

74AXP2T45

2-bit dual supply translating transceiver; 3-state

Rev. 2 — 23 June 2022

Product data sheet

1. General description

The 74AXP2T45 is a 2-bit, dual supply transceiver with 3-state outputs that enables bidirectional level translation. It features two 2-bit input-output ports (nA and nB), a direction control input (DIR) and dual supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). Both $V_{CC(A)}$ and $V_{CC(B)}$ can be supplied at any voltage between 0.9 V and 5.5 V making the device suitable for translating between any of the low voltage nodes (0.9 V, 1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V). No power supply sequencing is required and output glitches during power supply transitions are prevented using patented circuitry. As a result glitches will not appear on the outputs for supply transitions during power-up/down between 20 mV/ μ s and 5.5 V/s. Pins A and DIR are referenced to $V_{CC(A)}$ and pin B is referenced to $V_{CC(B)}$. A HIGH on DIR allows transmission from A to B and a LOW on DIR allows transmission from B to A.

The device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either $V_{CC(A)}$ or $V_{CC(B)}$ are at GND level, both A and B are in the high-impedance OFF-state.

2. Features and benefits

- Wide supply voltage range:
 - $V_{CC(A)}$: 0.9 V to 5.5 V
 - $V_{CC(B)}$: 0.9 V to 5.5 V
- Low input capacitance; $C_I = 1.4$ pF (typical)
- Low output capacitance; $C_O = 4.4$ pF (typical)
- Low dynamic power consumption; $C_{PD} = 11$ pF (typical)
- Low static power consumption; $I_{CC} = 2$ μ A (25 °C maximum)
- High noise immunity
- Complies with JEDEC standard:
 - JESD8-12 (1.1 V to 1.3 V; inputs)
 - JESD8-11 (1.4 V to 1.6 V)
 - JESD8-7 (1.65 V to 1.95 V)
 - JESD8-5 (2.3 V to 2.7 V)
 - JESD8C (2.7 V to 3.6 V)
 - JESD12-6 (4.5 V to 5.5 V)
- ESD protection:
 - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2 kV
 - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1 kV
- Latch-up performance exceeds 100 mA per JESD78D Class II
- Inputs accept voltages up to 5.5 V
- Low noise overshoot and undershoot < 10% of V_{CCO}
- I_{OFF} circuitry provides partial power-down mode operation
- Specified from -40 °C to +125 °C

3. Ordering information

Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
74AXP2T45DC	-40 °C to +125 °C	VSSOP8	plastic very thin shrink small outline package; 8 leads; body width 2.3 mm	SOT765-1
74AXP2T45GX	-40 °C to +125 °C	X2SON8	plastic thermal enhanced extremely thin small outline package; no leads; 8 terminals; body 1.35 × 0.8 × 0.32 mm	SOT1233-2

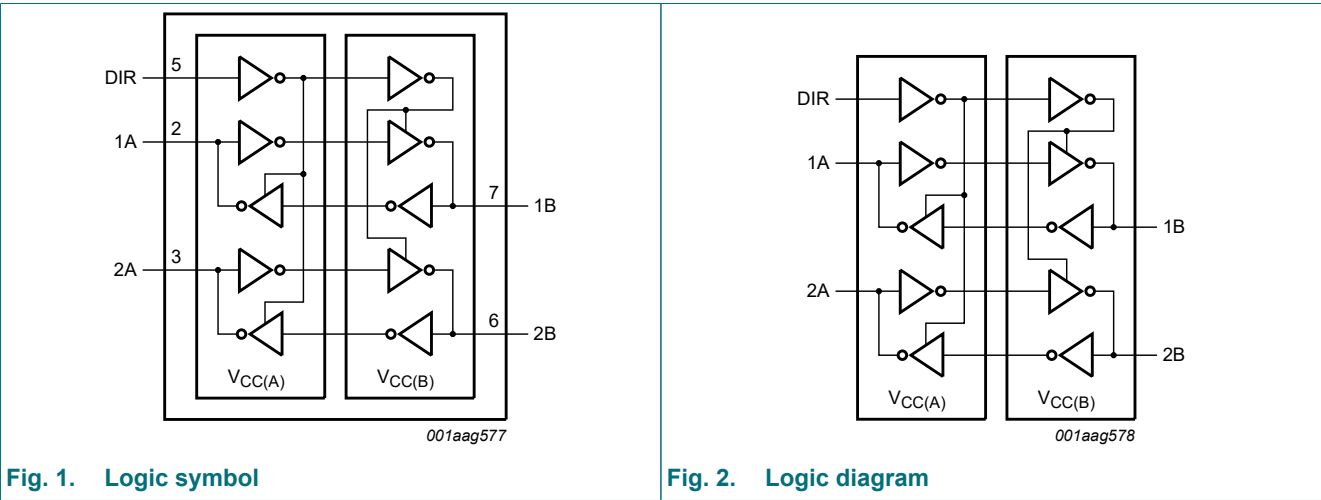
4. Marking

Table 2. Marking

Type number	Marking code[1]
74AXP2T45DC	R5
74AXP2T45GX	R5

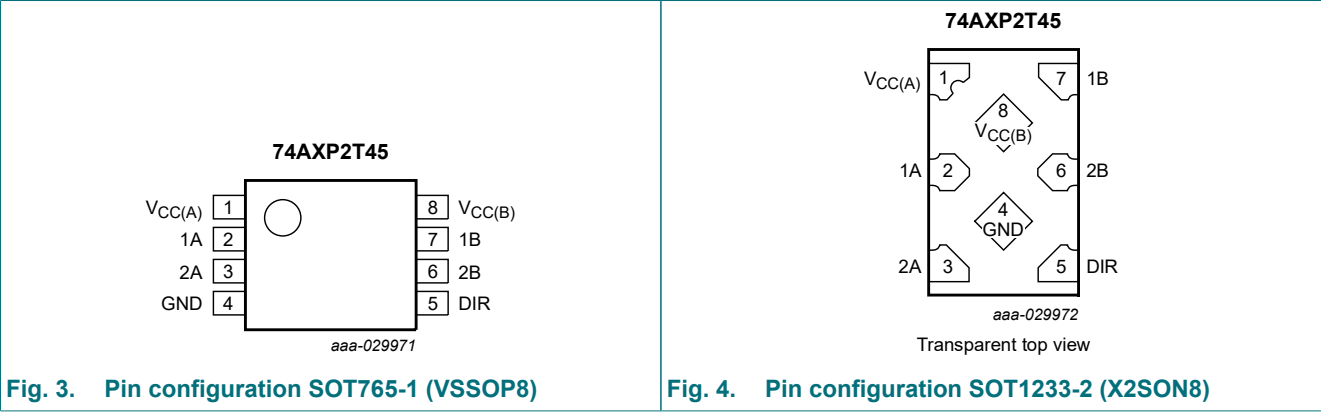
[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

5. Functional diagram



6. Pinning information

6.1. Pinning



6.2. Pin description

Table 3. Pin description

Symbol	Pin	Description
V _{CC(A)}	1	supply voltage A (nA, and DIR are referenced to V _{CC(A)})
1A	2	data input or output
2A	3	data input or output
GND	4	ground (0 V)
DIR	5	direction control
2B	6	data input or output
1B	7	data input or output
V _{CC(B)}	8	supply voltage B (nB is referenced to V _{CC(B)})

7. Functional description

Table 4. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

Supply voltage	Input	Input/output [1]	
V _{CC(A)} , V _{CC(B)}	DIR[2]	nA[2]	nB[2]
0.9 V to 5.5 V	L	nA = nB	input
0.9 V to 5.5 V	H	input	nB = nA
GND[1]	X	Z	Z

[1] If at least one of V_{CC(A)} or V_{CC(B)} is at GND level, the device goes into suspend mode.
[2] nA and DIR are referenced to V_{CC(A)}; nB is referenced to V_{CC(B)}.

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
$V_{CC(B)}$	supply voltage B		-0.5	+6.5	V
I_{IK}	input clamping current	$V_I < 0$ V	-20	-	mA
V_I	input voltage	[1]	-0.5	+6.5	V
I_{OK}	output clamping current	$V_O < 0$ V	-20	-	mA
V_O	output voltage	Active mode [1][2][3]	-0.5	$V_{CCO} + 0.5$	V
		Suspend or 3-state mode [1]	-0.5	+6.5	V
I_O	output current	$V_O = 0$ V to V_{CCO} [2]	-	±25	mA
I_{CC}	supply current	$I_{CC(A)}$ or $I_{CC(B)}$; per V_{CC} pin	-	100	mA
I_{GND}	ground current	per GND pin	-100	-	mA
T_{stg}	storage temperature		-65	+150	°C
P_{tot}	total power dissipation	$T_{amb} = -40$ °C to +125 °C			
		For SOT765-1 package [4]	-	250	mW
		For SOT1233-2 package [5]	-	300	mW

[1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V_{CCO} is the supply voltage associated with the output port.

[3] $V_{CCO} + 0.5$ V should not exceed 6.5 V.

[4] For SOT765-1 (VSSOP8) package: P_{tot} derates linearly with 4.9 mW/K above 99 °C.

[5] For SOT1233-2 (X2SON8) package: P_{tot} derates linearly with 7.7 mW/K above 118 °C.

9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		0.9	5.5	V
$V_{CC(B)}$	supply voltage B		0.9	5.5	V
V_I	input voltage		0	5.5	V
V_O	output voltage	Active mode [1]	0	V_{CCO}	V
		Suspend or 3-state mode	0	5.5	V
T_{amb}	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CCI} = 0.9$ V [2]	-	20	ns/V
		$V_{CCI} = 1.2$ V	-	20	ns/V
		$V_{CCI} = 1.4$ V to 1.95 V	-	20	ns/V
		$V_{CCI} = 2.3$ V to 2.7 V	-	20	ns/V
		$V_{CCI} = 3$ V to 3.6 V	-	10	ns/V
		$V_{CCI} = 4.5$ V to 5.5 V	-	8	ns/V

[1] V_{CCO} is the supply voltage associated with the output port.

[2] V_{CCI} is the supply voltage associated with the input port.

10. Static characteristics

Table 7. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	-40 °C to +125 °C	+25 °C		-40 °C to +85 °C	-40 °C to +125 °C	Unit
			Min	Typ	Max	Max	Max	
V _{IH}	HIGH-level input voltage	nA, nB and DIR input [1]						
		V _{CCI} = 0.9 V	0.7 × V _{CCI}	-	-	-	-	V
		V _{CCI} = 1.1 V to 1.95 V	0.65 × V _{CCI}	-	-	-	-	V
		V _{CCI} = 2.3 V to 2.7 V	1.6	-	-	-	-	V
		V _{CCI} = 3.0 V to 3.6 V	2.0	-	-	-	-	V
		V _{CCI} = 4.5 V to 5.5 V	0.7 × V _{CCI}	-	-	-	-	V
V _{IL}	LOW-level input voltage	nA, nB and DIR input [1]						
		V _{CCI} = 0.9 V	-	-	0.3 × V _{CCI}	0.3 × V _{CCI}	0.3 × V _{CCI}	V
		V _{CCI} = 1.1 V to 1.95 V	-	-	0.35 × V _{CCI}	0.35 × V _{CCI}	0.35 × V _{CCI}	V
		V _{CCI} = 2.3 V to 2.7 V	-	-	0.7	0.7	0.7	V
		V _{CCI} = 3.0 V to 3.6 V	-	-	0.8	0.8	0.8	V
		V _{CCI} = 4.5 V to 5.5 V	-	-	0.3 × V _{CCI}	0.3 × V _{CCI}	0.3 × V _{CCI}	V
V _{OH}	HIGH-level output voltage	V _I = V _{IH} [2]						
		I _O = -0.1 mA; V _{CCO} = 0.9 V to 5.5 V [3]	V _{CCO} - 0.1	0.9	-	-	-	V
		I _O = -1.5 mA; V _{CCO} = 1.1 V	0.825	-	-	-	-	V
		I _O = -3 mA; V _{CCO} = 1.4 V	1.05	-	-	-	-	V
		I _O = -4.5 mA; V _{CCO} = 1.65 V	1.2	-	-	-	-	V
		I _O = -8 mA; V _{CCO} = 2.3 V	1.7	-	-	-	-	V
		I _O = -10 mA; V _{CCO} = 3.0 V	2.2	-	-	-	-	V
		I _O = -12 mA; V _{CCO} = 4.5 V	3.7	-	-	-	-	V

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Symbol	Parameter	Conditions	-40 °C to +125 °C	+25 °C		-40 °C to +85 °C	-40 °C to +125 °C	Unit
			Min	Typ	Max	Max	Max	
V _{OL}	LOW-level output voltage	V _I = V _{IL} [2]						
		I _O = 0.1 mA; V _{CCO} = 0.9 V to 5.5 V [3]	-	0	0.1	0.1	0.1	V
		I _O = 1.5 mA; V _{CCO} = 1.1 V	-	-	0.275	0.275	0.275	V
		I _O = 3 mA; V _{CCO} = 1.4 V	-	-	0.35	0.35	0.35	V
		I _O = 4.5 mA; V _{CCO} = 1.65 V	-	-	0.45	0.45	0.45	V
		I _O = 8 mA; V _{CCO} = 2.3 V	-	-	0.7	0.7	0.7	V
		I _O = 10 mA; V _{CCO} = 3.0 V	-	-	0.8	0.8	0.8	V
		I _O = 8 mA; V _{CCO} = 4.5 V	-	-	0.5	0.5	0.5	V
		I _O = 12 mA; V _{CCO} = 4.5 V	-	-	0.8	0.8	0.8	V
I _I	input leakage current	DIR input; V _I = 0 V to 5.5 V; V _{CCI} = 0.9 V to 5.5 V	-	-	±0.1	±0.5	±1	µA
I _{OZ}	OFF-state output current	A or B port; V _O = 0 V or V _{CCO} ; V _{CCO} = 0.9 V to 5.5 V [2]	-	-	±0.1	±0.5	±2	µA
		suspend mode A port; V _O = 0 V or V _{CCO} ; V _{CC(A)} = 5.5 V; V _{CC(B)} = 0 V [2]	-	-	±0.1	±0.5	±2	µA
		suspend mode B port; V _O = 0 V or V _{CCO} ; V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V [2]	-	-	±0.1	±0.5	±2	µA
I _{OFF}	power-off leakage current	DIR input; V _I = 0 V to 5.5 V; V _{CC(A)} = 0 V; V _{CC(B)} = 0.9 V to 5.5 V	-	-	0.1	0.5	2	µA
		A port; V _I or V _O = 0 V to 5.5 V; V _{CC(A)} = 0 V; V _{CC(B)} = 0.9 V to 5.5 V	-	-	0.1	0.5	2	µA
		B port; V _I or V _O = 0 V to 5.5 V; V _{CC(B)} = 0 V; V _{CC(A)} = 0.9 V to 5.5 V	-	-	0.1	0.5	2	µA
ΔI _{OFF}	additional power-off leakage current	DIR input; V _I = 0 V or 5.5 V; V _{CC(A)} = 0 V to 0.1 V; V _{CC(B)} = 0.9 V to 5.5 V	-	-	±0.1	±0.5	±2	µA
		A port; V _O = 0 V or 5.5 V; V _{CC(A)} = 0 V to 0.1 V; V _{CC(B)} = 0.9 V to 5.5 V; V _I = 0 V or 5.5 V	-	-	±0.1	±0.5	±2	µA
		B port; V _O = 0 V or 5.5 V; V _{CC(B)} = 0 V to 0.1 V; V _{CC(A)} = 0.9 V to 5.5 V; V _I = 0 V or 5.5 V	-	-	±0.1	±0.5	±2	µA

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Symbol	Parameter	Conditions	-40 °C to +125 °C	+25 °C		-40 °C to +85 °C	-40 °C to +125 °C	Unit
			Min	Typ	Max	Max	Max	
I _{CC}	supply current	A port; V _I = 0 V or V _{CCI} ; I _O = 0 A [1]						
		V _{CC(A)} , V _{CC(B)} = 0.9 V to 5.5 V	-	-	2	5	13	µA
		V _{CC(A)} = 5.5 V; V _{CC(B)} = 0 V	-	-	2	5	13	µA
		V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V	-	-	±0.1	±0.4	±1	µA
		B port; V _I = 0 V or V _{CCI} ; I _O = 0 A						
		V _{CC(A)} , V _{CC(B)} = 0.9 V to 5.5 V	-	-	2	5	13	µA
		V _{CC(B)} = 5.5 V; V _{CC(A)} = 0 V	-	-	2	5	13	µA
		V _{CC(B)} = 0 V; V _{CC(A)} = 5.5 V	-	-	±0.1	±0.4	±1	µA
ΔI _{CC}	additional supply current	per input; other pins at V _{CCI} or ground (0 V); I _O = 0 A; V _{CC(A)} , V _{CC(B)} = 4.5 V to 5.5 V; V _I = V _{CCI} - 0.6 V [4]	-	2	100	150	200	µA

[1] V_{CCI} is the supply voltage associated with the control input or input port.

[2] V_{CCO} is the supply voltage associated with the output port.

[3] Typical values for V_{OL} and V_{OH} are measured at V_{CCO} is 0.9 V.

[4] Typical values for ΔI_{CC} are measured at V_{CC(A)}, V_{CC(B)} = 5 V.

Table 8. Typical total supply current $I_{CC(A)}$ at $T_{amb} = 25\text{ °C}$

Voltages are referenced to GND (ground = 0 V).

$V_{CC(A)}$	$V_{CC(B)}$								Unit
	0 V	0.9 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
0 V	0.00	0.01	0.01	0.01	0.01	0.01	0.01	0.01	μA
0.9 V	0.01	0.08	0.08	0.08	0.08	0.08	0.08	0.08	μA
1.2 V	0.01	0.10	0.10	0.10	0.10	0.10	0.10	0.10	μA
1.5 V	0.01	0.13	0.13	0.13	0.13	0.13	0.13	0.13	μA
1.8 V	0.01	0.16	0.16	0.16	0.16	0.16	0.16	0.16	μA
2.5 V	0.01	0.22	0.22	0.22	0.22	0.22	0.22	0.22	μA
3.3 V	0.01	0.29	0.29	0.29	0.29	0.29	0.29	0.29	μA
5.0 V	0.01	0.44	0.44	0.44	0.44	0.44	0.44	0.44	μA

Table 9. Typical total supply current $I_{CC(B)}$ at $T_{amb} = 25\text{ °C}$

Voltages are referenced to GND (ground = 0 V).

$V_{CC(A)}$	$V_{CC(B)}$								Unit
	0 V	0.9 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
0 V	0.00	0.01	0.01	0.01	0.01	0.01	0.01	0.01	μA
0.9 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA
1.2 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA
1.5 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA
1.8 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA
2.5 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA
3.3 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA
5.0 V	0.01	0.08	0.10	0.13	0.16	0.22	0.29	0.44	μA

11. Dynamic characteristics

Table 10. Typical dynamic characteristics at $V_{CC(A)} = 0.9\text{ V}$ and $T_{amb} = 25\text{ }^{\circ}\text{C}$

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	$V_{CC(B)}$							Unit
			0.9 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
t_{pd}	propagation delay	nA to nB [1]	40	22	18.5	16.5	15	15	15	ns
		nB to nA [1]	40	33	32	31	31	31	32	ns
t_{dis}	disable time	DIR to nA [1]	34	34	34	34	34	34	34	ns
		DIR to nB [1]	42	30	26	26	24	25	23	ns
t_{en}	enable time	DIR to nA [1]	82	63	58	57	55	56	55	ns
		DIR to nB [1]	74	56	53	51	49	49	49	ns

[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

Table 11. Typical dynamic characteristics at $V_{CC(B)} = 0.9\text{ V}$ and $T_{amb} = 25\text{ }^{\circ}\text{C}$

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	$V_{CC(A)}$							Unit
			0.9 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
t_{pd}	propagation delay	nA to nB [1]	40	33	32	31	31	31	32	ns
		nB to nA [1]	40	22	18.5	16.5	15	15	15	ns
t_{dis}	disable time	DIR to nA [1]	34	16	11	10	7.0	7.7	5.3	ns
		DIR to nB [1]	42	31	28	28	27	27	27	ns
t_{en}	enable time	DIR to nA [1]	82	53	47	45	42	42	42	ns
		DIR to nB [1]	74	49	43	41	38	39	37	ns

[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

Table 12. Typical dynamic characteristics at $T_{amb} = 25\text{ }^{\circ}\text{C}$

[1][2] Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7.

Symbol	Parameter	Conditions	$V_{CC(A)}$ and $V_{CC(B)}$							Unit
			0.9 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
C_{PD}	power dissipation capacitance	A port: (direction nA to nB); B port: (direction nB to nA)	1.5	1.6	1.7	1.8	1.9	2.2	2.7	pF
		A port: (direction nB to nA); B port: (direction nA to nB)	9.7	10.2	10.3	10.4	10.7	11	11.9	pF
C_I	input capacitance	$V_I = 0\text{ V}$ or V_{CCI} ; $V_{CCI} = 0\text{ V}$ to 5.5 V	1.4	1.4	1.4	1.4	1.4	1.4	1.4	pF
$C_{I/O}$	input/output capacitance	$V_O = 0\text{ V}$; $V_{CCO} = 0\text{ V}$	4.4	4.4	4.4	4.4	4.4	4.4	4.4	pF

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

$$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma(C_L \times V_{CC}^2 \times f_o) \text{ where:}$$

f_i = input frequency in MHz;

f_o = output frequency in MHz;

C_L = load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

$\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs.

[2] $f_i = 1\text{ MHz}$; $V_I = \text{GND to } V_{CC}$; $t_r = t_f = 1\text{ ns}$; $C_L = 0\text{ pF}$; $R_L = \infty\text{ }\Omega$.

Table 13. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	V _{CC(B)}												Unit
			1.2 V ± 0.1 V		1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t _{pd}	propagation delay	nA to nB [1]													
		V _{CC(A)} = 1.2 V ± 0.1 V	4.0	38	3.6	25	3.4	21	3.1	16	2.9	14.5	2.7	14.5	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	3.5	33	3.0	21	2.8	16.5	2.6	12.5	2.4	10.5	2.2	9.8	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	3.1	32	2.7	19	2.4	15	2.2	11	2.1	9.0	1.9	8.2	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	2.8	31	2.4	17.5	2.1	13.5	1.9	9.1	1.7	7.5	1.6	6.6	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	2.7	31	2.3	17	2.0	13	1.8	8.5	1.6	6.9	1.4	5.8	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	2.7	31	2.2	16.5	1.9	12.5	1.6	8.1	1.4	6.4	1.2	5.0	ns
		nB to nA													
		V _{CC(A)} = 1.2 V ± 0.1 V	4.0	38	3.5	33	3.1	32	2.8	31	2.7	31	2.7	31	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	3.6	25	3.0	21	2.7	19	2.4	17.5	2.3	17	2.2	16.5	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	3.4	21	2.8	16.5	2.4	15	2.1	13.5	2.0	13	1.9	12.5	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	3.1	16	2.6	12.5	2.2	11	1.9	9.1	1.8	8.5	1.6	8.1	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	2.9	14.5	2.4	10.5	2.1	9.0	1.7	7.5	1.6	6.9	1.4	6.4	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	2.7	14.5	2.2	9.8	1.9	8.2	1.6	6.6	1.4	5.8	1.2	5.0	ns

Symbol	Parameter	Conditions	V _{CC(B)}												Unit
			1.2 V ± 0.1 V		1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t _{en}	enable time	DIR to nA [1]													
		V _{CC(A)} = 1.2 V ± 0.1 V	9.6	67.3	9.6	67.3	9.6	67.3	9.6	67.3	9.6	67.3	9.6	67.3	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	7.4	37.5	7.4	37.5	7.4	37.5	7.4	37.5	7.4	37.5	7.4	37.5	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	6.7	29	6.7	29	6.7	29	6.7	29	6.7	29	6.7	29	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	4.9	19	4.9	19	4.9	19	4.9	19	4.9	19	4.9	19	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	5.3	17.3	5.3	17.3	5.3	17.3	5.3	17.3	5.3	17.3	5.3	17.3	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	3.7	12	3.7	12	3.7	12	3.7	12	3.7	12	3.7	12	ns
		DIR to nB													
		V _{CC(A)} = 1.2 V ± 0.1 V	8.9	58.3	8.5	49.3	8.3	47	8.0	45.8	7.8	45	7.6	44.7	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	7.4	45.2	6.9	32.5	6.7	29.8	6.5	27.2	6.3	26.6	6.1	26	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	7.1	42	6.7	28.9	6.4	26.2	6.2	23.9	6.1	23	5.9	22.5	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	5.7	37	5.3	25	5.0	22.5	4.8	20.1	4.6	19	4.5	18.4	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	6.2	37.2	5.8	23.8	5.5	21.2	5.3	18.6	5.1	17.7	4.9	17.1	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	5.1	33.7	4.6	21	4.3	18.2	4.0	15.7	3.8	14.6	3.6	13.9	ns

Symbol	Parameter	Conditions	V _{CC(B)}												Unit
			1.2 V ± 0.1 V		1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t _{dis}	disable time	DIR to nA [1]													
		V _{CC(A)} = 1.2 V ± 0.1 V	4.9	31	4.9	31	4.9	31	4.9	31	4.9	31	4.9	31	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	3.9	17.8	3.9	17.8	3.9	17.8	3.9	17.8	3.9	17.8	3.9	17.8	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	4.0	15.9	4.0	15.9	4.0	15.9	4.0	15.9	4.0	15.9	4.0	15.9	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	2.9	12.9	2.9	12.9	2.9	12.9	2.9	12.9	2.9	12.9	2.9	12.9	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	3.5	12.3	3.5	12.3	3.5	12.3	3.5	12.3	3.5	12.3	3.5	12.3	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	2.4	9.6	2.4	9.6	2.4	9.6	2.4	9.6	2.4	9.6	2.4	9.6	ns
		DIR to nB													
		V _{CC(A)} = 1.2 V ± 0.1 V	5.6	36.8	4.8	27.9	5.1	26.7	4.4	22.8	5.1	23.5	4.1	20.7	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	5.1	32.3	4.4	23.1	4.6	21.8	3.8	17.6	4.6	18.5	3.6	15.8	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	4.7	30.9	4.0	21.5	4.3	20	3.4	16	4.2	15.5	3.3	13.2	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	4.3	29	3.6	20	3.9	17.7	3.0	14	3.9	14.3	2.9	10.7	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	4.2	28.9	3.5	19	3.7	16.7	2.9	12.6	3.7	13	2.7	10.3	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	4.1	27.8	3.3	18.9	3.6	16.5	2.7	12.4	3.5	12.4	2.5	9.4	ns
t _t	transition time	nA, nB output													
		V _{CC(A)} = 1.1 V to 5.5 V	1.0	-	1.0	-	1.0	-	1.0	-	1.0	-	1.0	-	ns

[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

Table 14. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	V _{CC(B)}												Unit
			1.2 V ± 0.1 V		1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t _{pd}	propagation delay	nA to nB [1]													
		V _{CC(A)} = 1.2 V ± 0.1 V	4.0	38	3.6	26	3.4	22	3.1	17	2.9	15	2.7	15	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	3.5	33	3.0	22	2.8	17.5	2.6	13.5	2.4	11.5	2.2	10.5	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	3.1	32	2.7	20	2.4	16	2.2	12	2.1	9.7	1.9	9.4	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	2.8	31	2.4	18.5	2.1	14.5	1.9	9.8	1.7	8.1	1.6	7.1	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	2.7	31	2.3	18	2.0	14	1.8	9.2	1.6	7.5	1.4	6.3	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	2.7	31	2.2	17.5	1.9	13.5	1.6	8.8	1.4	6.9	1.2	5.5	ns
		nB to nA													
		V _{CC(A)} = 1.2 V ± 0.1 V	4.0	38	3.5	33	3.1	32	2.8	31	2.7	31	2.7	31	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	3.6	26	3.0	22	2.7	20	2.4	18.5	2.3	18	2.2	17.5	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	3.4	22	2.8	17.5	2.4	16	2.1	14.5	2.0	14	1.9	13.5	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	3.1	17	2.6	13.5	2.2	12	1.9	9.8	1.8	9.2	1.6	8.8	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	2.9	15	2.4	11.5	2.1	9.7	1.7	8.1	1.6	7.5	1.4	6.9	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	2.7	15	2.2	10.5	1.9	9.4	1.6	7.1	1.4	6.3	1.2	5.5	ns

Symbol	Parameter	Conditions	V _{CC(B)}												Unit
			1.2 V ± 0.1 V		1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t _{en}	enable time	DIR to nA [1]													
		V _{CC(A)} = 1.2 V ± 0.1 V	9.6	67.6	9.6	67.6	9.6	67.6	9.6	67.6	9.6	67.6	9.6	67.6	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	7.4	38	7.4	38	7.4	38	7.4	38	7.4	38	7.4	38	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	6.7	30.2	6.7	30.2	6.7	30.2	6.7	30.2	6.7	30.2	6.7	30.2	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	4.9	19.9	4.9	19.9	4.9	19.9	4.9	19.9	4.9	19.9	4.9	19.9	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	5.3	17.9	5.3	17.9	5.3	17.9	5.3	17.9	5.3	17.9	5.3	17.9	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	3.7	12.2	3.7	12.2	3.7	12.2	3.7	12.2	3.7	12.2	3.7	12.2	ns
		DIR to nB													
		V _{CC(A)} = 1.2 V ± 0.1 V	8.9	58.6	8.5	49.8	8.3	47.3	8.0	46	7.8	45.5	7.6	44.9	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	7.4	45.9	6.9	33.3	6.7	30	6.5	27.8	6.3	26.8	6.1	26.3	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	7.1	42.5	6.7	30	6.4	27	6.2	24.5	6.1	24	5.9	23	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	5.7	37.6	5.3	25.2	5.0	22.7	4.8	20.3	4.6	19.2	4.5	18.5	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	6.2	37.5	5.8	24.8	5.5	21.5	5.3	18.9	5.1	18	4.9	17.3	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	5.1	34.1	4.6	21.5	4.3	18.5	4.0	15.9	3.8	14.8	3.6	14	ns

Symbol	Parameter	Conditions	V _{CC(B)}												Unit
			1.2 V ± 0.1 V		1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
t _{dis}	disable time	DIR to nA [1]													
		V _{CC(A)} = 1.2 V ± 0.1 V	4.9	31.2	4.9	31.2	4.9	31.2	4.9	31.2	4.9	31.2	4.9	31.2	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	3.9	18	3.9	18	3.9	18	3.9	18	3.9	18	3.9	18	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	4.0	16	4.0	16	4.0	16	4.0	16	4.0	16	4.0	16	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	2.9	13	2.9	13	2.9	13	2.9	13	2.9	13	2.9	13	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	3.5	12.4	3.5	12.4	3.5	12.4	3.5	12.4	3.5	12.4	3.5	12.4	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	2.4	9.7	2.4	9.7	2.4	9.7	2.4	9.7	2.4	9.7	2.4	9.7	ns
		DIR to nB													
		V _{CC(A)} = 1.2 V ± 0.1 V	5.6	37	4.8	28.3	5.1	27.1	4.4	23.2	5.1	23.8	4.1	21	ns
		V _{CC(A)} = 1.5 V ± 0.1 V	5.1	32.6	4.4	23.6	4.6	22	3.8	18	4.6	18.7	3.6	16	ns
		V _{CC(A)} = 1.8 V ± 0.15 V	4.7	31.1	4.0	22	4.3	20.1	3.4	16.1	4.2	15.6	3.3	13.4	ns
		V _{CC(A)} = 2.5 V ± 0.2 V	4.3	29.8	3.6	20.2	3.9	17.9	3.0	14.1	3.9	14.4	2.9	10.9	ns
		V _{CC(A)} = 3.3 V ± 0.3 V	4.2	29.1	3.5	19.1	3.7	16.9	2.9	12.9	3.7	13.1	2.7	10.4	ns
		V _{CC(A)} = 5.0 V ± 0.5 V	4.1	28	3.3	19	3.6	16.7	2.7	12.5	3.5	12.5	2.5	9.5	ns
t _t	transition time	nA, nB output													
		V _{CC(A)} = 1.1 V to 5.5 V	1.0	-	1.0	-	1.0	-	1.0	-	1.0	-	1.0	-	ns

[1] t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

11.1. Waveforms and test circuit

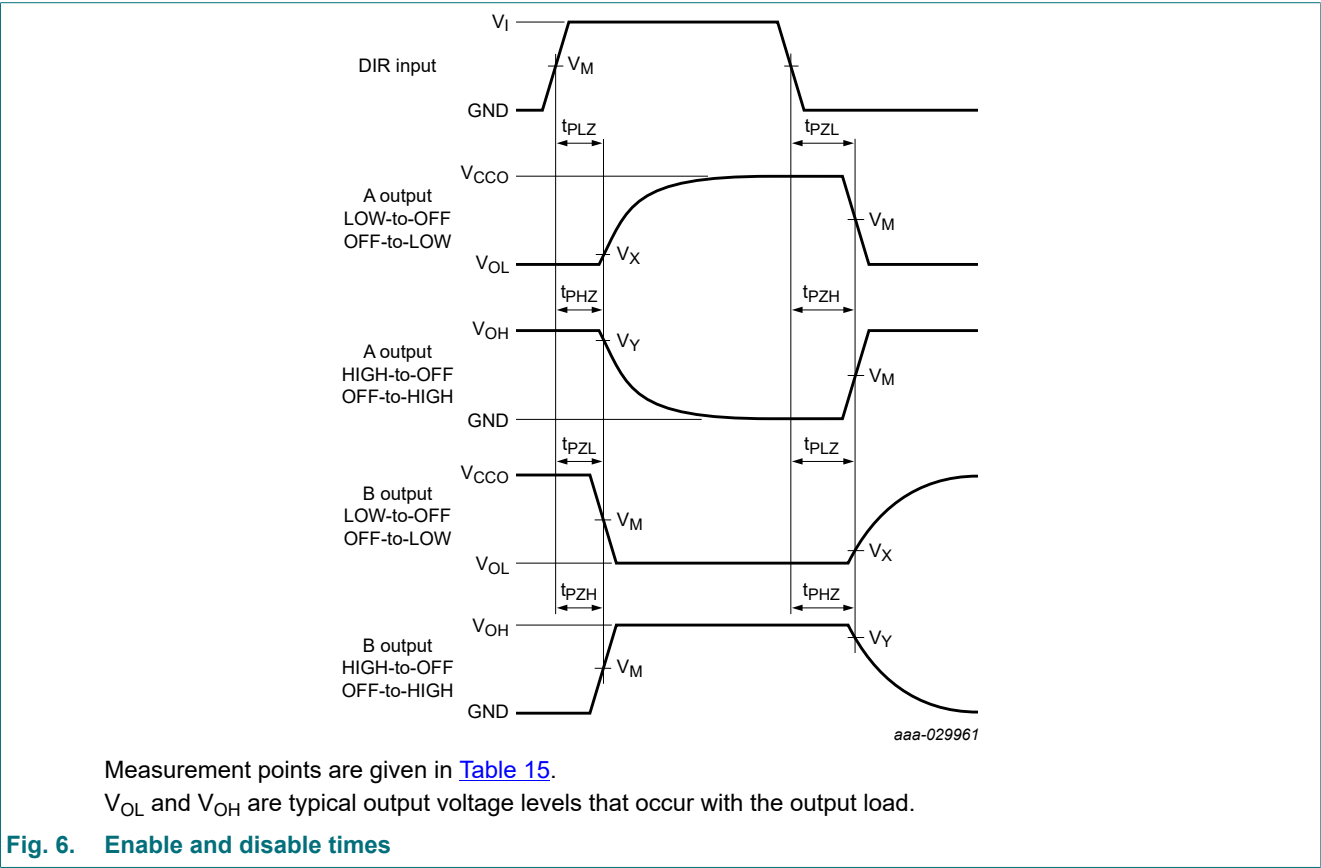
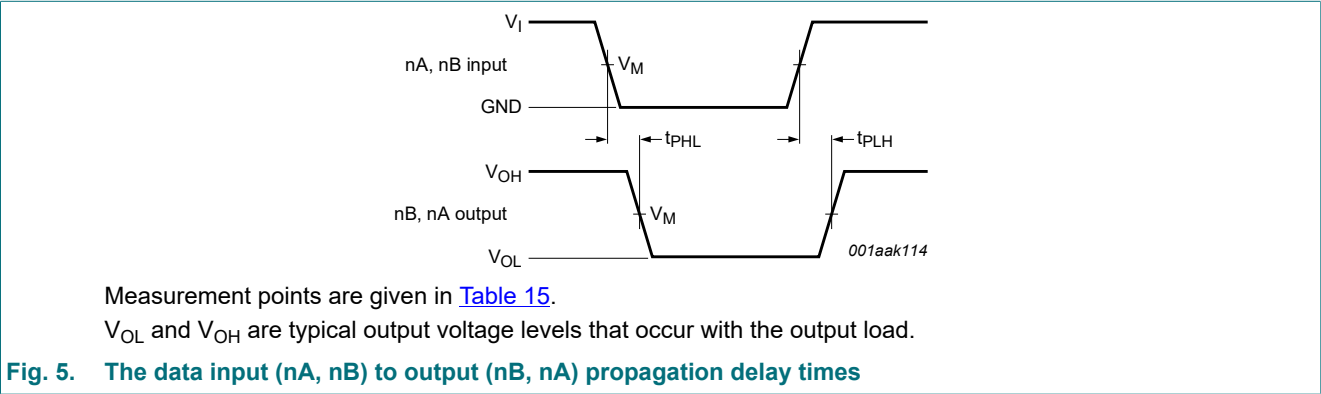


Table 15. Measurement points

Supply voltage	Input [1]	Output [2]		
$V_{CC(A)}, V_{CC(B)}$	V_M	V_M	V_X	V_Y
0.9 V to 1.6 V	$0.5 \times V_{CCI}$	$0.5 \times V_{CCO}$	$V_{OL} + 0.1 \text{ V}$	$V_{OH} - 0.1 \text{ V}$
1.65 V to 2.7 V	$0.5 \times V_{CCI}$	$0.5 \times V_{CCO}$	$V_{OL} + 0.15 \text{ V}$	$V_{OH} - 0.15 \text{ V}$
3.0 V to 5.5 V	$0.5 \times V_{CCI}$	$0.5 \times V_{CCO}$	$V_{OL} + 0.3 \text{ V}$	$V_{OH} - 0.3 \text{ V}$

[1] V_{CCI} is the supply voltage associated with the control input or input port.
[2] V_{CCO} is the supply voltage associated with the output port.

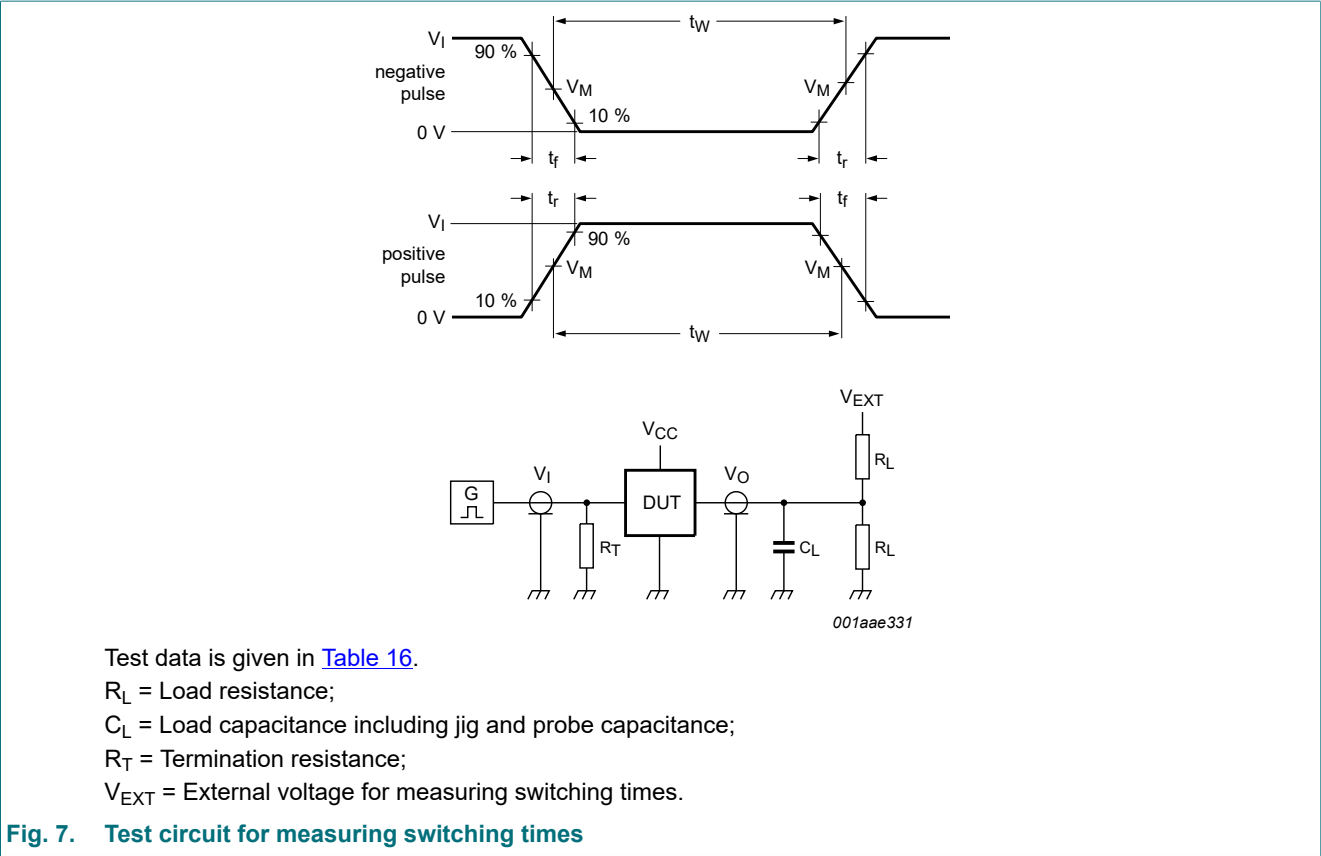
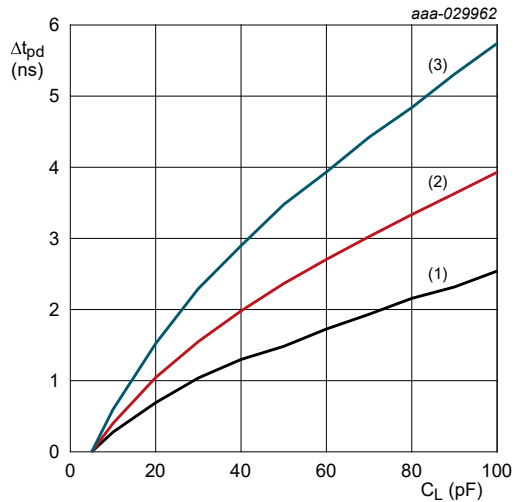


Table 16. Test data

Supply voltage	Load		Input		V_{EXT}		
$V_{CC(A)}, V_{CC(B)}$	C_L	R_L	t_r, t_f	V_I [1]	t_{PLH}, t_{PHL}	t_{PZH}, t_{PHZ}	t_{PZL}, t_{PLZ} [2]
0.9 V to 5.5 V	5 pF	10 k Ω	≤ 3.0 ns	V_{CCI}	GND	GND	$2 \times V_{CCO}$

[1] V_{CCI} is the supply voltage associated with the control input or input port.
[2] V_{CCO} is the supply voltage associated with the output port.

11.2. Additional propagation delay versus load capacitance graphs



$T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

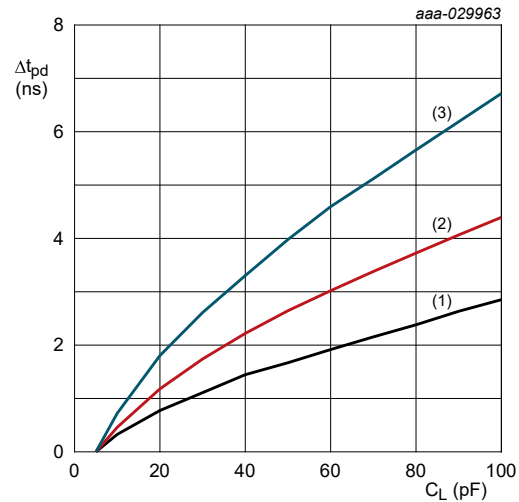
For t_{PLH} , t_{PHL} , t_{PZH} and t_{PZL}

(1) Minimum: $V_{CCO} = 5.5\text{ V}$

(2) Typical: $T_{amb} = 25\text{ }^{\circ}\text{C}$; $V_{CCO} = 5\text{ V}$

(3) Maximum: $V_{CCO} = 4.5\text{ V}$

Fig. 8. Additional propagation delay versus load capacitance



$T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

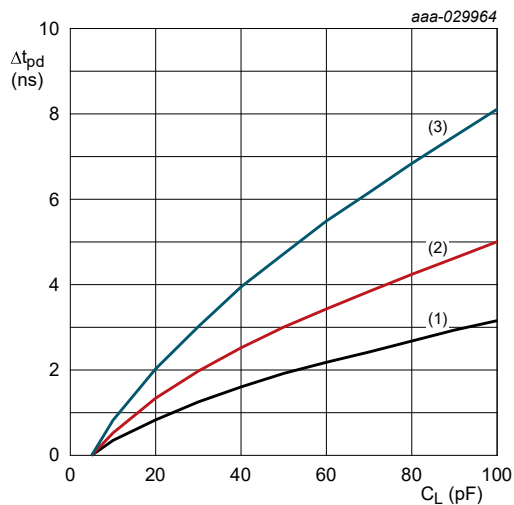
For t_{PLH} , t_{PHL} , t_{PZH} and t_{PZL}

(1) Minimum: $V_{CCO} = 3.6\text{ V}$

(2) Typical: $T_{amb} = 25\text{ }^{\circ}\text{C}$; $V_{CCO} = 3.3\text{ V}$

(3) Maximum: $V_{CCO} = 3\text{ V}$

Fig. 9. Additional propagation delay versus load capacitance



$T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

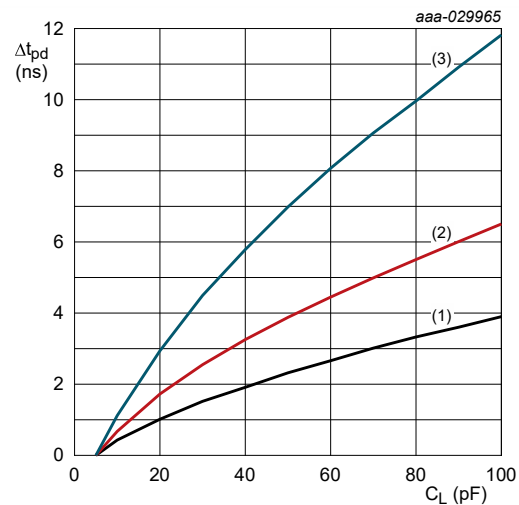
For t_{PLH} , t_{PHL} , t_{PZH} and t_{PZL}

(1) Minimum: $V_{CCO} = 2.7\text{ V}$

(2) Typical: $T_{amb} = 25\text{ }^{\circ}\text{C}$; $V_{CCO} = 2.5\text{ V}$

(3) Maximum: $V_{CCO} = 2.3\text{ V}$

Fig. 10. Additional propagation delay versus load capacitance



$T_{amb} = -40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

For t_{PLH} , t_{PHL} , t_{PZH} and t_{PZL}

(1) Minimum: $V_{CCO} = 1.95\text{ V}$

(2) Typical: $T_{amb} = 25\text{ }^{\circ}\text{C}$; $V_{CCO} = 1.8\text{ V}$

(3) Maximum: $V_{CCO} = 1.65\text{ V}$

Fig. 11. Additional propagation delay versus load capacitance

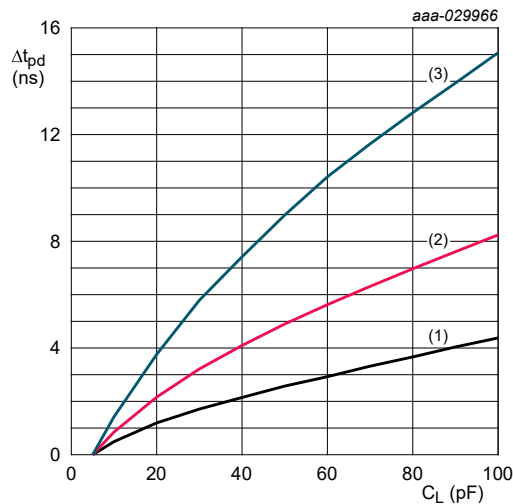


Fig. 12. Additional propagation delay versus load capacitance

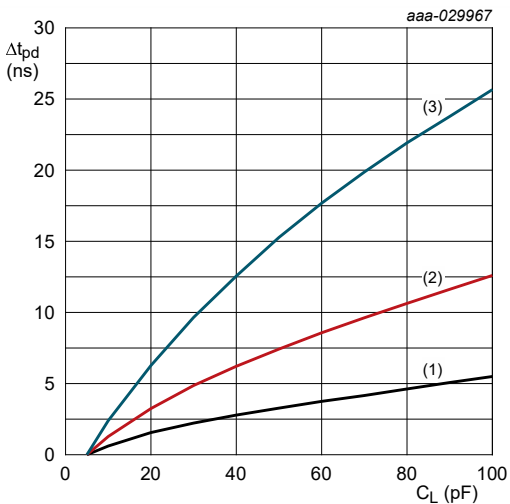


Fig. 13. Additional propagation delay versus load capacitance

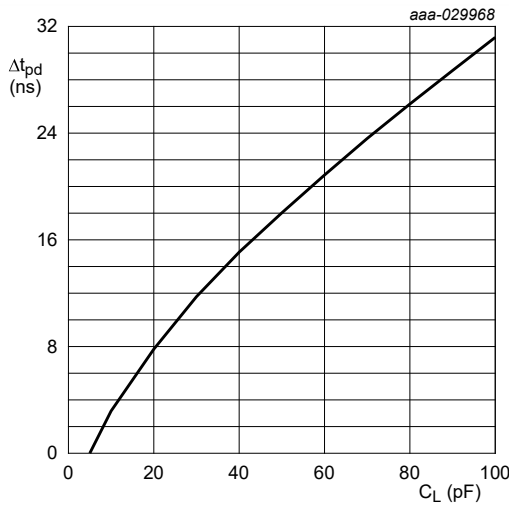


Fig. 14. Additional propagation delay versus load capacitance

12. Application information

12.1. Unidirectional logic level-shifting application

The circuit given in Fig. 15 is an example of the 74AXP2T45 being used in an unidirectional logic level-shifting application.

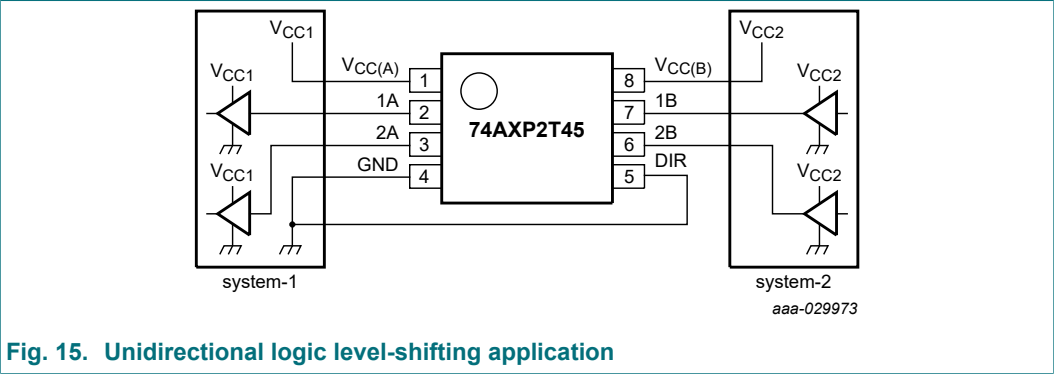


Fig. 15. Unidirectional logic level-shifting application

Table 17. Unidirectional logic level-shifting application

Pin	Name	Function	Description
1	V _{CC(A)}	V _{CC1}	supply voltage of system-1 (0.9 V to 5.5 V)
2	1A	OUT1	output level depends on V _{CC1} voltage
3	2A	OUT2	output level depends on V _{CC1} voltage
4	GND	GND	device GND
5	DIR	DIR	the GND (LOW level) determines B port to A port direction
6	2B	IN2	input threshold value depends on V _{CC2} voltage
7	1B	IN1	input threshold value depends on V _{CC2} voltage
8	V _{CC(B)}	V _{CC2}	supply voltage of system-2 (0.9 V to 5.5 V)

12.2. Bidirectional logic level-shifting application

Fig. 16 shows the 74AXP2T45 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable (OE) pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.

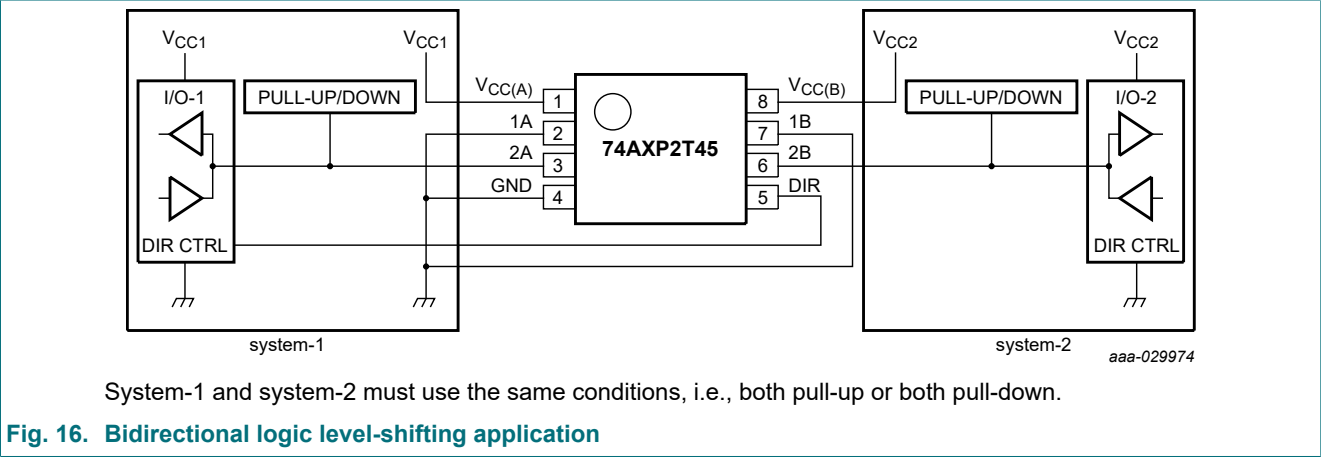


Table 18 gives a sequence that will illustrate data transmission from system-1 to system-2 and then from system-2 to system-1.

Table 18. Bidirectional logic level-shifting application [1] [2]

State	DIR CTRL	I/O-1	I/O-2	Description
1	H	output	input	system-1 data to system-2
2	H	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on the pull-up or pull-down.
3	L	Z	Z	DIR bit is set LOW. I/O-1 and I/O-2 still are disabled. The bus-line state depends on the pull-up or pull-down.
4	L	input	output	system-2 data to system-1

[1] System-1 and system-2 must use the same conditions, i.e., both pull-up or both pull-down.
[2] H = HIGH voltage level; L = LOW voltage level; Z = high-impedance OFF-state.

12.3. Enable times

Calculate the enable times for the 74AXP2T45 using the following formulas:

- Direction A to B:
 - $t_{PZL} \text{ (DIR to B)} = t_{PHL} \text{ (A to B)} + t_{PHZ} \text{ (DIR to A)}$
 - $t_{PZH} \text{ (DIR to B)} = t_{PLH} \text{ (A to B)} + t_{PLZ} \text{ (DIR to A)}$
- Direction B to A:
 - $t_{PZL} \text{ (DIR to A)} = t_{PHL} \text{ (B to A)} + t_{PHZ} \text{ (DIR to B)}$
 - $t_{PZH} \text{ (DIR to A)} = t_{PLH} \text{ (B to A)} + t_{PLZ} \text{ (DIR to B)}$

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74AXP2T45 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

13. Package outline

VSSOP8: plastic very thin shrink small outline package; 8 leads; body width 2.3 mm

SOT765-1

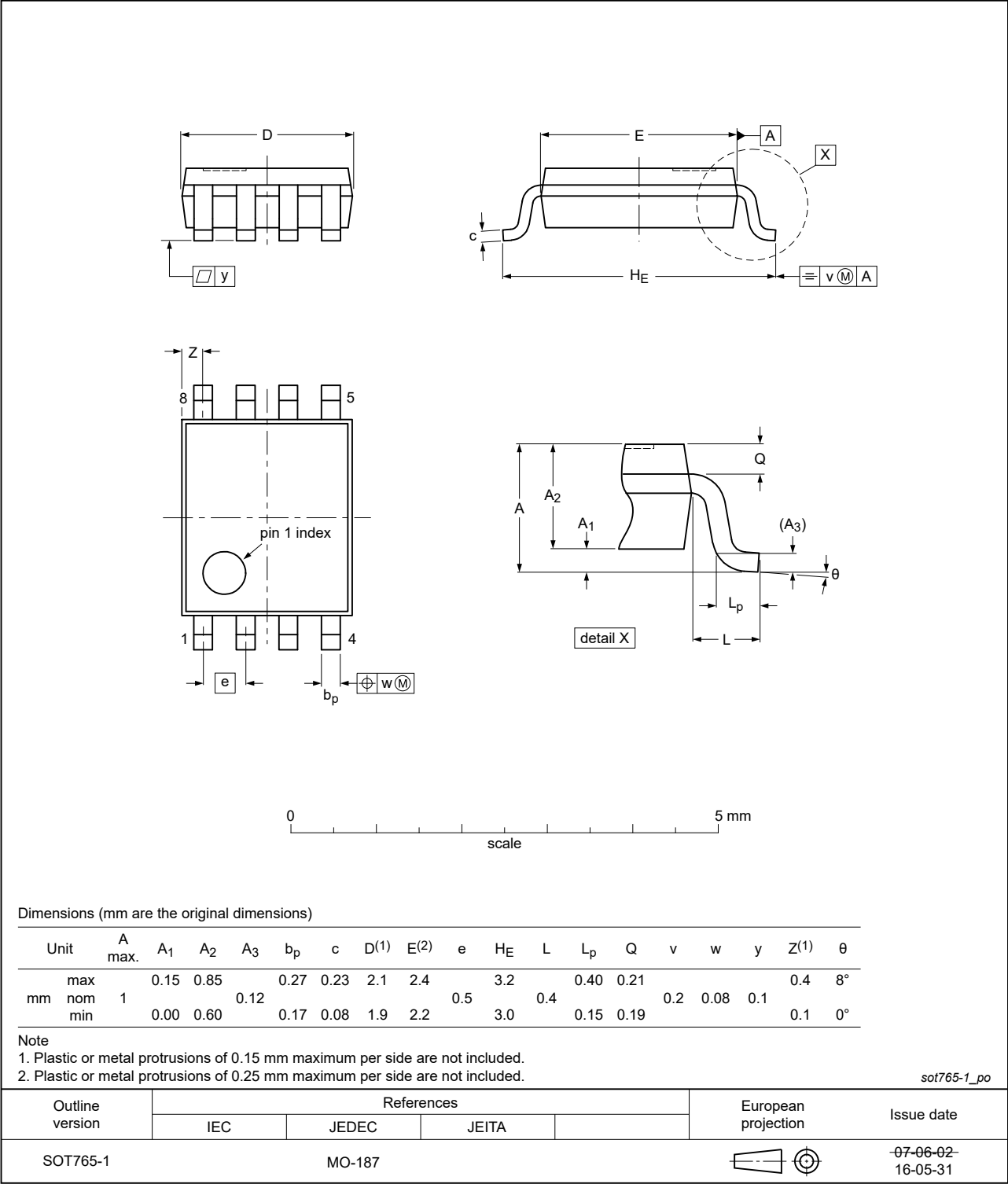


Fig. 17. Package outline SOT765-1 (VSSOP8)

X2SON8: plastic thermal enhanced extremely thin small outline package; no leads;
8 terminals; body 1.35 x 0.8 x 0.32 mm

SOT1233-2

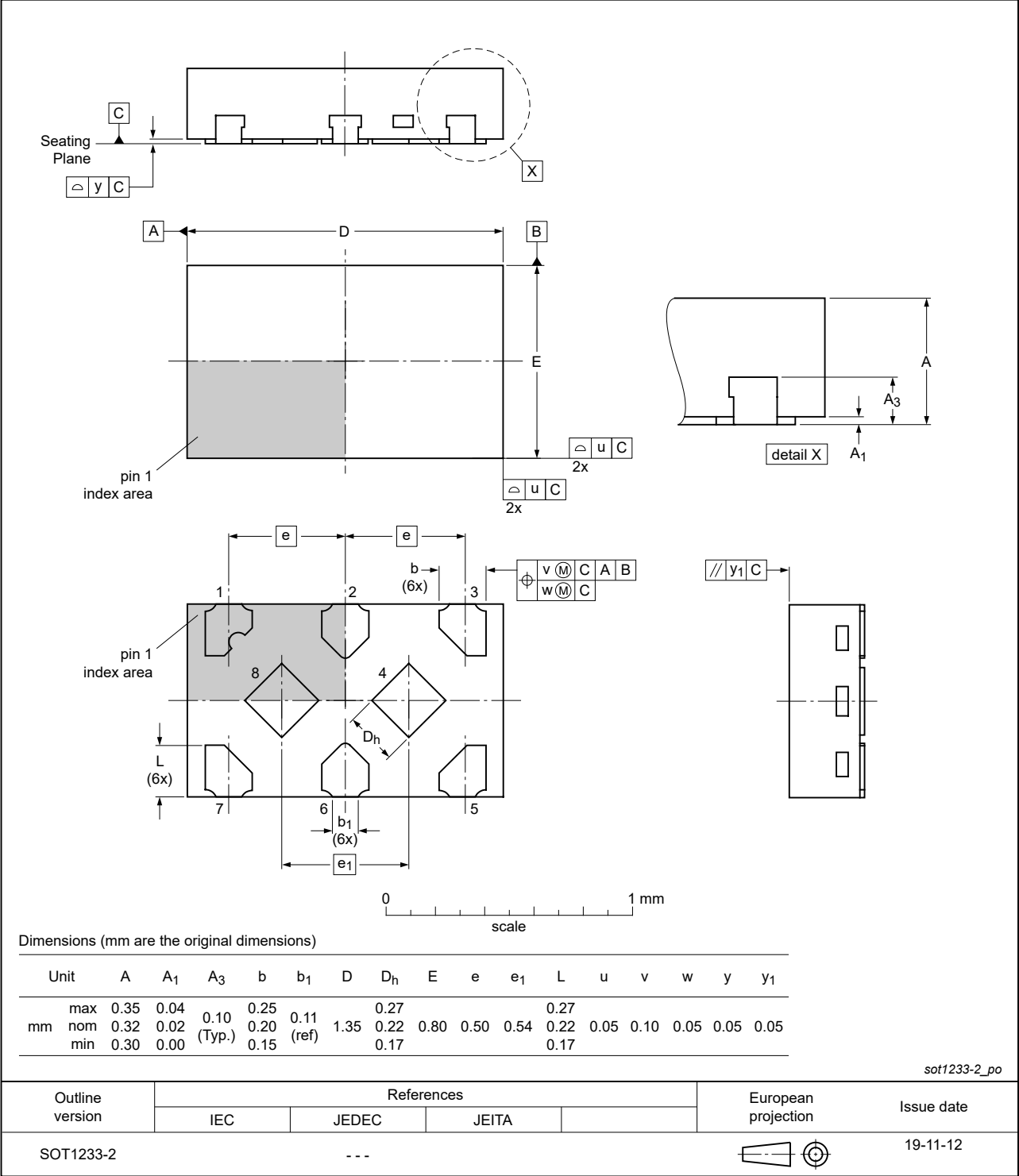


Fig. 18. Package outline SOT1233-2 (X2SON8)

14. Abbreviations

Table 19. Abbreviations

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model

15. Revision history

Table 20. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AXP2T45 v.2	20220623	Product data sheet	-	74AXP2T45 v.1
Modifications	• Package SOT1233 (X2SON8) changed to SOT1233-2 (X2SON8).			
74AXP2T45 v.1	20200319	Product data sheet	-	-

16. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <https://www.nexperia.com>.

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