



# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## General Description

The MAX9675 is a nonblocking 16 x 16 video crosspoint switch with buffered inputs and outputs. The device operates on  $\pm 5V$  analog supplies. Digital logic is supplied separately from an independent +2.7V to +5V supply. The MAX9675 inputs and outputs are buffered with all outputs able to drive a standard 75 $\Omega$  reverse-terminated video load.

The switching matrix and programmable gain are controlled through an SPI™/QSPI™-compatible 3-wire serial interface. The serial interface is designed to operate in either of two modes to provide fast updates and initialization. All outputs are held in the disabled state during power-up to avoid signal conflicts in large switching arrays.

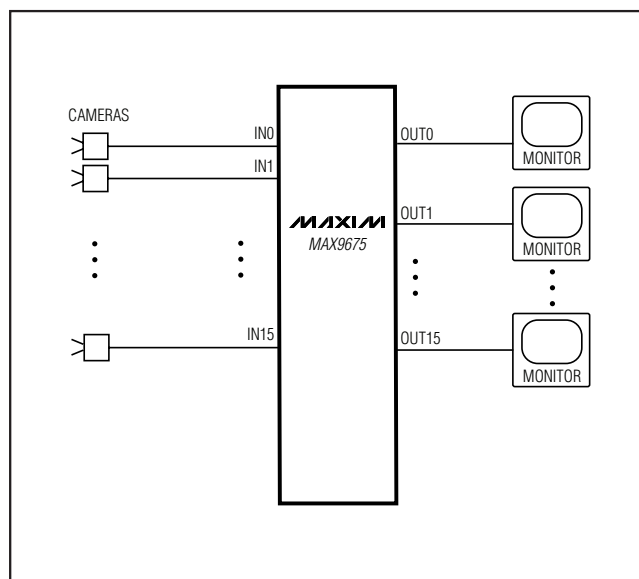
The programmability and high level of integration make the MAX9675 an ideal choice for nonblocking video switch arrays in security, surveillance, and video-on-demand systems.

The MAX9675 is available in a 100-pin TQFP package and specified over the extended -40°C to +85°C temperature range.

## Applications

Security Systems  
Video Routing  
Video-on-Demand Systems

## Typical Operating Circuit



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## Features

- ◆ 16 x 16 Nonblocking Matrix with Buffered Inputs and Outputs
- ◆ Operates at  $\pm 5V$  Supply
- ◆ Individually Programmable Output Buffer Gain ( $A_V = +1V/V$  or  $+2V/V$ )
- ◆ High-Impedance Output Disable for Wired-OR Connections
- ◆ 0.1dB Gain Flatness to 14MHz
- ◆ -3dB Bandwidth 110MHz
- ◆ -62dB Crosstalk, -110dB Isolation at 6MHz

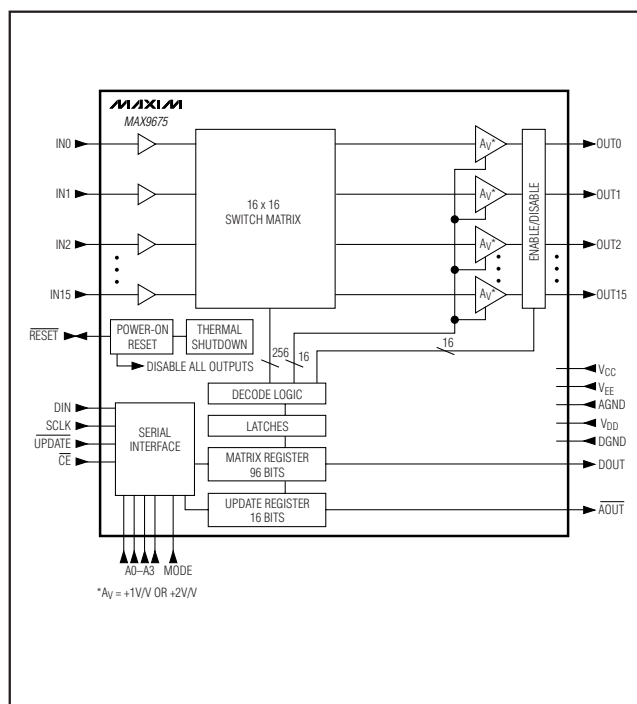
## Ordering Information

| PART        | TEMP RANGE     | PIN-PACKAGE |
|-------------|----------------|-------------|
| MAX9675ECQ+ | -40°C to +85°C | 100 TQFP    |

+Denotes a lead-free/RoHS-compliant package.

Pin Configuration appears at end of data sheet.

## Functional Diagram



# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## ABSOLUTE MAXIMUM RATINGS

Analog Supply Voltage ( $V_{CC} - V_{EE}$ ) .....+11V  
 Digital Supply Voltage ( $V_{DD} - DGND$ ) .....+6V  
 Analog Supplies to Analog Ground  
 ( $V_{CC} - AGND$ ) and ( $AGND - V_{EE}$ ) .....+6V  
 Analog Ground to Digital Ground .....-0.3V to +0.3V  
 IN<sub>-</sub> Voltage Range ..... ( $V_{CC} + 0.3V$ ) to ( $V_{EE} - 0.3V$ )  
 OUT<sub>-</sub> Short-Circuit Duration to AGND,  $V_{CC}$ , or  $V_{EE}$ .....Indefinite  
 SCLK,  $\overline{CE}$ ,  $\overline{UPDATE}$ , MODE, A<sub>-</sub>, DIN, DOUT,  
 RESET, AOUT.....( $V_{DD} + 0.3V$ ) to ( $DGND - 0.3V$ )

Current into Any Analog Input Pin (IN<sub>-</sub>) .....±50mA  
 Current into Any Analog Output Pin (OUT<sub>-</sub>).....±75mA  
 Continuous Power Dissipation ( $T_A = +70^\circ\text{C}$ )  
 100-Pin TQFP (derate 22.2mW/ $^\circ\text{C}$  above  $+70^\circ\text{C}$ ).....1777mW  
 Operating Temperature Range .....-40 $^\circ\text{C}$  to  $+85^\circ\text{C}$   
 Junction Temperature.....+150 $^\circ\text{C}$   
 Storage Temperature Range.....-65 $^\circ\text{C}$  to  $+150^\circ\text{C}$   
 Lead Temperature (soldering, 10s)..... +300 $^\circ\text{C}$

Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES $\pm 5V$

( $V_{CC} = +5V$ ,  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN-} = 0$ ,  $R_L = 150\Omega$  to AGND, and  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ\text{C}$ .) (Note 5)

| PARAMETER                             | SYMBOL            | CONDITIONS                                                                             | MIN | TYP | MAX  | UNITS |
|---------------------------------------|-------------------|----------------------------------------------------------------------------------------|-----|-----|------|-------|
| Operating Supply Voltage Range        | $V_{CC} - V_{EE}$ | Guaranteed by PSRR test                                                                | 4.5 |     | 10.5 | V     |
| Logic-Supply Voltage Range            | $V_{DD}$ to DGND  |                                                                                        | 2.7 |     | 5.5  | V     |
| Gain (Note 1)                         | $A_V$             | $(V_{EE} + 2.5V) < V_{IN-} < (V_{CC} - 2.5V)$ ,<br>$A_V = +1V/V$ , $R_L = 150\Omega$   |     | 1   |      | V/V   |
|                                       |                   | $(V_{EE} + 2.5V) < V_{IN-} < (V_{CC} - 2.5V)$ ,<br>$A_V = +1V/V$ , $R_L = 10k\Omega$   |     | 1   |      |       |
|                                       |                   | $(V_{EE} + 3.75V) < V_{IN-} < (V_{CC} - 3.75V)$ ,<br>$A_V = +2V/V$ , $R_L = 150\Omega$ |     | 2   |      |       |
|                                       |                   | $(V_{EE} + 3.75V) < V_{IN-} < (V_{CC} - 3.75V)$ ,<br>$A_V = +2V/V$ , $R_L = 10k\Omega$ |     | 2   |      |       |
|                                       |                   | $(V_{EE} + 1V) < V_{IN-} < (V_{CC} - 1.2V)$ ,<br>$A_V = +1V/V$ , $R_L = 10k\Omega$     |     | 1   |      |       |
| Gain Matching<br>(Channel to Channel) |                   | $R_L = 10k\Omega$                                                                      |     | 0.5 | 1.5  | %     |
|                                       |                   | $R_L = 150\Omega$                                                                      |     | 0.5 | 2    |       |

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## DC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES $\pm 5V$ (continued)

( $V_{CC} = +5V$ ,  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN\_} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ .) (Note 5)

| PARAMETER                            | SYMBOL       | CONDITIONS                                    |                                      | MIN             | TYP | MAX             | UNITS           |
|--------------------------------------|--------------|-----------------------------------------------|--------------------------------------|-----------------|-----|-----------------|-----------------|
| Temperature Coefficient of Gain      | $TC_{AV}$    |                                               |                                      | 10              |     |                 | ppm/ $^\circ C$ |
| Input Voltage Range                  | $V_{IN\_}$   | $A_V = +1V/V$                                 | $R_L = 10k\Omega$                    | $V_{EE} + 1$    |     | $V_{CC} - 1.2$  | V               |
|                                      |              |                                               | $R_L = 150\Omega$                    | $V_{EE} + 2.5$  |     | $V_{CC} - 2.5$  |                 |
|                                      |              | $A_V = +2V/V$                                 | $R_L = 10k\Omega$                    | $V_{EE} + 3$    |     | $V_{CC} - 3.1$  |                 |
|                                      |              |                                               | $R_L = 150\Omega$                    | $V_{EE} + 3.75$ |     | $V_{CC} - 3.75$ |                 |
| Output Voltage Range                 | $V_{OUT\_}$  | $R_L = 10k\Omega$                             |                                      | $V_{EE} + 1$    |     | $V_{CC} - 1.2$  | V               |
|                                      |              | $R_L = 150\Omega$                             |                                      | $V_{EE} + 2.5$  |     | $V_{CC} - 2.5$  | V               |
| Input Bias Current                   | $I_B$        |                                               |                                      | 4               |     | 11              | $\mu A$         |
| Input Resistance                     | $R_{IN\_}$   | $(V_{EE} + 1V) < V_{IN\_} < (V_{CC} - 1.2V)$  |                                      | 10              |     |                 | $M\Omega$       |
| Output Offset Voltage                | $V_{OFFSET}$ | $A_V = +1V/V$                                 |                                      | $\pm 5$         |     | $\pm 20$        | mV              |
|                                      |              | $A_V = +2V/V$                                 |                                      | $\pm 10$        |     | $\pm 40$        |                 |
| Output Short-Circuit Current         | $I_{SC}$     | Sinking or sourcing, $R_L = 1\Omega$          |                                      | $\pm 40$        |     |                 | mA              |
| Enabled Output Impedance             | $Z_{OUT}$    | $(V_{EE} + 1V) < V_{IN\_} < (V_{CC} - 1.2V)$  |                                      | 0.2             |     |                 | $\Omega$        |
| Output Leakage Current, Disable Mode | $I_{OD}$     | $(V_{EE} + 1V) < V_{OUT\_} < (V_{CC} - 1.2V)$ |                                      | 0.004           |     | 1               | $\mu A$         |
| DC Power-Supply Rejection Ratio      | PSRR         | $4.5V < (V_{CC} - V_{EE}) < 10.5V$            |                                      | 60              | 70  |                 | dB              |
| Quiescent Supply Current             | $I_{CC}$     | $R_L = \infty$                                | Outputs enabled, $T_A = +25^\circ C$ | 100             |     | 150             | mA              |
|                                      |              |                                               | Outputs enabled                      |                 |     | 175             |                 |
|                                      |              |                                               | Outputs disabled                     | 55              |     | 75              |                 |
|                                      | $I_{EE}$     | $R_L = \infty$                                | Outputs enabled, $T_A = +25^\circ C$ | 95              |     | 150             |                 |
|                                      |              |                                               | Outputs enabled                      |                 |     | 175             |                 |
|                                      |              |                                               | Outputs disabled                     | 50              |     | 75              |                 |
|                                      | $I_{DD}$     |                                               |                                      | 4               |     | 8               |                 |

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## LOGIC-LEVEL CHARACTERISTICS

( $V_{CC} = +5V$ ,  $V_{EE} = -5V$ ,  $V_{DD} = +2.7V$  to  $+5.5V$ ,  $AGND = DGND = 0$ ,  $V_{IN\_} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ .) (Notes 2, 5)

| PARAMETER                 | SYMBOL   | CONDITIONS                          |                              | MIN  | TYP   | MAX | UNITS   |
|---------------------------|----------|-------------------------------------|------------------------------|------|-------|-----|---------|
| Input-Voltage High Level  | $V_{IH}$ | $V_{DD} = +5V$                      |                              | 3    |       |     | V       |
|                           |          | $V_{DD} = +3V$                      |                              | 2    |       |     |         |
| Input-Voltage Low Level   | $V_{IL}$ | $V_{DD} = +5V$                      |                              |      |       | 0.8 | V       |
|                           |          | $V_{DD} = +3V$                      |                              |      |       | 0.6 |         |
| Input Current High Level  | $I_{IH}$ | $V_I > 2V$                          | Excluding $\overline{RESET}$ | -1   | +0.01 | +1  | $\mu A$ |
|                           |          |                                     | $\overline{RESET}$           | -30  | -20   |     |         |
| Input Current Low Level   | $I_{IL}$ | $V_I < 1V$                          | Excluding $\overline{RESET}$ | -1   | +0.01 | +1  | $\mu A$ |
|                           |          |                                     | $\overline{RESET}$           | -300 | -235  |     |         |
| Output-Voltage High Level | $V_{OH}$ | $I_{SOURCE} = 1mA$ , $V_{DD} = +5V$ |                              | 4.7  | 4.9   |     | V       |
|                           |          | $I_{SOURCE} = 1mA$ , $V_{DD} = +3V$ |                              | 2.7  | 2.9   |     |         |
| Output-Voltage Low Level  | $V_{OL}$ | $I_{SINK} = 1mA$ , $V_{DD} = +5V$   |                              |      | 0.1   | 0.3 | V       |
|                           |          | $I_{SINK} = 1mA$ , $V_{DD} = +3V$   |                              |      | 0.1   | 0.3 |         |
| Output Current High Level | $I_{OH}$ | $V_{DD} = +5V$ , $V_O = +4.9V$      |                              | 1    | 4     |     | mA      |
|                           |          | $V_{DD} = +3V$ , $V_O = +2.7V$      |                              | 1    | 8     |     |         |
| Output Current Low Level  | $I_{OL}$ | $V_{DD} = +5V$ , $V_O = +0.1V$      |                              | 1    | 4     |     | mA      |
|                           |          | $V_{DD} = +3V$ , $V_O = +0.3V$      |                              | 1    | 8     |     |         |

## AC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES $\pm 5V$

( $V_{CC} = +5V$ ,  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN\_} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)

| PARAMETER                     | SYMBOL          | CONDITIONS                           |               | MIN | TYP | MAX | UNITS      |
|-------------------------------|-----------------|--------------------------------------|---------------|-----|-----|-----|------------|
| Small-Signal -3dB Bandwidth   | $BW_{SS}$       | $V_{OUT\_} = 20mV_{P-P}$             | $A_V = +1V/V$ |     | 110 |     | MHz        |
|                               |                 |                                      | $A_V = +2V/V$ |     | 78  |     |            |
| Medium-Signal -3dB Bandwidth  | $BW_{MS}$       | $V_{OUT\_} = 200mV_{P-P}$            | $A_V = +1V/V$ |     | 80  |     | MHz        |
|                               |                 |                                      | $A_V = +2V/V$ |     | 75  |     |            |
| Large-Signal -3dB Bandwidth   | $BW_{LS}$       | $V_{OUT\_} = 2V_{P-P}$               | $A_V = +1V/V$ |     | 40  |     | MHz        |
|                               |                 |                                      | $A_V = +2V/V$ |     | 50  |     |            |
| Small-Signal 0.1dB Bandwidth  | $BW_{0.1dB-SS}$ | $V_{OUT\_} = 20mV_{P-P}$             | $A_V = +1V/V$ |     | 14  |     | MHz        |
|                               |                 |                                      | $A_V = +2V/V$ |     | 11  |     |            |
| Medium-Signal 0.1dB Bandwidth | $BW_{0.1dB-MS}$ | $V_{OUT\_} = 200mV_{P-P}$            | $A_V = +1V/V$ |     | 14  |     | MHz        |
|                               |                 |                                      | $A_V = +2V/V$ |     | 11  |     |            |
| Large-Signal 0.1dB Bandwidth  | $BW_{0.1dB-LS}$ | $V_{OUT\_} = 2V_{P-P}$               | $A_V = +1V/V$ |     | 14  |     | MHz        |
|                               |                 |                                      | $A_V = +2V/V$ |     | 11  |     |            |
| Slew Rate                     | SR              | $V_{OUT\_} = 2V$ step, $A_V = +1V/V$ |               |     | 150 |     | V/ $\mu s$ |
|                               |                 | $V_{OUT\_} = 2V$ step, $A_V = +2V/V$ |               |     | 150 |     |            |

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## AC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES $\pm 5V$ (continued)

( $V_{CC} = +5V$ ,  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN-} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ ,  $A_V = +1V/V$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)

| PARAMETER                                | SYMBOL       | CONDITIONS                |                 | MIN | TYP   | MAX | UNITS         |
|------------------------------------------|--------------|---------------------------|-----------------|-----|-------|-----|---------------|
| Settling Time                            | $t_{S0.1\%}$ | $V_{OUT-} = 0$ to 2V step | $A_V = +1V/V$   |     | 60    |     | ns            |
|                                          |              |                           | $A_V = +2V/V$   |     | 60    |     |               |
| Switching Transient (Glitch)<br>(Note 3) |              | $A_V = +1V/V$             |                 |     | 50    |     | mV            |
|                                          |              | $A_V = +2V/V$             |                 |     | 45    |     |               |
| AC Power-Supply Rejection Ratio          |              | $f = 100kHz$              |                 |     | 70    |     | dB            |
|                                          |              | $f = 1MHz$                |                 |     | 68    |     |               |
| Differential Gain Error<br>(Note 4)      |              | $R_L = 1k\Omega$          |                 |     | 0.002 |     | %             |
|                                          |              | $R_L = 150\Omega$         |                 |     | 0.02  |     |               |
| Differential Phase Error<br>(Note 4)     |              | $R_L = 1k\Omega$          |                 |     | 0.02  |     | degrees       |
|                                          |              | $R_L = 150\Omega$         |                 |     | 0.12  |     |               |
| Crosstalk, All Hostile                   |              | $f = 6MHz$                |                 |     | -62   |     | dB            |
| Off-Isolation, Input to Output           |              | $f = 6MHz$                |                 |     | -110  |     | dB            |
| Input Noise-Voltage Density              | $e_n$        | $BW = 6MHz$               |                 |     | 73    |     | $\mu V_{RMS}$ |
| Input Capacitance                        | $C_{IN}$     |                           |                 |     | 5     |     | pF            |
| Disabled Output Capacitance              |              | Amplifier in disable mode |                 |     | 3     |     | pF            |
| Capacitive Load at 3dB Output Peaking    |              |                           |                 |     | 30    |     | pF            |
| Output Impedance                         | $Z_{OUT}$    | $f = 6MHz$                | Output enabled  |     | 3     |     | $\Omega$      |
|                                          |              |                           | Output disabled |     | 4k    |     |               |

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## SWITCHING CHARACTERISTICS

( $V_{CC} = +5V$ ,  $V_{EE} = -5V$ ,  $V_{DD} = +2.7V$  to  $+5.5V$ ,  $DGND = AGND = 0$ ,  $V_{IN\_} = 0$  for dual supplies,  $R_L = 150\Omega$  to  $AGND$ ,  $C_L = 100pF$ ,  $A_v = +1V/V$ , and  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^\circ C$ .) (Note 5)

| PARAMETER                                       | SYMBOL       | CONDITIONS                                                                              | MIN | TYP | MAX | UNITS |
|-------------------------------------------------|--------------|-----------------------------------------------------------------------------------------|-----|-----|-----|-------|
| Delay: $\overline{UPDATE}$ to Video Out         | $t_{PdUdVo}$ | $V_{IN\_} = 0.5V$ step                                                                  |     | 200 | 450 | ns    |
| Delay: $\overline{UPDATE}$ to $\overline{AOUT}$ | $t_{PdUdAo}$ | MODE = 0, time to $\overline{AOUT} = \text{low}$ after $\overline{UPDATE} = \text{low}$ |     | 30  | 200 | ns    |
| Delay: SCLK to DOUT Valid                       | $t_{PdDo}$   | Logic state change in DOUT on active SCLK edge                                          |     | 30  | 200 | ns    |
| Delay: Output Disable                           | $t_{PdHOe}$  | $V_{OUT\_} = 0.5V$ , $1k\Omega$ pulldown to AGND                                        |     | 300 | 800 | ns    |
| Delay: Output Enable                            | $t_{PdLOe}$  | Output disabled, $1k\Omega$ pulldown to AGND, $V_{IN\_} = 0.5V$                         |     | 200 | 800 | ns    |
| Setup: $\overline{CE}$ to SCLK                  | $t_{SuCe}$   |                                                                                         |     |     | 100 | ns    |
| Setup: DIN to SCLK                              | $t_{SuDi}$   |                                                                                         | 100 |     |     | ns    |
| Hold Time: SCLK to DIN                          | $t_{HdDi}$   |                                                                                         | 100 |     |     | ns    |
| Minimum High Time: SCLK                         | $t_{MnHCK}$  |                                                                                         | 100 |     |     | ns    |
| Minimum Low Time: SCLK                          | $t_{MnLCK}$  |                                                                                         | 100 |     |     | ns    |
| Minimum Low Time: $\overline{UPDATE}$           | $t_{MnLUd}$  |                                                                                         | 100 |     |     | ns    |
| Setup Time: $\overline{UPDATE}$ to SCLK         | $t_{SuHUd}$  | Rising edge of $\overline{UPDATE}$ to falling edge of SCLK                              | 100 |     |     | ns    |
| Hold Time: SCLK to $\overline{UPDATE}$          | $t_{HdHUd}$  | Falling edge of SCLK to falling edge of $\overline{UPDATE}$                             | 100 |     |     | ns    |
| Setup Time: MODE to SCLK                        | $t_{SuMd}$   | Minimum time from clock edge to MODE with valid data clocking                           | 100 |     |     | ns    |
| Hold Time: MODE to SCLK                         | $t_{HdMd}$   | Minimum time from clock edge to MODE with valid data clocking                           | 100 |     |     | ns    |
| Minimum Low Time: $\overline{RESET}$            | $t_{MnLRst}$ |                                                                                         |     |     | 300 | ns    |
| Delay: $\overline{RESET}$                       | $t_{PdRst}$  | $10k\Omega$ pulldown to AGND, $0.5V$ step                                               |     |     | 600 | ns    |

**Note 1:** Associated output voltage may be determined by multiplying the input voltage by the specified gain ( $A_v$ ) and adding output offset voltage.

**Note 2:** Logic-level characteristics apply to the following pins: DIN, DOUT, SCLK,  $\overline{CE}$ ,  $\overline{UPDATE}$ ,  $\overline{RESET}$ , A3–A0, MODE, and  $\overline{AOUT}$ .

**Note 3:** Switching transient settling time is guaranteed by the settling time ( $t_s$ ) specification. Switching transient is a result of updating the switch matrix.

**Note 4:** Input test signal: 3.58MHz sine wave of amplitude 40IRE superimposed on a linear ramp (0 to 100IRE). IRE is a unit of video-signal amplitude developed by the International Radio Engineers: 140IRE = 1.0V.

**Note 5:** All devices are 100% production tested at  $T_A = +25^\circ C$ . Specifications over temperature limits are guaranteed by design.

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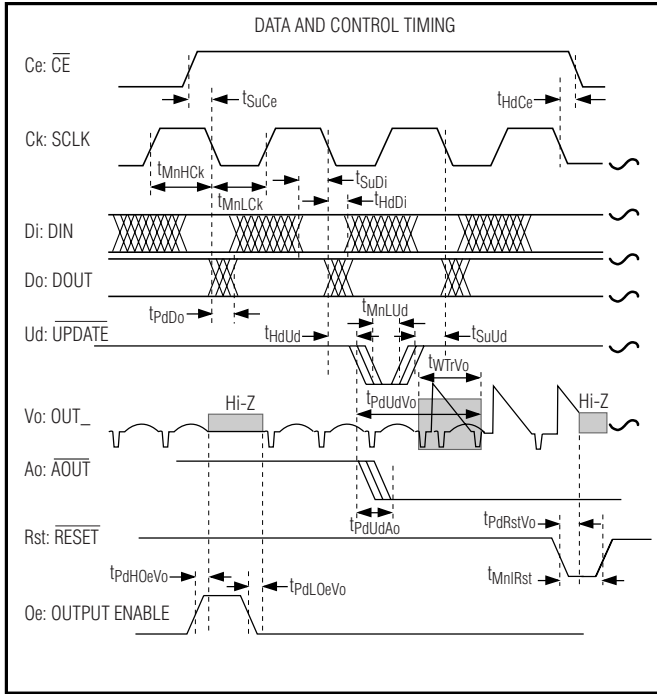
## Symbol Definitions

| SYMBOL | TYPE     | DESCRIPTION                        |
|--------|----------|------------------------------------|
| Ao     | Signal   | Address Valid Flag (AOUT)          |
| Ce     | Signal   | Clock Enable ( $\overline{CE}$ )   |
| Ck     | Signal   | Clock (SCLK)                       |
| Di     | Signal   | Serial-Data In (DIN)               |
| Do     | Signal   | Serial-Data Output (DOUT)          |
| Md     | Signal   | MODE                               |
| Oe     | Signal   | Output Enable                      |
| Rst    | Signal   | Reset Input ( $\overline{RESET}$ ) |
| Ud     | Signal   | $\overline{UPDATE}$                |
| Vo     | Signal   | Video Out (OUT)                    |
| H      | Property | High- or Low-to-High Transition    |
| Hd     | Property | Hold                               |
| L      | Property | Low- or High-to-Low Transition     |
| Mn     | Property | Minimum                            |
| Mx     | Property | Maximum                            |
| Pd     | Property | Propagation Delay                  |
| Su     | Property | Setup                              |
| Tr     | Property | Transition                         |
| W      | Property | Width                              |

## Naming Conventions

- All parameters with time units are given a "t" designation, with appropriate subscript modifiers.
- Propagation delays for clocked signals are from the active edge of clock.
- Propagation delay for level-sensitive signals is from input to output at the 50% point of a transition.
- Setup and hold times are measured from the 50% point of signal transition to the 50% point of the clocking signal transition.
- Setup time refers to any signal that must be stable before the active clock edge, even if the signal is not latched or clocked itself.
- Hold time refers to any signal that must be stable during and after active clock edge, even if the signal is not latched or clocked.
- Propagation delays to unobservable internal signals are modified to setup and hold designations applied to observable I/O signals.

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| TIMING PARAMETER DEFINITIONS |                                            |
|------------------------------|--------------------------------------------|
| NAME                         | DESCRIPTION                                |
| $t_{HdDi}$                   | Hold Time: Clock to Data In                |
| $t_{MnHck}$                  | Min High Time: Clk                         |
| $t_{MnLck}$                  | Min Low Time: Clk                          |
| $t_{MnLud}$                  | Min Low Time: Update                       |
| $t_{SuHud}$                  | Setup Time: UPDATE to Clk with UPDATE High |
| Not Valid                    | Setup Time: UPDATE to Clk with UPDATE Low  |
| $t_{HdHud}$                  | Hold Time: Clk to UPDATE with UPDATE high  |
| Not Valid                    | Hold Time: Clk to UPDATE with UPDATE Low   |
| $t_{PdDiDo}$                 | Asynchronous Delay: Data In to Data Out    |
| $t_{MnMd}$                   | Min Low Time: MODE                         |
| $t_{MxTr}$                   | Max Rise Time: Clk, Update                 |
| $t_{MnLrst}$                 | Min Low Time: Reset                        |
| $t_{PdRstVo}$                | Delay: Reset to Video Output               |

| TIMING PARAMETER DEFINITIONS |                                                      |
|------------------------------|------------------------------------------------------|
| NAME                         | DESCRIPTION                                          |
| $t_{PdUdVo}$                 | Delay: Update to Video Out                           |
| $t_{PdUdAo}$                 | Delay: UPDATE to Aout                                |
| $t_{PdDo}$                   | Delay: Clk to Data Out                               |
| $t_{PdHOeVo}$                | Delay: Output Enable to Video Output (High: Disable) |
| $t_{PdLOeVo}$                | Delay: Output Enable to Video Output (Low: Enable)   |
| $t_{SuCe}$                   | Setup: Clock Enable to Clock                         |
| $t_{SuDi}$                   | Setup Time: Data In to Clock                         |

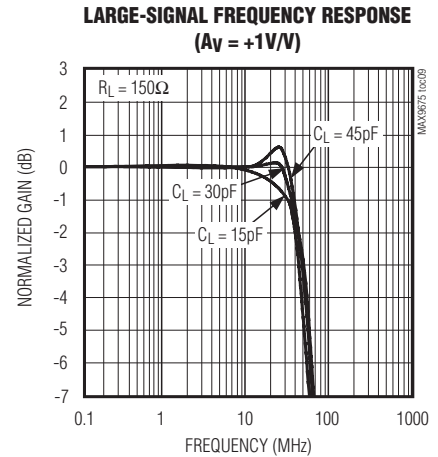
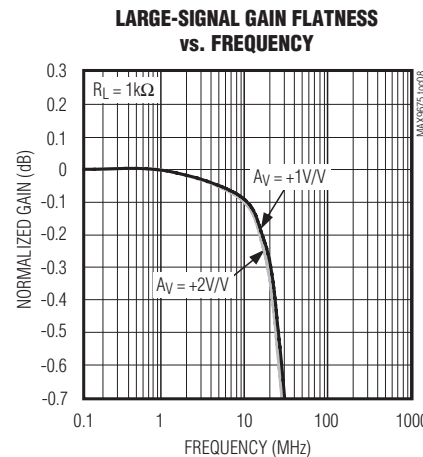
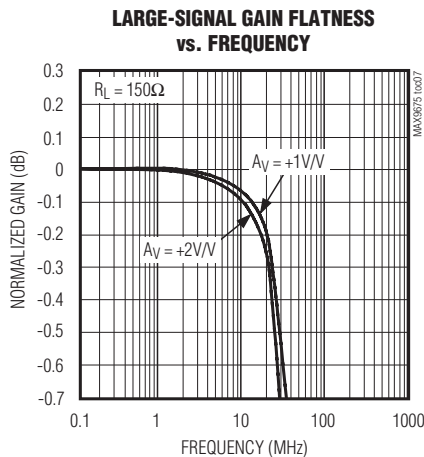
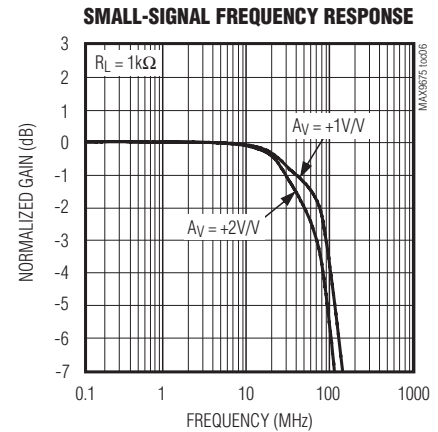
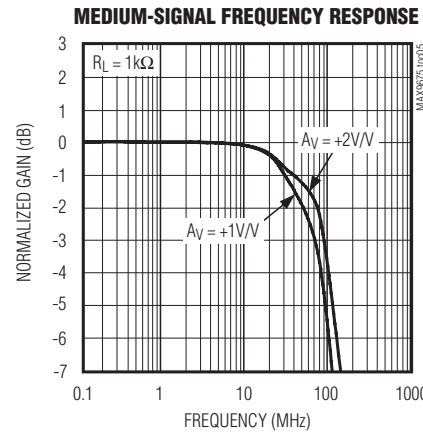
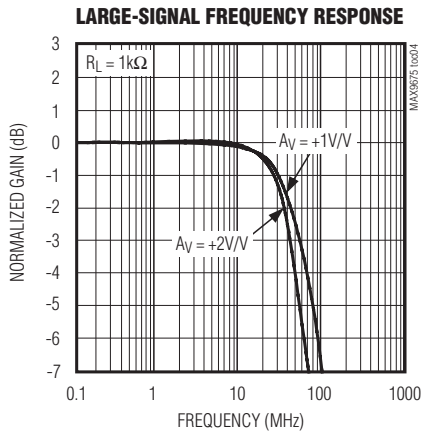
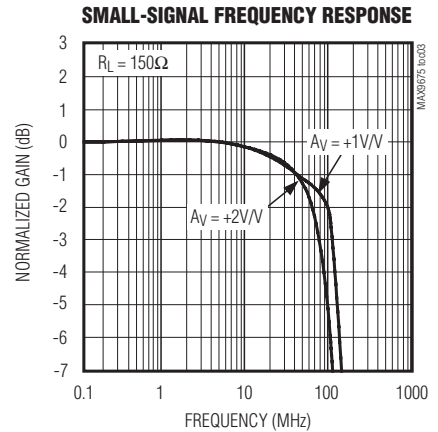
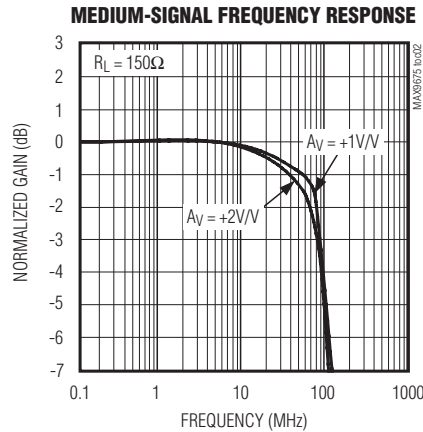
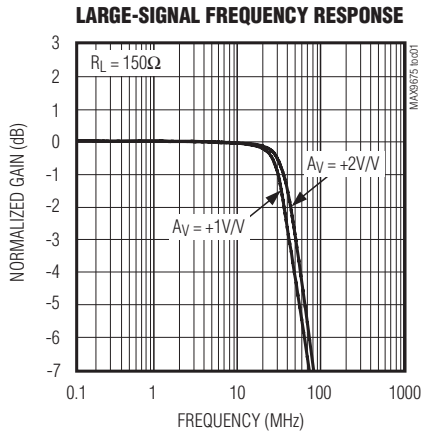
Figure 1. Timing Diagram

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## Typical Operating Characteristics

( $V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN-} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)

MAX9675

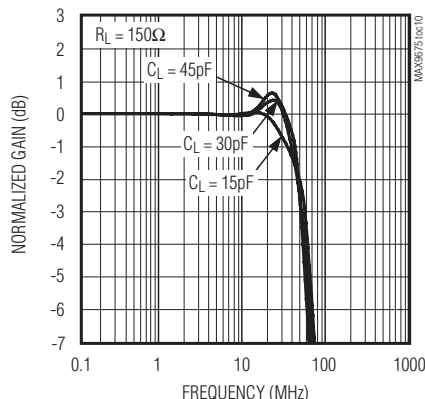


# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

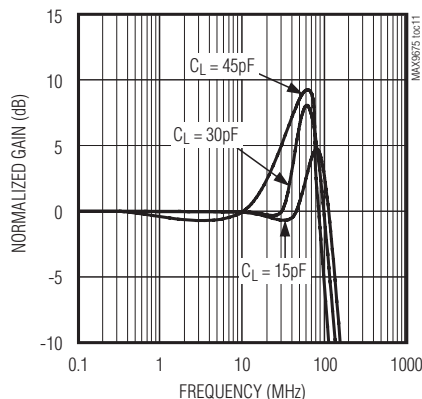
## Typical Operating Characteristics (continued)

( $V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN-} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)

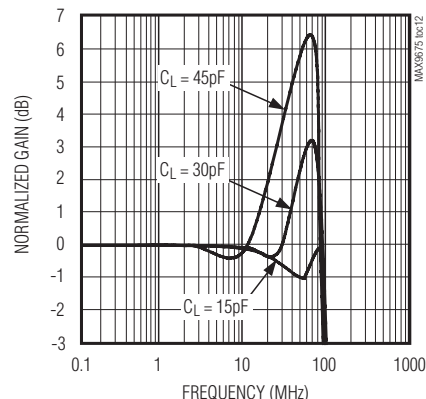
**LARGE-SIGNAL FREQUENCY RESPONSE**  
( $A_V = +2V/V$ )



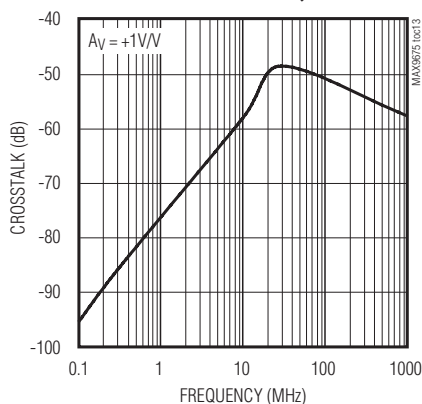
**MEDIUM-SIGNAL FREQUENCY RESPONSE**  
( $A_V = +1V/V$ )



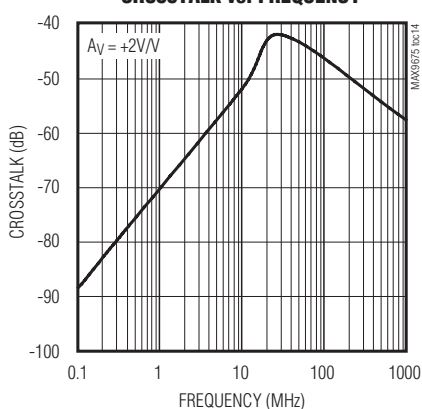
**MEDIUM-SIGNAL FREQUENCY RESPONSE**  
( $A_V = +2V/V$ )



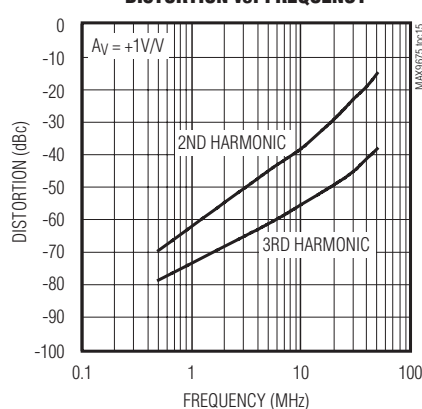
**CROSSTALK vs. FREQUENCY**



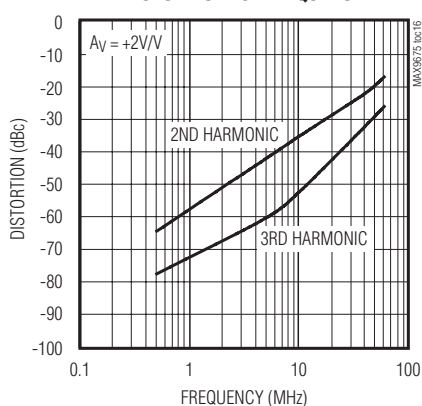
**CROSSTALK vs. FREQUENCY**



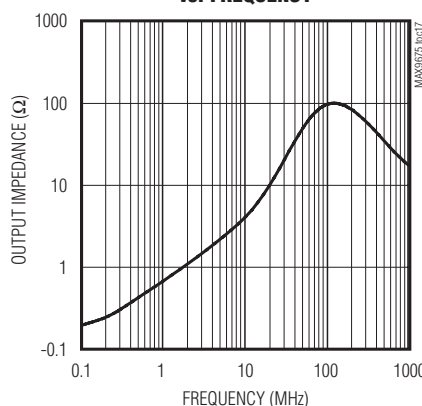
**DISTORTION vs. FREQUENCY**



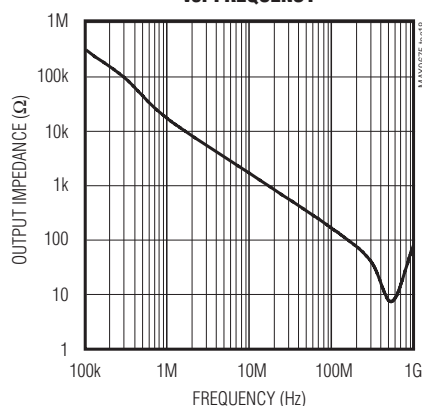
**DISTORTION vs. FREQUENCY**



**ENABLED OUTPUT IMPEDANCE vs. FREQUENCY**



**DISABLED OUTPUT IMPEDANCE vs. FREQUENCY**

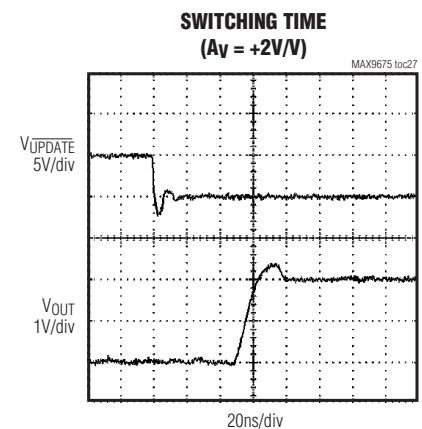
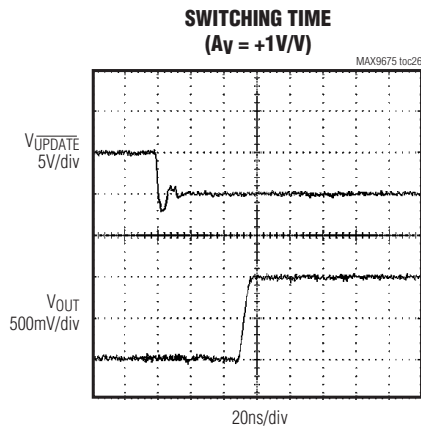
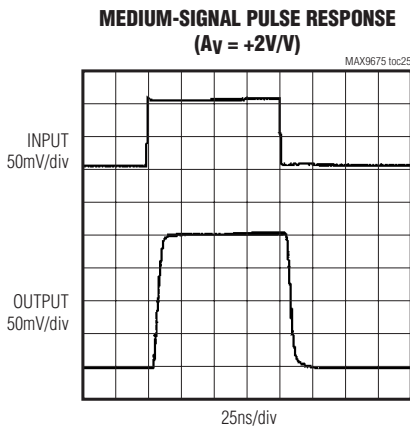
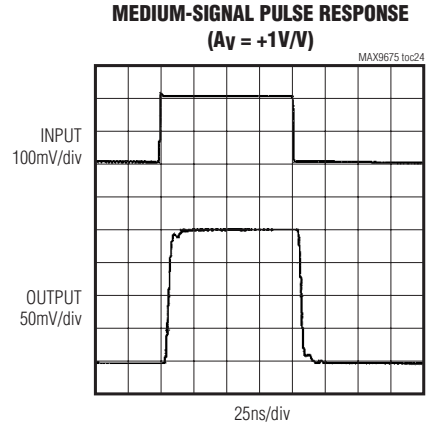
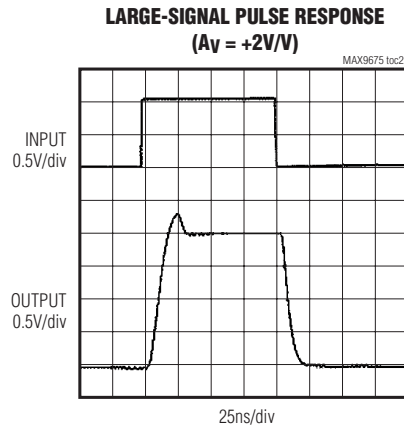
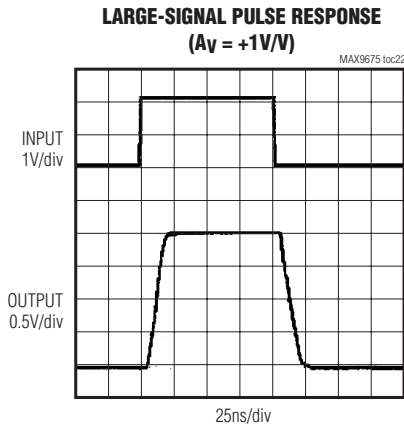
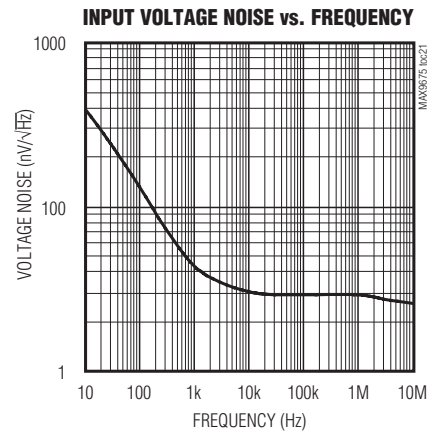
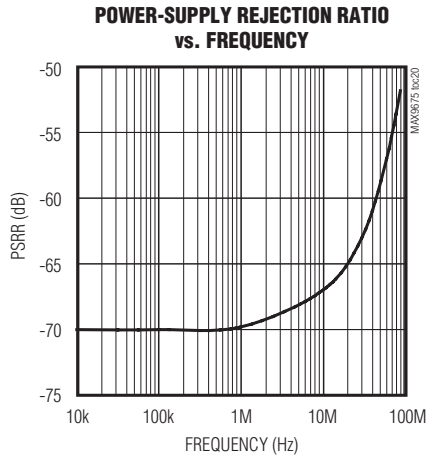
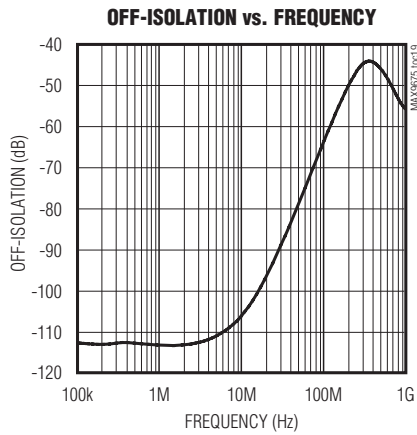


# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

MAX9675

## Typical Operating Characteristics (continued)

( $V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN\_} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)

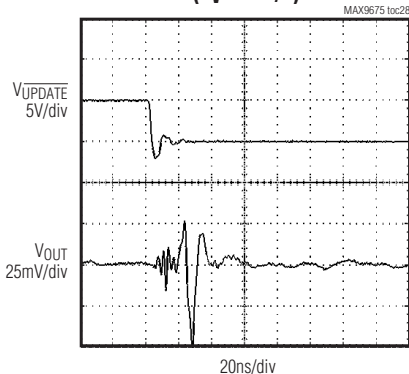


# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

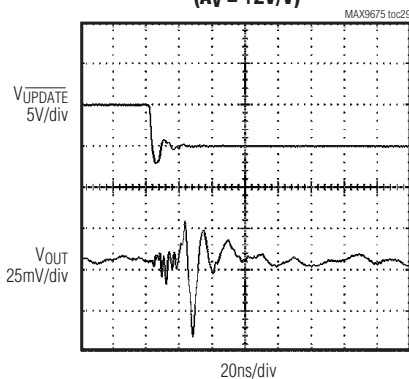
## Typical Operating Characteristics (continued)

( $V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN\_} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)

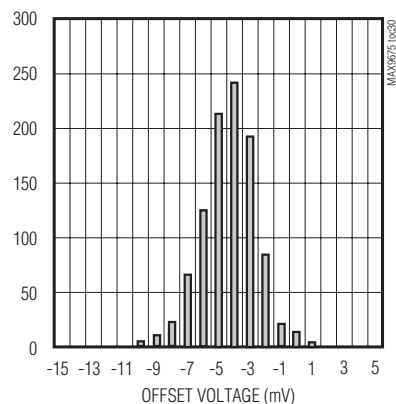
**SWITCHING TRANSIENT (GLITCH)**  
( $A_V = +1V/V$ )



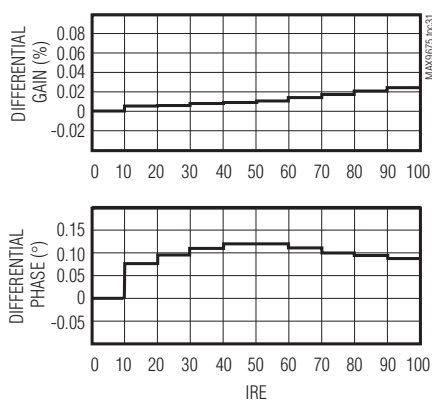
**SWITCHING TRANSIENT (GLITCH)**  
( $A_V = +2V/V$ )



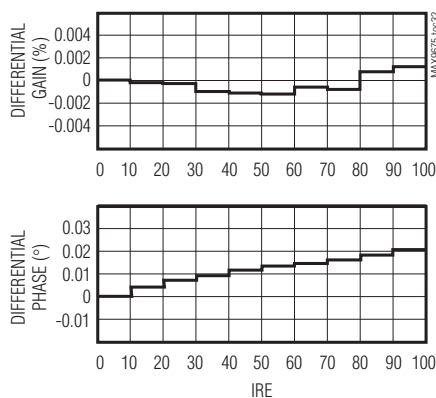
**OFFSET VOLTAGE DISTRIBUTION**



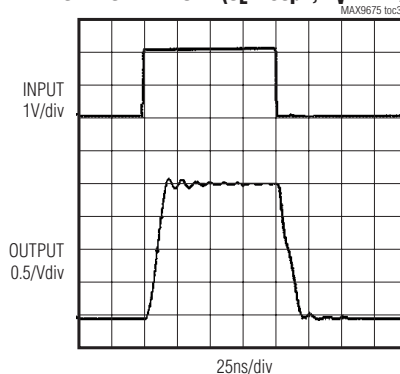
**DIFFERENTIAL GAIN AND PHASE**  
( $R_L = 150\Omega$ )



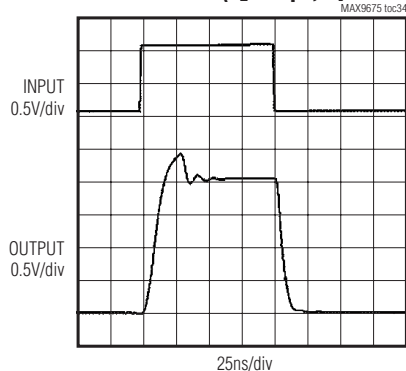
**DIFFERENTIAL GAIN AND PHASE**  
( $R_L = 1k\Omega$ )



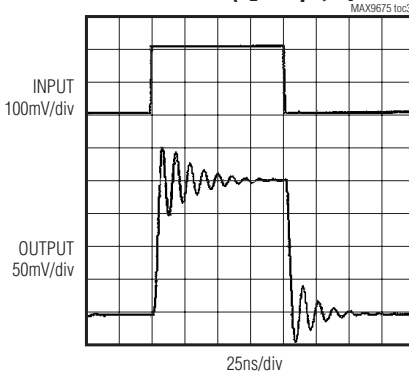
**LARGE-SIGNAL PULSE RESPONSE WITH CAPACITIVE LOAD ( $C_L = 30pF$ ,  $A_V = +1V/V$ )**



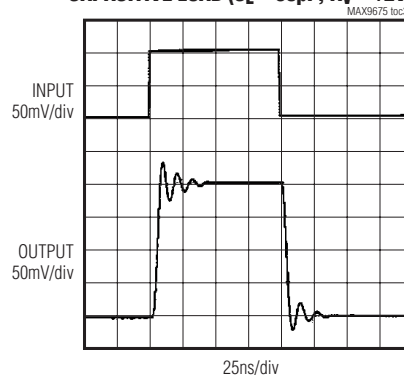
**LARGE-SIGNAL PULSE RESPONSE WITH CAPACITIVE LOAD ( $C_L = 30pF$ ,  $A_V = +2V/V$ )**



**MEDIUM-SIGNAL PULSE RESPONSE WITH CAPACITIVE LOAD ( $C_L = 30pF$ ,  $A_V = +1V/V$ )**



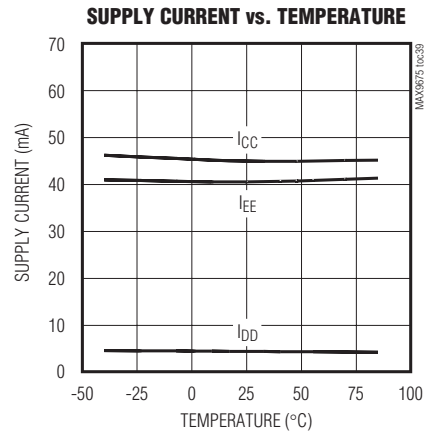
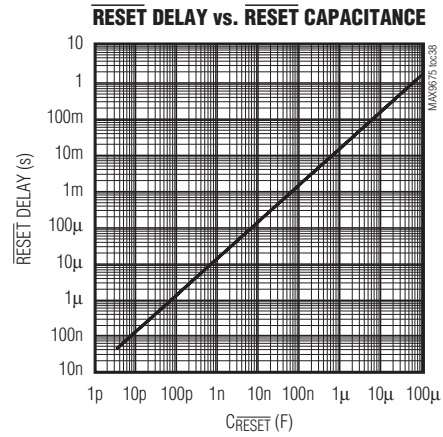
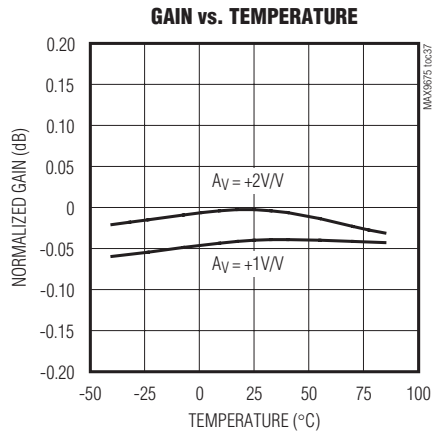
**MEDIUM-SIGNAL PULSE RESPONSE WITH CAPACITIVE LOAD ( $C_L = 30pF$ ,  $A_V = +2V/V$ )**



# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## Typical Operating Characteristics (continued)

( $V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ ,  $AGND = DGND = 0$ ,  $V_{IN\_} = 0$ ,  $R_L = 150\Omega$  to  $AGND$ , and  $T_A = +25^\circ C$ , unless otherwise noted.)



# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

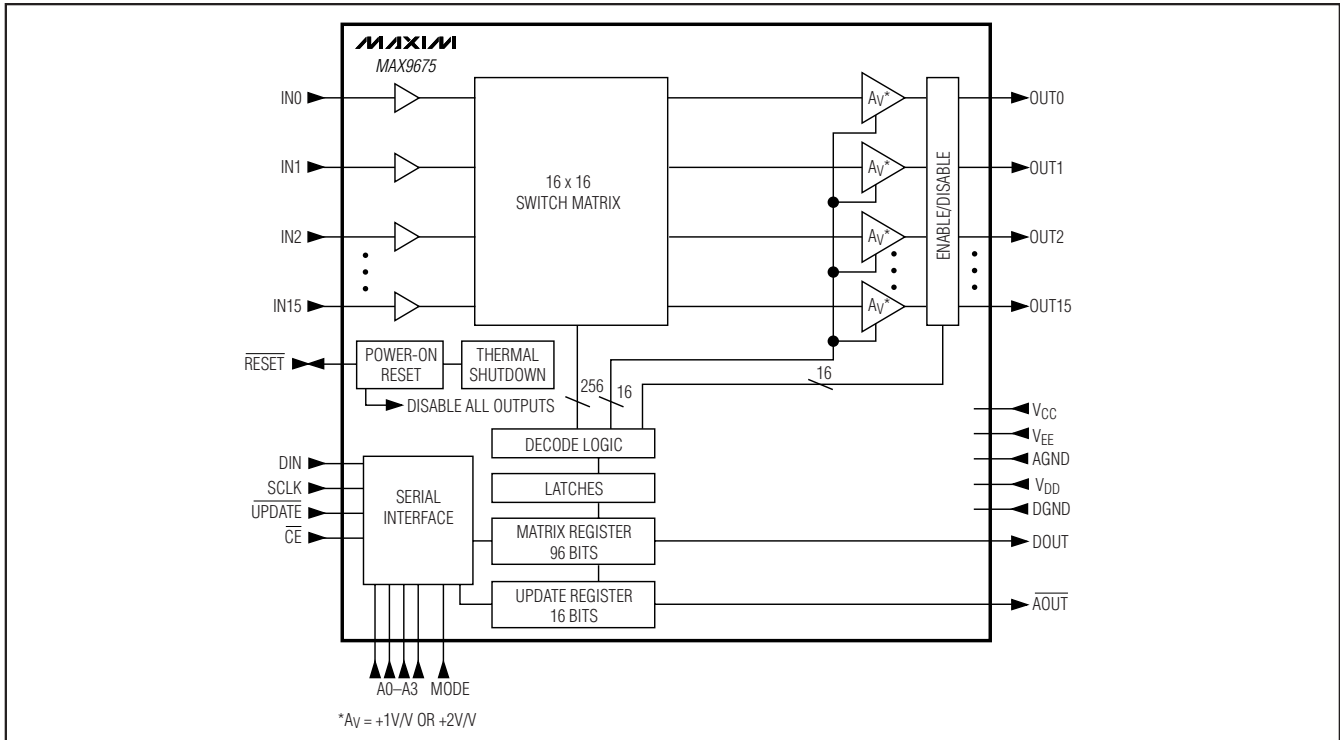
## Pin Description

| PIN                                                            | NAME                       | FUNCTION                                                                                                                                                                                                                                                                                                  |
|----------------------------------------------------------------|----------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1, 3, 5, 7, 9, 11, 13, 15, 17, 19, 21, 23                      | IN4–IN15                   | Buffered Analog Inputs                                                                                                                                                                                                                                                                                    |
| 2, 4, 6, 8, 10, 12, 14, 16, 45, 46, 82, 83, 84, 91, 93, 95, 97 | AGND                       | Analog Ground                                                                                                                                                                                                                                                                                             |
| 18, 20, 22, 24                                                 | A3–A0                      | Address Programming Inputs. Connect to DGND or V <sub>DD</sub> to select the address for Individual Output Address Mode (see Table 3).                                                                                                                                                                    |
| 25, 47, 51, 55, 59, 63, 67, 71, 75, 81                         | V <sub>CC</sub>            | Positive Analog Supply. Bypass each pin with a 0.1μF capacitor to AGND. Connect a single 10μF capacitor from one V <sub>CC</sub> pin to AGND.                                                                                                                                                             |
| 26, 27, 38–44, 76, 77, 85–89, 99, 100                          | N.C.                       | No Connection. Not internally connected. Connect to AGND.                                                                                                                                                                                                                                                 |
| 28                                                             | DOUT                       | Serial-Data Output. In Complete Matrix Mode, data is clocked through the 96-bit Matrix Control shift register. In Individual Output Address Mode, data at DIN passes directly to DOUT.                                                                                                                    |
| 29                                                             | DGND                       | Digital Ground                                                                                                                                                                                                                                                                                            |
| 30                                                             | $\overline{\text{AOUT}}$   | Address Recognition Output. $\overline{\text{AOUT}}$ drives low after successful chip address recognition.                                                                                                                                                                                                |
| 31                                                             | SCLK                       | Serial-Clock Input                                                                                                                                                                                                                                                                                        |
| 32                                                             | $\overline{\text{CE}}$     | Clock Enable Input. Drive low to enable the serial data interface.                                                                                                                                                                                                                                        |
| 33                                                             | MODE                       | Serial Interface Mode Select Input. Drive high for Complete Matrix Mode (Mode 1) or drive low for Individual Output Address Mode (Mode 0).                                                                                                                                                                |
| 34                                                             | $\overline{\text{RESET}}$  | Asynchronous Reset Input/Output. Drive $\overline{\text{RESET}}$ low to initiate hardware reset. All matrix settings are set to power up defaults and all analog outputs are disabled. Additional power-on-reset delay may be set by connecting a small capacitor from $\overline{\text{RESET}}$ to DGND. |
| 35                                                             | $\overline{\text{UPDATE}}$ | Update Input. Drive $\overline{\text{UPDATE}}$ low to transfer data from mode registers to the switch matrix.                                                                                                                                                                                             |
| 36                                                             | DIN                        | Serial-Data Input. Data is clocked in on the falling edge of SCLK.                                                                                                                                                                                                                                        |
| 37                                                             | V <sub>DD</sub>            | Digital Logic Supply. Bypass V <sub>DD</sub> with a 0.1μF capacitor to DGND.                                                                                                                                                                                                                              |
| 48, 50, 52, 54, 56, 58, 60, 62, 64, 66, 68, 70, 72, 74, 78, 80 | OUT15–OUT0                 | Buffered Analog Outputs. Gain is individually programmable for A <sub>v</sub> = +1V/V or A <sub>v</sub> = +2V/V through the serial interface. Outputs may be individually disabled (high impedance). On power-up, or assertion of $\overline{\text{RESET}}$ , all outputs are disabled.                   |
| 49, 53, 57, 61, 65, 69, 73, 79, 98                             | V <sub>EE</sub>            | Negative Analog Supply. Bypass each pin with a 0.1μF capacitor to AGND. Connect a single 10μF capacitor from one V <sub>EE</sub> pin to AGND.                                                                                                                                                             |
| 90, 92, 94, 96                                                 | IN0–IN3                    | Buffered Analog Inputs                                                                                                                                                                                                                                                                                    |

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## Functional Diagram

MAX9675



## Detailed Description

The MAX9675 is a highly integrated  $16 \times 16$  nonblocking video crosspoint switch matrix. All inputs and outputs are buffered, with all outputs able to drive standard  $75\Omega$  reverse-terminated video loads.

A 3-wire interface programs the switch matrix and initializes with a single update signal. The unique serial interface operates in one of two modes: Complete Matrix Mode (Mode 1) or Individual Output Address Mode (Mode 0).

In the *Functional Diagram*, the signal path of the MAX9675 is from the inputs (IN0–IN15), through the switching matrix, buffered by the output amplifiers, and presented at the output terminals (OUT0–OUT15). The other functional blocks are the serial interface and control logic. Each of the functional blocks is described in detail below.

### Analog Outputs

The MAX9675 outputs are high-speed voltage feedback amplifiers capable of driving  $150\Omega$  ( $75\Omega$  back-terminated) loads. The gain,  $A_v = +1V/V$  or  $+2V/V$ , is selectable through programming bit 4 of the serial control word.

Amplifier compensation is automatically optimized to maximize the bandwidth for each gain selection. Each output can be individually enabled and disabled through bit 5 of the serial control word. When disabled, the output is high impedance, presenting typically a  $4k\Omega$  load, and  $3pF$  output capacitance, allowing multiple outputs to be connected together in building large arrays. On power-up (or asynchronous  $\overline{RESET}$ ), all outputs are initialized in the disabled state to avoid output conflicts in large-array configurations. The programming and operation of the MAX9675 is output referred. Outputs are configured individually to connect to any one of the 16 analog inputs, programmed to the desired gain ( $A_v = +1V/V$  or  $+2V/V$ ), or disabled in a high-impedance state.

### Analog Inputs

The MAX9675 offers 16 analog input channels. Each input is buffered before the crosspoint switch matrix, allowing one input to cross-connect to up to 16 outputs. The input buffers are voltage feedback amplifiers with high-input impedance and low-input bias current. This allows the use of very simple input clamp circuits.

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

Table 1. Operation Truth Table

| $\overline{\text{CE}}$ | $\overline{\text{UPDATE}}$ | SCLK | DIN            | DOUT              | MODE | $\overline{\text{AOUT}}$ | $\overline{\text{RESET}}$ | OPERATION/COMMENTS                                                                                                                                                                                                                                                                                                          |
|------------------------|----------------------------|------|----------------|-------------------|------|--------------------------|---------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1                      | X                          | X    | X              | X                 | X    | X                        | 1                         | No change in logic.                                                                                                                                                                                                                                                                                                         |
| 0                      | 1                          | ↓    | D <sub>i</sub> | D <sub>i-96</sub> | 1    | 1                        | 1                         | Data at DIN is clocked on the negative edge of the SCLK into the 96-bit Complete Matrix Mode register. DOUT supplies original data in 96 SCLK pulses later.                                                                                                                                                                 |
| 0                      | 0                          | X    | X              | X                 | 1    | 1                        | 1                         | Data in the serial 96-bit Complete Matrix Mode register is transferred into parallel latches that control the switching matrix.                                                                                                                                                                                             |
| 0                      | 1                          | ↓    | D <sub>i</sub> | D <sub>i</sub>    | 0    | 1                        | 1                         | Data at DIN is routed to the Individual Output Address Mode shift register. DIN is also connected directly to DOUT so that all devices on the serial bus may be addressed in parallel.                                                                                                                                      |
| 0                      | 0                          | X    | D <sub>i</sub> | D <sub>i</sub>    | 0    | 0                        | 1                         | The 4-bit chip address A <sub>3</sub> to A <sub>0</sub> is compared to D <sub>13</sub> to D <sub>10</sub> . If equal, the remaining 10 bits in the Individual Output Address Mode register are decoded, allowing reprogramming for a single output. $\overline{\text{AOUT}}$ signals a successful individual matrix update. |
| X                      | X                          | X    | X              | X                 | X    | X                        | 0                         | Asynchronous reset. All outputs are disabled. Other logic remains unchanged.                                                                                                                                                                                                                                                |

## Switch Matrix

The MAX9675 has 256 individual T-switches making a 16 x 16 switch matrix. The switching matrix is 100% nonblocking, which means that any input may be routed to any output. The switch matrix programming is output referred. Each output may be connected to any one of the 16 analog inputs. Any one input can be routed to all 16 outputs with no signal degradation.

## Digital Interface

The digital interface consists of the following pins: DIN, DOUT, SCLK, AOUT, UPDATE, CE, A3–A0, MODE, and RESET. DIN is the serial-data input; DOUT is the serial-data output. SCLK is the serial-data clock that clocks data into the Data Input registers (Figure 2). Data at DIN is loaded at each falling edge of SCLK. DOUT is the data shifted out of the 96-bit Complete Matrix Mode (Mode = 1). DIN passes directly to DOUT when in Individual Output Address Mode (Mode = 0).

The falling edge of  $\overline{\text{UPDATE}}$  latches the data and programs the matrix. When using Individual Output Address Mode, the address recognition output  $\overline{\text{AOUT}}$  drives low when control word bits D<sub>13</sub> to D<sub>10</sub> match the address programming inputs (A3–A0) and  $\overline{\text{UPDATE}}$  is low. Table 1 is the operation truth table.

## Programming the Matrix

The MAX9675 offers two programming modes: Individual Output Address Mode and Complete Matrix Mode. These two distinct programming modes are selected by toggling a single MODE pin high or low. Both modes operate with the same physical board layout. This flexibility allows initial programming of the IC by daisy-chaining and sending one long data word while still being able to address immediately and update individual outputs in the matrix.

### Individual Output Address Mode (MODE = 0)

Drive MODE to logic-low to select mode 0. Individual outputs are programmed through the serial interface

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

**Table 2. 16-Bit Serial Control Word Bit Assignments (Mode 0: Individual Output Address Mode)**

| BIT      | NAME              | FUNCTION                                                            |
|----------|-------------------|---------------------------------------------------------------------|
| 0 (LSB)  | Input Address 0   | LSB of input channel select address                                 |
| 1        | Input Address 1   |                                                                     |
| 2        | Input Address 2   |                                                                     |
| 3        | Input Address 3   | MSB of input channel select address                                 |
| 4        | Gain Set          | Gain Select for output buffer, 0 = gain of +1V/V, 1 = gain of +2V/V |
| 5        | Output Enable     | Enable bit for output, 0 = disable, 1 = enable                      |
| 6        | Output Address B0 | LSB of output buffer address                                        |
| 7        | Output Address B1 |                                                                     |
| 8        | Output Address B2 |                                                                     |
| 9        | Output Address B3 | MSB of output buffer address                                        |
| 10       | IC Address A0     | LSB of selected chip address                                        |
| 11       | IC Address A1     |                                                                     |
| 12       | IC Address A2     |                                                                     |
| 13       | IC Address A3     | MSB of selected chip address                                        |
| 14       | X                 | Don't care                                                          |
| 15 (MSB) | X                 | Don't care                                                          |

with a single 16-bit control word. The control word consists of two don't care MSBs, the chip address bits, output address bits, an output enable/disable bit, an output gain-set bit, and input address bits (Tables 2 through 6, and Figure 2).

In mode 0, data at DIN passes directly to DOUT through the data routing gate (Figure 3). In this configuration, the 16-bit control word is simultaneously sent to all chips in an array of up to 16 addresses.

## **Complete Matrix Mode (MODE = 1)**

Drive MODE to logic-high to select mode 1. A single 96-bit control word consisting of sixteen 6-bit control words programs all outputs. The 96-bit control word's

**Table 3. Chip Address Programming for 16-Bit Control Word (Mode 0: Individual Output Address Mode)**

| IC ADDRESS BIT |    |    |          | ADDRESS            |                        |
|----------------|----|----|----------|--------------------|------------------------|
| A3 (MSB)       | A2 | A1 | A0 (LSB) | CHIP ADDRESS (HEX) | CHIP ADDRESS (DECIMAL) |
| 0              | 0  | 0  | 0        | 0h                 | 0                      |
| 0              | 0  | 0  | 1        | 1h                 | 1                      |
| 0              | 0  | 1  | 0        | 2h                 | 2                      |
| 0              | 0  | 1  | 1        | 3h                 | 3                      |
| 0              | 1  | 0  | 0        | 4h                 | 4                      |
| 0              | 1  | 0  | 1        | 5h                 | 5                      |
| 0              | 1  | 1  | 0        | 6h                 | 6                      |
| 0              | 1  | 1  | 1        | 7h                 | 7                      |
| 1              | 0  | 0  | 0        | 8h                 | 8                      |
| 1              | 0  | 0  | 1        | 9h                 | 9                      |
| 1              | 0  | 1  | 0        | Ah                 | 10                     |
| 1              | 0  | 1  | 1        | Bh                 | 11                     |
| 1              | 1  | 0  | 0        | Ch                 | 12                     |
| 1              | 1  | 0  | 1        | Dh                 | 13                     |
| 1              | 1  | 1  | 0        | Eh                 | 14                     |
| 1              | 1  | 1  | 1        | Fh                 | 15                     |

first 6-bit control word (MSBs) programs output 15, and the last 6-bit control word (LSBs) programs output 0 (Table 7 and Figures 4 and 5). Data clocked into the 96-bit Complete Matrix Mode register is latched on the falling edge of UPDATE, and the outputs are immediately updated.

## **Initialization String**

The Complete Matrix Mode (Mode = 1) is convenient to use to program the matrix at power-up. In a large matrix consisting of many MAX9675 devices, all the devices can be programmed by sending a single bit stream equal to  $n \times 96$  bits, where  $n$  is the number of MAX9675 devices on the bus. The first 96-bit data word programs the last MAX9675 in line (see the *Matrix Programming* section).

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

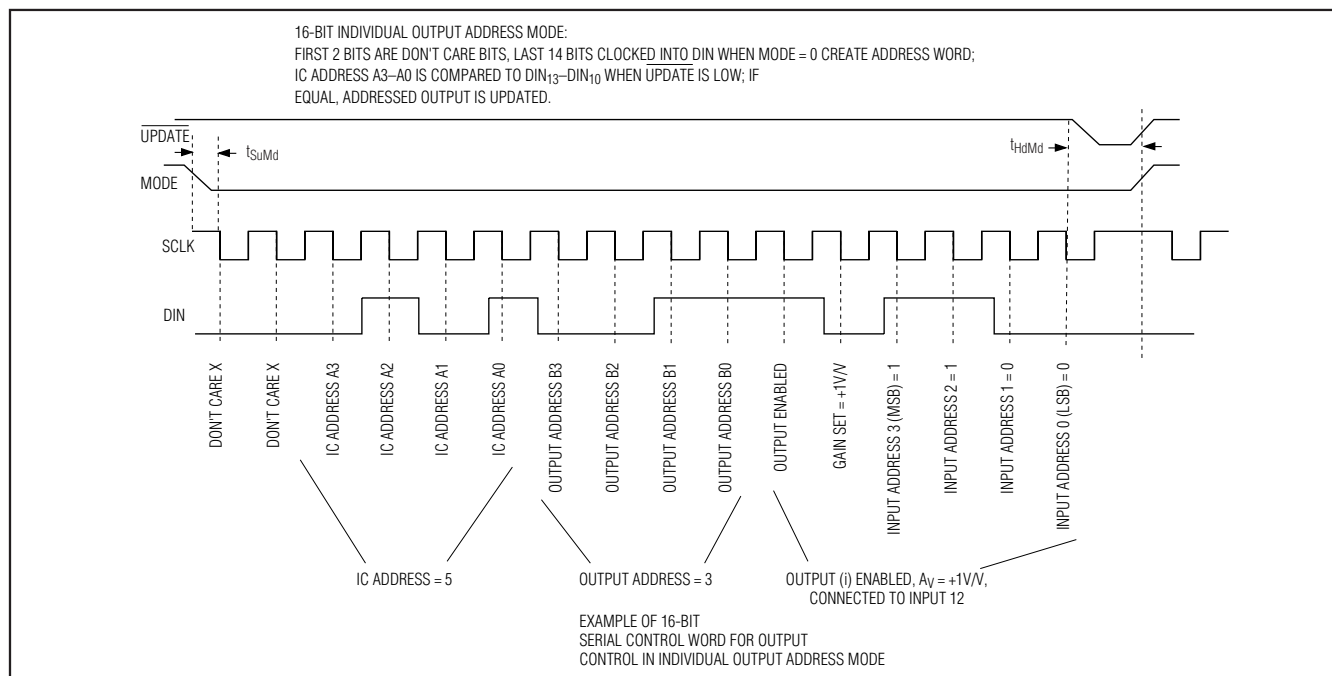


Figure 2. Mode 0: Individual Output Address Mode Timing and Programming Example

Table 4. Chip Address A3–A0 Pin Programming

| PIN             |                 |                 |                 | ADDRESS            |                        |
|-----------------|-----------------|-----------------|-----------------|--------------------|------------------------|
| A3              | A2              | A1              | A0              | CHIP ADDRESS (HEX) | CHIP ADDRESS (DECIMAL) |
| DGND            | DGND            | DGND            | DGND            | 0h                 | 0                      |
| DGND            | DGND            | DGND            | V <sub>DD</sub> | 1h                 | 1                      |
| DGND            | DGND            | V <sub>DD</sub> | DGND            | 2h                 | 2                      |
| DGND            | DGND            | V <sub>DD</sub> | V <sub>DD</sub> | 3h                 | 3                      |
| DGND            | V <sub>DD</sub> | DGND            | DGND            | 4h                 | 4                      |
| DGND            | V <sub>DD</sub> | DGND            | V <sub>DD</sub> | 5h                 | 5                      |
| DGND            | V <sub>DD</sub> | V <sub>DD</sub> | DGND            | 6h                 | 6                      |
| DGND            | V <sub>DD</sub> | V <sub>DD</sub> | V <sub>DD</sub> | 7h                 | 7                      |
| V <sub>DD</sub> | DGND            | DGND            | DGND            | 8h                 | 8                      |
| V <sub>DD</sub> | DGND            | DGND            | V <sub>DD</sub> | 9h                 | 9                      |
| V <sub>DD</sub> | DGND            | V <sub>DD</sub> | DGND            | Ah                 | 10                     |
| V <sub>DD</sub> | DGND            | V <sub>DD</sub> | V <sub>DD</sub> | Bh                 | 11                     |
| V <sub>DD</sub> | V <sub>DD</sub> | DGND            | DGND            | Ch                 | 12                     |
| V <sub>DD</sub> | V <sub>DD</sub> | DGND            | V <sub>DD</sub> | Dh                 | 13                     |
| V <sub>DD</sub> | V <sub>DD</sub> | V <sub>DD</sub> | DGND            | Eh                 | 14                     |
| V <sub>DD</sub> | V <sub>DD</sub> | V <sub>DD</sub> | V <sub>DD</sub> | Fh                 | 15                     |

Table 5. Output Selection Programming

| OUTPUT ADDRESS BIT |    |    |          | SELECTED OUTPUT |
|--------------------|----|----|----------|-----------------|
| B3 (MSB)           | B2 | B1 | B0 (LSB) |                 |
| 0                  | 0  | 0  | 0        | 0               |
| 0                  | 0  | 0  | 1        | 1               |
| 0                  | 0  | 1  | 0        | 2               |
| 0                  | 0  | 1  | 1        | 3               |
| 0                  | 1  | 0  | 0        | 4               |
| 0                  | 1  | 0  | 1        | 5               |
| 0                  | 1  | 1  | 0        | 6               |
| 0                  | 1  | 1  | 1        | 7               |
| 1                  | 0  | 0  | 0        | 8               |
| 1                  | 0  | 0  | 1        | 9               |
| 1                  | 0  | 1  | 0        | 10              |
| 1                  | 0  | 1  | 1        | 11              |
| 1                  | 1  | 0  | 0        | 12              |
| 1                  | 1  | 0  | 1        | 13              |
| 1                  | 1  | 1  | 0        | 14              |
| 1                  | 1  | 1  | 1        | 15              |

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

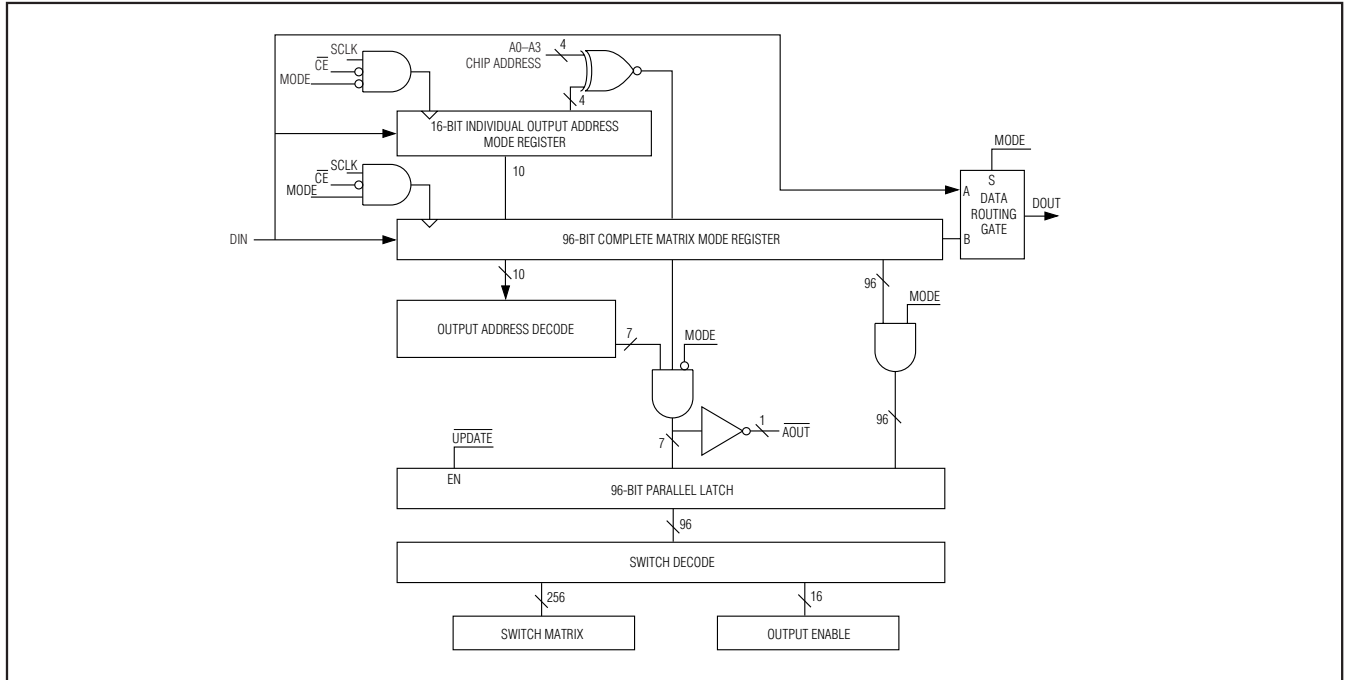


Figure 3. Serial Interface Block Diagram

Table 6. Input Selection Programming

| INPUT ADDRESS BIT |    |    |          | SELECTED INPUT |
|-------------------|----|----|----------|----------------|
| B3 (MSB)          | B2 | B1 | B0 (LSB) |                |
| 0                 | 0  | 0  | 0        | 0              |
| 0                 | 0  | 0  | 1        | 1              |
| 0                 | 0  | 1  | 0        | 2              |
| 0                 | 0  | 1  | 1        | 3              |
| 0                 | 1  | 0  | 0        | 4              |
| 0                 | 1  | 0  | 1        | 5              |
| 0                 | 1  | 1  | 0        | 6              |
| 0                 | 1  | 1  | 1        | 7              |
| 1                 | 0  | 0  | 0        | 8              |
| 1                 | 0  | 0  | 1        | 9              |
| 1                 | 0  | 1  | 0        | 10             |
| 1                 | 0  | 1  | 1        | 11             |
| 1                 | 1  | 0  | 0        | 12             |
| 1                 | 1  | 0  | 1        | 13             |
| 1                 | 1  | 1  | 0        | 14             |
| 1                 | 1  | 1  | 1        | 15             |

Table 7. 6-Bit Serial Control Word Bit Assignments (Mode 1: Complete Matrix Mode)

| BIT     | NAME            | FUNCTION                                                            |
|---------|-----------------|---------------------------------------------------------------------|
| 5 (MSB) | Output Enable   | Enable bit for output, 0 = disable, 1 = enable                      |
| 4       | Gain Set        | Gain Select for output buffer, 0 = gain of +1V/V, 1 = gain of +2V/V |
| 3       | Input Address 3 | MSB of input channel select address                                 |
| 2       | Input Address 2 |                                                                     |
| 1       | Input Address 1 |                                                                     |
| 0 (LSB) | Input Address 0 | LSB of input channel select address                                 |

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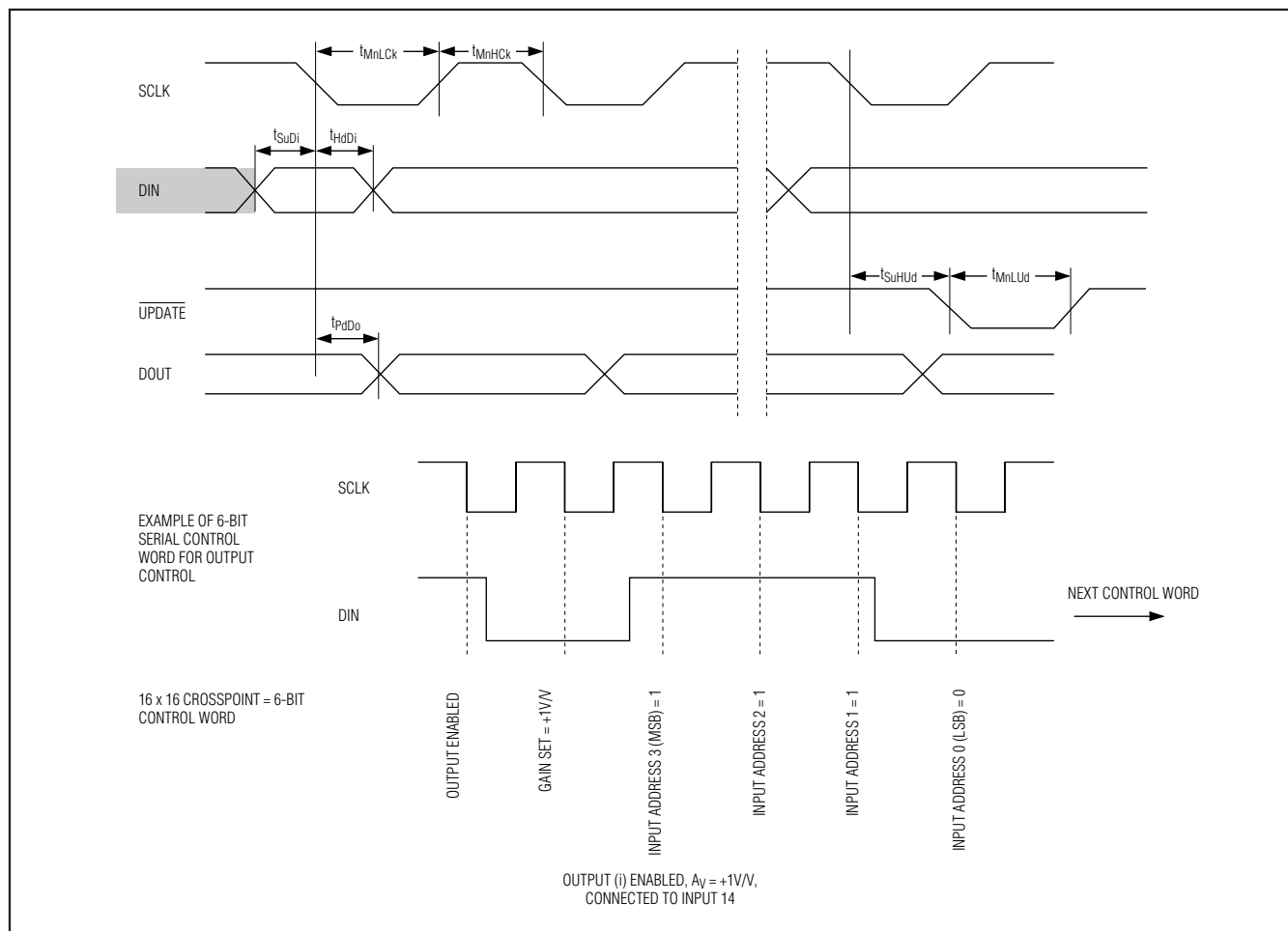


Figure 4. 6-Bit Control Word and Programming Example (Mode 1: Complete Matrix Mode Programming)

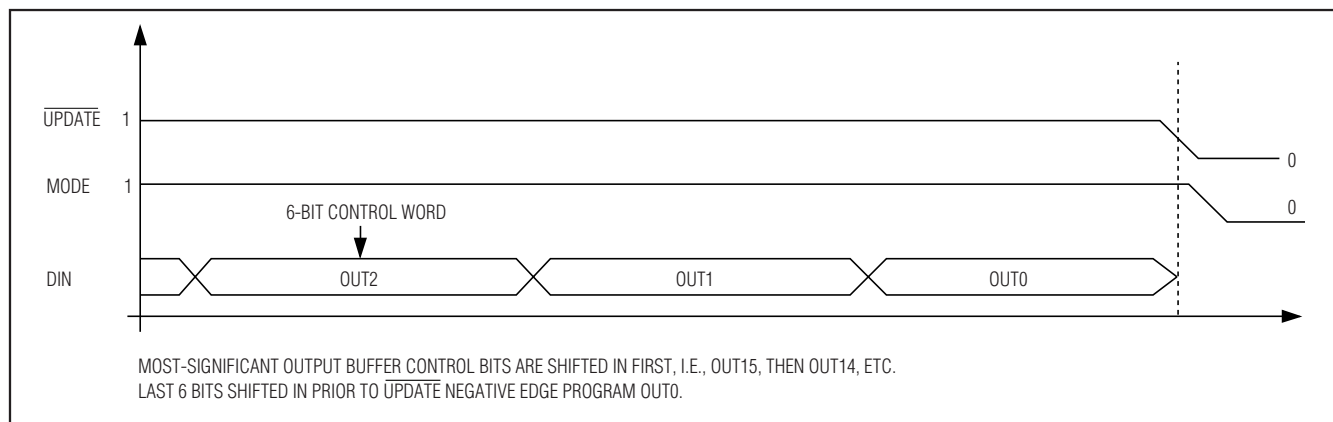


Figure 5. Mode 1: Complete Matrix Mode Programming

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## **RESET**

The MAX9675 features an asynchronous bidirectional **RESET** with an internal 20k $\Omega$  pullup resistor to  $V_{DD}$ . When **RESET** is pulled low, either by internal circuitry, or driven externally, the analog output buffers are latched into a high-impedance state. After **RESET** is released, the output buffers remain disabled. The outputs may be enabled by sending a new 96-bit data word or a 16-bit individual output address word. A reset is initiated from any of three sources. **RESET** can be driven low by external circuitry to initiate a reset, or **RESET** can be pulled low by internal circuitry during power-up (power-on reset) or thermal shutdown.

Since driving **RESET** low only clears the output buffer enable bit in the matrix control latches, **RESET** can be used to disable all outputs simultaneously. If no new data has been loaded into the 96-bit complete matrix mode register, a single **UPDATE** restores the previous matrix control settings.

## **Power-On Reset**

The power-on reset ensures all output buffers are in a disabled state when power is initially applied. A  $V_{DD}$  voltage comparator generates the power-on reset. When the voltage at  $V_{DD}$  is less than 2.5V, the power-on-reset comparator pulls **RESET** low through internal circuitry. As the digital supply voltage ramps up crossing 2.5V, the MAX9675 holds **RESET** low for 40ns (typ). Connecting a small capacitor from **RESET** to DGND extends the power-on-reset delay. See the **RESET Delay vs. RESET Capacitance** graph in the *Typical Operating Characteristics*.

## **Thermal Shutdown**

The MAX9675 features thermal shutdown protection with temperature hysteresis. When the die temperature exceeds +150°C, the MAX9675 pulls **RESET** low, disabling the output buffers. When the die cools by 20°C, the **RESET** pulldown is deasserted, and output buffers remain disabled until the device is programmed again.

## **Applications Information**

### **Building Large Video-Switching Systems**

The MAX9675 can be easily used to create larger switching matrices. The number of ICs required to implement the matrix is a function of the number of input channels, the number of outputs required, and whether the array needs to be nonblocking. The most straightforward technique for implementing nonblocking matrices is to arrange the building blocks in a grid. The inputs connect to each vertical bank of devices in parallel with the other banks. The outputs of each building block in a vertical column connect together in a

wired-OR configuration. Figure 6 shows a 128-input, 32-output, nonblocking array using the MAX9675 16 x 16 crosspoint devices.

The wired-OR connection of the outputs shown in the diagram is possible because the outputs of the IC devices can be placed in a disabled or high-impedance output state. This disable state of the output buffers is designed for a maximum impedance vs. frequency while maintaining a low-output capacitance. These characteristics minimize the adverse loading effects from the disabled outputs. Larger arrays are constructed by extending this connection technique to more devices.

### **Driving a Capacitive Load**

Figure 6 shows an implementation requiring many outputs to be wired together. This creates a situation where each output buffer sees not only the normal load impedance, but also the disabled impedance of all the other outputs. This impedance has a resistive and a capacitive component. The resistive components reduce the total effective load for the driving output. Total capacitance is the sum of the capacitance of all the disabled outputs and is a function of the size of the matrix. Also, as the size of the matrix increases, the length of the PCB traces increases, adding more capacitance. The output buffers have been designed to drive more than 30pF of capacitance while still maintaining a good AC response. Depending on the size of the array, the capacitance seen by the output can exceed this amount. There are several ways to improve the situation. The first is to use more building-block crosspoint devices to reduce the number of outputs that need to be wired together (Figure 7).

In Figure 7, the additional devices are placed in a second bank to multiplex the signals. This reduces the number of wired-OR connections. Another solution is to put a small resistor in series with the output before the capacitive load to limit excessive ringing and oscillations. Figure 8 shows the graph of the Optimal Isolation Resistor vs. Capacitive Load. A lowpass filter is created from the series resistor and parasitic capacitance to ground. A single R-C does not affect the performance at video frequencies, but in a very large system there may be many R-Cs cascaded in series. The cumulative effect is a slight rolling off of the high frequencies causing a "softening" of the picture. There are two solutions to achieve higher performance. One way is to design the PCB traces associated with the outputs such that they exhibit some inductance. By routing the traces in a repeating "S" configuration, the traces that are nearest each other exhibit a mutual inductance increasing the total inductance. This series inductance causes the

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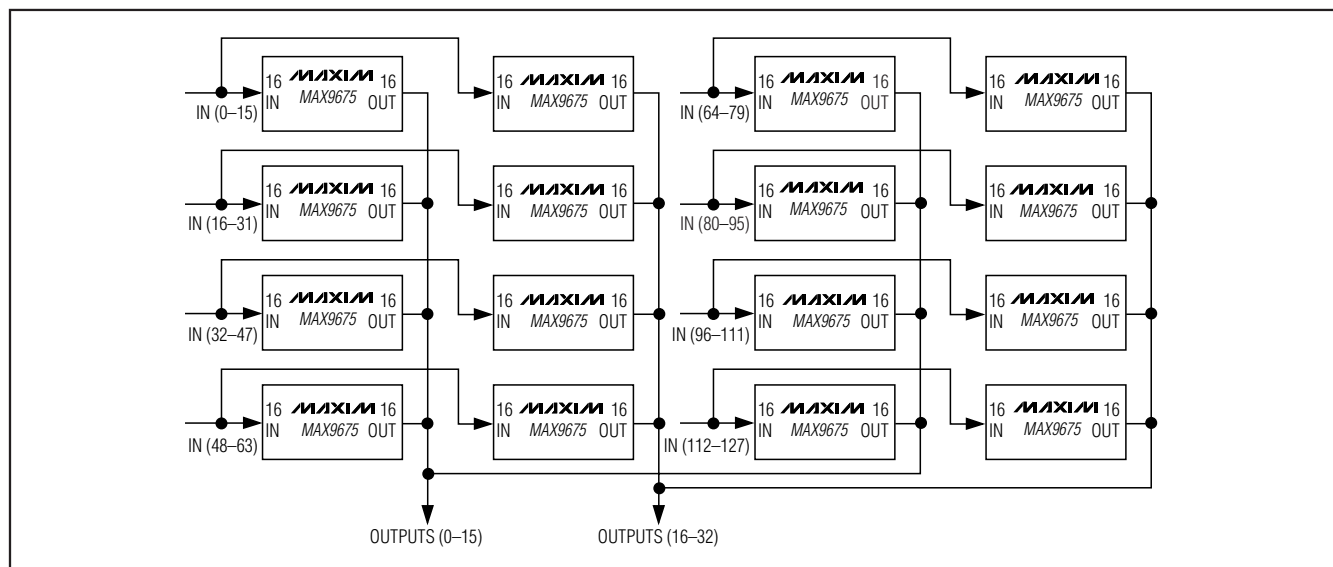


Figure 6. 128 x 32 Nonblocking Matrix Using 16 x 16 Crosspoint Devices

amplitude response to increase or peak at higher frequencies, offsetting the rolloff from the parasitic capacitance. Another solution is to add a small-value inductor to the output.

## Crosstalk Signal and Board Routing Issues

Improper signal routing causes performance problems such as crosstalk. The MAX9675 has a typical crosstalk rejection of -62dB at 6MHz. A bad PCB layout degrades the crosstalk rejection by 20dB or more. To achieve the best crosstalk performance:

- 1) **Place ground isolation between long critical signal PCB trace runs.** These traces act as a shield to potential interfering signals. Crosstalk can be degraded by parallel traces as well as directly above and below on adjoining PCB layers.
- 2) **Maintain controlled-impedance traces.** Design as many of the PCB traces as possible to be 75Ω transmission lines. This lowers the impedance of the traces, reducing a potential source of crosstalk. More power is dissipated due to the output buffer driving a lower impedance.
- 3) **Minimize ground-current interaction by using a good ground plane strategy.**

In addition to crosstalk, another key issue of concern is isolation. Isolation is the rejection of undesirable feed-through from input to output with the output disabled. The MAX9675 achieves a -110dB isolation at 6MHz by selecting the pinout configuration such that the inputs and outputs are on opposite sides of the package.

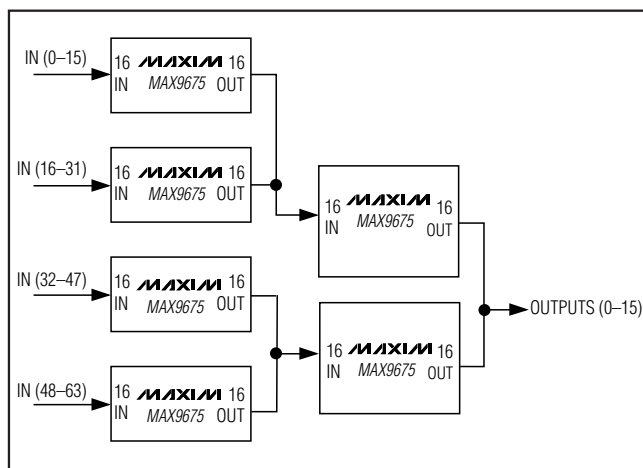


Figure 7. 64 x 16 Nonblocking Matrix with Reduced Capacitive Loading

Coupling through the power supply is a function of the quality and location of the supply bypassing. Use appropriate low-impedance components and locate them as close as possible to the IC. Avoid routing the inputs near the outputs.

## Power-Supply Bypassing

The MAX9675 operates from a  $\pm 5V$  supply. For dual-supply operation, bypass all supply pins to ground with 0.1μF capacitors.

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## Driving a PCB Interconnect or a Cable ( $A_V = +1V/V$ or $+2V/V$ )

The MAX9675 output buffers can be programmed to either  $A_V = +1V/V$  or  $+2V/V$ . The  $+1V/V$  configuration is typically used when driving a short-length (less than 3cm), high-impedance “local” PCB trace. To drive a cable or a  $75\Omega$  transmission line trace, program the gain of the output buffer to  $+2V/V$  and place a  $75\Omega$  resistor in series with the output. The series termination resistor and the  $75\Omega$  load impedance act as a voltage-divider that divides the video signal in half. Set the gain to  $+2V/V$  to transmit a standard 1V video signal down a cable. The series  $75\Omega$  resistor is called the back-match, reverse termination, or series termination. This  $75\Omega$  resistor reduces reflections, and provides isolation, increasing the output-capacitive-driving capability.

## Matrix Programming

The MAX9675's unique digital interface simplifies programming multiple MAX9675 devices in an array. Multiple devices are connected with DOUT of the first device connecting to DIN of the second device, and so on (Figure 9). Two distinct programming modes, individual output address mode (MODE = 0) and complete matrix mode (MODE = 1), are selected by toggling a single MODE control pin high or low. Both modes operate with the same physical board layout. This allows initial programming of the IC by daisy-chaining and sending one long data word while still being able to address immediately and update individual locations in the matrix.

### Individual Output Address Mode (Mode 0)

In Individual Output Address Mode, the devices are connected in a serial bus configuration, with the data routing gate (Figure 3) connecting DIN to DOUT, making each device a virtual node on the serial bus. A single 16-bit control word is sent to all devices simultaneously. Only the device with the corresponding chip address responds to the programming word, and updates its output. In this mode, the chip address is set through hardware pin strapping of A3–A0. The host then communicates with the device by sending a 16-bit word consisting of 2 don't care MSB bits, 4 chip address bits, and 10 bits of data to make the word

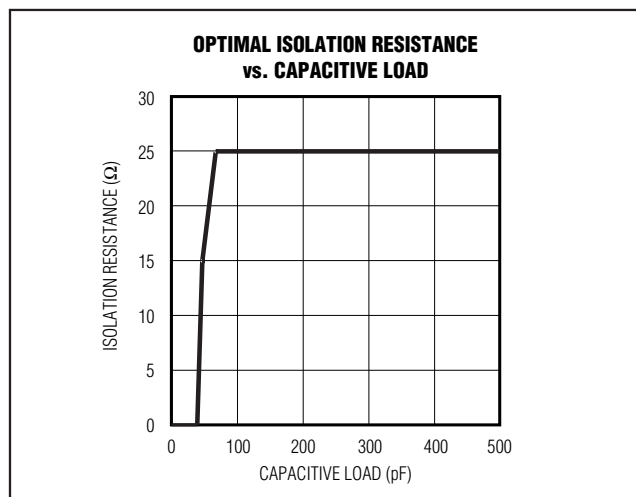


Figure 8. Optimal Isolation Resistor vs. Capacitive Load

exactly 2 bytes in length. The 10 data bits are broken down into 4 bits to select the output to be programmed; 1 bit to set the output enable; 1 bit to set gain; and 4 bits to select the input to be connected to that output. In this method, the matrix is programmed one output at a time.

### Complete Matrix Mode (Mode 1)

In Complete Matrix Mode, the devices are connected in a daisy-chain fashion where  $n \times 96$  bits are sent to program the entire matrix, and where  $n$  = the number of MAX9675 devices connected in series. This long data word is structured such that the first bit is the LSB of the last device in the chain and the last data bit is the MSB of the first device in the chain. The total length of the data word is equal to the number of crosspoint devices to be programmed in series times 96 bits per crosspoint device. This programming method is most often used at startup to initially configure the switching matrix.

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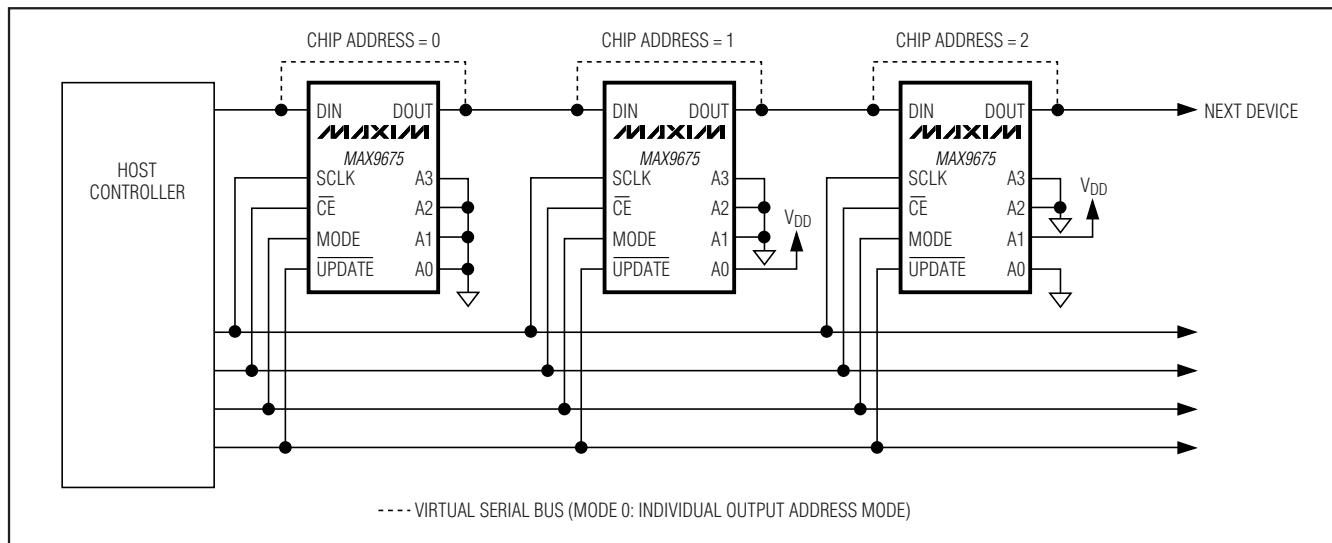


Figure 9. Matrix Mode Programming

## Chip Information

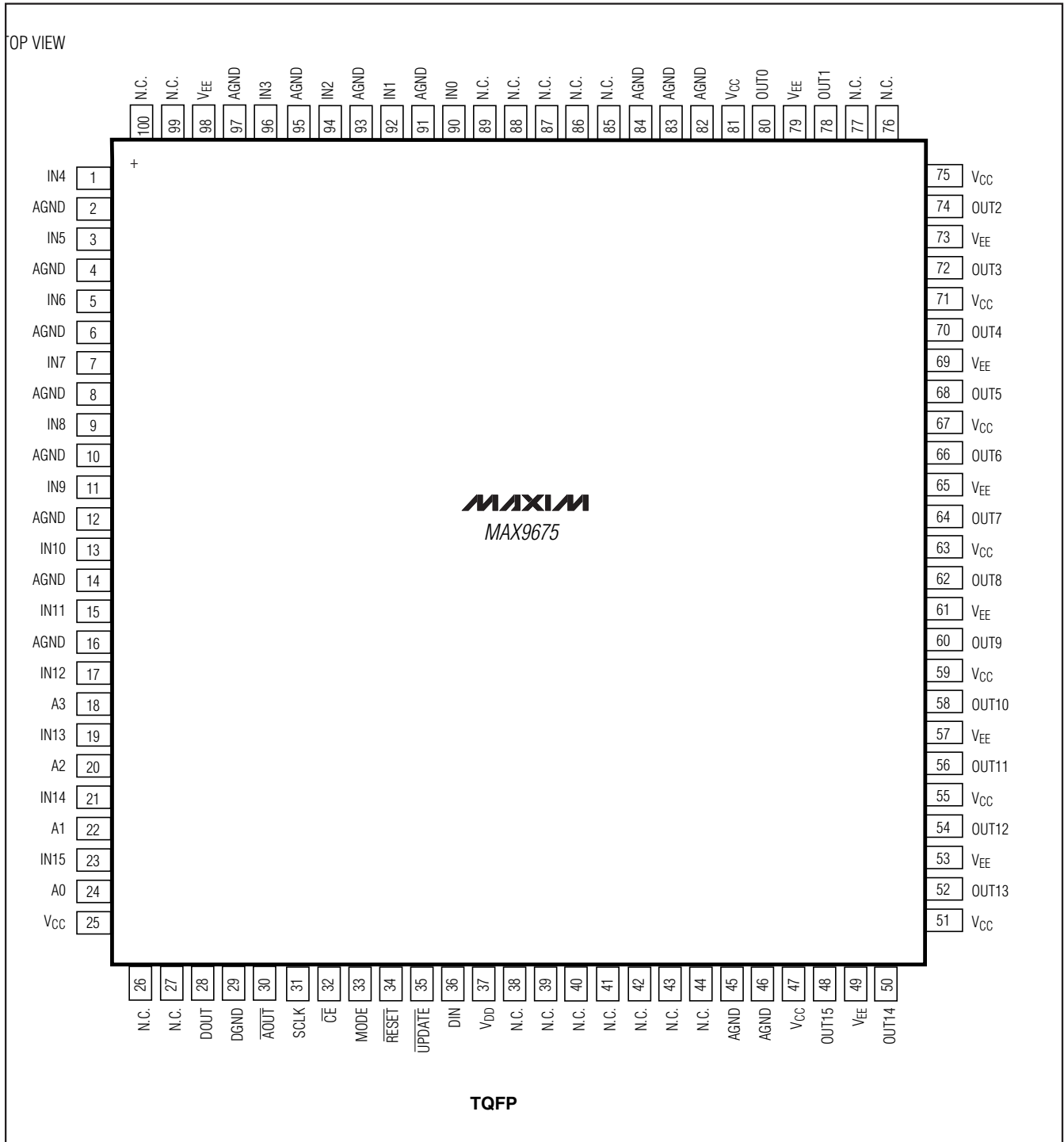
TRANSISTOR COUNT: 24,467

PROCESS: BiCMOS

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## Pin Configuration

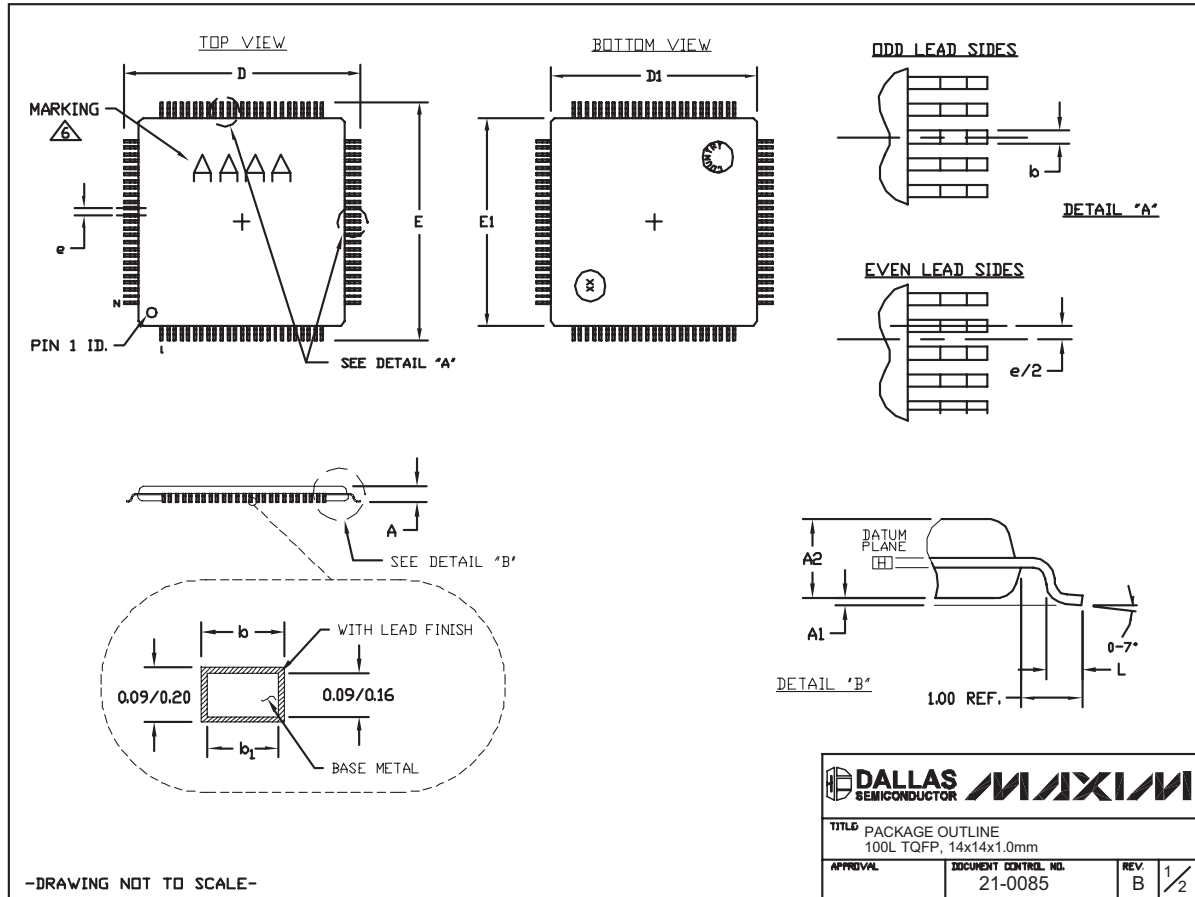
**MAX9675**



# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## Package Information

For the latest package outline information and land patterns, go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).



100L TQFP.EPS

# 110MHz, 16 x 16 Video Crosspoint Switch with Programmable Gain

## Package Information (continued)

For the latest package outline information and land patterns, go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).

MAX9675

### NOTES:

1. ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5-1982.
2. DATUM PLANE (B) LOCATED AT MOLD PARTING LINE AND COINCIDENT WITH LEAD, WHERE LEAD EXITS PLASTIC BODY AT BOTTOM OF PARTING LINE.
3. DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE MOLD PROTRUSION IS 0.254 MM ON D1 AND E1 DIMENSIONS.
4. THE TOP OF PACKAGE IS SMALLER THAN THE BOTTOM OF PACKAGE BY 0.15 MILLIMETERS.
5. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08mm TOTAL IN EXCESS OF THE b DIMENSION AT MAXIMUM MATERIAL CONDITION.
6. MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.
7. THIS OUTLINE CONFORMS TO JEDEC PUBLICATION 95 REGISTRATION MS-026.
8. LEADS SHALL BE COPLANAR WITHIN 0.08mm.

| SYMBOL | TQFP PACKAGE VARIATION        |       |
|--------|-------------------------------|-------|
|        | ALL DIMENSIONS IN MILLIMETERS |       |
|        | 100L, 14x14x1.0               |       |
|        | MIN.                          | MAX.  |
| A      | ~                             | 1.20  |
| A1     | 0.05                          | 0.15  |
| A2     | 0.95                          | 1.05  |
| D      | 15.80                         | 16.20 |
| D1     | 13.80                         | 14.20 |
| E      | 15.80                         | 16.20 |
| E1     | 13.80                         | 14.20 |
| L      | 0.45                          | 0.75  |
| N      | 100                           |       |
| e      | 0.50 BSC.                     |       |
| b      | 0.17                          | 0.27  |
| bl     | 0.17                          | 0.23  |

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| <b>TITLE</b> PACKAGE OUTLINE,<br>100L TQFP, 14x14x1.0mm                               |                                        |
| <b>APPROVAL</b>                                                                       | <b>DOCUMENT CONTROL NO.</b><br>21-0085 |
| <b>REV.</b><br>B                                                                      | <b>2/2</b>                             |

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