

MAX22025-MAX22028/ MAX22025F-MAX22028F

Compact, Isolated, Half-Duplex RS-485/RS-422 Transceivers with AutoDirection Control

General Description

The MAX22025-MAX22028/MAX22025F-MAX22028F compact isolated RS-485/RS-422 transceivers provide 3.5kV_{RMS} of digital galvanic isolation between the cable-side (RS-485/RS-422 driver/ receiver-side) and the UART-side of the device. Isolation improves communication by breaking ground loops and reduces noise when there are large differences in ground potential between ports. These devices allow for robust communication up to 0.5Mbps or 16Mbps.

The MAX22025-MAX22028/MAX22025F-MAX22028F feature Maxim's proprietary AutoDirection control making these devices ideal for applications such as isolated RS-485 ports, where the driver input is used in conjunction with the driver-enable signal to drive the differential bus.

The MAX22025/MAX22027/MAX22025F/MAX22027F feature reduced slew rate drivers that minimize EMI and reduce reflections caused by improper termination of cable allowing error-free transmission up to 0.5Mbps. The MAX22026/MAX22028/MAX22026F/MAX22028F driver outputs are not slew-rate limited, allowing transmit speeds up to 16Mbps.

The receiver output of the MAX22025/MAX22026/MAX22025F/MAX22026F does not follow ($V_A - V_B$) when the device is in the driver-enabled state. The receiver output on the MAX22027/MAX22028/MAX22027F/MAX22028F always follows ($V_A - V_B$).

The driver outputs and receiver inputs are protected from ± 10 kV electrostatic discharge (ESD) to GNDB on the cable side, as specified by the Human Body Model (HBM). The MAX22025-MAX22028/MAX22025F-MAX22028F are available in a compact 8-pin wide body SOIC package and operate over the -40°C to +85°C temperature range.

Applications

- Utility Meters
- Industrial Automation Equipment
- Programmable Logic Controllers
- HVAC

Benefits and Features

- High-Level Integration Reduces Overall Solution Size
 - Fully Isolated Half-Duplex RS-485/RS-422 Transceivers
 - Compact 8-Pin Wide Body SOIC Package (5.5mm Creepage)
- Integrated Protection Ensures Robust Communication
 - ± 10 kV ESD (HBM) on Driver Outputs/Receiver Inputs
 - Failsafe Receiver Prevents Fault Transition on Receiver Input Short or Open Events (MAX22025F-MAX22028F)
 - Withstands 3.5kV_{RMS} Isolation Voltage for 60 Seconds (V_{ISO})
 - Withstands 630V_{PEAK} Maximum Repetitive Peak-Isolation Voltage (V_{IORM})
 - Continuously Withstands 445V_{RMS} Maximum Working-Isolation Voltage (V_{IOWM})
- Enables Flexible System Design
 - 0.5Mbps Maximum Data Rate with Slew-Rate Limited Driver (MAX22025/MAX22027/MAX22025F/MAX22027F)
 - 16Mbps Maximum Data Rate (MAX22026/MAX22028/MAX22026F/MAX22028F)
 - AutoDirection Eliminates the Need for $\overline{DE}$ and $\overline{RE}$ Control Signals

Safety Regulatory Approvals

- UL According to UL1577
- cUL According to CSA Bulletin 5A

Functional Diagram

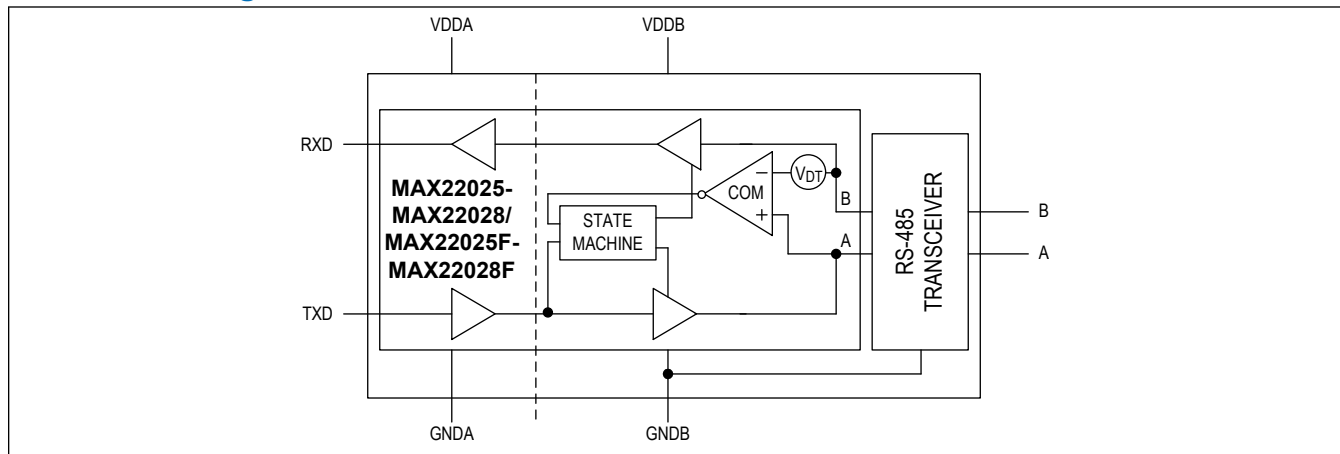


TABLE OF CONTENTS

General Description	1
Applications	1
Benefits and Features	1
Safety Regulatory Approvals	1
Functional Diagram	2
Absolute Maximum Ratings	6
Package Information	6
8 Wide SOIC	6
DC Electrical Characteristics	7
Switching Electrical Characteristics (MAX22025/MAX22027/MAX22025F/MAX22027F)	9
Switching Electrical Characteristics (MAX22026/MAX22028/MAX22026F/MAX22028F)	9
Insulation Characteristics	10
Typical Operating Characteristics	13
Pin Configuration	16
MAX22025-MAX22028F	16
Pin Description	17
Function Tables	17
Function Tables	17
Detailed Description	18
Isolation	18
AutoDirection Circuitry	18
Pullup and Pulldown Resistors	18
Receive State	19
Failsafe Receiver (MAX22025F-MAX22028F only)	19
Receiver Output (RXD)	19
ESD Protection	19
ESD Test Conditions	19
Human Body Model (HBM)	19
Typical Application Circuits	21
Typical Application Circuit 1	21
Typical Application Circuit 2	21
Ordering Information	22
Revision History	23

LIST OF FIGURES	
Figure 1. Driver DC Test Load	11
Figure 2. Driver Timing Test Circuit.	11
Figure 3. Driver Propagation Delays	11
Figure 4. Receiver Propagation Delay Test Circuit.	11
Figure 5. Receiver Propagation Delays.	12
Figure 6. Human Body ESD Test Model	19
Figure 7. Human Body Current Waveform	20

MAX22025-MAX22028/ MAX22025F-MAX22028F	Compact, Isolated, Half-Duplex RS-485/RS-422 Transceivers with AutoDirection Control
---	---

LIST OF TABLES	
Table 1. Safety Regulatory Approvals.	18

Absolute Maximum Ratings

V _{DDA} , TXD to GNDA	-0.3V to +6V	Continuous Power Dissipation (T _A = +70°C)	
V _{DDB} to GNDB	-0.3V to +6V	8-pin Wide SOIC (derate 23mW/°C above +70°C)	1847mW
RXD to GNDA	-0.3V to (V _{DDA} + 0.3V)	Operating Temperature Range	-40°C to +85°C
A, B to GNDB	-8V to +13V	Junction Temperature	+150°C
Short Circuit Duration (RXD to GNDA)	Continuous	Storage Temperature Range	-65°C to +150°C
Short Circuit Duration (A, B to GNDB)	Continuous	Lead Temperature (soldering, 10s)	+300°C
		Soldering Temperature (reflow)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

8 Wide SOIC

Package Code	W8MS+1
Outline Number	21-0262
Land Pattern Number	90-0258
THERMAL RESISTANCE, FOUR-LAYER BOARD	
Junction to Ambient (θ _{JA})	43.3°C/W
Junction to Case (θ _{JC})	36.5°C/W

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

DC Electrical Characteristics

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 4.75V$ to $5.25V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^\circ C$.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
POWER							
Supply Voltage	V _{DDA}			1.71		5.5	V
	V _{DDB}			4.75		5.25	
Supply Current	I _{DDA}	V _{DDA} = 3.3V, RXD is unconnected, TXD = low, no bus load			0.39	0.7	mA
	I _{DDB}	V _{DDB} = 5V, RXD is unconnected, TXD = low, no bus load			4.0	5.5	
V _{DDA} Undervoltage Lockout Threshold	V _{UVLOA}	V _{DDA} rising		1.5	1.6	1.66	V
V _{DDA} Undervoltage Lockout Threshold Hysteresis	V _{UVHYSTA}				45		mV
LOGIC INTERFACE (TXD, RXD)							
Input High Voltage	V _{IH}	TXD to GNDA	2.25V ≤ V _{DDA} ≤ 5.5V	0.7 x V _{DDA}			V
			1.71V ≤ V _{DDA} < 2.25V	0.75 x V _{DDA}			
Input Low Voltage	V _{IL}	TXD to GNDA	2.25V ≤ V _{DDA} ≤ 5.5V			0.8	V
			1.71V ≤ V _{DDA} < 2.25V			0.7	
Input Hysteresis	V _{HYS}	TXD to GNDA			410		mV
Input Capacitance	C _{IN}	TXD, f = 1MHz			2		pF
Input Pullup Current	I _{PU}	TXD		-10	-5	-1.5	μA
Output Voltage High	V _{OH}	RXD to GNDA, I _{OUT} = -4mA		V _{DDA} -0.4			V
Output Voltage Low	V _{OL}	RXD to GNDA, I _{OUT} = 4mA				0.4	V
DRIVER							
Differential Driver Output	V _{OD}	R _L = 100Ω, TXD = low, Figure 1		2.0		V _{DDB}	V
		R _L = 54Ω, TXD = low, Figure 1		1.5		V _{DDB}	
		-7V ≤ V _{CM} ≤ +12V, TXD = low, Figure 1		1.5		5	
Driver Common-Mode Output Voltage	V _{OC}	R _L = 100Ω or 54Ω, TXD = low, Figure 1		V _{DDB} /2		3	V
Driver Disable Threshold	V _{DT}	TXD = low to high (Note 3)		0.6		1	V
Driver Short-Circuit Output Current	I _{OSD}	GNDB ≤ V _{OUT} ≤ +12V, output low		+50		+250	mA
		-7V ≤ V _{OUT} ≤ V _{DDB} , output high		-250		-50	
Driver Short-Circuit Foldback Output Current	I _{SH}	(V _{DDB} -1V) ≤ V _{OUT} ≤ +12V, output low		+20			mA
		-7V ≤ V _{OUT} ≤ V _{DDB} , output high				-20	
RECEIVER							
Input Current (A and B)	I _A , I _B	V _{DDB} = GNDB or 5V, receive state	V _{IN} = +12V			+250	μA
			V _{IN} = -7V	-200			

DC Electrical Characteristics (continued)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 4.75V$ to $5.25V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^{\circ}C$.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Receiver Differential Threshold Voltage	V_{TH}	$-7V \leq V_{CM} \leq +12V$	MAX22025-MAX22028	-200	+200	mV
			MAX22025F-MAX22028F	-200	-50	
Receiver Input Hysteresis	ΔV_{TH}	$V_{CM} = 0V$		25		mV
Receiver Input Resistance	R_{IN}	$-7V \leq V_{CM} \leq +12V$, Receive state		60		k Ω
THERMAL SHUTDOWN						
Thermal Shutdown Threshold	T_{SHDN}	Temperature rising		+135		$^{\circ}C$
Thermal Shutdown Hysteresis	T_{SHDN_HYS}			20		$^{\circ}C$
PROTECTION						
ESD Protection (A and B Pins to GNDB)		Human Body Model		± 10		kV
ESD Protection (A and B Pins to GNDA) with 47pF Capacitor Connected between GNDA and GNDB		Human Body Model		± 7		kV
ESD Protection (All Other Pins)		Human Body Model		± 4		kV

Switching Electrical Characteristics (MAX22025/MAX22027/MAX22025F/MAX22027F)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 4.75V$ to $5.25V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^\circ C$.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Common Mode Transient Immunity	CMTI	(Note 5)		50		kV/ μ s
DRIVER						
Driver Propagation Delay	t_{DPLH} , t_{DPLH}	$R_L = 110\Omega$, $C_L = 50pF$, Figure 2 and Figure 3 (Note 4)	200		1000	ns
Driver Differential Output Rise or Fall Time	t_{LH} , t_{HL}	$R_L = 110\Omega$, $C_L = 50pF$, Figure 2 and Figure 3 (Note 4)	200		900	ns
Maximum Data Rate	DR_{MAX}		0.5			Mbps
Driver Enable from Power Up	t_{PORD}			100	150	μ s
RECEIVER						
Receiver Propagation Delay	t_{RPLH} , t_{RPHL}	$C_L = 15pF$, Figure 4 and Figure 5 (Note 4)			80	ns
Receiver Output Skew $ t_{RPLH} - t_{RPHL} $	t_{RSKEW}	$C_L = 15pF$, Figure 5 (Note 4)			13	ns
Maximum Data Rate	DR_{MAX}		16			Mbps
Receiver Enable from Power Up	t_{PORR}			100	150	μ s

Switching Electrical Characteristics (MAX22026/MAX22028/MAX22026F/MAX22028F)

($V_{DDA} - V_{GNDA} = 1.71V$ to $5.5V$, $V_{DDB} - V_{GNDB} = 4.75V$ to $5.25V$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^\circ C$.) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Common Mode Transient Immunity	CMTI	(Note 5)		50		kV/ μ s
DRIVER						
Driver Propagation Delay	t_{DPLH} , t_{DPLH}	$R_L = 110\Omega$, $C_L = 50pF$, Figure 2 and Figure 3 (Note 4)			50	ns
Driver Differential Output Rise or Fall Time	t_{LH} , t_{HL}	$R_L = 110\Omega$, $C_L = 50pF$, Figure 2 and Figure 3 (Note 4)			15	ns
Maximum Data Rate	DR_{MAX}		16			Mbps
Driver Enable from Power Up	t_{PORD}			100	150	μ s
RECEIVER						
Receiver Propagation Delay	t_{RPLH} , t_{RPHL}	$C_L = 15pF$, Figure 4 and Figure 5 (Note 4)			80	ns
Receiver Output Skew $ t_{RPLH} - t_{RPHL} $	t_{RSKEW}	$C_L = 15pF$, Figure 5 (Note 4)			13	ns
Maximum Data Rate	DR_{MAX}		16			Mbps
Receiver Enable from Power Up	t_{PORR}			100	150	μ s

Insulation Characteristics

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Maximum Repetitive Peak Withstand Voltage	V_{IORM}	(Note 6)		630		V_P
Maximum Working Isolation Voltage	V_{IOWM}	GNDA to GNDB continuous (Note 6)		445		V_{RMS}
Maximum Transient Isolation Voltage	V_{IOTM}			5000		V_P
Maximum Withstand Isolation Voltage	V_{ISO}	GNDA to GNDB for 60s (Note 7)		3500		V_{RMS}
Maximum Surge Isolation Voltage	V_{IOSM}	Basic Insulation, 1.2/50 μ s pulse per IEC61000-4-5		10		kV
Insulation Resistance	R_S	$T_A = +150^{\circ}\text{C}$, $V_{IO} = 500\text{V}$		$>10^9$		Ω
Barrier Capacitance Side A to Side B	CIO	GNDA to GNDB		2		pF
Minimum Creepage Distance	CPG			5.5		mm
Minimum Clearance Distance	CLR			5.5		mm
Internal Clearance		Distance through insulation		0.015		mm
Comparative Tracking Resistance Index	CTI			>400		
Climatic Category				40/125/ 21		
Pollution Degree				2		

Note 1: All devices are 100% production tested at $T_A = +85^{\circ}\text{C}$. Specifications over temperature are guaranteed by design.

Note 2: All currents into the device are positive. All currents out of the device are negative. All voltages are referenced to their respective ground (GNDA or GNDB), unless otherwise noted.

Note 3: This is the differential voltage from A to B that the driving device must see on the bus to disable its driver.

Note 4: Not production tested. Guaranteed by design.

Note 5: CMTI is the maximum sustainable common-mode voltage slew rate while maintaining the correct output states. CMTI applies to both rising and falling common-mode voltage edges. Tested with the transient generator connected between GNDA and GNDB. $V_{CM} = 1\text{kV}$

Note 6: V_{IORM} , V_{IOWM} , and V_{ISO} are defined by the IEC 60747-5-5 standard..

Note 7: Product is qualified at V_{ISO} for 60 seconds. Not production tested.

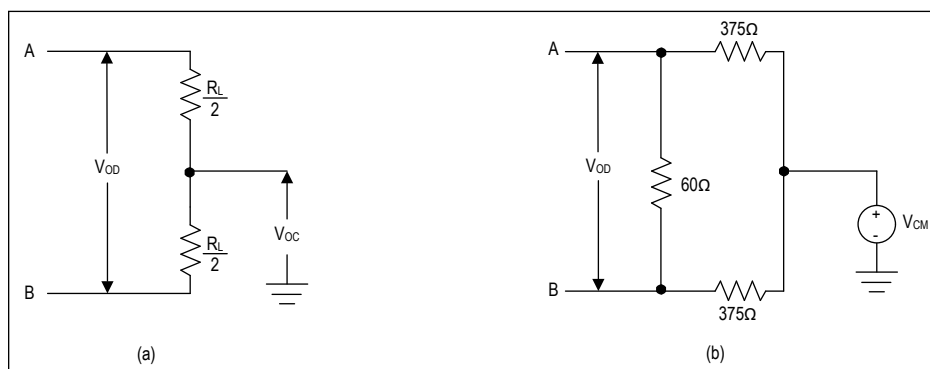


Figure 1. Driver DC Test Load

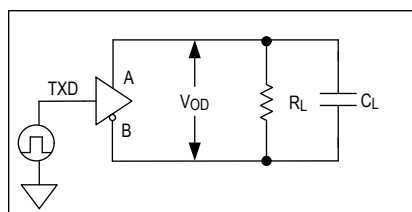


Figure 2. Driver Timing Test Circuit

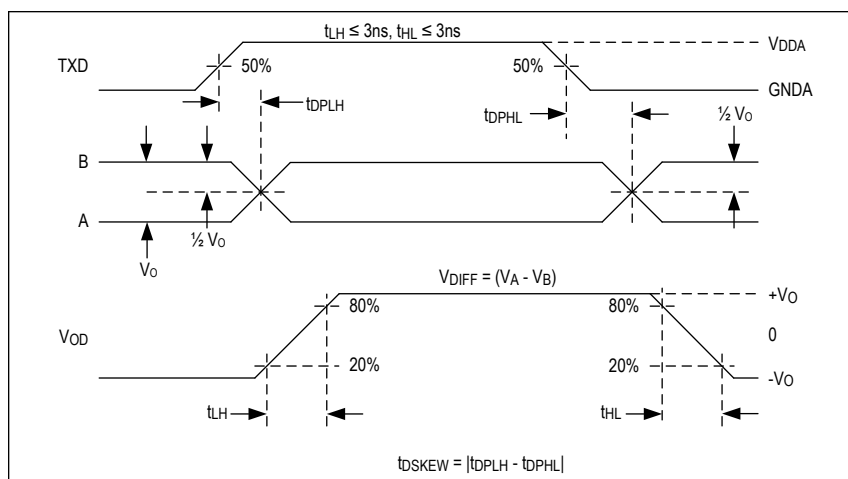


Figure 3. Driver Propagation Delays

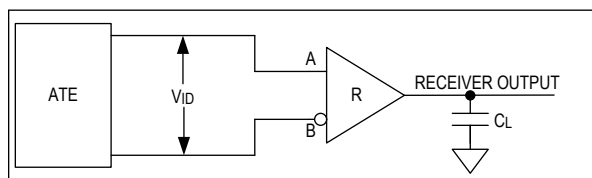


Figure 4. Receiver Propagation Delay Test Circuit

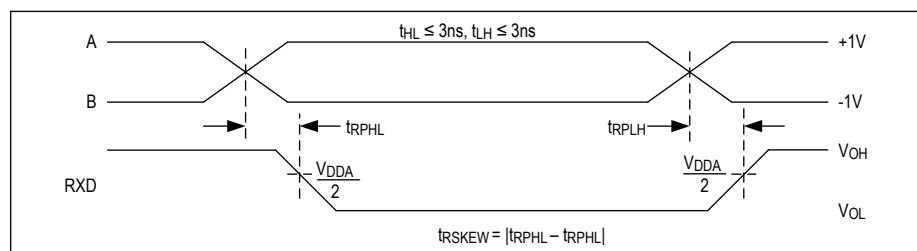
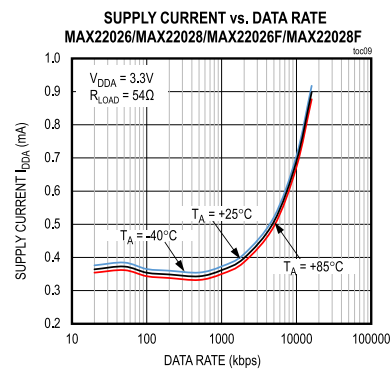
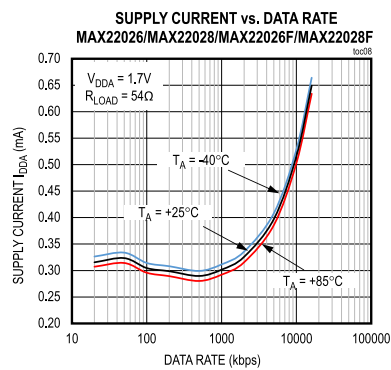
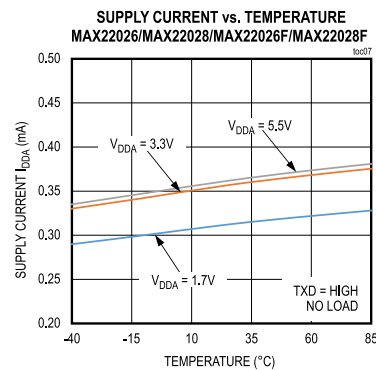
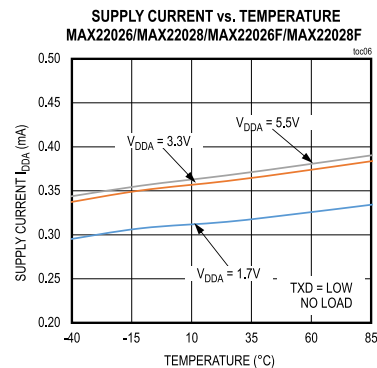
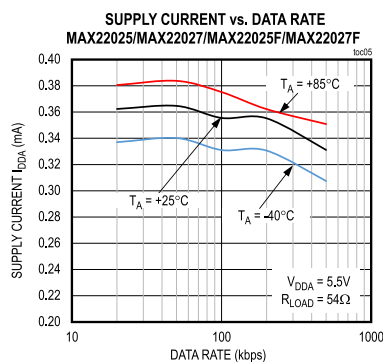
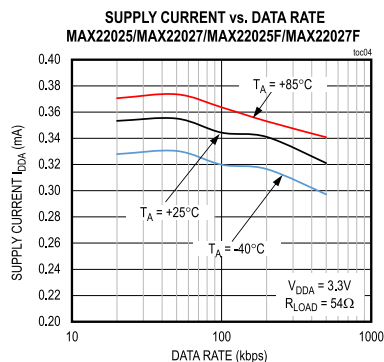
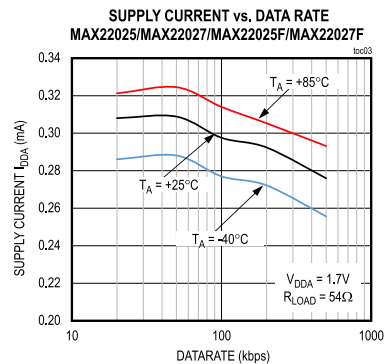
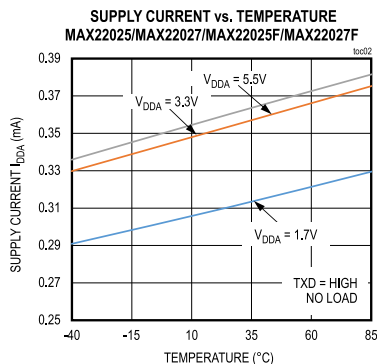
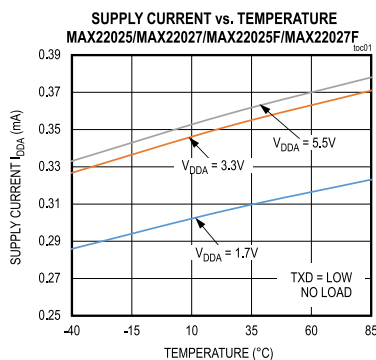


Figure 5. Receiver Propagation Delays

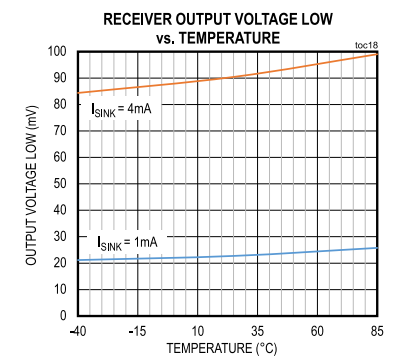
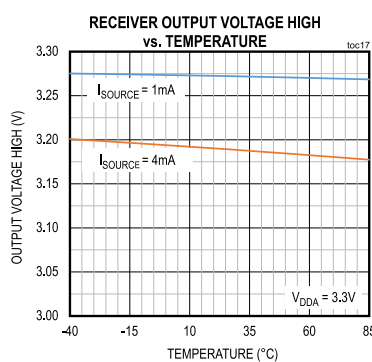
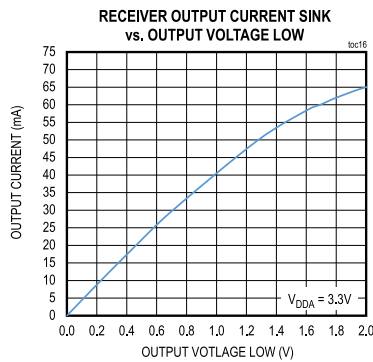
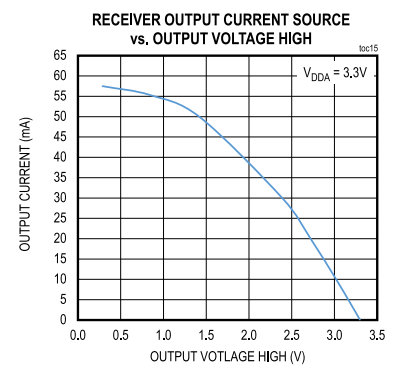
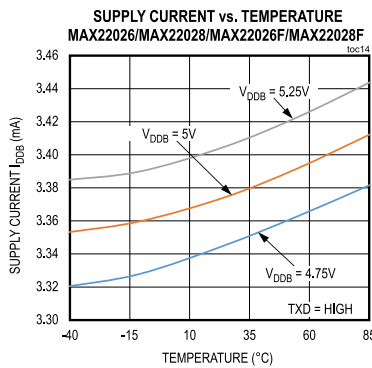
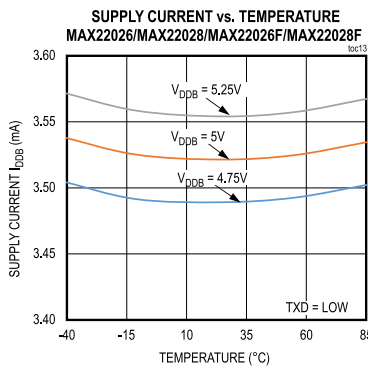
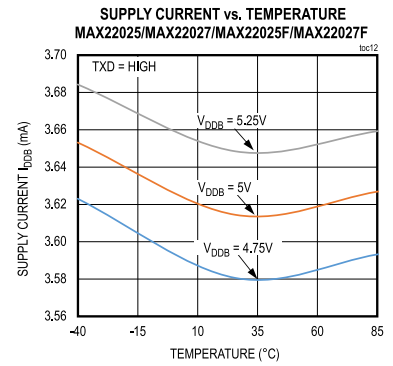
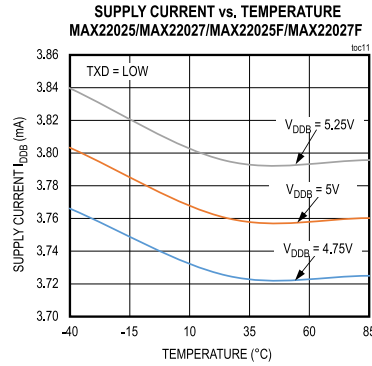
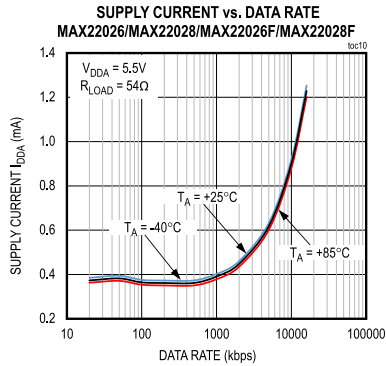
Typical Operating Characteristics

($V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^\circ C$, unless otherwise noted.)



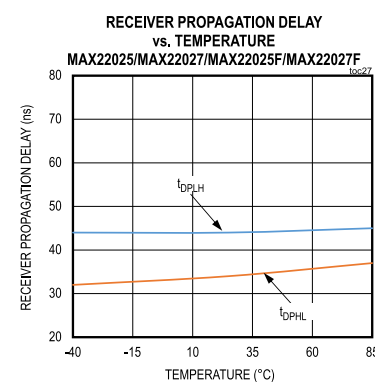
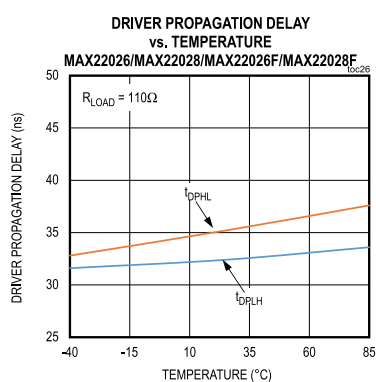
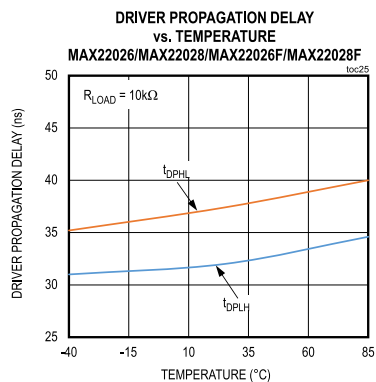
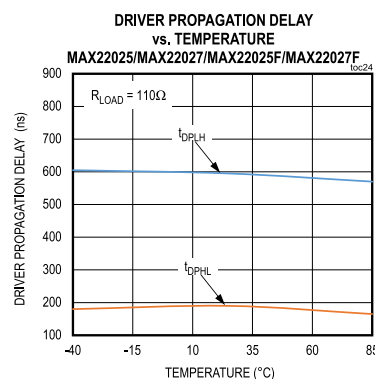
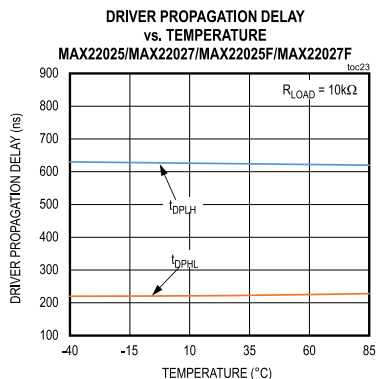
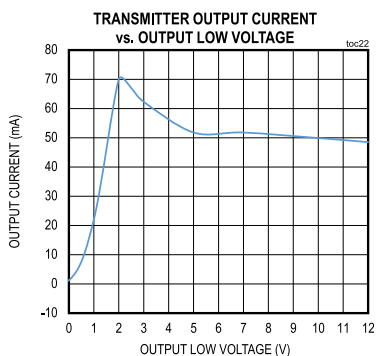
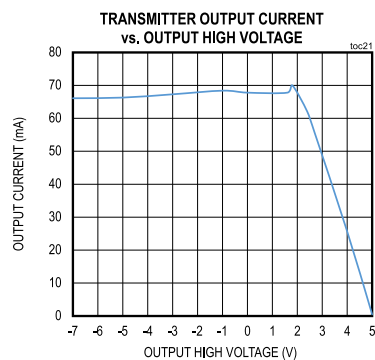
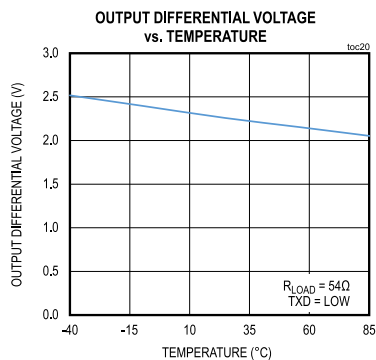
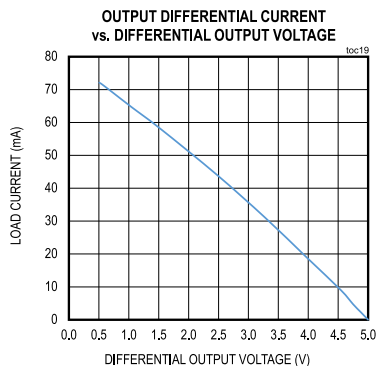
Typical Operating Characteristics (continued)

($V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^\circ C$, unless otherwise noted.)



Typical Operating Characteristics (continued)

($V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^\circ C$, unless otherwise noted.)

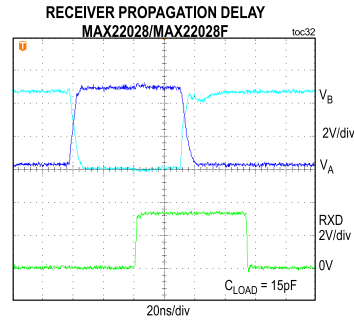
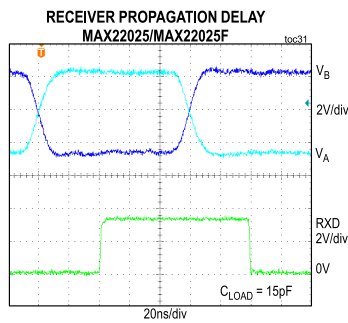
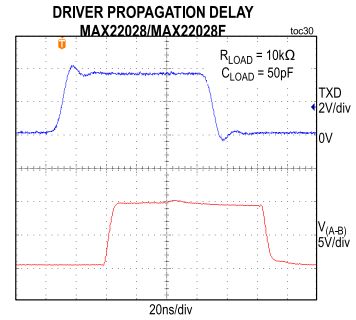
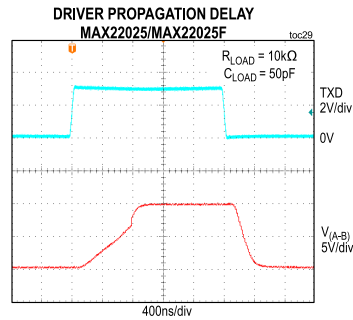
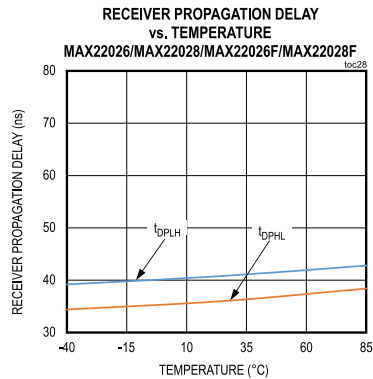


MAX22025-MAX22028/
MAX22025F-MAX22028F

Compact, Isolated, Half-Duplex RS-485/RS-422
Transceivers with AutoDirection Control

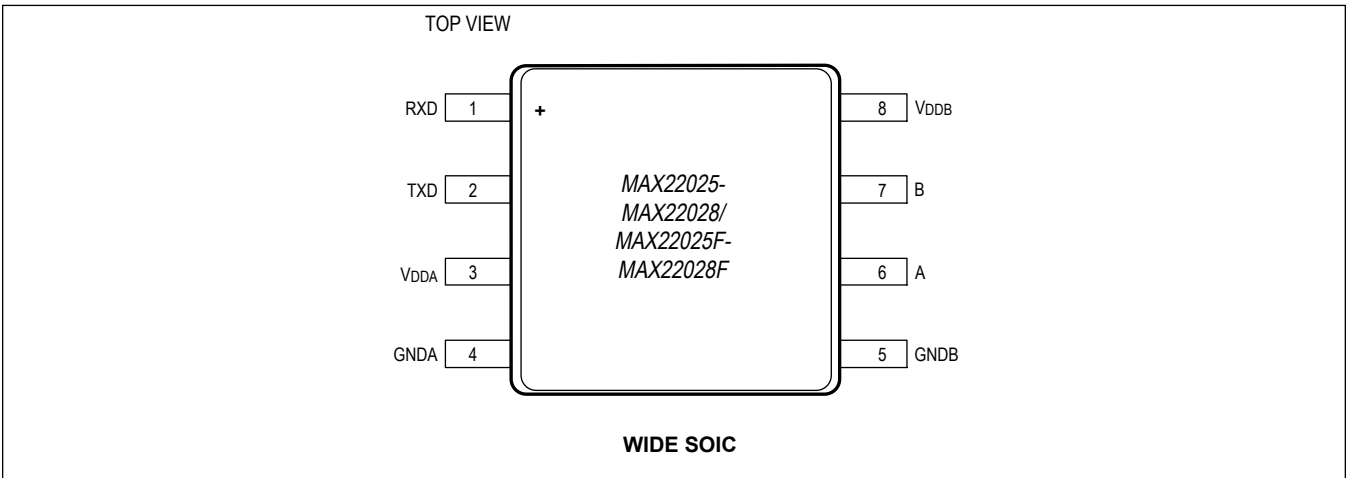
Typical Operating Characteristics (continued)

($V_{DDA} - V_{GNDA} = 3.3V$, $V_{DDB} - V_{GNDB} = 5V$, $V_{GNDA} = V_{GNDB}$, and $T_A = +25^{\circ}C$, unless otherwise noted.)



Pin Configuration

MAX22025-MAX22028F



Pin Description

PIN	NAME	FUNCTION	REF SUPPLY
1	RXD	Receiver Data Output. See the Function Tables for more information.	GNDA
2	TXD	Driver Input. TXD is the input to the internal state machine that automatically enables and disables the driver. See the Function Tables and AutoDirection Circuitry sections for more information. TXD has an internal 5μA pullup to V _{DDA} .	GNDA
3	V _{DDA}	UART/Logic-Side Power Input. Bypass V _{DDA} to GNDA with both 0.1μF and 1μF capacitors as close to the device as possible.	GNDA
4	GNDA	UART/Logic-Side Ground. GNDA is the ground reference for digital signals.	-
5	GNDB	Cable Side Ground. GNDB is the ground reference for the RS-485/RS-422 bus signals.	-
6	A	Noninverting Driver Output/Receiver Input	GNDB
7	B	Inverting Driver Output/Receiver Input	GNDB
8	V _{DDB}	Cable Side Power Input. Bypass V _{DDB} to GNDB with both 0.1μF and 1μF capacitors as close to the device as possible.	GNDB

Function Tables

Function Tables

TRANSMIT FUNCTIONALITY					
TXD	(V _A - V _B)	PREVIOUS STATE	CURRENT STATE	A	B
0	X	X	Driver Enabled	0	1
1	(V _A - V _B) ≥ V _{DT}	X	Receiver Enabled	High-Z	High-Z
1	(V _A - V _B) < V _{DT}	Driver Enabled	Driver Enabled	1	0
		Receiver Enabled	Receiver Enabled	High-Z	High-Z

X = Don't care

RXD FUNCTIONALITY (STANDARD RECEIVER)			
CURRENT STATE	(V _A - V _B)	RXD	
		MAX22025/MAX22026	MAX22027/MAX22028
Receiver Enabled	(V _A - V _B) ≥ +200mV	1	1
	(V _A - V _B) ≤ -200mV	0	0
Driver Enabled	(V _A - V _B) ≥ +200mV	1	1
	(V _A - V _B) ≤ -200mV	1	0

RXD FUNCTIONALITY (FAILSAFE RECEIVER)			
CURRENT STATE	(V _A - V _B)	RXD	
		MAX22025F/MAX22026F	MAX22027F/MAX22028F
Receiver Enabled	(V _A - V _B) ≥ -50mV	1	1
	(V _A - V _B) ≤ -200mV	0	0
Driver Enabled	(V _A - V _B) ≥ -50mV	1	1
	(V _A - V _B) ≤ -200mV	1	0

Detailed Description

The MAX22025-MAX22028/MAX22025F-MAX22028F isolated RS-485/RS-422 transceivers provide 3.5kV_{RMS} (60s) of galvanic isolation between the RS-485/RS-422 cable side of the transceiver and the UART side. These devices allow up to 0.5Mbps (MAX22025/MAX22027/MAX22025F/MAX22027F) or 16Mbps (MAX22026/MAX22028/MAX22026F/MAX22028F) communication across an isolation barrier when a large potential exists between grounds on each side of the barrier.

Isolation

Data isolation is achieved using high-voltage capacitors that allow data transmission between the UART side and the RS-485/RS-422 cable side of the transceiver.

The devices withstand differences in ground potential between the two power domains of up to 3.5kV_{RMS} (V_{ISO}) for up to 60s, and up to 445V_{RMS} (V_{IOWM}) for extended periods of time. See [Table 1](#) for certification information.

Table 1. Safety Regulatory Approvals

UL
The MAX22025-MAX22028 and MAX22025F-MAX22028F are certified under UL1577. For more details, refer to File E351759.
Rated up to 3500V _{RMS} for single protection.
cUL (Equivalent to CSA notice 5A)
The MAX22025-MAX22028 and MAX22025F-MAX22028F are certified up to 3500V _{RMS} for single protection. For more details, refer to File E351759.

AutoDirection Circuitry

Internal circuitry in the MAX22025-MAX22028/MAX22025F-MAX22028F, in conjunction with an external pullup resistor on A and pulldown resistor on B (see [Typical Application Circuit](#)), acts to automatically disable or enable the driver and the receiver to keep the bus in the correct state. This Auto Direction circuitry consists of a state machine and an additional receive comparator that determine whether this device is trying to drive the bus or another node on the network is driving the bus.

The internal state machine has two inputs:

- TXD
- The current state of (V_A-V_B), which is determined by a dedicated differential comparator.

The state machine also has two outputs:

- DRIVER_ENABLE—Internal signal that enables and disables the driver
- RECEIVER_ENABLE—Internal signal that is the inverse of the DRIVER_ENABLE signal.

When TXD is low, the device always drives the bus low. When TXD switches high, the device drives the bus for a short time, then disables the driver and allows the external pullup/pulldown resistors to hold the bus in the high state. During each low-to-high transition of TXD, the driver stays enabled until (V_A-V_B) ≥ V_{DT}. The driver is then disabled and the pullup/pulldown resistors hold the A and B lines in the correct state.

Pullup and Pulldown Resistors

The pullup and pulldown resistors on the A and B lines are required for proper operation of the device although their exact value is not critical. They function to hold the bus in the high state following a low-to-high transition. Sizing of these resistors is determined in the same way as when using any other RS-485 driver and depends on how the line is terminated and how many nodes are on the bus. The most important factor when sizing these resistors is to guarantee that the idle voltage on the bus (V_A-V_B) is greater than the receiver input threshold (+200mV for the MAX22025-MAX22028, -50mV for the MAX22025F-MAX22028F) in order to remain compatible with standard RS-485 receiver thresholds.

Receive State

When not transmitting data, the MAX22025-MAX22028/MAX22025F-MAX22028F require the TXD input be high to remain in the receive state. A conventional RS-485 transceiver has DE and $\overline{\text{RE}}$ inputs that are used to enable and disable the driver and receiver. However, the MAX22025-MAX22028/MAX22025F-MAX22028F do not have a DE input, and instead use an internal state machine to enable and disable the drivers.

Failsafe Receiver (MAX22025F-MAX22028F only)

The MAX22025F-MAX22028F guarantee a logic high on the receiver output when the receiver inputs are shorted or open, or when they are connected to a terminated transmission line with all drivers disabled. If the differential receiver input voltage ($V_A - V_B$) is greater than or equal to -50mV, RXD is a logic-high.

Receiver Output (RXD)

The receiver output (RXD) of the MAX22025/MAX22026/MAX22025F/MAX22026F does not follow TXD when the device is in the driver-enabled state. This allows for line interference detection by verifying that RXD remains high throughout data transmission. On the MAX22027/MAX22028/MAX22027F/MAX22028F, the receiver output (RXD) always follows ($V_A - V_B$).

ESD Protection

ESD protection structures are incorporated on all pins to protect against electrostatic discharge encountered during handling and assembly. The driver outputs and receiver inputs of the devices have extra protection against static electricity to both the UART side and cable side ground references. The ESD structures withstand high-ESD events during normal operation and when powered down. After an ESD event, the devices keep working without latch-up or damage. Bypass V_{DDA} to GNDA and bypass V_{ddb} to GNDB with 0.1 μF and 1 μF capacitors to ensure maximum ESD protection.

ESD Test Conditions

ESD performance depends on a variety of conditions. Contact Maxim for a reliability report that documents test setup, test methodology, and test results.

Human Body Model (HBM)

[Figure 6](#) shows the HBM test model, while [Figure 7](#) shows the current waveform it generates when discharged in a low-impedance state. This model consists of a 100pF capacitor charged to the ESD voltage of interest, which is then discharged into the test device through a 1.5k Ω resistor.

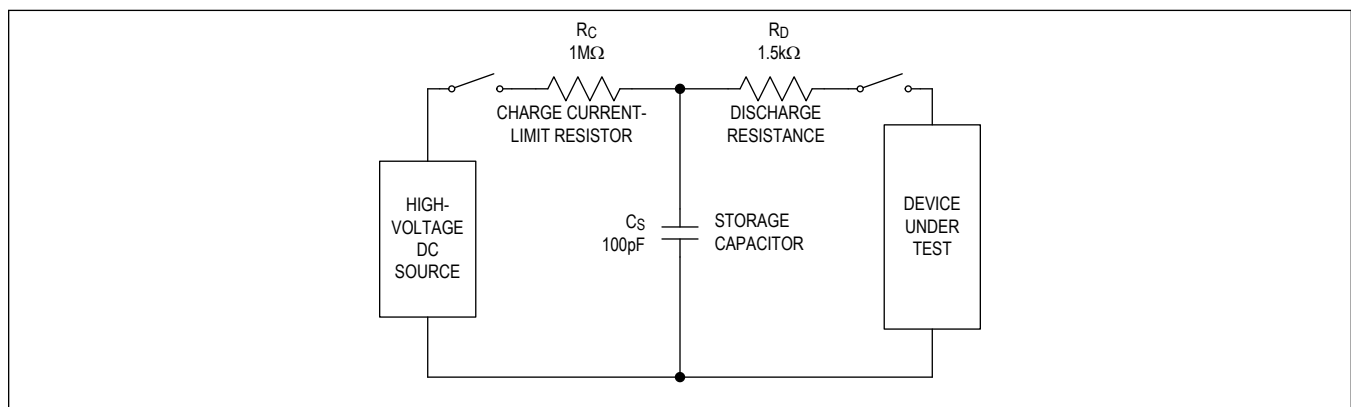


Figure 6. Human Body ESD Test Model

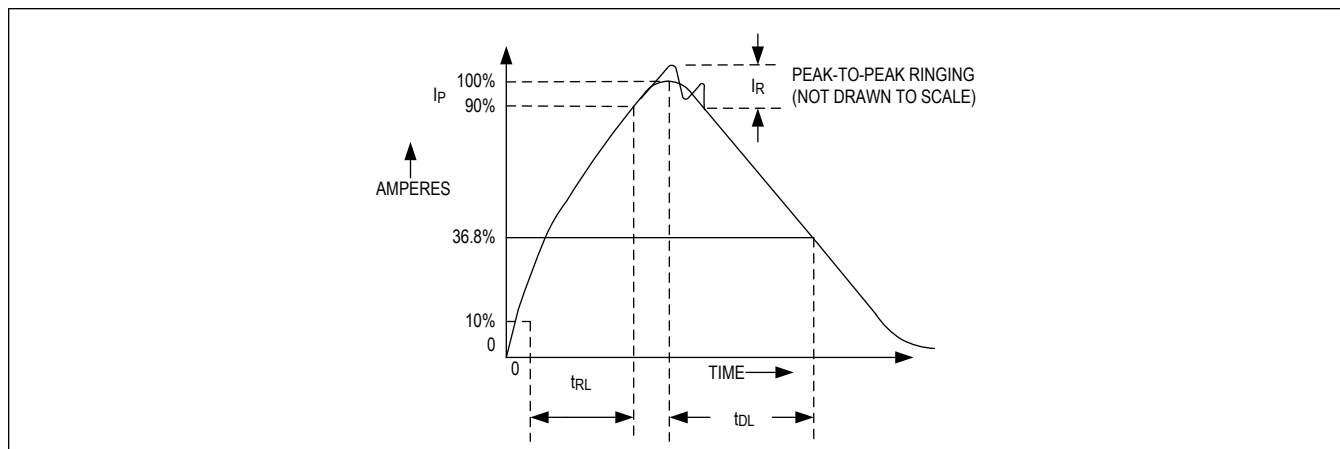
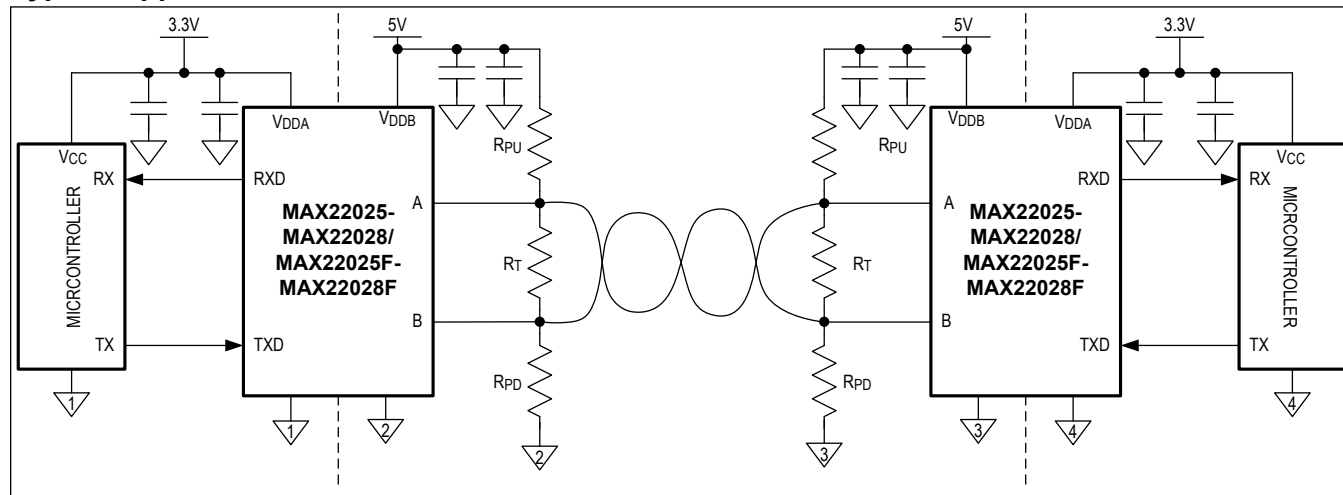


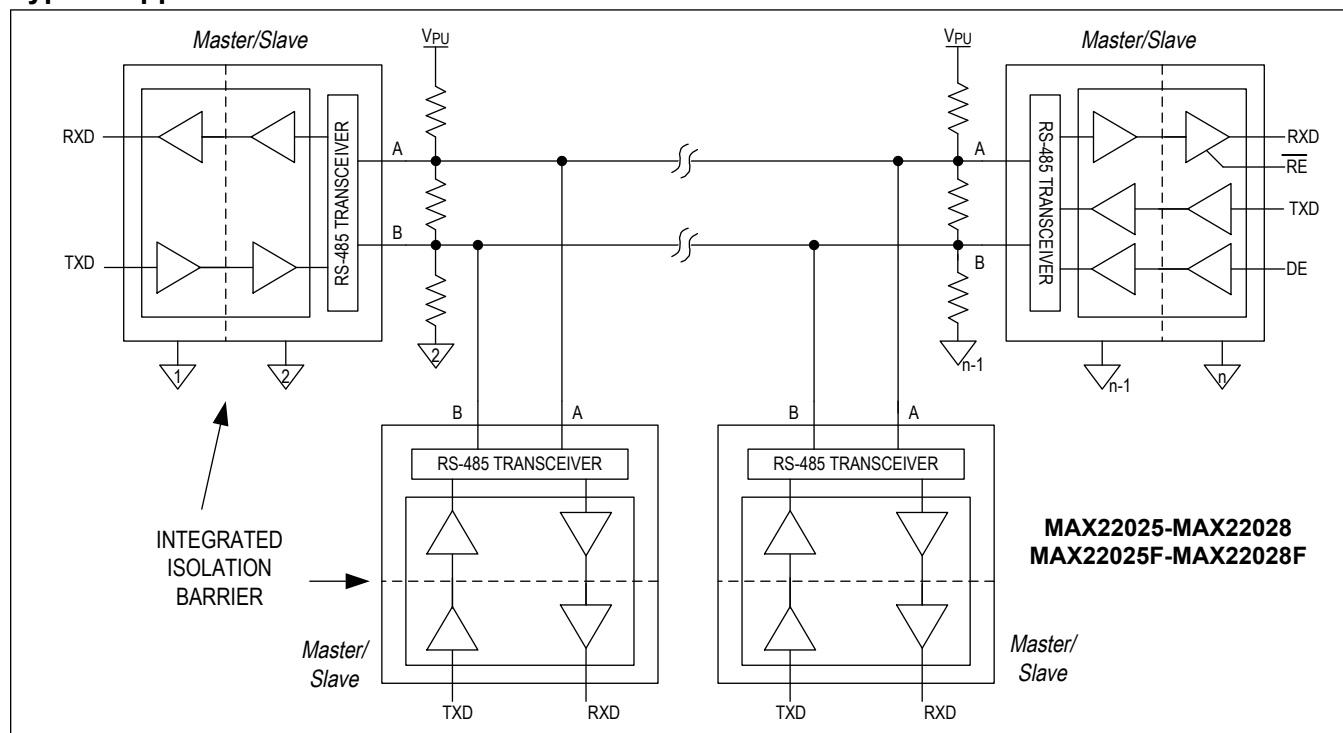
Figure 7. Human Body Current Waveform

Typical Application Circuits

Typical Application Circuit 1



Typical Application Circuit 2



MAX22025-MAX22028/
MAX22025F-MAX22028F

Compact, Isolated, Half-Duplex RS-485/RS-422
Transceivers with AutoDirection Control

Ordering Information

PART	TEMP RANGE	FAIL-SAFE RECEIVER	RXD IN DRIVER-ENABLED STATE	DRIVER SPEED (Mbps)	PIN-PACKAGE
MAX22025AWA+	-40°C to +85°C	NO	HIGH	0.5	8 Wide SOIC
MAX22025AWA+T	-40°C to +85°C	NO	HIGH	0.5	8 Wide SOIC
MAX22026AWA+	-40°C to +85°C	NO	HIGH	16	8 Wide SOIC
MAX22026AWA+T	-40°C to +85°C	NO	HIGH	16	8 Wide SOIC
MAX22027AWA+	-40°C to +85°C	NO	FOLLOWS (V _A -V _B)	0.5	8 Wide SOIC
MAX22027AWA+T	-40°C to +85°C	NO	FOLLOWS (V _A -V _B)	0.5	8 Wide SOIC
MAX22028AWA+	-40°C to +85°C	NO	FOLLOWS (V _A -V _B)	16	8 Wide SOIC
MAX22028AWA+T	-40°C to +85°C	NO	FOLLOWS (V _A -V _B)	16	8 Wide SOIC
MAX22025FAWA+	-40°C to +85°C	YES	HIGH	0.5	8 Wide SOIC
MAX22025FAWA+T	-40°C to +85°C	YES	HIGH	0.5	8 Wide SOIC
MAX22026FAWA+	-40°C to +85°C	YES	HIGH	16	8 Wide SOIC
MAX22026FAWA+T	-40°C to +85°C	YES	HIGH	16	8 Wide SOIC
MAX22027FAWA+	-40°C to +85°C	YES	FOLLOWS (V _A -V _B)	0.5	8 Wide SOIC
MAX22027FAWA+T	-40°C to +85°C	YES	FOLLOWS (V _A -V _B)	0.5	8 Wide SOIC
MAX22028FAWA+	-40°C to +85°C	YES	FOLLOWS (V _A -V _B)	16	8 Wide SOIC
MAX22028FAWA+T	-40°C to +85°C	YES	FOLLOWS (V _A -V _B)	16	8 Wide SOIC

+Denotes a lead(Pb)-free/RoHS-compliant package.

T = Tape and reel.

*Future product—contact factory for availability

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	8/19	Initial release	—
1	9/19	Updated the <i>Electrical Characteristics</i> section and added future product designation to MAX22025AWA+ and MAX22025AWA+T in the <i>Ordering Information</i> table	3, 15
2	11/19	Removed future product designation from MAX22025AWA+ and MAX22025AWA+T in the <i>Ordering Information</i> table	15
3	2/20	Updated the title, <i>General Description</i> , <i>Benefits and Features</i> , <i>Functional Diagram</i> , <i>DC Electrical Characteristics</i> , <i>Switching Electrical Characteristics</i> , <i>Pin Configuration</i> , <i>Functional Tables</i> , <i>Detailed Description</i> , <i>AutoDirection Circuitry</i> , <i>Pullup and Pulldown Resistors</i> , <i>Receive State</i> , <i>Receiver Output (RXD)</i> , and <i>Typical Application Circuits</i> sections; updated TOC01–TOC14, TOC23–TOC32; added the <i>Safety Regulatory Approvals</i> table and <i>Failsafe Receiver (MAX22025F–MAX22028F)</i> section; added MAX22025FAWA+, MAX22025FAWA+T, MAX22026FAWA+, MAX22026FAWA+T, MAX22027FAWA+, MAX22027FAWA+T, MAX22028FAWA+, and MAX22028FAWA+T as future parts to the <i>Ordering Information</i> table	1–16
3.1		Corrected typo	1
4	4/20	Removed future product designation from MAX22025FAWA+ and MAX22025FAWA+T in the <i>Ordering Information</i> table	15
5	3/21	Removed future product designation from MAX22028FAWA+ and MAX22028FAWA+T and added a Fail-Safe Receiver column in the <i>Ordering Information</i> table	19
6	3/21	Removed future product designation from MAX22026FAWA+, MAX22026FAWA+T, MAX22027FAWA+, and MAX22027FAWA+T in the <i>Ordering Information</i> table and updated the <i>Isolation</i> and <i>Receiver Output (RXD)</i> sections	15, 16, 19
7	2/22	Removed future product designation from MAX22026AWA and MAX22026AWA+T in the <i>Ordering Information</i> table	21
8	3/22	Removed future product designation from MAX22027AWA and MAX22027AWA+T in the <i>Ordering Information</i> table	21