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LMV951

1V, 2.7 MHz, Rail-to-Rail Input and Output Amplifier with Shutdown Option

General Description

The LMV951 amplifier is capable of operating at supply voltages from 0.9V to 3V with guaranteed specs at 1V and 1.8V single supply.

The input common mode range extends to both power supply rails without the offset glitch and input bias current phase reversal inherent to most rail to rail input amplifiers.

Contrary to a conventional rail to rail output amplifier the LMV951 has a buffered output stage providing an open loop gain which is relatively unaffected by resistive output loading. At 1V supply voltage, the LMV951 is able to source and sink in excess of 35 mA and offers a gain bandwidth product of 2.7 MHz.

In shutdown mode the LMV951 consumes less than 50 nA of supply current.

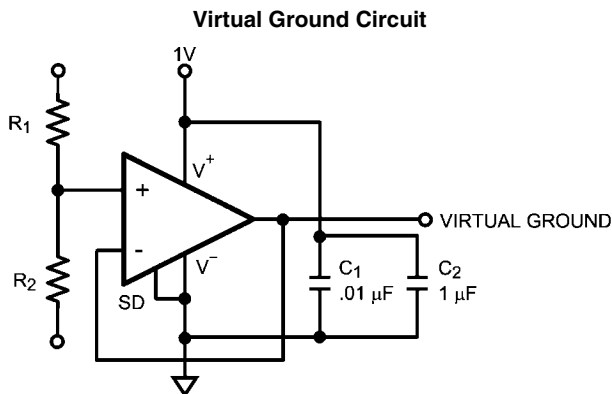
Features

(Typical 1.0V supply, unless otherwise noted)

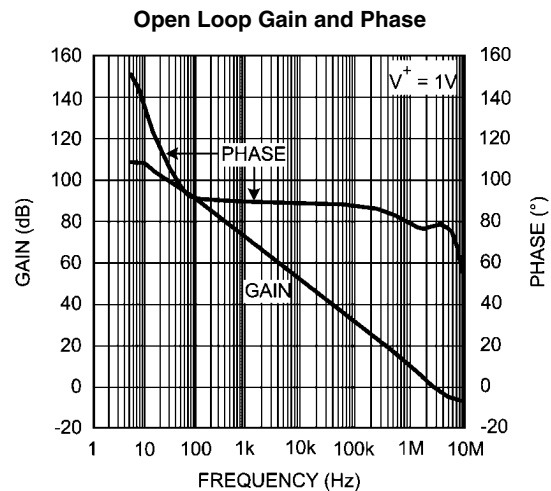
- Guaranteed 1V single supply operation
- Wide bandwidth
- No V_{OS} glitch over the input CMVR
- No input I_{BIAS} current reversal over V_{CM} range
- Buffered output stage
- High output drive capability
 - Sink current 35 mA
 - Source current 45 mA
- Rail-to-rail buffered output
 - @ 600 Ω load 32 mV from either rail
 - @ 2 k Ω load 12 mV from either rail
- Temperature range -40°C to 125°C

Applications

- Battery operated systems
- Battery monitoring
- Supply current monitoring



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Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

ESD Tolerance (Note 2)

Human Body Model 2000V

Machine Model 200V

Supply Voltage ($V^+ - V^-$) 3.1V V_{IN} Differential $\pm 0.3V$ Voltage at Input/Output Pin $V^+ +0.3V, V^- -0.3V$ Current at Input Pin $\pm 10\text{ mA}$ Junction Temperature (Note 3) $+150^\circ\text{C}$ Mounting Temperature
Infrared or Convection (20 sec) 235°C **Operating Ratings** (Note 1)Temperature Range (Note 3) -40°C to $+125^\circ\text{C}$

Supply Voltage 0.9V to 3V

Thermal Resistance (θ_{JA}) (Note 3) 170°C/W **1V Electrical Characteristics** (Note 4)

Unless otherwise specified, all limits guaranteed for at $T_A = 25^\circ\text{C}$, $V^+ = 1$, $V^- = 0V$, $V_{CM} = 0.5V$, Shutdown = $0V$, and $R_L = 1\text{ M}\Omega$.

Boldface limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 5)	Typ (Note 6)	Max (Note 5)	Units
V_{OS}	Input Offset Voltage			1.5	2.8 3.0	mV
TC V_{OS}	Input Offset Average Drift			0.15		$\mu\text{V}/^\circ\text{C}$
I_B	Input Bias Current			32	80 85	nA
I_{OS}	Input Offset Current			0.2		nA
CMRR	Common Mode Rejection Ratio	$0V \leq V_{CM} \leq 1V$	67 55	77		dB
		$0.1V \leq V_{CM} \leq 1V$	76 73	85		
PSRR	Power Supply Rejection Ratio	$1V \leq V^+ \leq 1.8V, V_{CM} = 0.5V$	70 67	92		dB
		$1V \leq V^+ \leq 3V, V_{CM} = 0.5V$	68 65	85		
V_{CM}	Input Common-Mode Voltage Range	CMRR $\geq 67\text{ dB}$	0		1.2	V
		CMRR $\geq 55\text{ dB}$	0		1.2	
A_V	Large Signal Voltage Gain	$V_{OUT} = 0.1V$ to $0.9V$ $R_L = 600\Omega$ to $0.5V$	90 85	106		dB
		$V_{OUT} = 0.1V$ to $0.9V$ $R_L = 2\text{ k}\Omega$ to $0.5V$	90 86	112		
V_{OUT}	Output Voltage Swing High	$R_L = 600\Omega$ to $0.5V$	50 62	25		mV from rail
		$R_L = 2\text{ k}\Omega$ to $0.5V$	25 36	12		
	Output Voltage Swing Low	$R_L = 600\Omega$ to $0.5V$	70 85	32		
		$R_L = 2\text{ k}\Omega$ to $0.5V$	35 40	10		
I_{OUT}	Output Short Circuit Current (Note 7)	Sourcing $V_O = 0V, V_{IN(DIFF)} = \pm 0.2V$	20 15	45		mA
		Sinking $V_O = 1V, V_{IN(DIFF)} = \pm 0.2V$	20 13	35		
I_S	Supply Current	Active Mode $V_{SD} < 0.4V$		370	480 520	μA
		Shutdown Mode $V_{SD} > 0.6V$		0.01	1.0 3.0	
SR	Slew Rate	(Note 8)		1.4		V/ μs

Symbol	Parameter	Conditions	Min (Note 5)	Typ (Note 6)	Max (Note 5)	Units
GBWP	Gain Bandwidth Product			2.7		MHz
e_n	Input - Referred Voltage Noise	$f = 1 \text{ kHz}$		25		$\text{nV}/\sqrt{\text{Hz}}$
i_n	Input-Referred Current Noise	$f = 1 \text{ kHz}$		0.2		$\text{pA}/\sqrt{\text{Hz}}$
THD	Total Harmonic Distortion	$f = 1 \text{ kHz}, A_V = 1, R_L = 1 \text{ k}\Omega$		0.02		%
I_{SD}	Shutdown Pin Current	Active Mode, $V_{SD} = 0\text{V}$		.001	1	μA
		Shutdown Mode, $V_{SD} = 1\text{V}$		.001	1	
V_{SD}	Shutdown Pin Voltage Range	Active Mode	0		0.4	V
		Shutdown Mode	0.65		1	

1.8V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits guaranteed for at $T_A = 25^\circ\text{C}$, $V^+ = 1.8\text{V}$, $V^- = 0\text{V}$, $V_{CM} = 0.9\text{V}$, Shutdown = 0V , and $R_L = 1 \text{ M}\Omega$. **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min (Note 5)	Typ (Note 6)	Max (Note 5)	Units
V_{OS}	Input Offset Voltage			1.5	2.8 3.0	mV
TC V_{OS}	Input Offset Average Drift			0.15		$\mu\text{V}/^\circ\text{C}$
I_B	Input Bias Current			36	80 85	nA
I_{OS}	Input Offset Current			0.2		nA
CMRR	Common Mode Rejection Ratio	$0\text{V} \leq V_{CM} \leq 1.8\text{V}$	82 80	93		dB
PSRR	Power Supply Rejection Ratio	$1\text{V} \leq V^+ \leq 1.8\text{V}, V_{CM} = 0.5\text{V}$	70 67	92		dB
		$1\text{V} \leq V^+ \leq 3\text{V}, V_{CM} = 0.5\text{V}$	68 65	85		
V_{CM}	Input Common-Mode Voltage Range	CMRR $\geq 82 \text{ dB}$	-0.2		2	V
		CMRR $\geq 80 \text{ dB}$	-0.2		2	
A_V	Large Signal Voltage Gain	$V_{OUT} = 0.2 \text{ to } 1.6\text{V}$ $R_L = 600\Omega \text{ to } 0.9\text{V}$	86 83	110		dB
		$V_{OUT} = 0.2 \text{ to } 1.6\text{V}$ $R_L = 2 \text{ k}\Omega \text{ to } 0.9\text{V}$	86 83	116		
V_{OUT}	Output Voltage Swing High	$R_L = 600\Omega \text{ to } 0.9\text{V}$	50 60	33		mV from rail
		$R_L = 2 \text{ k}\Omega \text{ to } 0.9\text{V}$	25 34	13		
	Output Voltage Swing Low	$R_L = 600\Omega \text{ to } 0.9\text{V}$	80 105	54		
		$R_L = 2 \text{ k}\Omega \text{ to } 0.9\text{V}$	35 44	17		
I_{OUT}	Output Short Circuit Current (Note 7)	Sourcing $V_O = 0\text{V}, V_{IN(DIFF)} = \pm 0.2\text{V}$	50 35	85		mA
		Sinking $V_O = 1.8\text{V}, V_{IN(DIFF)} = \pm 0.2\text{V}$	45 25	80		
I_S	Supply Current	Active Mode $V_{SD} < 0.5\text{V}$		570	780 880	μA
		Shutdown Mode $V_{SD} > 1.3\text{V}$		0.3	2.2 10	
SR	Slew Rate	(Note 8)		1.4		V/ μs
GBWP	Gain Bandwidth Product			2.8		MHz

Symbol	Parameter	Conditions	Min (Note 5)	Typ (Note 6)	Max (Note 5)	Units
e_n	Input - Referred Voltage Noise	$f = 1 \text{ kHz}$		25		$\text{nV}/\sqrt{\text{Hz}}$
i_n	Input-Referred Current Noise	$f = 1 \text{ kHz}$		0.2		$\text{pA}/\sqrt{\text{Hz}}$
THD	Total Harmonic Distortion	$f = 1 \text{ kHz}, A_V = 1, R_L = 1 \text{ k}\Omega$		0.02		%
I_{SD}	Shutdown Pin Current	Active Mode, $V_{SD} = 0\text{V}$		.001	1	μA
		Shutdown Mode, $V_{SD} = 1.8\text{V}$		.001	1	
V_{SD}	Shutdown Pin Voltage Range	Active Mode	0		0.5	V
		Shutdown Mode	1.45		1.8	

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics.

Note 2: Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC). Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

Note 3: The maximum power dissipation is a function of $T_{J(\text{MAX})}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = T_{J(\text{MAX})} - T_A / \theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

Note 4: Electrical table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions is very limited self-heating of the device.

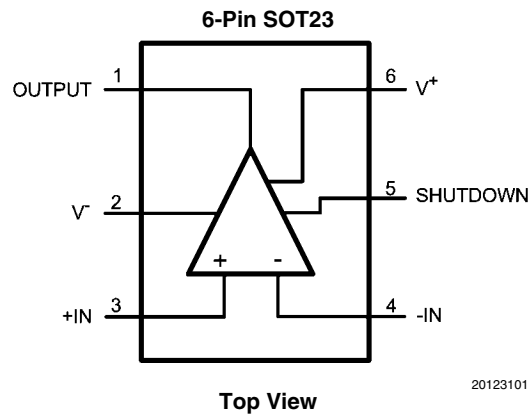
Note 5: All limits are guaranteed by testing or statistical analysis.

Note 6: Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

Note 7: The short circuit test is a momentary test, the short circuit duration is 1.5 ms

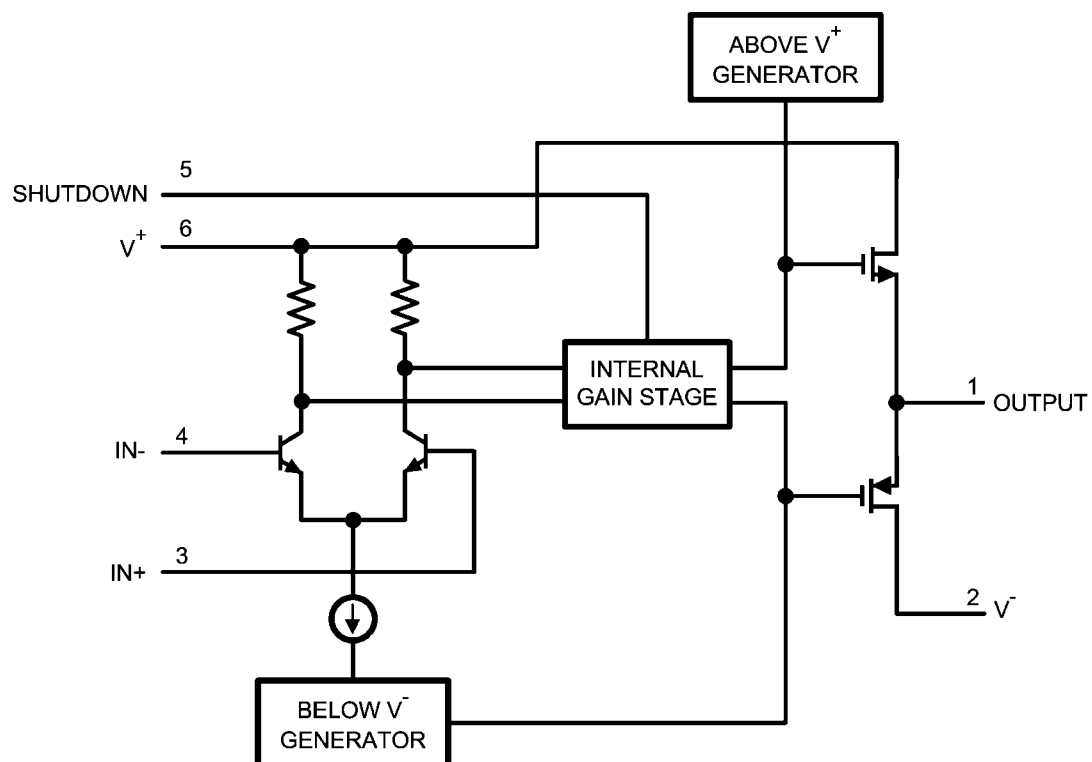
Note 8: Number specified is the average of the positive and negative slew rates.

Connection Diagram



Ordering Information

Package	Part Number	Package Marking	Transport Media	NSC Drawing
6-Pin SOT23	LMV951MK	AS3A	1k Units Tape and Reel	MK06A
	LMV951MKX		3k Units Tape and Reel	

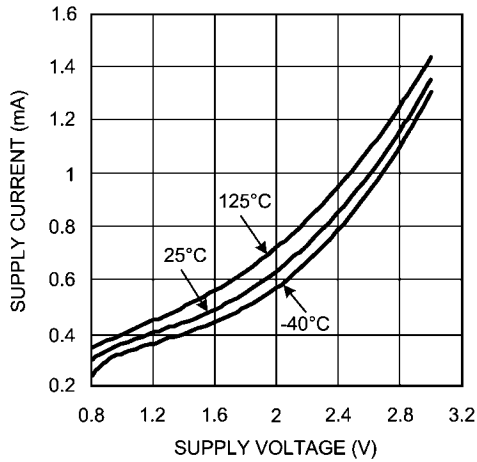


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Typical Performance Characteristics

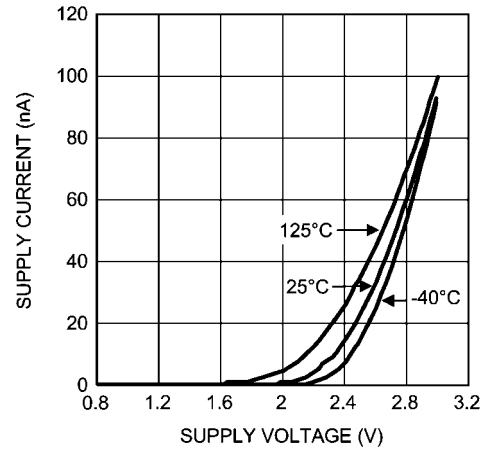
Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 1\text{V}$, $V^- = 0\text{V}$, $V_{CM} = V^+/2 = V_O$. **Boldface** limits apply at the temperature extremes.

Supply Current vs. Supply Voltage



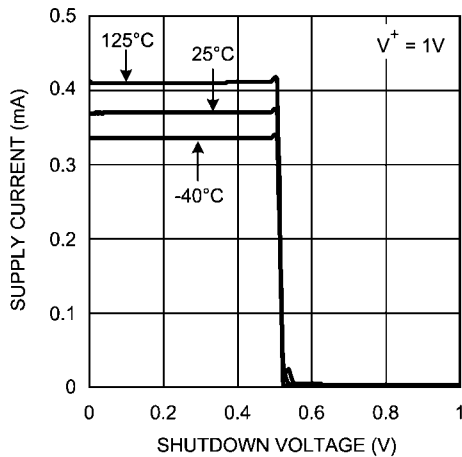
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Supply Current vs. Supply Voltage in Shutdown Mode



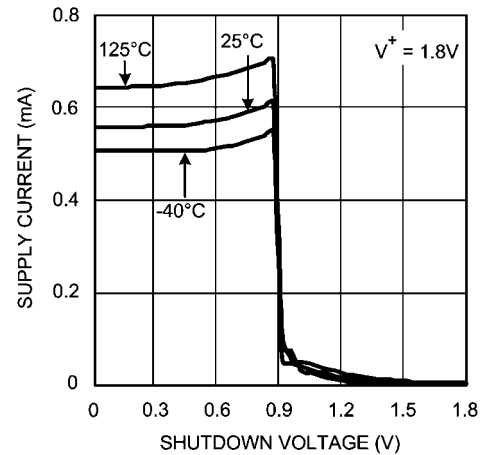
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Supply Current vs. Shutdown Voltage



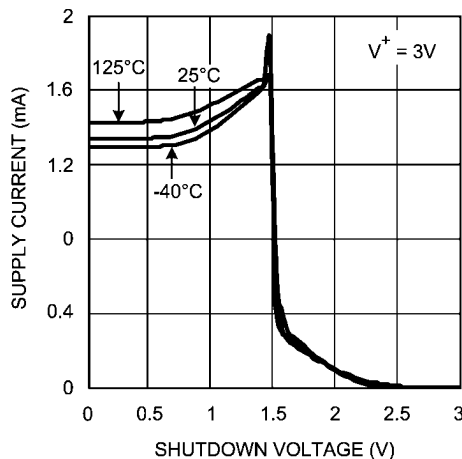
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Supply Current vs. Shutdown Voltage



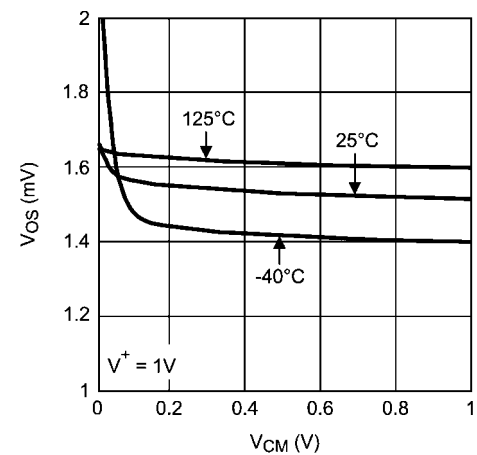
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Supply Current vs. Shutdown Voltage

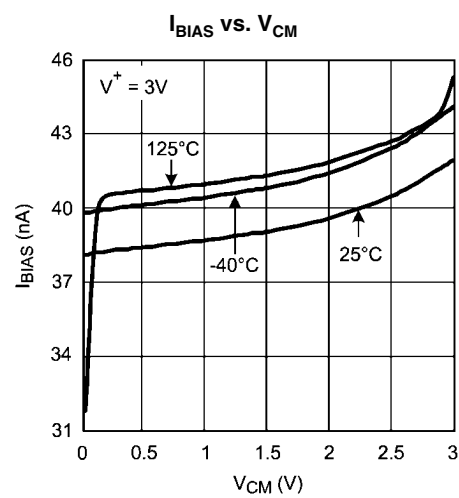
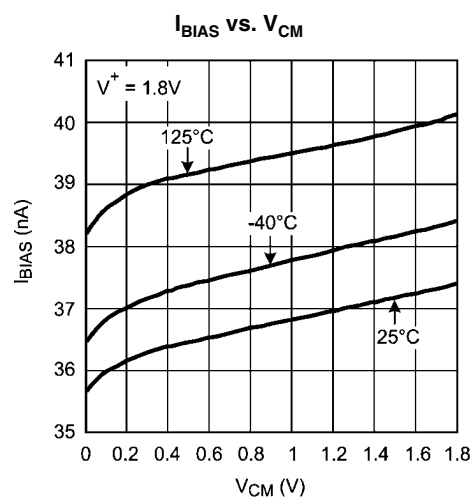
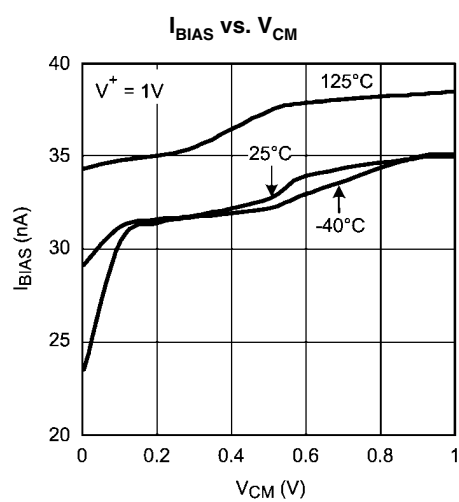
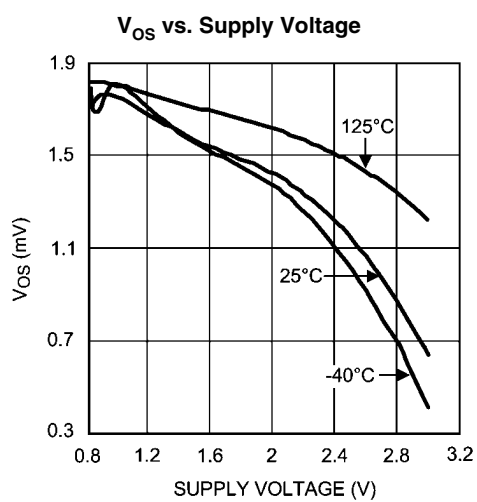
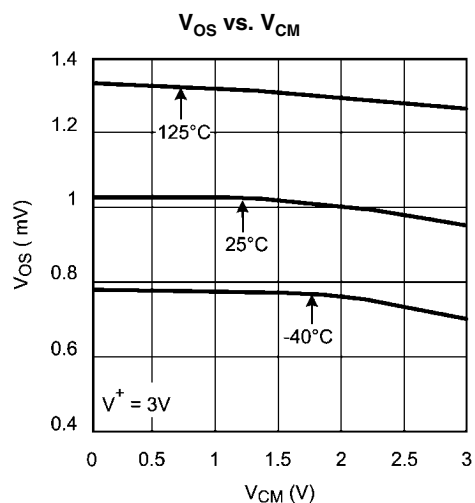
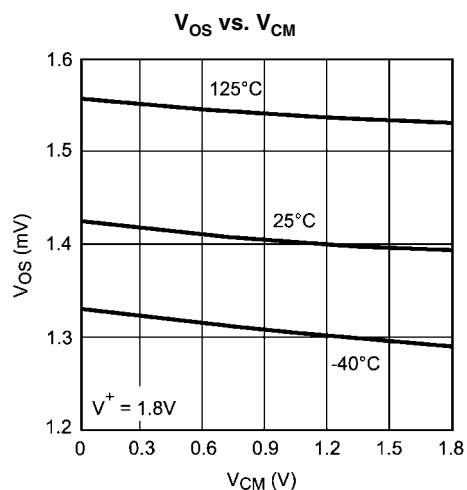


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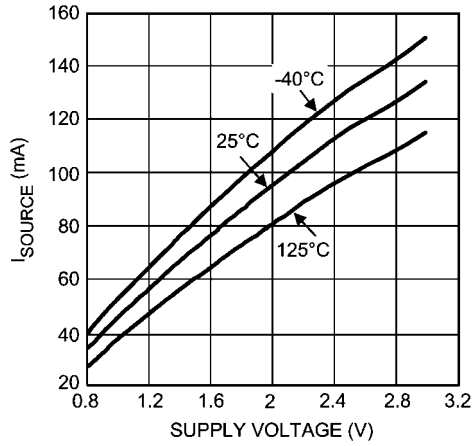
V_{OS} vs. V_{CM}



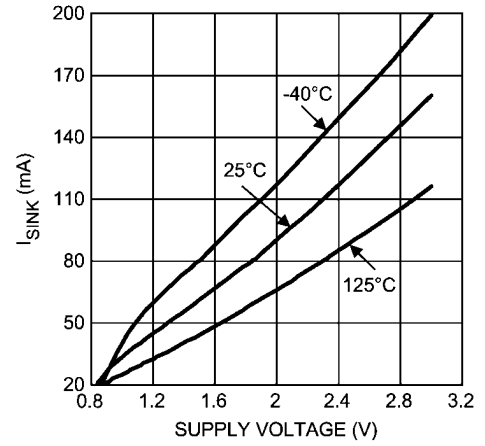
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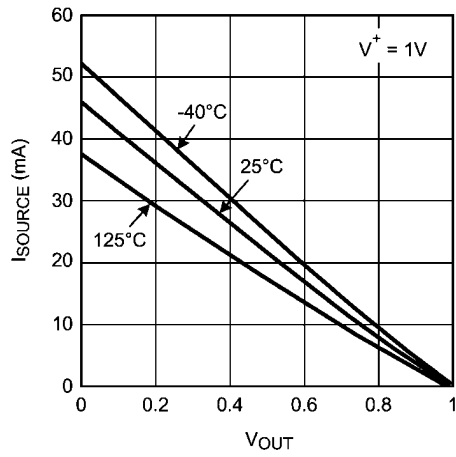
Sourcing Current vs. Supply Voltage



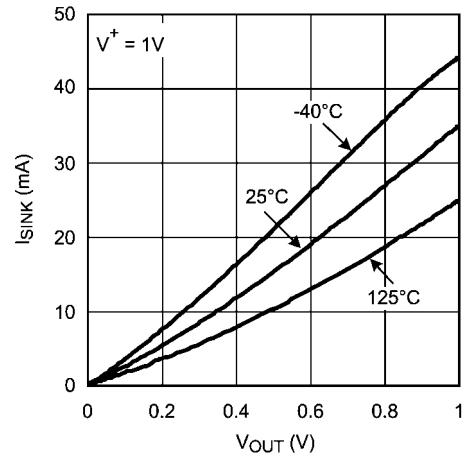
Sinking Current vs. Supply Voltage



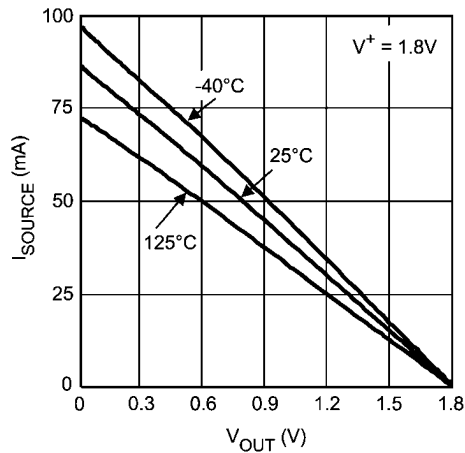
Sourcing Current vs. Output Voltage



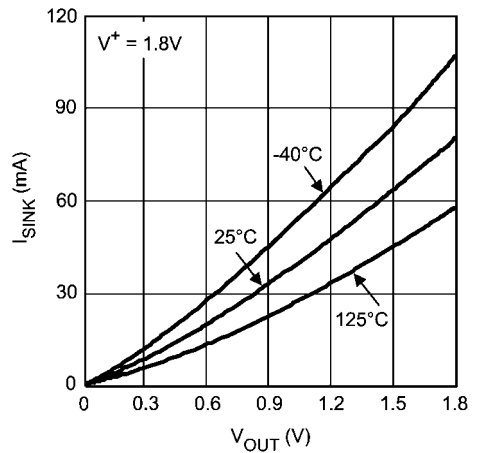
Sinking Current vs. Output Voltage



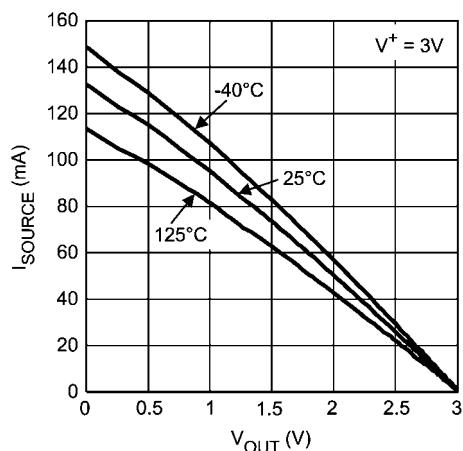
Sourcing Current vs. Output Voltage



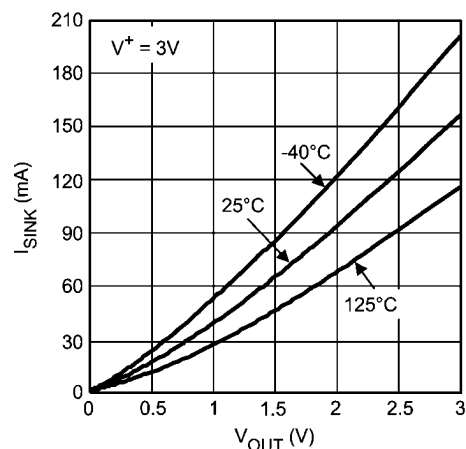
Sinking Current vs. Output Voltage



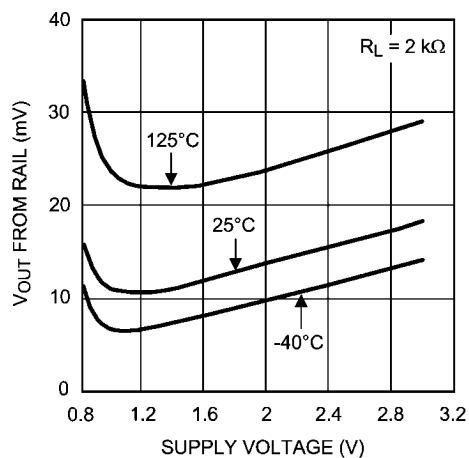
Sourcing Current vs. Output Voltage



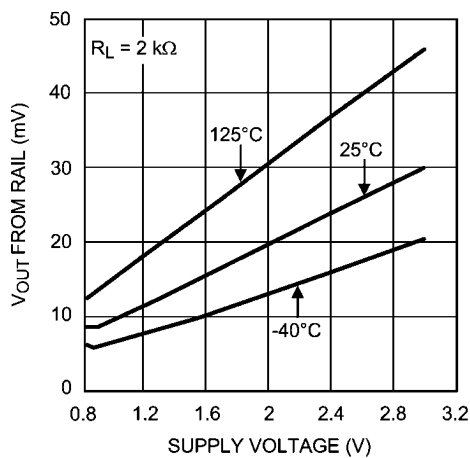
Sinking Current vs. Output Voltage



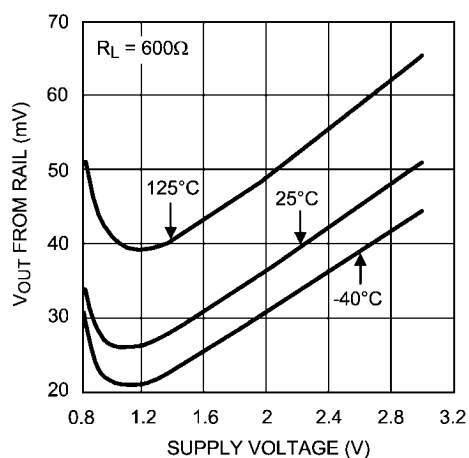
Positive Output Swing vs. Supply Voltage



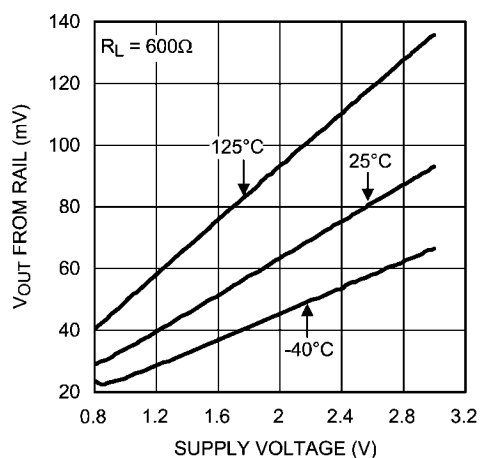
Negative Output Swing vs. Supply Voltage



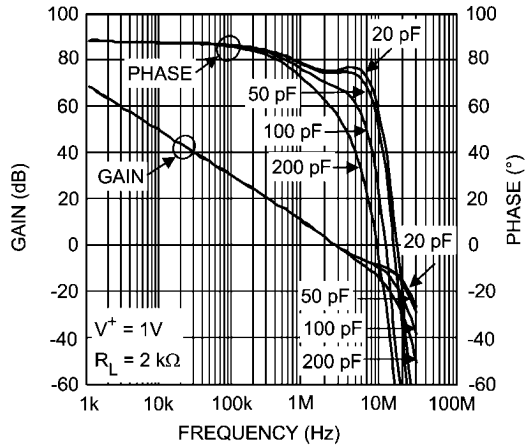
Positive Output Swing vs. Supply Voltage



Negative Output Swing vs. Supply Voltage

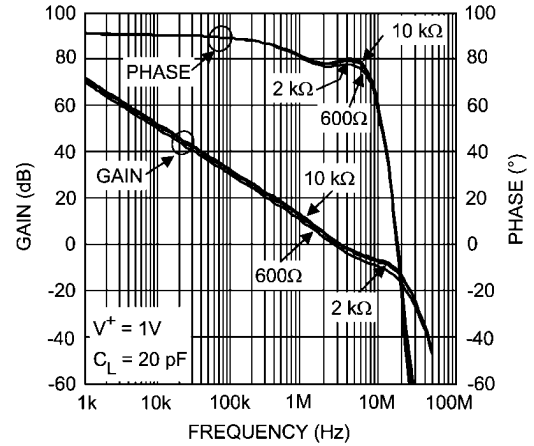


Open Loop Gain and Phase with Capacitive Load



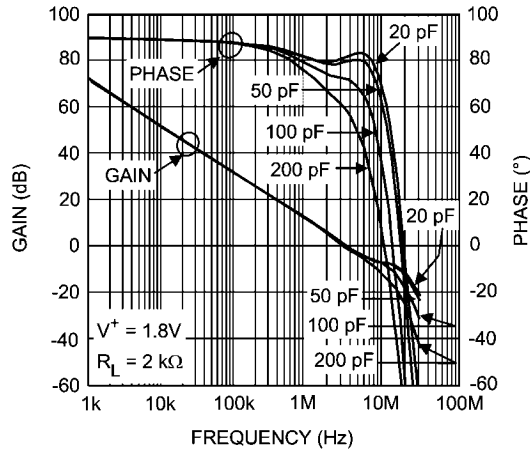
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Open Loop Gain and Phase with Resistive Load



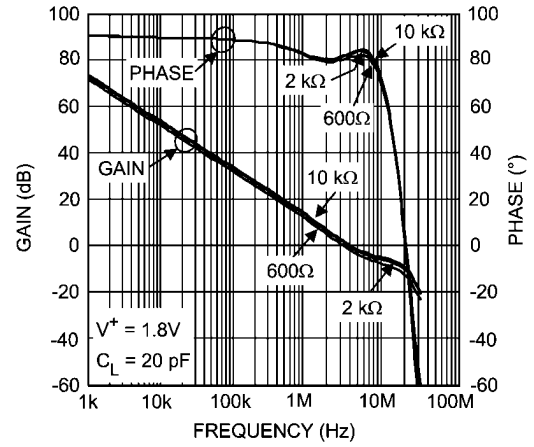
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Open Loop Gain and Phase with Capacitive Load



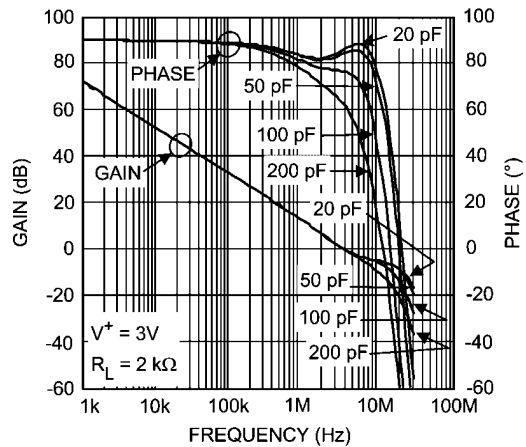
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Open Loop Gain and Phase with Resistive Load



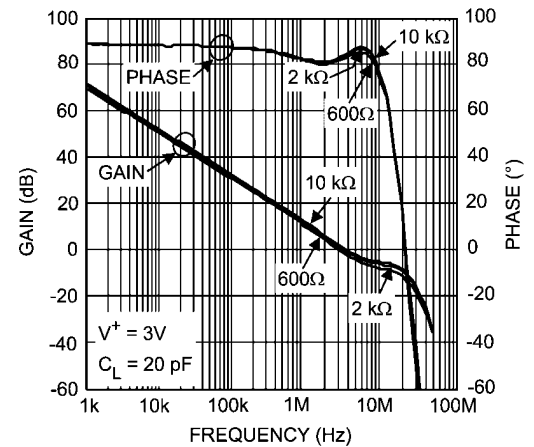
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Open Loop Gain and Phase with Capacitive Load

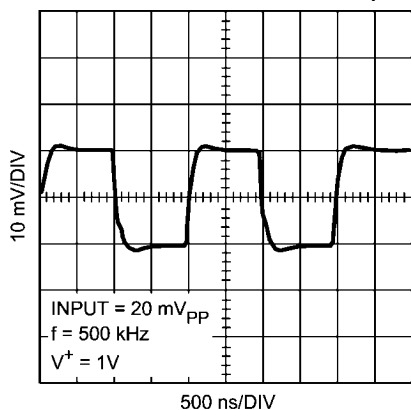


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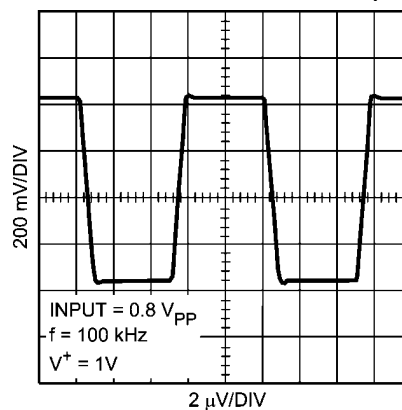
Open Loop Gain and Phase with Resistive Load



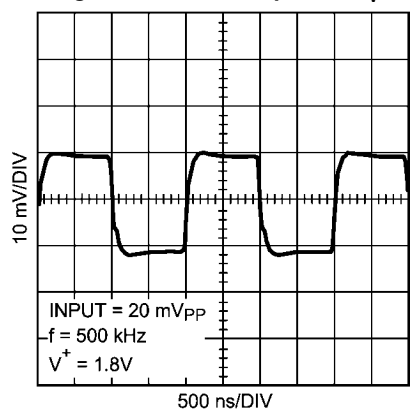
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Small Signal Transient Response, $A_V = +1$ 

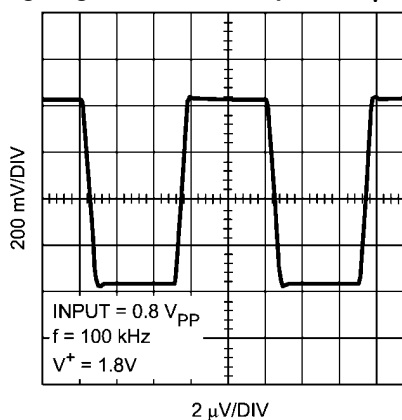
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Large Signal Transient Response, $A_V = +1$ 

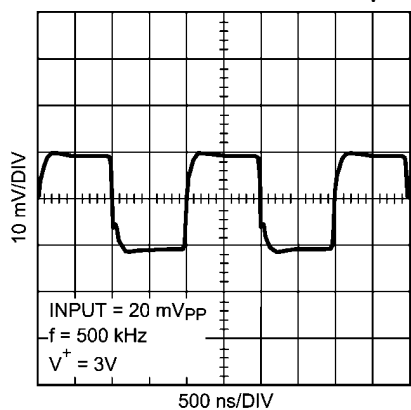
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Small Signal Transient Response, $A_V = +1$ 

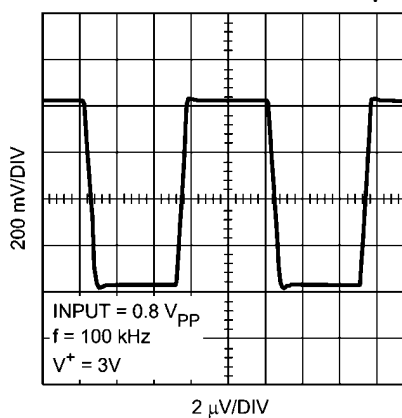
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Large Signal Transient Response, $A_V = +1$ 

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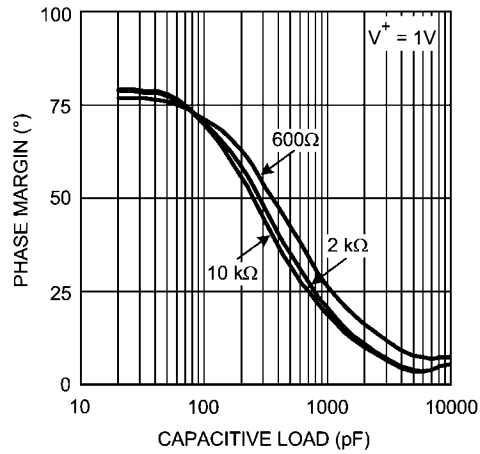
Small Signal Transient Response, $A_V = +1$ 

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Large Signal Transient Response, $A_V = +1$ 

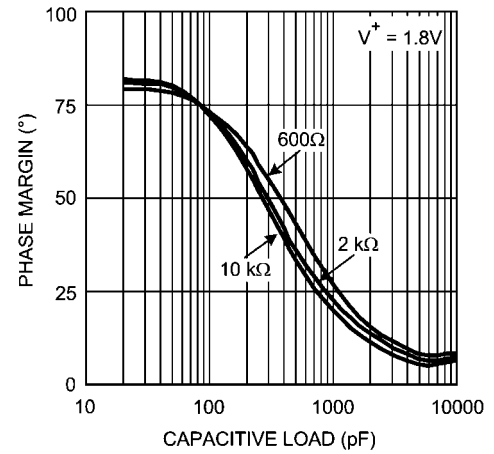
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Phase Margin vs. Capacitive Load (stability)



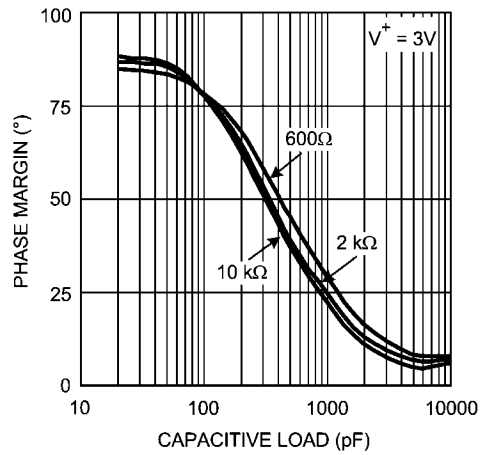
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Phase Margin vs. Capacitive Load (stability)



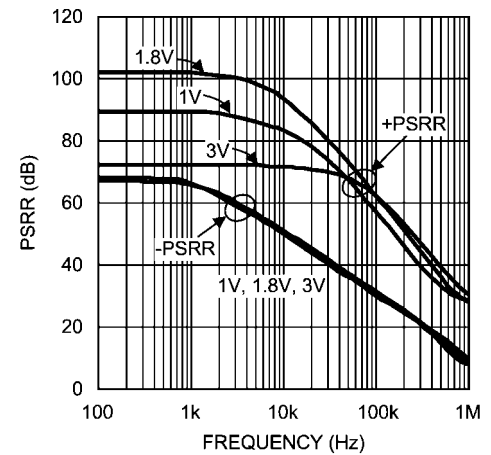
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Phase Margin vs. Capacitive Load (stability)



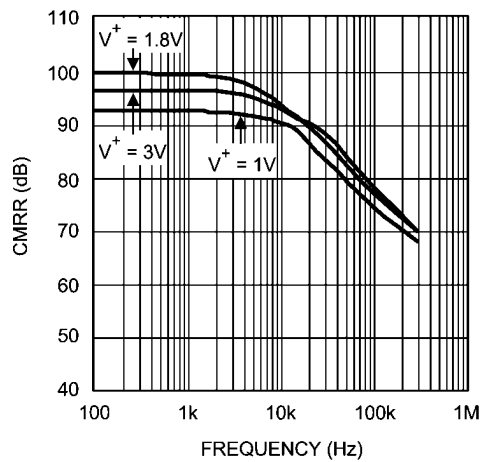
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PSRR vs. Frequency



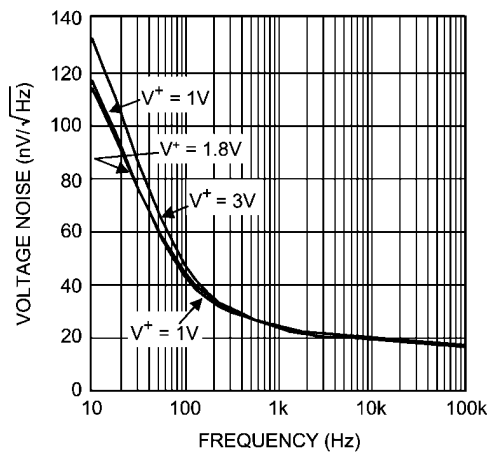
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CMRR vs. Frequency

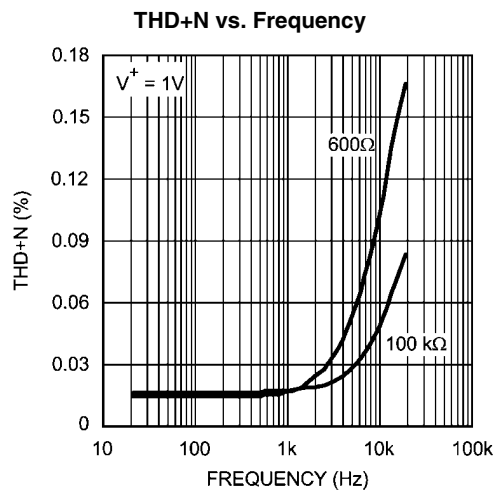


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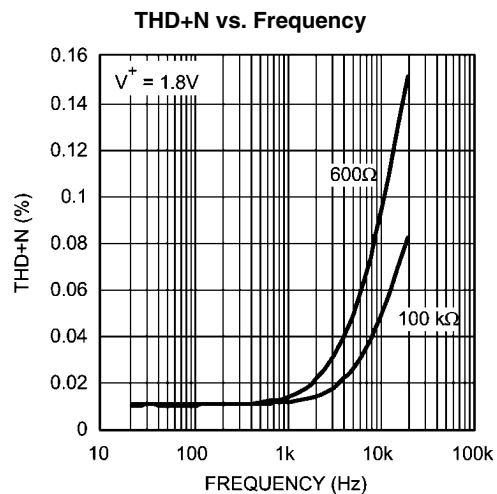
Input Referenced Voltage Noise vs. Frequency



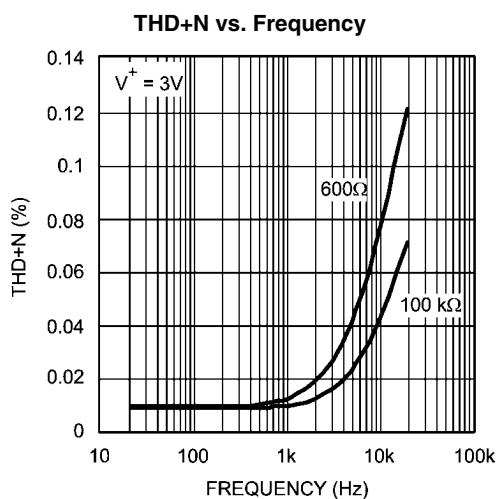
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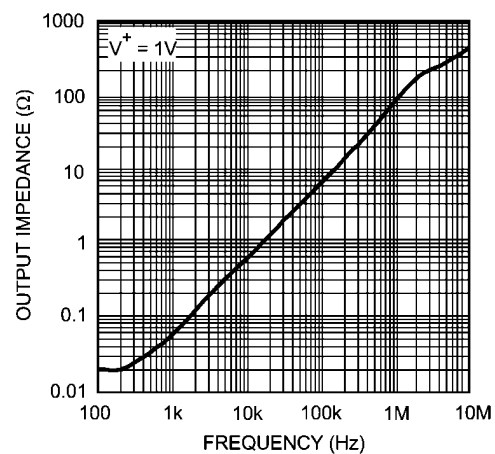
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Closed Loop Output Impedance vs. Frequency

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Application Information

CIRCUIT DESCRIPTION AND ADVANTAGE OF THE LMV951

The LMV951 utilizes an internal voltage generator which allows for rail to rail input and output operation from 1 to 3V supplies. An internal switching frequency between 10 MHz and 15 MHz is used for generating the internal voltages.

The bipolar input stage provides rail to rail input operation with no input bias current phase reversal and a constant input offset voltage over the entire input common mode range.

The CMOS output stage provides a gain that is virtually independent of resistive loads and an output drive current in excess of 35 mA at 1V. A further benefit of the output stage is that the LMV951 is stable in positive unity gain at capacitive loads in excess of 1000 pF.

Battery Operated Systems

The maximum operating voltage is 3V and the operating characteristics are guaranteed down to 1V which makes the LMV951 an excellent choice for battery operated systems using one or two NiCd or NiMH cells. The LMV951 is also functional at 0.9V making it an appropriate choice for a single cell alkaline battery.

Shutdown Capability

While in shutdown mode, the LMV951 typically consumes less than 50 nA of supply current making it ideal for power conscious applications. Full functionality is restored within 3 μ s of enable.

Small Size

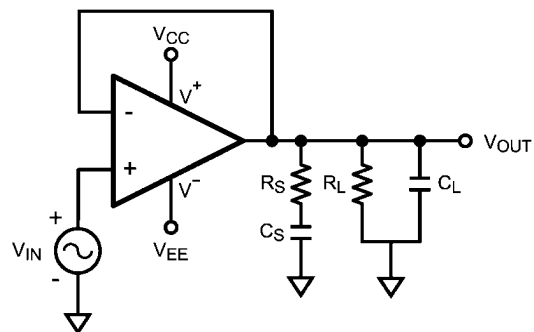
The small footprint of the LMV951 package is ideal for high density board systems. By using the small 6-Pin SOT23 package, the amplifier can be placed closer to the signal source, reducing noise pickup and increasing signal integrity.

Power Supply Bypassing

As in any high performance IC, proper power supply bypassing is necessary for optimizing the performance of the LMV951. The internal voltage generator needs proper bypassing for optimum operation. A surface mount ceramic .01 μ F capacitor must be located as close as possible to the V^+ and V^- pins (pins 2 and 6). This capacitor needs to have low ESR and a self resonant frequency above 15 MHz. A small tantalum or electrolytic capacitor with a value between 1 μ F and 10 μ F also needs to be located close to the LMV951.

DRIVING CAPACITIVE LOAD

The unity gain follower is the most sensitive op amp configuration to capacitive loading; the LMV951 can drive up to 10,000 pF in this configuration without oscillation. If the application requires a phase margin greater than those shown in the datasheet graphs, a snubber network is recommended. The snubber offers the advantage of reducing the output signal ringing while maintaining the output swing which ensures a wider dynamic range; this is especially important at lower supply voltages.

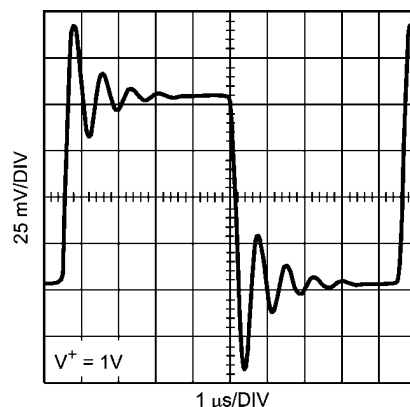


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FIGURE 1. Snubber Network to Improve Phase Margin

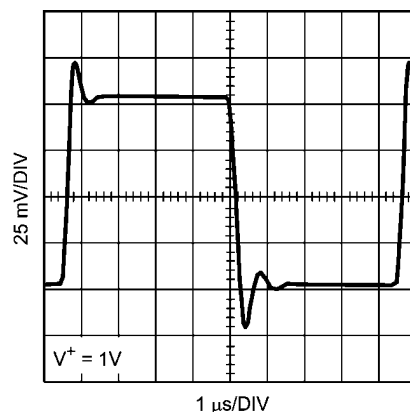
The chart below gives recommended values for some common values of large capacitors. For these values $R_L = 2 \text{ k}\Omega$;

C_L	R_S	C_S
500 pF	330 Ω	6800 pF
680 pF	270 Ω	8200 pF
1000 pF	220 Ω	.015 μ F



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FIGURE 2. 1000 pF and no Snubber



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FIGURE 3. 1000 pF with Snubber

BRIDGE CONFIGURATION AMPLIFIER

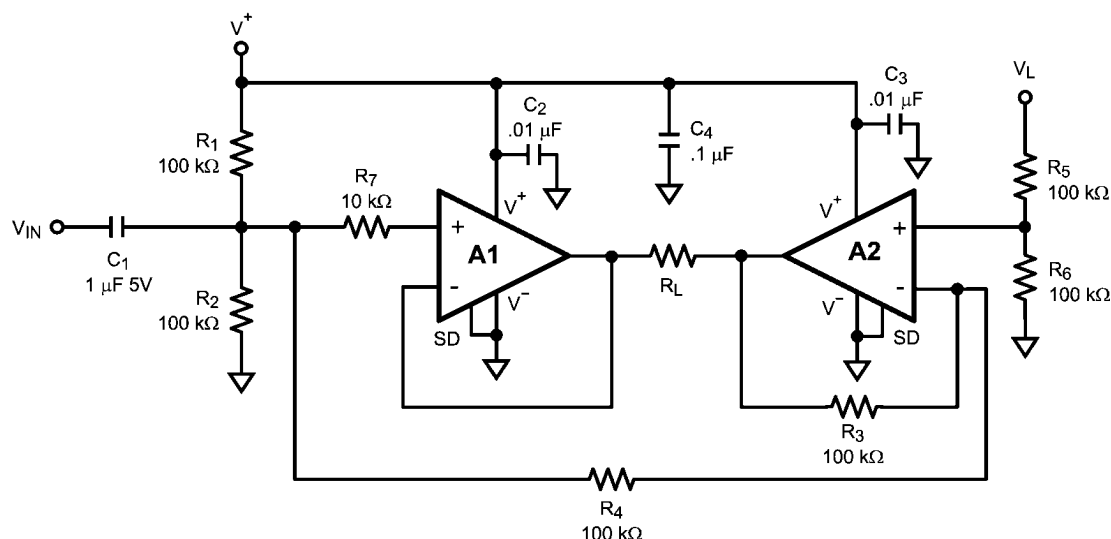
Some applications may benefit from doubling the voltage across the load. With $V^+ = 1V$ a bridge configuration can provide a $2 V_{PP}$ output to the load with a resistance as low as 300Ω . The output stage of the LMV951 enables it to drive a load of 120Ω and still swing at least 70% of the supply rails.

The bridge configuration shown in *Figure 4* enables the amplifier to maintain a low dropout voltage thus maximizing its dynamic range. It has been configured in a gain of 1 and uses the fewest number of parts.

Resistor values have been selected to keep the current consumption to a minimum and voltage errors due to bias cur-

rents negligible. Using the selected resistor values makes this circuit quite practical in a battery operated design. R_1 , R_2 and R_5 , R_6 set up a virtual ground that is half of V^+ . Note that the accuracy of the resistor values will establish how well the two virtual grounds match. Any errors in the virtual grounds will show as current across R_L when there is no input signal.

AC coupling the input signal sets the DC bias point of this signal to the virtual ground of the circuit. Using the large resistor values with a $1 \mu F$ capacitor (C_1) sets the frequency rolloff of this circuit below 10 Hz.



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FIGURE 4. Bridge Amplifier

- C_2 and C_3 are $.01 \mu F$ ceramic capacitors that must be located as close as possible to pin 6, the V^+ pin. As covered in the power supply bypassing section these capacitors must have low ESR and a self resonant frequency above 15 MHz.
- C_4 is a $1 \mu F$ tantalum or electrolytic capacitor that should also be located close to the supply pin.
- To use the shutdown feature tie pin 5 of the two parts together and connect through a $470 k\Omega$ resistor to V^+ . Add a switch between pin 5 and ground. Closing the switch keeps the parts in the active mode, opening the switch sets the parts in the shutdown mode without adding any additional current to V^+ .

VIRTUAL GROUND CIRCUIT

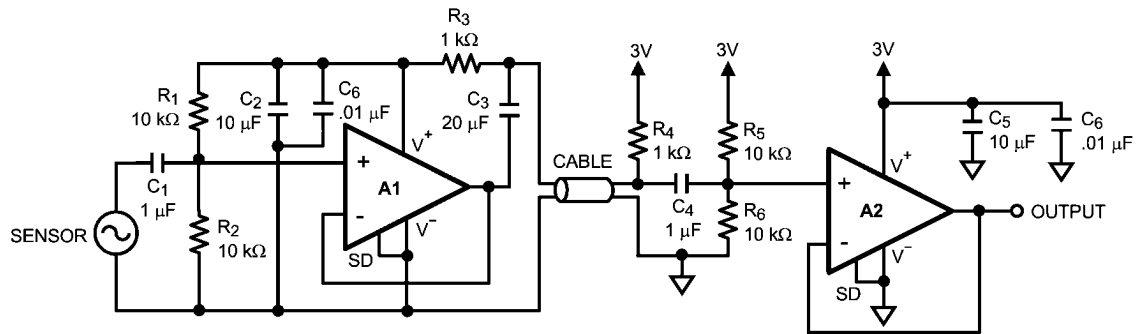
The front page of this data sheet shows the LMV951 being used in a system establishing a virtual ground. Having a buffered output stage gives this part the ability to handle load currents higher than 35 mA at 1V.

R_3 and R_4 are used to set the voltage of the virtual ground. To maintain low noise the values should be between $1 k\Omega$ and $10 k\Omega$. C_1 and C_2 provide the recommended bypassing for the LMV951. These caps must be placed as close as possible to pins 2 and 6.

TWO WIRE LINE TRANSMISSION

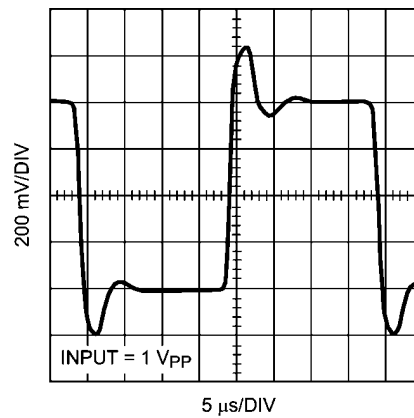
The robust output stage of the LMV951 makes it an excellent choice for driving long cables. The circuit shown below in *Figure 5* can drive a long cable using only two wires; power and ground.

When many sensors are located remotely from the control area the wiring becomes a significant expense. Using only two wires helps minimize the wiring expense in a large project such as an industrial plant. *Figure 6* shows a 25 kHz signal after passing through 1000 ft. of twisted pair cable. *Figure 7* shows a 200 kHz signal after passing through 50 ft. of twisted pair cable.



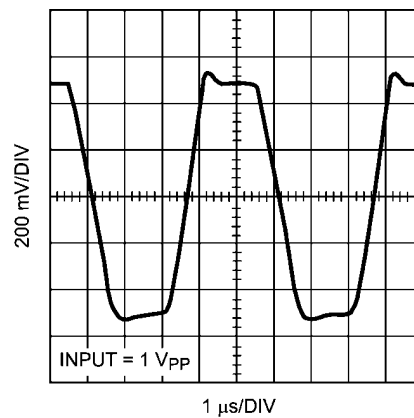
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FIGURE 5. Two Wire Line Driver



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FIGURE 6. 25 kHz Through 1000 ft.



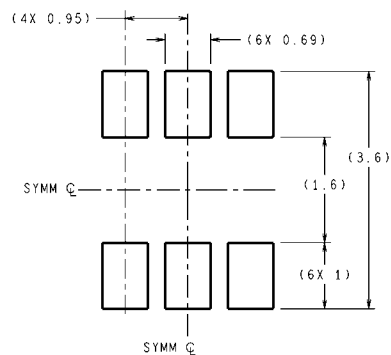
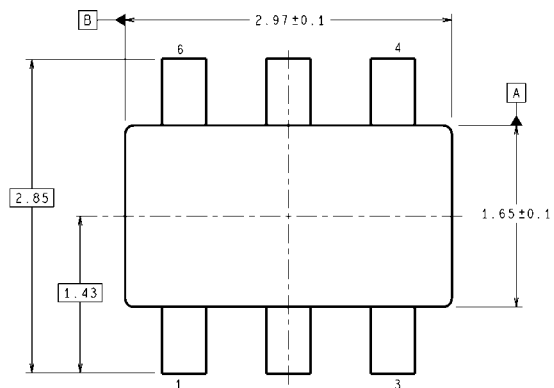
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FIGURE 7. 200 kHz Through 50 ft.

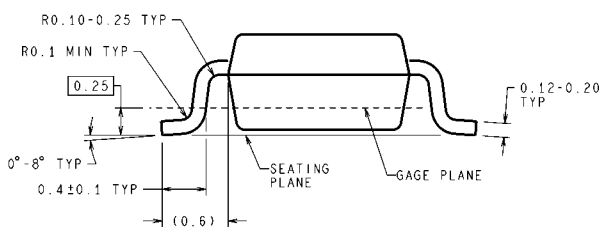
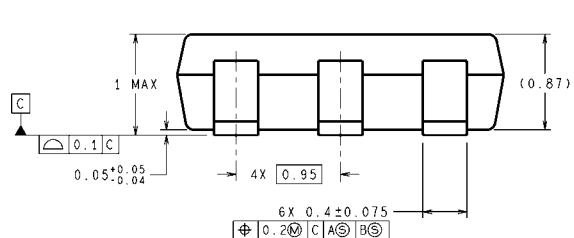
The power supply of 3V is recommended to power this system. A1 and A2 are set up as unity gain buffers. It is easy to configure A1 with the required gain if a gain of greater than one is required. C_1 along with R_1 and R_2 are used to ensure

the correct DC operating point at the input of A1. C_4 along with R_5 and R_6 are used to setup the correct DC operating point for A2. C_1 , C_3 , and C_4 have been selected to give about a 20% droop with a 1 kHz square wave input.

Physical Dimensions inches (millimeters) unless otherwise noted



RECOMMENDED LAND PATTERN



DIMENSIONS ARE IN MILLIMETERS

MK06A (Rev D)

6-Pin SOT23
NS Package Number MK06A

Notes

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