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NTE4006B

Integrated Circuit

CMOS, 18-Stage Static Shift Register

Description:

The NTE4006B is a shift register in a 14-Lead DIP type package and is comprised of four separate shift register sections sharing a common clock: two sections have four stages, and two sections have five stages with an output tap on both the fourth and fifth stages. This makes it possible to obtain a shift register of 4, 5, 8, 9, 10, 12, 13, 14, 16, 17, or 18 bits by appropriate selection of inputs and outputs. This part is particularly useful in serial shift registers and time delay circuits.

Features:

- Output Transitions Occur on the Falling Edge of the Clock Pulse
- Supply Voltage Range: 3Vdc to 18Vdc
- Can be Cascaded to Provide Longer Shift Register Lengths
- Capable of Driving Two Low-Power TTL Loads or One Low-Power Schottky TTL Load Over the Rated Temperature Range

Absolute Maximum Ratings: (Voltages referenced to V_{SS} , Note 1)

DC Supply Voltage, V_{DD}	-0.5 to +18.0V
Input Voltage (DC or Transient), V_{in}	-0.5 to V_{DD} to +0.5V
Output Voltage (DC or Transient), V_{out}	-0.5 to V_{DD} to +0.5V
Input Current (DC or Transient, Per Pin), I_{in}	± 10 mA
Output Current (DC or Transient, Per Pin), I_{out}	± 10 mA
Power Dissipation (Per Package), P_D	500mW
Temperature Derating (from +65° to +125°C)	-7.0mW/°C
Storage Temperature, T_{stg}	-65° to +150°C
Lead Temperature (During Soldering, 8sec max), T_L	+260°C

Note 1. Maximum Ratings are those values beyond which damage to the device may occur.

Electrical Characteristics: (Voltages referenced to V_{SS} , Note 2)

Parameter	Symbol	V_{DD} Vdc	-55°C		+25°C			+125°C		Unit
			Min	Max	Min	Typ	Max	Min	Max	
Output Voltage "0" Level $V_{in} = V_{DD}$ or 0 "1" Level $V_{in} = 0$ or V_{DD}	V_{OL}	5.0	–	0.05	–	0	0.05	–	0.05	Vdc
		10	–	0.05	–	0	0.05	–	0.05	Vdc
		15	–	0.05	–	0	0.05	–	0.05	Vdc
	V_{OH}	5.0	4.95	–	4.95	5.0	–	4.95	–	Vdc
		10	9.95	–	9.95	10	–	9.95	–	Vdc
		15	14.95	–	14.95	15	–	14.95	–	Vdc
Input Voltage "0" Level ($V_O = 4.5$ or $0.5V_{dc}$) ($V_O = 9.0$ or $1.0V_{dc}$) ($V_O = 13.5$ or $1.5V_{dc}$) "1" Level ($V_O = 0.5$ or $4.5V_{dc}$) ($V_O = 1.0$ or $9.0V_{dc}$) ($V_O = 1.5$ or $13.5V_{dc}$)	V_{IL}	5.0	–	1.5	–	2.25	1.5	–	1.5	Vdc
		10	–	3.0	–	4.50	3.0	–	3.0	Vdc
		15	–	4.0	–	6.75	4.0	–	4.0	Vdc
	V_{IH}	5.0	3.5	–	3.5	2.75	–	3.5	–	Vdc
		10	7.0	–	7.0	5.50	–	7.0	–	Vdc
		15	11.0	–	11.0	8.25	–	11.0	–	Vdc
Output Drive Current Source ($V_{OH} = 2.5V_{dc}$) ($V_{OH} = 4.6V_{dc}$) ($V_{OH} = 9.5V_{dc}$) ($V_{OH} = 13.5V_{dc}$) Sink ($V_{OL} = 0.4V_{dc}$) ($V_{OL} = 0.5V_{dc}$) ($V_{OL} = 1.5V_{dc}$)	I_{OH}	5.0	–3.0	–	–2.4	–4.2	–	–1.7	–	mAdc
		5.0	–0.64	–	–0.51	–0.88	–	–0.36	–	mAdc
		10	–1.6	–	–1.3	–2.25	–	–0.9	–	mAdc
		15	–4.2	–	–3.4	–8.8	–	–2.4	–	mAdc
	I_{OL}	5.0	0.64	–	0.51	0.88	–	0.36	–	mAdc
		10	1.6	–	1.3	2.25	–	0.9	–	mAdc
		15	4.2	–	3.4	8.8	–	2.4	–	mAdc
Input Current	I_{in}	15	–	± 0.1	–	± 0.00001	± 0.1	–	± 0.1	μ Adc
Input Capacitance ($V_{IN} = 0$)	C_{in}	–	–	–	–	5.0	7.5	–	–	pF
Quiescent Current (Per Package)	I_{DD}	5.0	–	5.0	–	0.005	5.0	–	150	μ Adc
		10	–	10	–	0.010	10	–	300	μ Adc
		15	–	20	–	0.015	20	–	600	μ Adc
Total Supply Current (Dynamic plus Quiescent, Per Package, $C_L = 50pF$ on all buffers switching Note 3, Note 4)	I_T	5.0	$I_T = (1.3\mu A/kHz) f + I_{DD}$							μ Adc
		10	$I_T = (2.6\mu A/kHz) f + I_{DD}$							μ Adc
		15	$I_T = (3.9\mu A/kHz) f + I_{DD}$							μ Adc

Note 2. Data labeled "Typ" is not to be used for design purposes but is intended as an indication of the device's potential performance.

Note 3. The formulas given are for the typical characteristics only at +25°C.

Note 4. To calculate total supply current at loads other than 50pF:

$$I_T(C_L) = I_T(50pF) + (C_L - 50) V_{fk}$$

where: I_T is in μA (per package), C_L in pF, $V = (V_{DD} - V_{SS})$ in volts, f in kHz is input frequency, and $k = 0.001$.

Switching Characteristics: ($C_L = 50\text{pF}$, $T_A = +25^\circ\text{C}$, Note 2)

Parameter	Symbol	V_{DD} Vdc	Min	Typ	Max	Unit
Output Rise and Fall Time $t_{TLH}, t_{THL} = (1.5\text{ns/pf}) C_L + 33\text{ns}$ $t_{TLH}, t_{THL} = (0.75\text{ns/pf}) C_L + 12.5\text{ns}$ $t_{TLH}, t_{THL} = (0.55\text{ns/pf}) C_L + 9.5\text{ns}$	$t_{TLH},$ t_{THL}	5.0	–	100	200	ns
		10	–	50	100	ns
		15	–	40	80	ns
Propagation Delay Time $t_{PLH}, t_{PHL} = (1.7\text{ns/pf}) C_L + 220\text{ns}$ $t_{PLH}, t_{PHL} = (0.66\text{ns/pf}) C_L + 77\text{ns}$ $t_{PLH}, t_{PHL} = (0.5\text{ns/pf}) C_L + 55\text{ns}$	$t_{PLH},$ t_{PHL}	5.0	–	300	600	ns
		10	–	110	220	ns
		15	–	80	160	ns
Clock Pulse Width	t_{WH}	5.0	200	100	–	ns
		10	120	60	–	ns
		15	80	40	–	ns
Clock Pulse Frequency	f_{cl}	5.0	–	5.0	2.5	MHz
		10	–	8.3	4.2	MHz
		15	–	12	6.0	MHz
Clock Pulse Rise and Fall Time (Note 5)	$t_{TLH},$ t_{THL}	5.0	–	–	15	μs
		10	–	–	5	μs
		15	–	–	4	μs
Setup Time	t_{su}	5.0	0	–50	–	ns
		10	0	–15	–	ns
		15	0	–8.0	–	ns
Hold Time	t_h	5.0	180	75	–	ns
		10	90	25	–	ns
		15	75	20	–	ns

Note 2. Data labeled “Typ” is not to be used for design purposes but is intended as an indication of the device’s potential performance.

Note 3. The formulas given are for the typical characteristics only at $+25^\circ\text{C}$.

Note 5. When shift register sections are cascaded, the maximum rise and fall times of the clock input should be equal to or less than the rise and fall times of the data outputs driving data inputs, plus the propagation delay of the output driving stage for the output capacitance load.

Truth Table (Single Stage):

D_n	C	Q_{n+1}
0		0
1		1
X		Q_n

X = Don't Care

Pin Connection Diagram

