 111017                      | OR | AE              | AF                      | IR |  |
| 0                           | L  | L               | Н                       | Н  |  |
| 1 to X                      | Н  | L               | Н                       | Н  |  |
| (X + 1) to [2048 – (Y + 1)] | Н  | Н               | Н                       | Н  |  |
| (2048 – Y) to 2047          | Н  | Н               | L                       | Н  |  |
| 2048                        | Н  | Н               | L                       | L  |  |

 $<sup>^{\</sup>dagger}$  X is the almost-empty offset for  $\overline{AE}$ . Y is the almost-full offset for  $\overline{AF}$ .



<sup>‡</sup>When a word is present in the FIFO output register, its previous memory location is free.

## CLOCKED FIRST-IN, FIRST-OUT MEMORY SCAS439D – JUNE 1994 – REVISED FEBRUARY 1999

#### output-ready flag

The OR flag of a FIFO is synchronized to CLKB. When OR is high, new data is present in the FIFO output register. When OR is low, the previous data word is present in the FIFO output register and attempted FIFO reads are ignored.

A FIFO read pointer is incremented each time a new word is clocked to its output register. When a word is written to a FIFO, it can be shifted to the FIFO output register in a minimum of three cycles of CLKB; therefore, an OR flag is low if a word in memory is the next data to be sent to the FIFO output register and three CLKB cycles have not elapsed since the word was written. The output-ready flag of the FIFO remains low until the third low-to-high transition of CLKB occurs, simultaneously forcing the OR flag high and shifting the word to the FIFO output register.

A low-to-high transition on CLKB begins the first synchronization cycle of a write if the clock transition occurs at time  $t_{sk(1)}$ , or greater, after the write. Otherwise, the subsequent CLKB cycle can be the first synchronization cycle (see Figure 6).

#### input-ready flag

The IR flag of a FIFO is synchronized to the CLKA. When the IR flag is high, a memory location is free in the SRAM to write new data. No memory locations are free when the IR flag is low and attempted writes to the FIFO are ignored.

Each time a word is written to a FIFO, its write pointer is incremented. When a word is read from a FIFO, its previous memory location can be written in a minimum of three cycles of CLKA; therefore, an IR flag is low if less than two cycles of CLKA have elapsed since the next memory write location has been read. The second low-to-high transition on CLKA after the read sets the IR flag high, and data can be written in the following cycle.

A low-to-high transition on CLKA begins the first synchronization cycle of a read if the clock transition occurs at time  $t_{sk(1)}$ , or greater, after the read. Otherwise, the subsequent CLKA cycle can be the first synchronization cycle (see Figure 7).

#### almost-empty flag

The  $\overline{AE}$  flag of a FIFO is synchronized to CLKB. The almost-empty state is defined by the contents of register X. This register is loaded with a preset value during a FIFO reset, programmed from port A, or programmed serially (see *almost-empty flag and almost-full flag offset programming*). The  $\overline{AE}$  flag is low when the FIFO contains X or fewer words and is high when the FIFO contains (X + 1) or more words. A data word present in the FIFO output register has been read from memory.

Two low-to-high transitions of CLKB are required after a FIFO write for the  $\overline{AE}$  flag to reflect the new level of fill; therefore, the  $\overline{AE}$  flag of a FIFO containing (X + 1) or more words remains low if two cycles of CLKB have not elapsed since the write that filled the memory to the (X + 1) level. An  $\overline{AE}$  flag is set high by the second low-to-high transition of CLKB after the FIFO write that fills memory to the (X + 1) level. A low-to-high transition of CLKB begins the first synchronization cycle if it occurs at time  $t_{sk(2)}$ , or greater, after the write that fills the FIFO to (X + 1) words. Otherwise, the subsequent CLKB cycle can be the first synchronization cycle (see Figure 8).



SCAS439D - JUNE 1994 - REVISED FEBRUARY 1999

#### almost-full flag

The AF flag of a FIFO is synchronized to the port clock that writes data to its array (CLKA). The almost-full state is defined by the contents of register Y. This register is loaded with a preset value during a FIFO reset, programmed from port A, or programmed serially (see *almost-empty flag and almost-full flag offset programming*). The AF flag is low when the number of words in the FIFO is greater than or equal to 2048 – Y). The AF flag is high when the number of words in the FIFO is less than or equal to [2048 – (Y + 1)]. A data word present in the FIFO output register has been read from memory.

Two low-to-high transitions of CLKA are required after a FIFO read for its AF flag to reflect the new level of fill. Therefore, the AF flag of a FIFO containing [ 2048 - (Y + 1)] or less words remains low if two cycles of CLKA have not elapsed since the read that reduced the number of words in memory to [2048 - (Y + 1)]. An AF flag is set high by the second low-to-high transition of CLKA after the FIFO read that reduces the number of words in memory to [2048 - (Y + 1)]. A low-to-high transition of CLKA begins the first synchronization cycle if it occurs at time  $t_{sk(2)}$ , or greater, after the read that reduces the number of words in memory to [2048 - (Y + 1)]. Otherwise, the subsequent CLKA cycle can be the first synchronization cycle (see Figure 9).

#### synchronous retransmit

The synchronous-retransmit feature of the SN74ACT3651 allows FIFO data to be read repeatedly starting at a user-selected position. The FIFO is first put into retransmit mode (RTM) to select a beginning word and prevent ongoing FIFO write operations from destroying retransmit data. Data vectors with a minimum length of three words can retransmit repeatedly, starting at the selected word. The FIFO can be taken out of RTM at any time without affecting normal device operation.

The FIFO is put in retransmit mode by a low-to-high transition on CLKB when the RTM input is high and OR is high. This rising CLKB edge marks the data present in the FIFO output register as the first retransmit data. The FIFO goes out of retransmit mode when RTM goes low (see Figure 10).

When two or more reads have been done past the initial retransmit word, a retransmit is initiated by a low-to-high transition on CLKB when the read-from-mark (RFM) input is high. This rising CLKB edge shifts the first retransmit word to the FIFO output register and subsequent reads can begin immediately. Retransmit loops can be done endlessly while the FIFO is in RTM. RFM must be low during the CLKB rising edge that takes the FIFO out of retransmit mode.

When the FIFO is put into RTM, it operates with two read pointers. The current read pointer operates normally, incrementing each time a new word is shifted to the FIFO output register and used by the OR and  $\overline{AE}$  flags. The shadow read pointer stores the SRAM location at the time the device is put into RTM and does not change until the device is taken out of RTM. The shadow read pointer is used by the IR and  $\overline{AF}$  flags. Data writes can proceed while the FIFO is in RTM, but  $\overline{AF}$  is set low by the write that stores (2048 – Y) words after the first retransmit word. The IR flag is set low by the 2048th write after the first retransmit word.

When the FIFO is in RTM and RFM is high, a rising CLKB edge loads the current read pointer with the shadow read-pointer value and the OR flag reflects the new level of fill immediately. If the retransmit changes the FIFO status out of the almost-empty range, up to two CLKB rising edges after the retransmit cycle are needed to switch  $\overline{AE}$  high (see Figure 11). The rising CLKB edge that takes the FIFO out of retransmit mode shifts the read pointer used by the IR and  $\overline{AF}$  flags from the shadow to the current read pointer. If the change of read pointer used by IR and  $\overline{AF}$  should cause one or both flags to transition high, at least two CLKA synchronizing cycles are needed before the flags reflect the change. A rising CLKA edge after the FIFO is taken out of retransmit mode is the first synchronizing cycle of IR if it occurs at time  $t_{sk(1)}$ , or greater, after the rising CLKB edge (see Figure 12). A rising CLKA edge after the FIFO is taken out of RTM is the first synchronizing cycle of  $\overline{AF}$  if it occurs at time  $t_{sk(2)}$ , or greater, after the rising CLKB edge (see Figure 14).



#### mailbox registers

Two 36-bit bypass registers pass command and control information between port A and port B. The mailbox-select (MBA, MBB) inputs choose between a mail register and a FIFO for a port data-transfer operation. A low-to-high transition on CLKA writes A0-A35 data to the mail1 register when a port-A write is selected by  $\overline{CSA}$ ,  $\overline{W/RA}$ , and  $\overline{ENA}$  with MBA high. A low-to-high transition on CLKB writes B0-B35 data to the mail2 register when a port-B write is selected by  $\overline{CSB}$ ,  $\overline{W/RB}$ , and  $\overline{ENB}$  with MBB high. Writing data to a mail register sets its corresponding flag ( $\overline{MBF1}$  or  $\overline{MBF2}$ ) low. Attempted writes to a mail register are ignored while its mail flag is low.

When the port-B data (B0-B35) outputs are active, the data on the bus comes from the FIFO output register when the MBB input is low and from the mail1 register when MBB is high. Mail2 data is always present on the port-A data (A0-A35) outputs when they are active. The mail1 register flag ( $\overline{\text{MBF1}}$ ) is set high by a low-to-high transition on CLKB when a port-B read is selected by  $\overline{\text{CSB}}$ ,  $\overline{\text{W}}/\text{RB}$ , and ENB with MBB high. The mail2 register flag ( $\overline{\text{MBF2}}$ ) is set high by a low-to-high transition on CLKA when a port-A read is selected by  $\overline{\text{CSA}}$ ,  $\overline{\text{W/RA}}$ , and ENA with MBA high. The data in a mail register remains intact after it is read and changes only when new data is written to the register.

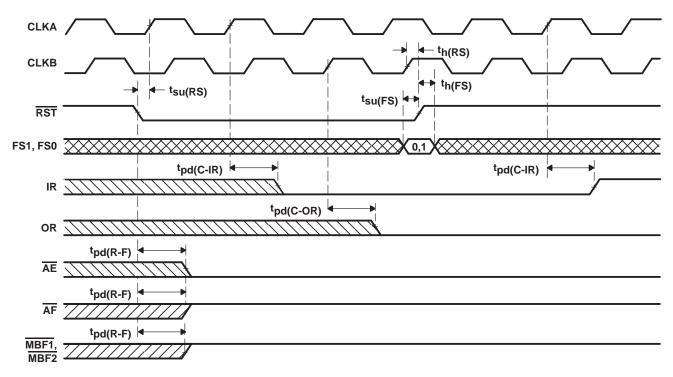
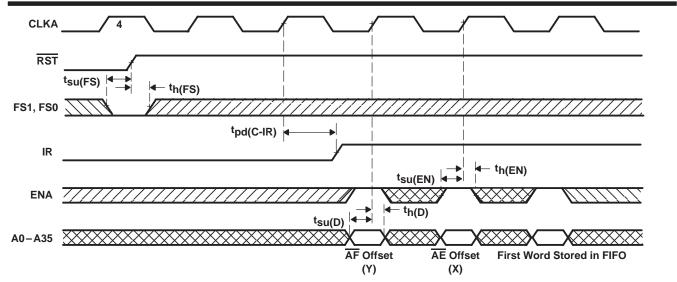


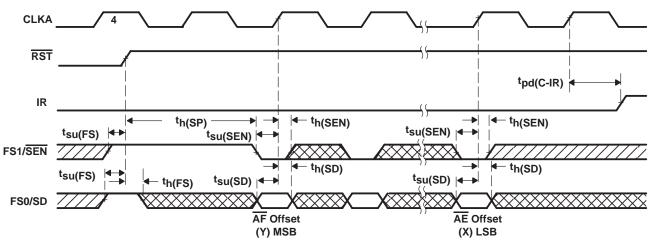
Figure 1. FIFO Reset Loading X and Y With a Preset Value of Eight





NOTE A:  $\overline{CSA} = L$ ,  $W/\overline{R}A = H$ , MBA = L. It is not necessary to program offset register on consecutive clock cycles.

Figure 2. Programming the AF Flag and AE Flag Offset Values From Port A



NOTE A: It is not necessary to program offset-register bits on consecutive clock cycles. FIFO write attempts are ignored until IR is set high.

Figure 3. Programming the AF Flag and AE Flag Offset Values Serially



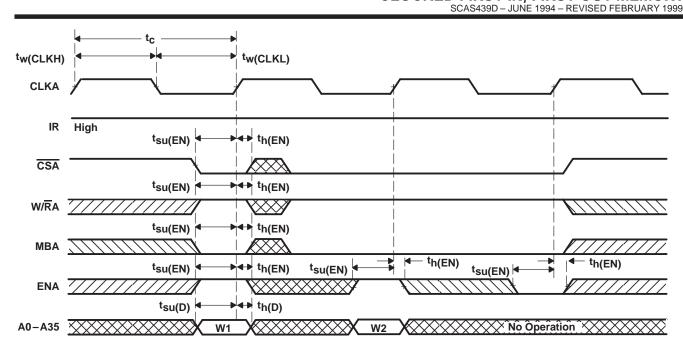


Figure 4. FIFO Write-Cycle Timing

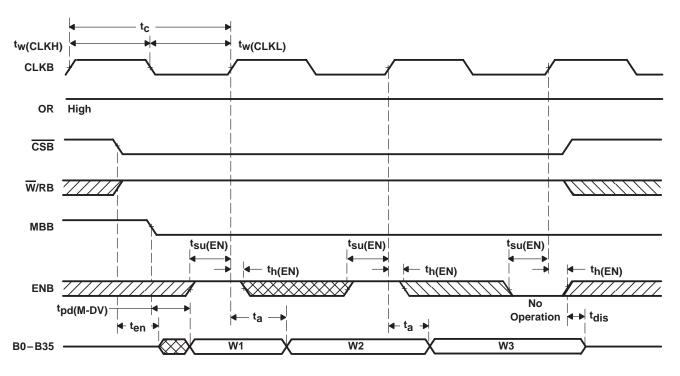
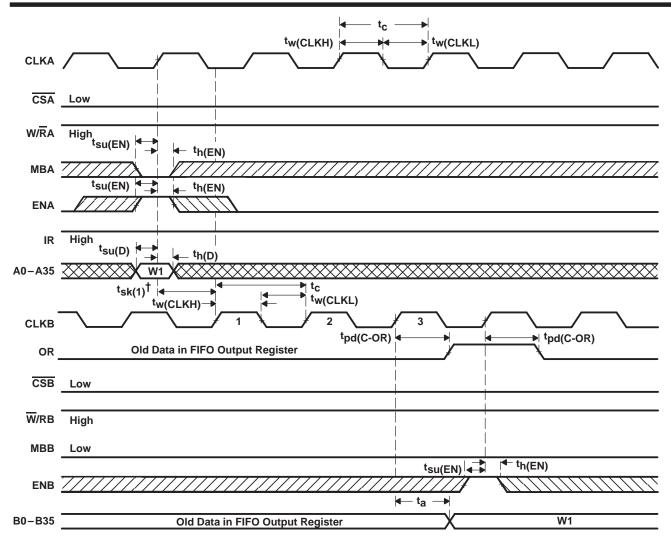


Figure 5. FIFO Read-Cycle Timing

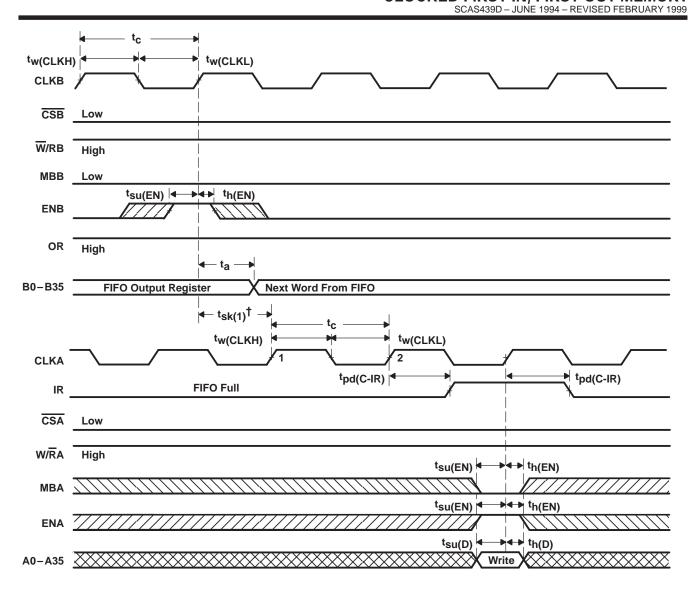




<sup>†</sup> t<sub>Sk(1)</sub> is the minimum time between a rising CLKA edge and a rising CLKB edge for OR to transition high and to clock the next word to the FIFO output register in three CLKB cycles. If the time between the rising CLKA edge and rising CLKB edge is less than t<sub>Sk(1)</sub>, then the transition of OR high and the first word load to the output register can occur one CLKB cycle later than shown.

Figure 6. OR-Flag Timing and First-Data-Word Fall Through When the FIFO Is Empty

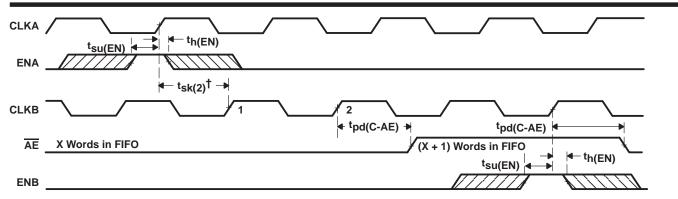




<sup>†</sup> t<sub>SK(1)</sub> is the minimum time between a rising CLKB edge and a rising CLKA edge for IR to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than t<sub>SK(1)</sub>, then IR can transition high one CLKA cycle later than shown.

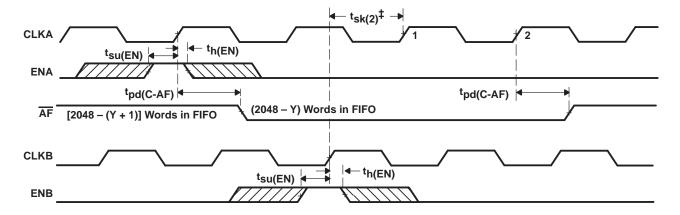
Figure 7. IR-Flag Timing and First Available Write When the FIFO Is Full

SCAS439D - JUNE 1994 - REVISED FEBRUARY 1999



<sup>†</sup> t<sub>sk(2)</sub> is the minimum time between a rising CLKA edge and a rising CLKB edge for  $\overline{AE}$  to transition high in the next CLKB cycle. If the time between the rising CLKA edge and rising CLKB edge is less than  $\underline{t_{sk(2)}}$ , then AE can transition high one CLKB cycle later than shown. NOTE A: FIFO write (CSA = L, W/RA = H, MBA = L), FIFO read (CSB = L, W/RB = H, MBB = L)

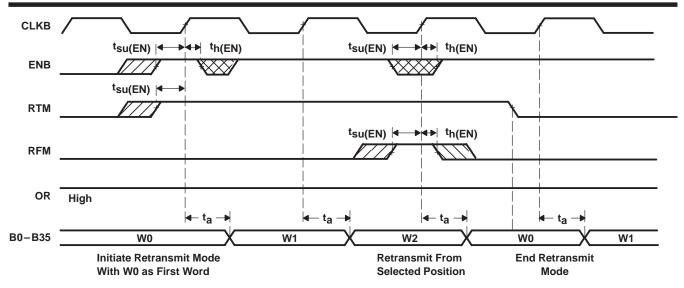
Figure 8. Timing for AE When FIFO Is Almost Empty



<sup>‡</sup>t<sub>sk(2)</sub> is the minimum time between a rising CLKA edge and a rising CLKB edge for  $\overline{AF}$  to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than  $t_{sk(2)}$ , then AF can transition high one CLKA cycle later than shown. NOTE A: FIFO write ( $\overline{CSA} = L$ , W/ $\overline{RA} = H$ , MBA = L), FIFO read ( $\overline{CSB} = L$ , W/RB = H, MBB = L)

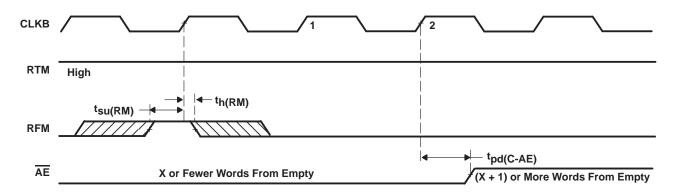
Figure 9. Timing for AF When FIFO Is Almost Full





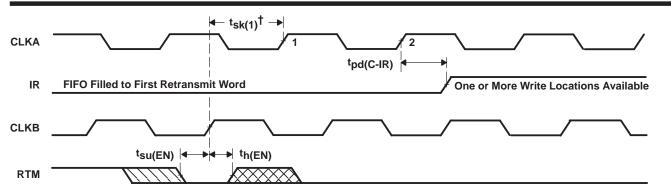
NOTE A:  $\overline{\text{CSB}} = \text{L}$ ,  $\overline{\text{W}}/\text{RB} = \text{H}$ , MBB = L. No input enables other than RTM and RFM are needed to control retransmit mode or begin a retransmit. Other enables are shown only to relate retransmit operations to the FIFO output register.

Figure 10. Retransmit Timing Showing Minimum Retransmit Length



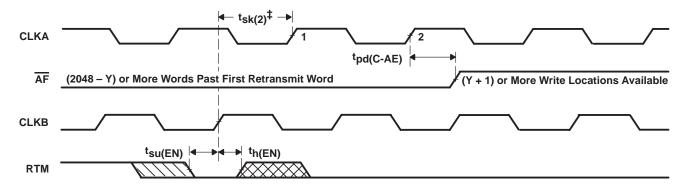
NOTE A: X is the value loaded in the  $\overline{AE}$ -flag offset register.

Figure 11. AE Maximum Latency When Retransmit Increases the Number of Stored Words Above X



<sup>†</sup>t<sub>sk(1)</sub> is the minimum time between a rising CLKB edge and a rising CLKA edge for IR to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than t<sub>sk(1)</sub>, then IR can transition high one CLKA cycle later than shown.

Figure 12. IR Timing From the End of Retransmit Mode When One or More Write Locations Are Available



<sup>‡</sup> t<sub>sk(2)</sub> is the minimum time between a rising CLKB edge and a rising CLKA edge for  $\overline{AF}$  to transition high in the next CLKA cycle. If the time between the rising CLKB edge and rising CLKA edge is less than t<sub>sk(2)</sub>, then  $\overline{AF}$  can transition high one CLKA cycle later than shown. NOTE A: Y is the value loaded in the  $\overline{AF}$  flag offset register.

Figure 13. AF Timing From the End of Retransmit Mode When (Y + 1) or More Write Locations Are Available



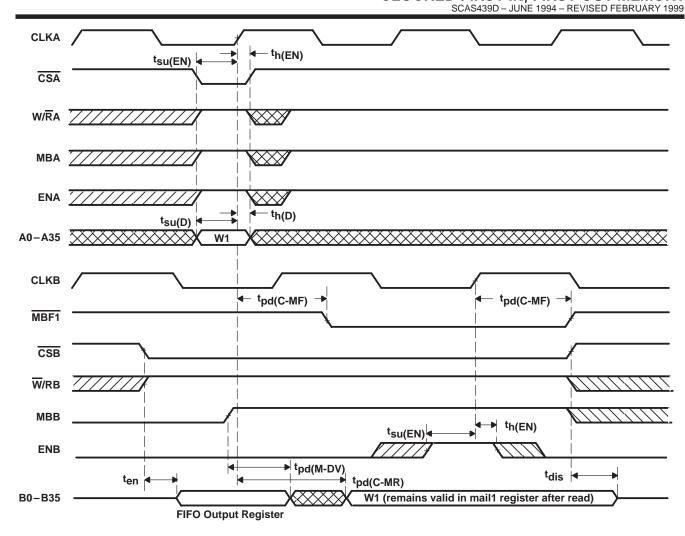


Figure 14. Timing for Mail1 Register and MBF1 Flag



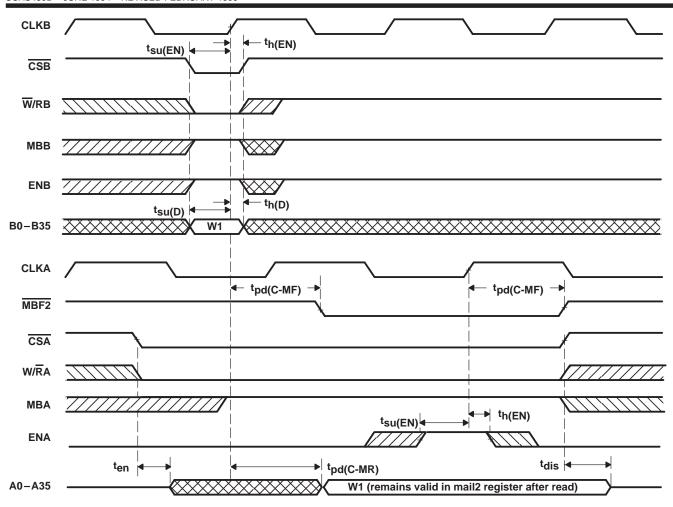


Figure 15. Timing for Mail2 Register and MBF2 Flag



SCAS439D – JUNE 1994 – REVISED FEBRUARY 1999

## absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

| Supply voltage range, V <sub>CC</sub>                          | 0.5 V to 7 V                     |
|--|----------------------------------|
| Input voltage range, V <sub>I</sub> (see Note 1)               |                                  |
| Output voltage range, VO (see Note 1)                          | 0.5 V to V <sub>CC</sub> + 0.5 V |
| Input clamp current, $I_{IK}$ ( $V_I < 0$ or $V_I > V_{CC}$ )  | ±20 mA                           |
| Output clamp current, $I_{OK}$ ( $V_O < 0$ or $V_O > V_{CC}$ ) |                                  |
| Continuous output current, $I_O(V_O = 0 \text{ to } V_{CC})$   |                                  |
| Continuous current through V <sub>CC</sub> or GND              |                                  |
| Package thermal impedance, $\theta_{JA}$ (see Note 2): PCB pa  | ckage 28°C/W                     |
| -  | kage 46°C/W                      |
| Storage temperature range, T <sub>stq</sub>                    | 65°C to 150°C                    |

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### recommended operating conditions

|                 |                                | MIN | MAX | UNIT |
|-----------------|--------------------------------|-----|-----|------|
| VCC             | Supply voltage                 | 4.5 | 5.5 | V    |
| VIH             | High-level input voltage       | 2   |     | V    |
| V <sub>IL</sub> | Low-level input voltage        |     | 0.8 | V    |
| ІОН             | High-level output current      |     | -4  | mA   |
| l <sub>OL</sub> | Low-level output current       |     | 8   | mA   |
| TA              | Operating free-air temperature | 0   | 70  | °C   |

## electrical characteristics over recommended operating conditions (unless otherwise noted)

| PARAMETER            |                           | TEST CONDIT  | IONS                  |        | MIN | TYP‡ | MAX | UNIT |
|----------------------|---------------------------|--|-----------------------|--------|-----|------|-----|------|
| Voн                  | $V_{CC} = 4.5 V,$         | $I_{OH} = -4 \text{ mA}$   |                       |        | 2.4 |      |     | V    |
| $v_{OL}$             | $V_{CC} = 4.5 \text{ V},$ | $I_{OL} = 8 \text{ mA}$  |                       |        |     |      | 0.5 | V    |
| lį                   | $V_{CC} = 5.5 V,$         | $V_I = V_{CC}$ or 0  |                       |        |     |      | ±5  | μΑ   |
| I <sub>OZ</sub>      | $V_{CC} = 5.5 \text{ V},$ | VO = VCC or 0  |                       |        |     |      | ±5  | μΑ   |
| Icc                  | $V_{CC} = 5.5 V$ ,        | $V_{I} = V_{CC} - 0.2 \text{ V or } 0$   | 1                     |        |     |      | 400 | μΑ   |
|                      |                           |  | CSA = V <sub>IH</sub> | A0-A35 |     | 0    |     |      |
|                      |                           | $V_{CC} = 5.5 \text{ V}$ , One input at 3.4 V, Other inputs at $V_{CC}$ or GND |                       | B0-B35 |     | 0    |     |      |
| ∆ICC§                |                           |  |                       | A0-A35 |     |      | 1   | mA   |
|                      | Other inputs at vee       | 01 0110  | CSB = V <sub>IL</sub> | B0-B35 |     |      | 1   |      |
|                      |                           |  | All other input       | S      |     |      | 1   |      |
| C <sub>i/o</sub>     | V <sub>I</sub> = 0,       | f = 1 MHz  |                       |        |     | 5    | ·   | pF   |
| C <sub>control</sub> | V <sub>I</sub> = 0,       | f = 1 MHz  |                       |        |     | 4    | ·   | pF   |

<sup>‡</sup> All typical values are at  $V_{CC} = 5 \text{ V}$ ,  $T_A = 25^{\circ}\text{C}$ .



NOTES: 1. The input and output voltage ratings may be exceeded provided the input and output current ratings are observed.

<sup>2.</sup> The package thermal impedance is calculated in accordance with JESD 51.

<sup>§</sup> This is the supply current when each input is at one of the specified TTL voltage levels rather than 0 V or VCC (at 25°C).

## CLOCKED FIRST-IN, FIRST-OUT MEMORY SCAS439D – JUNE 1994 – REVISED FEBRUARY 1999

## timing requirements over recommended ranges of supply voltage and operating free-air temperature (see Figures 1 through 16)

|                        |  | 'ACT36 | 551-15 | 'ACT36 | 51-20 | 'ACT36 | 51-30            | UNIT |
|------------------------|--|--------|--------|--------|-------|--------|------------------|------|
|                        |  | MIN    | MAX    | MIN    | MAX   | MIN    | MAX              | UNII |
| fclock                 | Clock frequency, CLKA or CLKB  |        | 66.7   |        | 50    |        | 33.4             | MHz  |
| t <sub>C</sub>         | Clock cycle time, CLKA or CLKB   | 15     |        | 20     |       | 30     |                  | ns   |
| tw(CH)                 | Pulse duration, CLKA and CLKB high   | 6      |        | 8      |       | 12     |                  | ns   |
| tw(CL)                 | Pulse duration, CLKA and CLKB low  | 6      |        | 8      |       | 12     |                  | ns   |
| t <sub>su(D)</sub>     | Setup time, A0−A35 before CLKA↑ and B0−B35 before CLKB↑  | 4      |        | 5      |       | 6      |                  | ns   |
| t <sub>su(EN)</sub>    | Setup time, CSA, W/RA, ENA, and MBA before CLKA↑; CSB, W/RB, ENB, MBB, RTM, and RFM before CLKB↑ | 4      |        | 5      |       | 6      |                  | ns   |
| t <sub>su(RS)</sub>    | Setup time, RST low before CLKA↑ or CLKB↑†   | 5      |        | 6      |       | 7      |                  | ns   |
| t <sub>su(FS)</sub>    | Setup time, FS0 and FS1 before RST high  | 12     |        | 13     |       | 14     |                  | ns   |
| t <sub>su(SD)</sub> ‡  | Setup time, FS0/SD before CLKA↑  | 4      |        | 5      |       | 6      |                  | ns   |
| t <sub>su(SEN)</sub> ‡ | Setup time, FS1/SEN before CLKA↑   | 5      |        | 6      |       | 7      |                  | ns   |
| <sup>t</sup> h(D)      | Hold time, A0-A35 after CLKA↑ and B0-B35 after CLKB↑   | 1      |        | 1      |       | 1      |                  | ns   |
| <sup>t</sup> h(EN)     | Hold time, CSA, W/RA, ENA, and MBA after CLKA↑; CSB, W/RB, ENB, RFM, and MBB after CLKB↑         | 0      |        | 0      |       | 0      |                  | ns   |
| th(RS)                 | Hold time, RST low after CLKA↑ or CLKB↑†   | 5      |        | 6      |       | 7      |                  | ns   |
| th(FS)                 | Hold time, FS0 and FS1 after RST high  | 2      |        | 3      |       | 3      |                  | ns   |
| th(SP) <sup>‡</sup>    | Hold time, FS1/SEN high after RST high   | 1      |        | 1      |       | 1      |                  | ns   |
| th(SD) <sup>‡</sup>    | Hold time, FS0/SD after CLKA↑  | 0      |        | 0      |       | 0      |                  | ns   |
| th(SEN) <sup>‡</sup>   | Hold time, FS1/SEN after CLKA↑   | 0      |        | 0      |       | 0      |                  | ns   |
| t <sub>sk(1)</sub> §   | Skew time between CLKA↑ and CLKB↑ for OR and IR  | 6      |        | 8      |       | 10     | , and the second | ns   |
| t <sub>sk(2)</sub> §   | Skew time between CLKA↑ and CLKB↑ for AE and AF  | 12     |        | 16     |       | 20     |                  | ns   |

<sup>†</sup> Requirement to count the clock edge as one of at least four needed to reset a FIFO



<sup>‡</sup> Applies only when serial load method is used to program flag offset registers

Skew time is not a timing constraint for proper device operation and is included only to illustrate the timing relationship between CLKA cycle and CLKB cycle.

# switching characteristics over recommended ranges of supply voltage and operating free-air temperature, $C_L$ = 30 pF (see Figures 1 through 16)

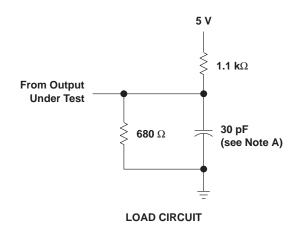
|                        | PARAMETER   | 'ACT36 | §51-15 | 'ACT36 | 51-20 | 'ACT36 | 51-30 | UNIT |
|------------------------|---|--------|--------|--------|-------|--------|-------|------|
|                        | PARAMETER   | MIN    | MAX    | MIN    | MAX   | MIN    | MAX   | UNII |
| fmax                   |   | 66.7   |        | 50     |       | 33.4   |       | MHz  |
| ta                     | Access time, CLKB↑ to B0-B35  | 3      | 11     | 3      | 13    | 3      | 15    | ns   |
| tpd(C-IR)              | Propagation delay time, CLKA↑ to IR   | 1      | 8      | 1      | 10    | 1      | 12    | ns   |
| tpd(C-OR)              | Propagation delay time, CLKB↑ to OR   | 1      | 8      | 1      | 10    | 1      | 12    | ns   |
| tpd(C-AE)              | Propagation delay time, CLKB↑ to AE   | 1      | 8      | 1      | 10    | 1      | 12    | ns   |
| tpd(C-AF)              | Propagation delay time, CLKA↑ to AF   | 1      | 8      | 1      | 10    | 1      | 12    | ns   |
| tpd(C-MF)              | Propagation delay time, CLKA↑ to MBF1 low or MBF2 high and CLKB↑ to MBF2 low or MBF1 high   | 0      | 8      | 0      | 10    | 0      | 12    | ns   |
| t <sub>pd</sub> (C-MR) | Propagation delay time, CLKA↑ to B0−B35 <sup>†</sup> and CLKB↑ to A0−A35 <sup>‡</sup>   | 3      | 13     | 3      | 15    | 3      | 17    | ns   |
| tpd(M-DV)              | Propagation delay time, MBB to B0-B35 valid   | 3      | 10     | 3      | 12    | 3      | 14    | ns   |
| tpd(R-F)               | Propagation delay time, RST low to AE low and AF high   | 1      | 15     | 1      | 20    | 1      | 30    | ns   |
| t <sub>en</sub>        | Enable time, $\overline{\text{CSA}}$ and $\overline{\text{W/RA}}$ low to A0-A35 active and $\overline{\text{CSB}}$ low and $\overline{\text{W/RB}}$ high to B0-B35 active | 2      | 13     | 2      | 15    | 2      | 17    | ns   |
| <sup>t</sup> dis       | Disable time, CSA or W/RA high to A0-A35 at high impedance and CSB high or W/RB low to B0-B35 at high impedance   | 1      | 13     | 1      | 15    | 1      | 17    | ns   |

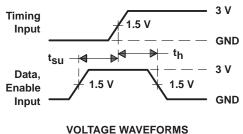
<sup>†</sup> Writing data to the mail1 register when the B0-B35 outputs are active and MBB is high

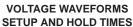


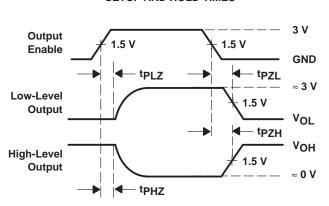
<sup>&</sup>lt;sup>‡</sup> Writing data to the mail2 register when the A0-A35 outputs are active and MBA is high

#### PARAMETER MEASUREMENT INFORMATION



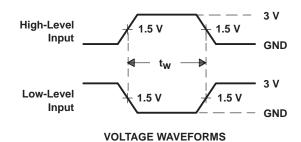






**VOLTAGE WAVEFORMS ENABLE AND DISABLE TIMES** 

NOTES: A. Includes probe and jig capacitance B. tpzL and tpzH are the same as ten C. tpLz and tpHz are the same as tdis



**PULSE DURATIONS** 

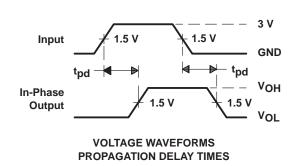


Figure 16. Load Circuit and Voltage Waveforms



## **TYPICAL CHARACTERISTICS**

## **SUPPLY CURRENT CLOCK FREQUENCY** 250 f<sub>data</sub> = 1/2 f<sub>clock</sub> T<sub>A</sub> = 25°C C<sub>L</sub> = 0 pF $V_{CC} = 5.5 V$ $V_{CC} = 5.0 V$ 200 I<sub>CC(f)</sub> - Supply Current - mA $V_{CC} = 4.5 V$ 150 100 50 0 0 10 20 70 30 40 50 60

Figure 17

f<sub>clock</sub> - Clock Frequency - MHz



#### PACKAGE OPTION ADDENDUM

www.ti.com 13-Oct-2009

#### **PACKAGING INFORMATION**

| Orderable Device  | Status <sup>(1)</sup> | Package<br>Type | Package<br>Drawing | Pins | Package<br>Qty | e Eco Plan <sup>(2)</sup> | Lead/Ball Finish | MSL Peak Temp <sup>(3)</sup> |
|-------------------|-----------------------|-----------------|--------------------|------|----------------|---------------------------|------------------|------------------------------|
| SN74ACT3651-15PCB | ACTIVE                | HLQFP           | PCB                | 120  | 90             | Green (RoHS & no Sb/Br)   | CU NIPDAU        | Level-3-260C-168 HR          |
| SN74ACT3651-15PQ  | ACTIVE                | BQFP            | PQ                 | 132  | 36             | Green (RoHS & no Sb/Br)   | CU NIPDAU        | Level-4-260C-72 HR           |
| SN74ACT3651-20PCB | ACTIVE                | HLQFP           | PCB                | 120  | 90             | Green (RoHS & no Sb/Br)   | CU NIPDAU        | Level-3-260C-168 HR          |

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <a href="http://www.ti.com/productcontent">http://www.ti.com/productcontent</a> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

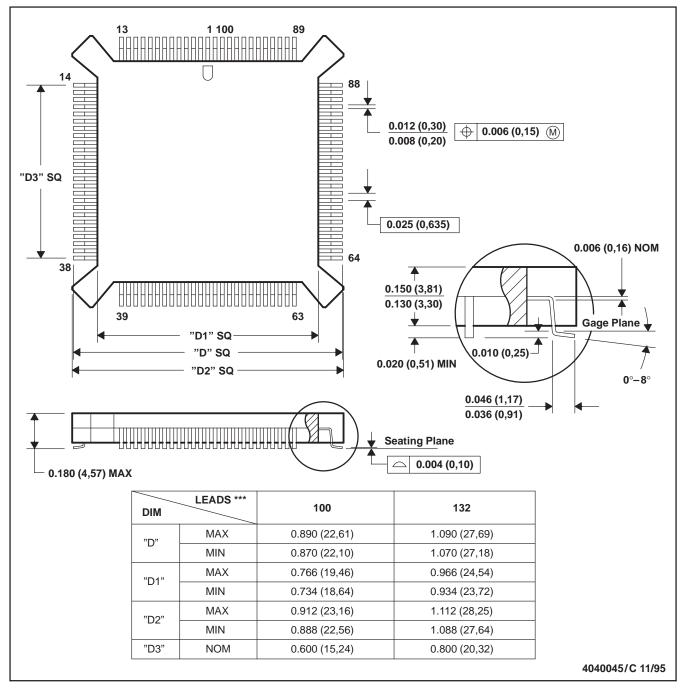
Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

## PQ (S-PQFP-G\*\*\*)

#### 100 LEAD SHOWN

## PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in inches (millimeters).

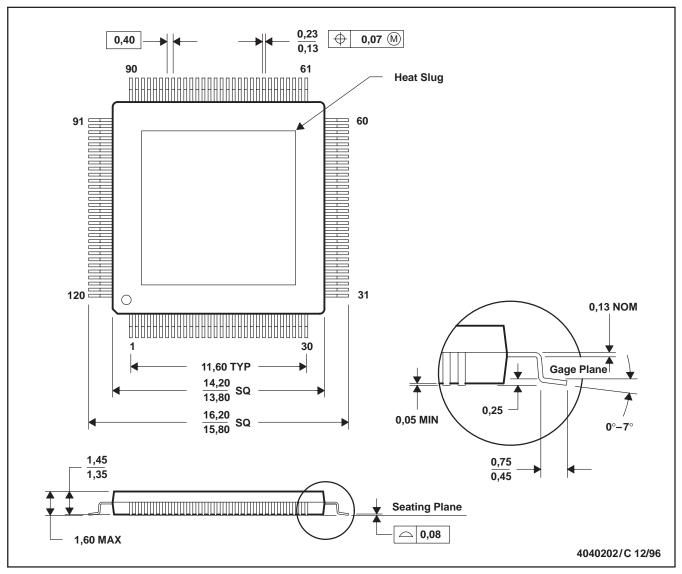
B. This drawing is subject to change without notice.

C. Falls within JEDEC MO-069



## PCB (S-PQFP-G120)

#### PLASTIC QUAD FLATPACK (DIE DOWN)



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Thermally enhanced molded plastic package with a heat slug (HSL)
- D. Falls within JEDEC MS-026

#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

**Applications Products Amplifiers** amplifier.ti.com Audio www.ti.com/audio Data Converters Automotive www.ti.com/automotive dataconverter.ti.com DLP® Products Broadband www.dlp.com www.ti.com/broadband DSP Digital Control dsp.ti.com www.ti.com/digitalcontrol Clocks and Timers www.ti.com/clocks Medical www.ti.com/medical Military Interface www.ti.com/military interface.ti.com Optical Networking Logic logic.ti.com www.ti.com/opticalnetwork Power Mgmt power.ti.com Security www.ti.com/security Telephony Microcontrollers microcontroller.ti.com www.ti.com/telephony Video & Imaging www.ti-rfid.com www.ti.com/video RF/IF and ZigBee® Solutions www.ti.com/lprf Wireless www.ti.com/wireless

> Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2009, Texas Instruments Incorporated