

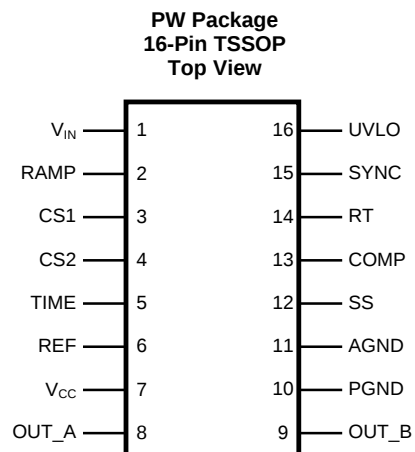
Table of Contents

1 Features	1	7.3 Feature Description	12
2 Applications	1	7.4 Device Functional Modes	17
3 Description	1	8 Application and Implementation	18
4 Revision History	2	8.1 Application Information	18
5 Pin Configuration and Functions	3	8.2 Typical Application	18
6 Specifications	5	8.3 System Examples	23
6.1 Absolute Maximum Ratings	5	9 Power Supply Recommendations	24
6.2 ESD Ratings	5	10 Layout	24
6.3 Recommended Operating Conditions	5	10.1 Layout Guidelines	24
6.4 Thermal Information	5	10.2 Layout Example	24
6.5 Electrical Characteristics	6	11 Device and Documentation Support	25
6.6 Typical Performance Characteristics	8	11.1 Trademarks	25
7 Detailed Description	10	11.2 Electrostatic Discharge Caution	25
7.1 Overview	10	11.3 Glossary	25
7.2 Functional Block Diagram	11	12 Mechanical, Packaging, and Orderable Information	26

4 Revision History

DATE	REVISION	NOTES
June, 2015	*	Initial release.

5 Pin Configuration and Functions



Pin Functions

PIN		I/O ⁽¹⁾	DESCRIPTION
NAME	NO.		
AGND	11	G	Analog ground. Connect directly to power ground. For the PW package option the exposed pad is electrically connected to AGND.
COMP	13	I	Input to the pulse width modulator. An internal 5-kΩ resistor pull-up is provided on this pin. The external opto-coupler sinks current from COMP to control the PWM duty cycle.
CS1	3	I	Current sense input for cycle-by-cycle limiting. If CS1 exceeds 0.5 V the outputs will go into cycle-by-cycle current limit. CS1 is held low for 50 ns after OUT_A switches high providing leading edge blanking.
CS2	4	I	Current sense input for soft restart. If CS2 exceeds 0.5 V the outputs will be disabled and a softstart commenced. The soft-start capacitor will be fully discharged and then released with a pull-up current of 1 μA. After the first output pulse (when SS = 1 V), the SS charge current will revert back to 20 μA.
EP	-	-	Exposed pad, underside of the PW package option. Internally bonded to the die substrate. Connect to GND potential for low thermal impedance.
OUT_A	8	O	Main output driver. Output of the main switch PWM output gate driver. Output capability of 3-A peak sink current.
OUT_B	9	O	Active Clamp output driver. Output of the active clamp switch gate driver. Capable of 1.25-A peak sink current.
PGND	10	G	Power ground. Connect directly to analog ground.
RAMP	2	I	Modulator ramp signal. An external RC circuit from V _{IN} sets the ramp slope. This pin is discharged at the conclusion of every cycle by an internal FET, initiated by either the internal clock or the V x Sec clamp comparator.
REF	6	O	Precision 5-V reference output. Maximum output current: 10 mA locally decouple with a 0.1-μF capacitor. Reference stays low until the V _{CC} UV comparator is satisfied.
RT	14	I	Oscillator timing resistor pin. An external resistor connected from RT to ground sets the internal oscillator frequency.
SS	12	I	Soft-start control. An external capacitor and an internal 20-μA current source set the softstart ramp. The SS current source is reduced to 1 μA initially following a CS2 over-current event or an over temperature event.
SYNC	15	I	Oscillator UP/DOWN synchronization input. The internal oscillator can be synchronized to an external clock with a frequency 20% lower than the internal oscillator's free running frequency. There is no constraint on the maximum sync frequency.
TIME	5	I	Output overlap/deadtime control. An external resistor (R _{SET}) sets either the overlap time or dead time for the active clamp output. An R _{SET} resistor connected between TIME and GND produces in-phase OUT_A and OUT_B pulses with overlap. An R _{SET} resistor connected between TIME and REF produces out-of-phase OUT_A and OUT_B pulses with deadtime.
UVLO	16	I	Line Under-Voltage shutdown. An external voltage divider from the power source sets the shutdown comparator levels. The comparator threshold is 2.5 V. Hysteresis is set by an internal current source (20 μA) that is switched on or off as the UVLO pin potential crosses the 2.5 V threshold.
VCC	7	P	Output from the internal high voltage start-up regulator. The V _{CC} voltage is regulated to 7.6 V. If an auxiliary winding raises the voltage on this pin above the regulation setpoint, the internal start-up regulator will shutdown, reducing the device power dissipation.
VIN	1	I	Source input voltage. Input to start-up regulator. Input range 13 V to 90 V, with transient capability to 105 V.

(1) P = Power, G = Ground, I = Input, O = Output, I/O = Input/Output

6 Specifications

6.1 Absolute Maximum Ratings⁽¹⁾

over operating free-air temperature range (unless otherwise noted)⁽²⁾

		MIN	MAX	UNIT
V _{IN} to GND		–0.3	105	V
V _{CC} to GND		–0.3	16	V
CS1, CS2 to GND		–0.3	7	V
All other inputs to GND		–0.3	7	V
Junction Temperature			150	°C
Storage temperature, T _{stg}		–55	150	°C

- (1) If Military/Aerospace specified devices are required, please contact the TI Sales Office/ Distributors for availability and specifications.
(2) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD) Electrostatic discharge ⁽¹⁾	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽²⁾	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽³⁾	±500	

- (1) For detailed information on soldering plastic TSSOP package, refer to the Packaging Data Book.
(2) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible with the necessary precautions. Pins listed as ±2000 V may actually have higher performance.
(3) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM	MAX	UNIT
V _{IN} Input Voltage	13		90	V
External Voltage Applied to V _{CC}	8		15	V
Operating Junction Temperature	–40		125	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TSSOP 16 PINS	UNIT
R _{θJA}	Junction-to-ambient thermal resistance	95.9	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	27.0	
R _{θJB}	Junction-to-board thermal resistance	41.0	
Ψ _{JT}	Junction-to-top characterization parameter	1.1	
Ψ _{JB}	Junction-to-board characterization parameter	40.4	
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	n/a	

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Electrical Characteristics

Specifications with standard typeface are for $T_J = 25^\circ\text{C}$, and all MIN and MAX values apply over full Operating Junction Temperature range. $V_{IN} = 48\text{V}$, $V_{CC} = 10\text{V}$, $R_T = 31.3\text{k}\Omega$, $R_{SET} = 27.4\text{k}\Omega$ unless otherwise stated ⁽¹⁾

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
STARTUP REGULATOR						
V_{CC} Reg	V_{CC} regulation	No load	7.3	7.6	7.9	V
	V_{CC} current limit	⁽²⁾	20	25		mA
$I-V_{IN}$	Startup regulator leakage (external V_{CC} supply)	$V_{IN} = 100\text{ V}$		165	500	μA
V_{CC} SUPPLY						
	V_{CC} under-voltage lockout voltage (positive going V_{CC})		V_{CC} Reg – 220mV	V_{CC} Reg - 120mV		V
	V_{CC} under-voltage hysteresis		1.0	1.5	2.0	V
	V_{CC} supply current (I_{CC})	$C_{GATE} = 0$			4.2	mA
REFERENCE SUPPLY						
V_{REF}	REF voltage	$I_{REF} = 0\text{ mA}$	4.85	5	5.15	V
	REF voltage regulation	$I_{REF} = 0\text{ mA to }10\text{ mA}$		25	50	mV
	REF current limit		10	20		mA
CURRENT LIMIT						
CS1 Prop	CS1 delay to output	CS1 step from 0 V to 0.6 V, Time to onset of OUT transition (90%), $C_{GATE} = 0$		40		ns
CS2 Prop	CS2 delay to output	CS2 step from 0 V to 0.6 V, Time to onset of OUT transition (90%), $C_{GATE} = 0$		50		ns
	Cycle-by-cycle threshold voltage (CS1)		0.45	0.5	0.55	V
	Cycle skip threshold voltage (CS2)	Resets SS capacitor; auto restart	0.45	0.5	0.55	V
	Leading edge blanking time (CS1)			50		ns
	CS1 sink impedance (clocked)	CS1 = 0.4 V		30	50	Ω
	CS1 sink impedance (post fault discharge)	CS1 = 0.6 V		15	30	Ω
	CS2 sink impedance (post fault discharge)	CS2 = 0.6 V		55	95	Ω
	CS1 and CS2 leakage current	CS = CS threshold – 100 mV			1	μA
SOFT-START						
	Soft-start current source normal		17	22	27	μA
	Soft-start current source following a CS2 event		0.5	1	1.5	μA
OSCILLATOR						
	Frequency1	$T_A = 25^\circ\text{C}$, $T_J = T_{LOW}$ to T_{HIGH}	180 175	200	220 225	kHz
	Frequency2	$R_T = 10.4\text{ k}\Omega$	510	580	650	kHz
	Sync threshold			2		V
	Min sync pulse width				100	ns
	Sync frequency range		160			kHz

- (1) All electrical characteristics having room temperature limits are tested during production with $T_A = T_J = 25^\circ\text{C}$. All hot and cold limits are specified by correlating the electrical characteristics to process and temperature variations and applying statistical process control.
- (2) Device thermal limitations may limit usable range.

Electrical Characteristics (continued)

Specifications with standard typeface are for $T_J = 25^\circ\text{C}$, and all MIN and MAX values apply over full Operating Junction Temperature range. $V_{IN} = 48\text{V}$, $V_{CC} = 10\text{V}$, $R_T = 31.3\text{k}\Omega$, $R_{SET} = 27.4\text{k}\Omega$ unless otherwise stated ⁽¹⁾

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
PWM COMPARATOR					
Delay to output	COMP step 5 V to 0 V, Time to onset of OUT_A transition low		40		ns
Duty cycle range		0		80	%
COMP to PWM offset		0.7	1	1.3	V
COMP open circuit voltage		4.3		5.9	V
COMP short circuit current	COMP = 0 V	0.6	1	1.4	mA
VOLT x SECOND CLAMP					
Ramp clamp level	Delta RAMP measured from onset of OUT_A to ramp peak, COMP = 5 V	2.4	2.5	2.6	V
UVLO SHUTDOWN					
Undervoltage shutdown threshold		2.44	2.5	2.56	V
Undervoltage shutdown hysteresis		16	20	24	μA
OUTPUT SECTION					
OUT_A high saturation	MOS device at $I_{OUT} = -10\text{ mA}$		5	10	Ω
OUTPUT_A peak current sink	Bipolar device at $V_{CC}/2$		3		A
OUT_A low saturation	MOS device at $I_{OUT} = 10\text{ mA}$		6	9	Ω
OUTPUT_A rise time	$C_{GATE} = 2.2\text{ nF}$		20		ns
OUTPUT_A fall time	$C_{GATE} = 2.2\text{ nF}$		15		ns
OUT_B high saturation	MOS device at $I_{OUT} = -10\text{ mA}$		10	20	Ω
OUTPUT_B peak current sink	Bipolar device at $V_{CC}/2$		1		A
OUT_B low saturation	MOS device at $I_{OUT} = 10\text{ mA}$		12	18	Ω
OUTPUT_B rise time	$C_{GATE} = 1\text{ nF}$		20		ns
OUTPUT_B fall time	$C_{GATE} = 1\text{ nF}$		15		ns
OUTPUT TIMING CONTROL					
Overlap time	$R_{SET} = 38\text{ k}\Omega$ connected to GND, 50% to 50% transitions	75	105	135	ns
Deadtime	$R_{SET} = 29.5\text{ k}\Omega$ connected to REF, 50% to 50% transitions	75	105	135	ns
THERMAL SHUTDOWN					
T_{SD} Thermal shutdown threshold			165		$^\circ\text{C}$
Thermal shutdown hysteresis			25		$^\circ\text{C}$

6.6 Typical Performance Characteristics

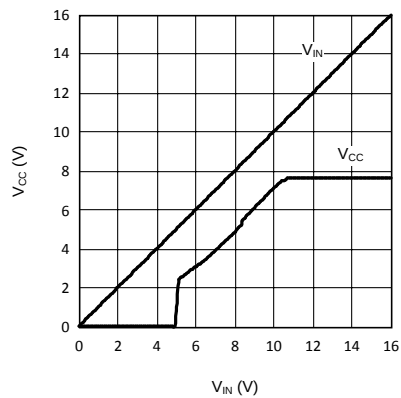


Figure 1. V_{CC} Regulator Start-up Characteristics, V_{CC} vs V_{IN}

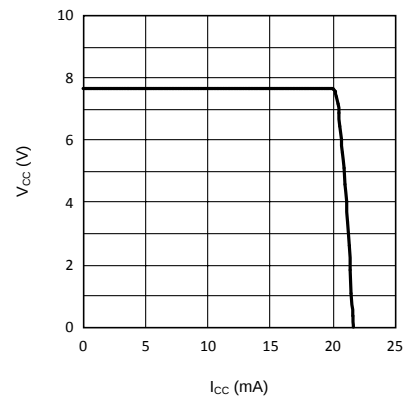


Figure 2. V_{CC} vs I_{CC}

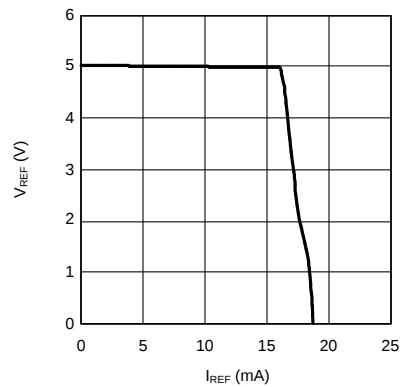


Figure 3. V_{REF} vs I_{REF}

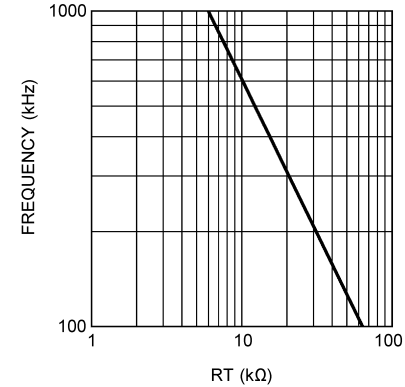


Figure 4. Oscillator Frequency vs R_T

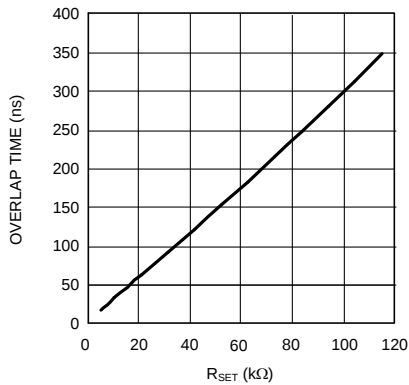


Figure 5. Overlap Time vs R_{SET}

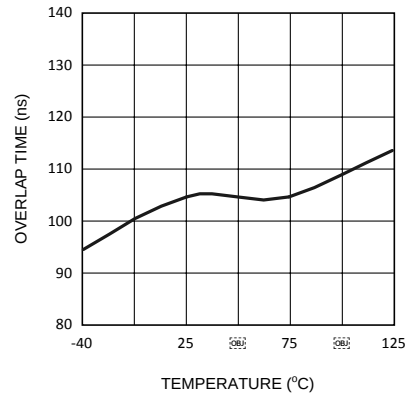


Figure 6. Overlap Time vs Temperature $R_{SET} = 38 \text{ k}\Omega$

Typical Performance Characteristics (continued)

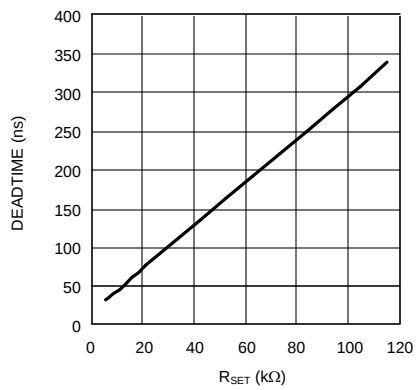


Figure 7. Dead Time vs R_{SET}

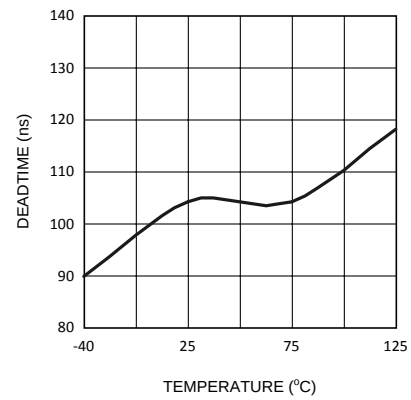


Figure 8. Dead Time vs Temperature R_{SET} = 29.5 kΩ

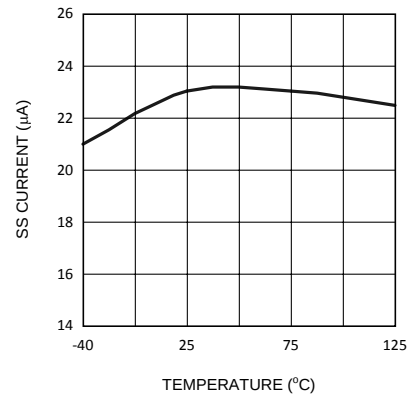


Figure 9. SS Pin Current vs Temperature

7 Detailed Description

7.1 Overview

The LM5025D is a functional variant of the LM5025 active clamp PWM controller. The functional differences of the LM5025D are:

- The CS1 and CS2 absolute maximum ratings have been increased to 7 V.
- The CS1 and CS2 current limit thresholds have been increased to 0.5 V.
- The internal CS2 filter discharge device has been disabled and no longer operates each clock cycle.
- The internal V_{CC} and V_{REF} regulators continue to operate when the line UVLO pin is below threshold.

The LM5025D PWM controller contains all of the features necessary to implement power converters utilizing the active clamp reset techniques. The device can be configured to control either a P-Channel clamp switch or an N-Channel clamp switch. With the active clamp technique higher efficiencies and greater power densities can be realized compared to conventional catch winding or RDC clamp / reset techniques. Two control outputs are provided, the main power switch control (OUT_A) and the active clamp switch control (OUT_B). The active clamp output can be configured for either a specified overlap time (for P-Channel switch applications) or a specified dead time (for N_Channel applications). The two internal compound gate drivers parallel both MOS and Bipolar devices, providing superior gate drive characteristics. This controller is designed for high-speed operation including an oscillator frequency range up to 1 MHz and total PWM and current sense propagation delays less than 100 ns. The LM5025D includes a high-voltage, start-up regulator that operates over a wide input range of 13 V to 90 V. Additional features include: Line Under-Voltage Lockout (UVLO), softstart, oscillator UP/DOWN sync capability, precision reference and thermal shutdown.

7.2 Functional Block Diagram

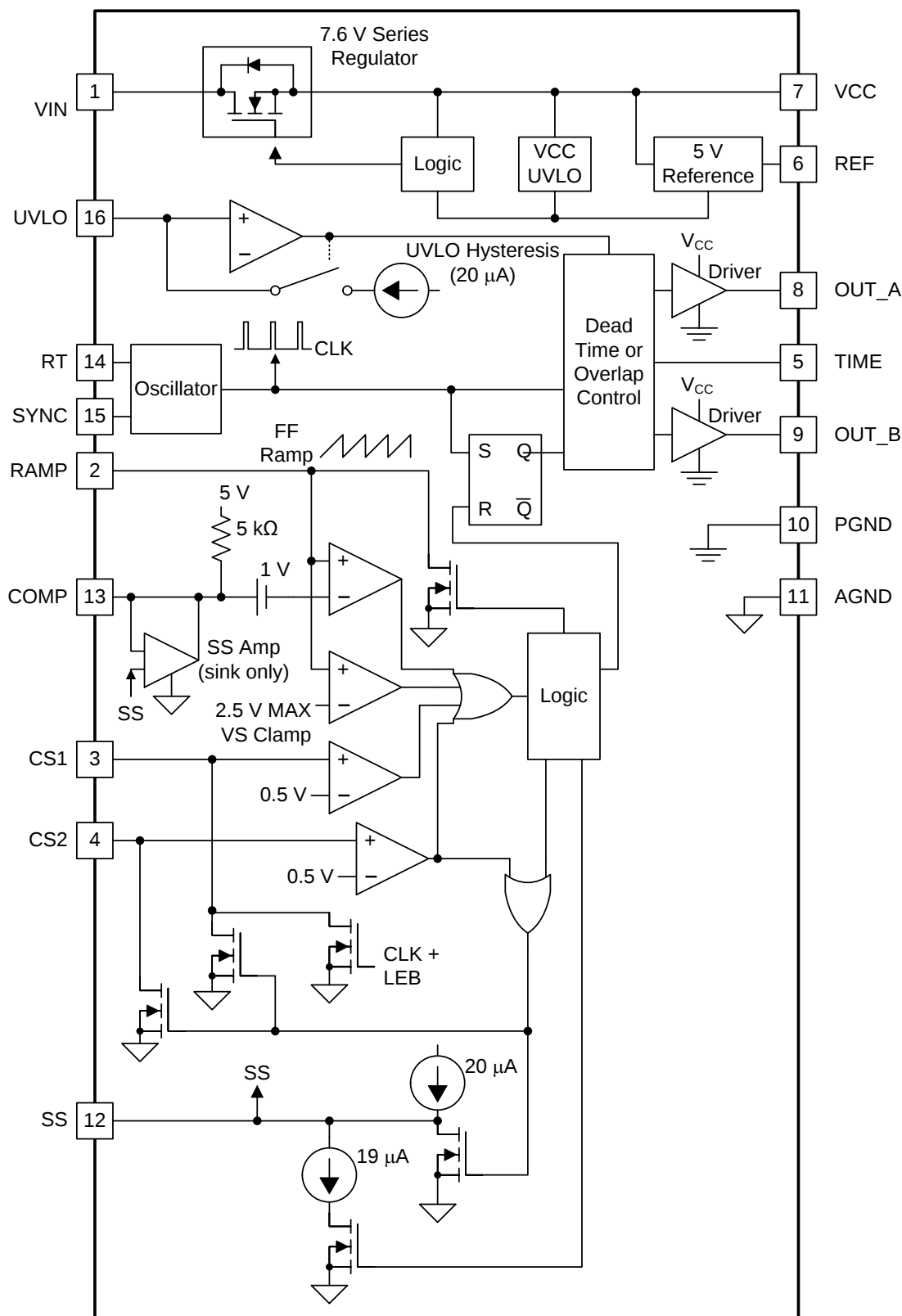


Figure 10. Simplified Block Diagram

7.3 Feature Description

7.3.1 High Voltage Start-Up Regulator

The LM5025D contains an internal high voltage start-up regulator that allows the input pin (V_{IN}) to be connected directly to the line voltage. The regulator output is internally current limited to 20 mA. When power is applied, the regulator is enabled and sources current into an external capacitor connected to the V_{CC} pin. The recommended capacitance range for the V_{CC} regulator is 0.1 μ F to 100 μ F. When the voltage on the V_{CC} pin reaches the regulation point of 7.6 V and the internal voltage reference (REF) reaches its regulation point of 5 V, the controller outputs are enabled. The outputs remain enabled until V_{CC} falls below 6.2 V or the line Under-Voltage Lock Out detector indicates that V_{IN} is out of range. In typical applications, an auxiliary transformer winding is connected through a diode to the V_{CC} pin. This winding must raise the V_{CC} voltage above 8 V to shut off the internal start-up regulator. Powering V_{CC} from an auxiliary winding improves efficiency while reducing the controller power dissipation.

When the converter auxiliary winding is inactive, external current draw on the V_{CC} line should be limited so the power dissipated in the start-up regulator does not exceed the maximum power dissipation of the controller.

An external start-up regulator or other bias rail can be used instead of the internal start-up regulator by connecting the V_{CC} and the V_{IN} pins together and feeding the external bias voltage into the two pins.

7.3.2 Line Under-Voltage Detector

The LM5025D contains a line Under-Voltage Lock Out (UVLO) circuit. An external set-point voltage divider from V_{IN} to GND, sets the operational range of the converter. The divider must be designed such that the voltage at the UVLO pin is greater than 2.5 V when V_{IN} is in the desired operating range. If the undervoltage threshold is not met, both outputs are disabled, all other functions of the controller remain active. UVLO hysteresis is accomplished with an internal 20- μ A current source that is switched on or off into the impedance of the set-point divider. When the UVLO threshold is exceeded, the current source is activated to instantly raise the voltage at the UVLO pin. When the UVLO pin voltage falls below the 2.5 V threshold, the current source is turned off causing the voltage at the UVLO pin to fall. The UVLO pin can also be used to implement a remote enable / disable function. Pulling the UVLO pin below the 2.5 V threshold disables the PWM outputs.

7.3.3 PWM Outputs

The relative phase of the main (OUT_A) and active clamp outputs (OUT_B) can be configured for the specific application. For active clamp configurations utilizing a ground referenced P-Channel clamp switch, the two outputs should be in phase with the active clamp output overlapping the main output. For active clamp configurations utilizing a high-side, N-Channel switch, the active clamp output should be out of phase with main output and there should be a dead time between the two gate drive pulses. A distinguishing feature of the LM5025D is the ability to accurately configure either dead time (both off) or overlap time (both on) of the gate driver outputs. The overlap / deadtime magnitude is controlled by the resistor value connected to the TIME pin of the controller. The opposite end of the resistor can be connected to either REF for deadtime control or GND for overlap control. The internal configuration detector senses the connection and configures the phase relationship of the main and active clamp outputs.

Feature Description (continued)

7.3.4 Compound Gate Drivers

The LM5025D contains two unique compound gate drivers, which parallel both MOS and Bipolar devices to provide high drive current throughout the entire switching event. The Bipolar device provides most of the drive current capability and provides a relatively constant sink current which is ideal for driving large power MOSFETs. As the switching event nears conclusion and the Bipolar device saturates, the internal MOS device continues to provide a low impedance to complete the switching event.

During turn-off at the Miller plateau region, typically around 2 V to 3 V, is where gate-driver current capability is needed most. The resistive characteristics of all MOS gate drivers are adequate for turn-on since the supply to output voltage differential is fairly large at the Miller region. During turn-off however, the voltage differential is small and the current source characteristic of the Bipolar gate driver is beneficial to provide fast drive capability.

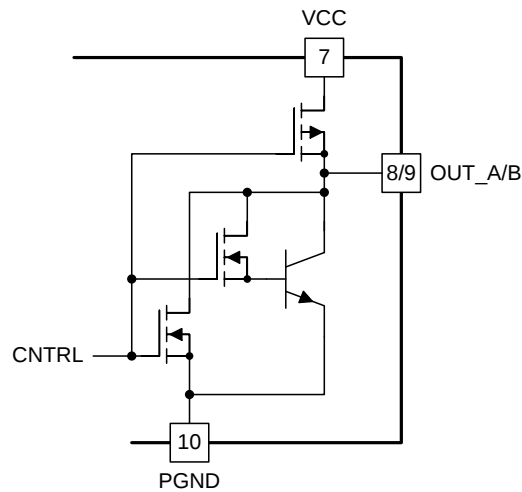


Figure 11. Compound Gate Drivers

7.3.5 PWM Comparator

The PWM comparator compares the ramp signal (RAMP) to the loop error signal (COMP). This comparator is optimized for speed in order to achieve minimum controllable duty cycles. The internal 5-k Ω pull-up resistor, connected between the internal 5-V reference and COMP, can be used as the pull-up for an optocoupler. The comparator polarity is such that 0 V on the COMP pin produces a zero duty cycle on both gate driver outputs.

7.3.6 Volt Second Clamp

The Volt x Second Clamp comparator compares the ramp signal (RAMP) to a fixed 2.5-V reference. By proper selection of RFF and CFF, the maximum ON time of the main switch can be set to the desired duration. The ON time set by Volt x Second Clamp varies inversely with the line voltage because the RAMP capacitor is charged by a resistor connected to V_{IN} while the threshold of the clamp is a fixed voltage (2.5 V).

The C_{FF} ramp capacitor is discharged at the conclusion of every cycle by an internal discharge switch controlled by either the internal clock or by the V x S Clamp comparator, whichever event occurs first.

Feature Description (continued)

7.3.7 Current Limit

The LM5025D contains two modes of over-current protection. If the sense voltage at the CS1 input exceeds 0.5 V the present power cycle is terminated (cycle-by-cycle current limit). If the sense voltage at the CS2 input exceeds 0.5 V, the controller terminates the present cycle, discharge the softstart capacitor and reduce the softstart current source to 1 μ A. The softstart (SS) capacitor is released after being fully discharged and slowly charges with a 1- μ A current source. When the voltage at the SS pin reaches approximately 1 V, the PWM comparator produces the first output pulse at OUT_A. After the first pulse occurs, the softstart current source reverts to the normal 20- μ A level. Fully discharging and then slowly charging the SS capacitor protects a continuously over-loaded converter with a low duty-cycle hiccup mode.

These two modes of over-current protection allow the user great flexibility to configure the system behavior in over-load conditions. If it is desired for the system to act as a current source during an over-load, then the CS1 cycle-by-cycle current limiting should be used. In this case the current sense signal should be applied to the CS1 input and the CS2 input should be grounded. If during an overload condition it is desired for the system to briefly shutdown, followed by softstart retry, then the CS2 hiccup current limiting mode should be used. In this case the current sense signal should be applied to the CS2 input and the CS1 input should be grounded. This shutdown / soft-start retry repeats indefinitely while the over-load condition remains. The hiccup mode will greatly reduce the thermal stresses to the system during heavy overloads. The cycle-by-cycle mode has higher system thermal dissipations during heavy overloads, but provides the advantage of continuous operation for short duration overload conditions.

It is possible to utilize both over-current modes concurrently, whereby slight overload conditions activate the CS1 cycle-by-cycle mode while more severe overloading activates the CS2 hiccup mode. Generally the CS1 input is configured to monitor the main switch FET current of each cycle. The CS2 input can be configured in several different ways depending upon the system requirements.

- The CS2 input can also be set to monitor the main switch FET current except scaled to a higher threshold than CS1.
- An external over-current timer can be configured which trips after a pre-determined over-current time, driving the CS2 input high, initiating a hiccup event.
- In a closed loop voltage regulation system, the COMP input rises to saturation when the cycle-by-cycle current limit is active. An external filter/delay timer and voltage divider can be configured between the COMP pin and the CS2 pin to scale and delay the COMP voltage. If the CS2 pin voltage reaches 0.5 V a hiccup event initiates.

A small RC filter, located near the controller, is recommended for each of the CS pins. The CS1 input has an internal FET which discharges the current sense filter capacitor at the conclusion of every cycle, to improve dynamic performance. This same FET remains on an additional 50 ns at the start of each main switch cycle to attenuate the leading edge spike in the current sense signal. The CS2 discharge FET only operates following a CS2 event, UVLO and thermal shutdown.

Feature Description (continued)

The LM5025D CS comparators are very fast and may respond to short duration noise pulses. Layout considerations are critical for the current sense filter and sense resistor. The capacitor associated with the CS filter must be placed very close to the device and connected directly to the pins of the device (CS and GND). If a current sense transformer is used, both leads of the transformer secondary should be routed to the filter network, which should be located close to the device. If a sense resistor in the source of the main switch MOSFET is used for current sensing, a low inductance type of resistor is required. When designing with a current sense resistor, all of the noise sensitive low power ground connections should be connected together near the device GND and a single connection should be made to the power ground (sense resistor ground point).

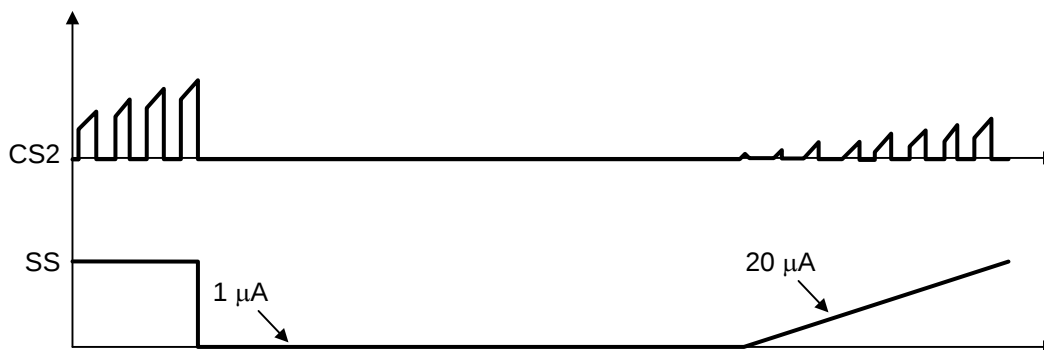


Figure 12. Current Limit

Feature Description (continued)

7.3.8 Oscillator and Sync Capability

The LM5025D oscillator is set by a single external resistor connected between the RT pin and GND. The RT resistor should be located very close to the device and connected directly to the pins of the device (RT and GND).

A unique feature of LM5025D is the ability to synchronize the oscillator to an external clock with a frequency that is either higher or lower than the frequency of the internal oscillator. The lower frequency sync frequency range is 80% of the free running internal oscillator frequency. There is no constraint on the maximum SYNC frequency. A minimum pulse width of 100 ns is required for the synchronization clock. If the synchronization feature is not required, the SYNC pin should be connected to GND to prevent any abnormal interference. The internal oscillator can be completely disabled by connecting the RT pin to REF. Once disabled, the sync signal acts directly as the master clock for the controller. Both the frequency and the maximum duty cycle of the PWM controller can be controlled by the SYNC signal (within the limitations of the Volt x Second Clamp). The maximum duty cycle (D) is (1-D) of the SYNC signal.

7.3.9 Feed-Forward Ramp

An external resistor (R_{FF}) and capacitor (C_{FF}) connected to V_{IN} and GND are required to create the PWM ramp signal. The slope of the signal at the RAMP pin varies in proportion to the input line voltage. This varying slope provides line feedforward information necessary to improve line transient response with voltage mode control. The RAMP signal is compared to the error signal at the COMP pin by the pulse width modulator comparator to control the duty cycle of the main switch output. The volt second clamp comparator also monitors the RAMP pin and if the ramp amplitude exceeds 2.5 V the present cycle is terminated. The ramp signal is reset to GND at the end of each cycle by either the internal clock or the volt second comparator, whichever occurs first.

7.3.10 Soft-Start

The softstart feature allows the power converter to gradually reach the initial steady state operating point, thus reducing start-up stresses and surges. At power on, a 20- μ A current is sourced out of the softstart pin (SS) into an external capacitor. The capacitor voltage ramps up slowly and limits the COMP pin voltage and therefore the PWM duty cycle. In the event of a fault as determined by V_{CC} undervoltage, line undervoltage (UVLO) or second level current limit, the output gate drivers are disabled and the softstart capacitor is fully discharged. When the fault condition is no longer present a softstart sequence is initiated. Following a second level current limit detection (CS2), the softstart current source is reduced to 1 μ A until the first output pulse is generated by the PWM comparator. The current source returns to the nominal 20 μ A level after the first output pulse (~1 V at the SS pin).

7.3.11 Thermal Protection

Internal thermal shutdown circuitry is provided to protect the integrated circuit in the event the maximum junction temperature is exceeded. When activated, typically at 165°C, the controller is forced into a low-power standby state with the output drivers and the bias regulator disabled. The device restarts after the thermal hysteresis (typically 25°C). During a restart after thermal shutdown, the softstart capacitor is fully discharged and then charged in the low current mode (1 μ A) similar to a second level current limit event. The thermal protection feature is provided to prevent catastrophic failures from accidental device overheating.

7.4 Device Functional Modes

The LM5025D active clamp voltage mode PWM controller has six functional modes. The modes transition diagram is shown below.

- UVLO Mode
- Soft-Start Mode
- Normal Operation Mode
- Cycle-by-Cycle Current Limit Mode
- Hiccup Mode
- Thermal Shut Down Mode

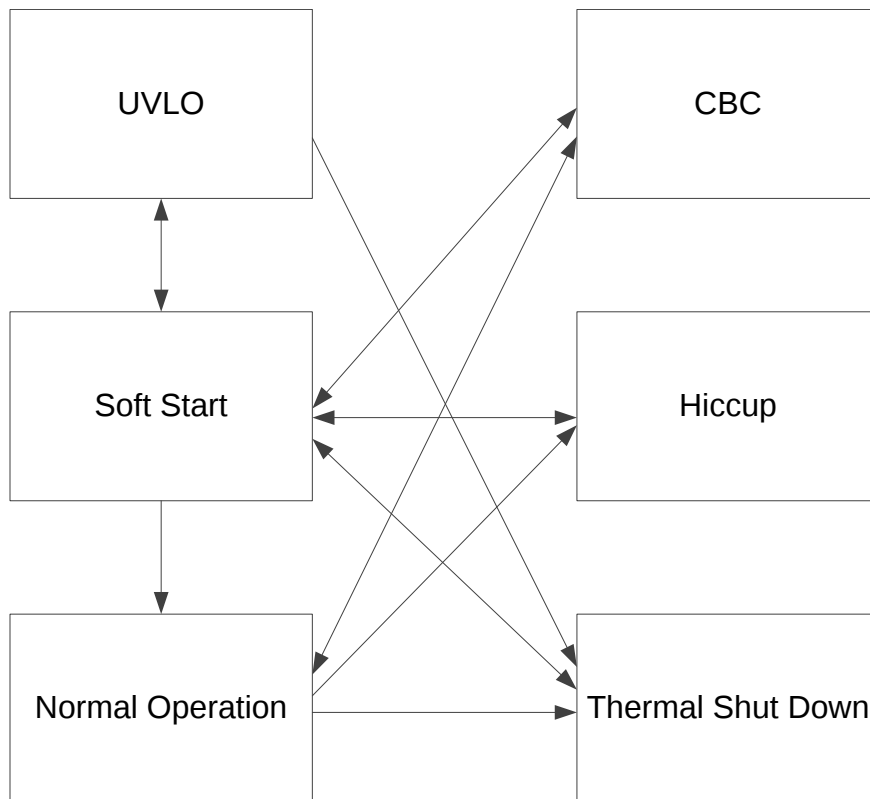


Figure 13. Functional Mode Transition Diagram

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LM5025D PWM controller contains all of the features necessary to implement power converters utilizing the Active Clamp and Reset technique. This section provides design guidance for a typical active clamp forward converter design. Design requirements and detailed design procedure are described in [Design Requirements](#) and [Application Curves](#). Application curves are given in Section 8.2.3. An actual application schematic of a 36-V to 78-V input, 3.3-V, 30-A output active clamp forward converter is also provided.

8.2 Typical Application

[Figure 14](#) shows a simplified schematic of an active clamp forward power converter.

Power converters based on the Forward topology offer high efficiency and good power handling capability in applications up to several hundred Watts. The operation of the transformer in a forward topology does not inherently self-reset each power switching cycle, a mechanism to reset the transformer is required. The active clamp reset mechanism is presently finding extensive use in medium level power converters in the 50 W to 200 W range.

The Forward converter is derived from the Buck topology family, employing a single modulating power switch. The main difference between the topologies is the forward topology employs a transformer to provide input/output ground isolation and a step down or step up function.

Each cycle, the main primary switch turns on and applies the input voltage across the primary winding. The transformer turns the voltage to a lower level on the secondary side. The clamp capacitor along with the reset switch reverse biases the transformer primary each cycle when the main switch turns off. This reverse voltage resets the transformer. The clamp capacitor voltage is $V_{IN} / (1-D)$.

The secondary rectification employs self-driven synchronous rectification to maintain high efficiency and ease of drive.

Feedback from the output is processed by an amplifier and reference, generating an error voltage, which is coupled back to the primary side control through an opto-coupler. The LM5025D voltage mode controller pulse width modulates the error signal with a ramp signal derived from the input voltage. Deriving the ramp signal slope from the input voltage provides line feed-forward, which improves line transient rejection. The LM5025D also provides a controlled delay necessary for the reset switch.

Typical Application (continued)

8.2.1 Design Requirements

This typical application provides an example of a fully-functional power converter based on the Active Clamp Forward topology in an industry standard half-brick footprint.

The design requirements are:

- Input Range: 36 V to 78 V (100 V peak)
- Output Voltage: 3.3 V
- Output Current: 0 A to 30 A
- Measured Efficiency: 90.5% at 30 A, 92.5% at 15 A
- Frequency of Operation: 230 kHz
- Board Size: 2.3 x 2.4 x 0.5 inches
- Load Regulation: 1%
- Line Regulation: 0.1%
- Line UVLO, Hiccup Current Limit

8.2.2 Detailed Design Procedure

Before the controller design begins, the power stage design must be completed. This chapter describes the calculations needed to configure the LM5025D controller to meet the power stage design requirements.

8.2.2.1 Oscillator

The desired switching frequency F is set by a resistor connected between RT pin and ground. The resistance value R_T is calculated from:

$$R_T = (5725/F)^{1.026}$$

where

- F is in kHz and R_T in k Ω . (1)

8.2.2.2 Soft-Start Ramp Time and Hiccup Interval

The soft-start ramp time and hiccup interval is programmed by a capacitor (C_{SS}) on the SS pin to ground. The soft-start ramp time is determined by comparing the SS pin voltage with COMP pin voltage. When the SS voltage is less than COMP voltage, the COMP voltage is clamped by SS voltage. The PWM duty is limited by the clamped COMP voltage, so that soft start can be achieved. The first PWM pulse is generated after COMP voltage reaches 1 V. So the soft-start ramp time of the output voltage can be estimated by:

$$T_{SS}(\text{ms}) = C_{SS}(\text{nF}) \times \frac{V_{SS} - 1\text{V}}{20\mu\text{A}}$$

where

- V_{SS} is the steady state COMP pin voltage. This voltage is determined by the output voltage, voltage divider, and the compensation network. (2)

In hiccup mode, the SS current source is reduced to 1 μA . When the first PWM pulse is generated, the current source switches to 20 μA , and the power supply tries to start up again. The hiccup interval can be calculated by:

$$T_{\text{hiccup}}(\text{ms}) = C_{SS}(\text{nF}) \times \frac{1\text{V}}{1\mu\text{A}} \quad (3)$$

Typical Application (continued)

8.2.2.3 Feed-Forward Ramp and Maximum On Time Clamp

An example illustrates the use of the Volt x Second Clamp comparator to achieve a 50% duty cycle limit, at 200kHz, at a 48-V line input: A 50% duty cycle at a 200 KHz requires a 2.5 μ s of ON time. At 48-V input the Volt x Second product is 120 V x μ s (48 V x 2.5 μ s). To achieve this clamp level:

$$R_{FF} \times C_{FF} = V_{IN} \times T_{ON} / 2.5V \quad (4)$$

$$48 \times 2.5 \mu F / 2.5 = 48 \mu F \quad (5)$$

Select $C_{FF} = 470$ pF

$R_{FF} = 102$ k Ω

The recommended capacitor value range for C_{FF} is 100 pF to 1000 pF.

8.2.2.4 Dead Times

The magnitude of the overlap/dead time can be calculated as follows:

$$\text{Overlap Time (ns)} = 2.8 \times R_{SET} - 1.2$$

$$\text{Dead Time (ns)} = 2.9 \times R_{SET} + 20$$

R_{SET} in k Ω , Time in ns

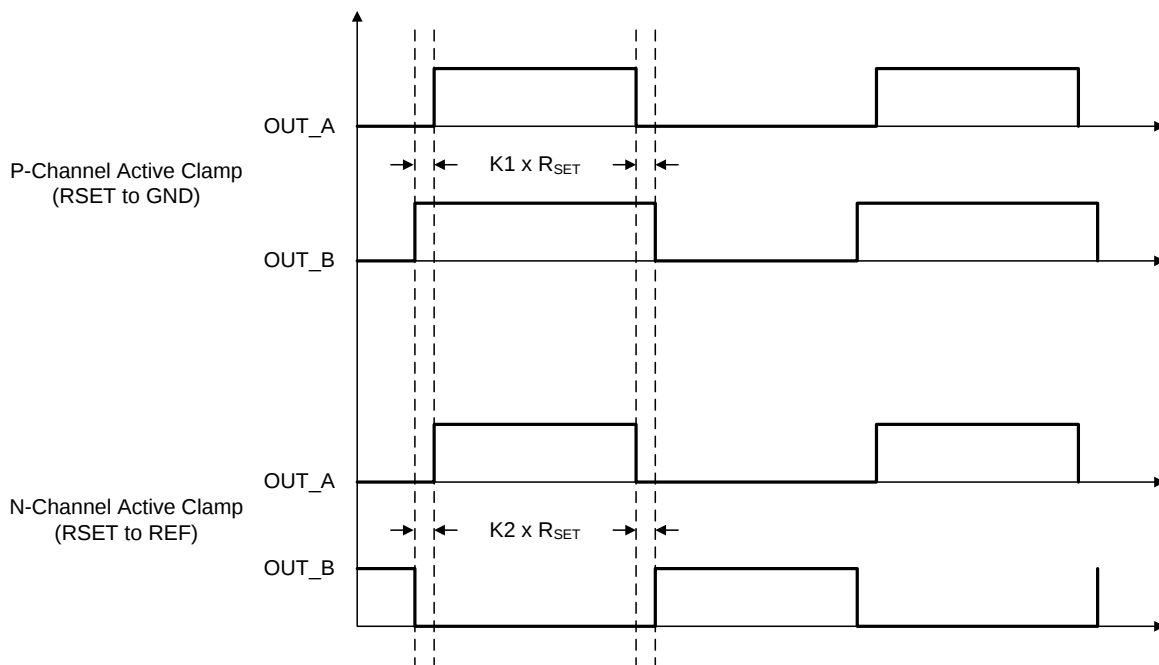
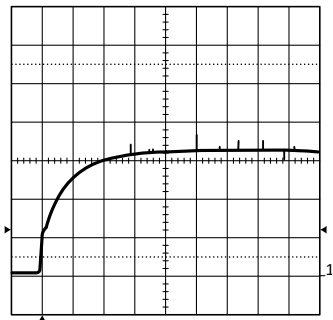


Figure 15. PWM Outputs

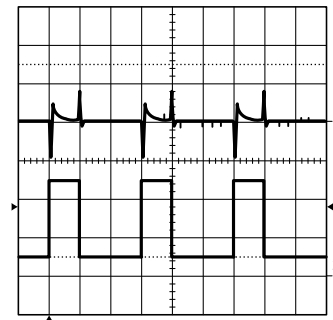
Typical Application (continued)

8.2.3 Application Curves



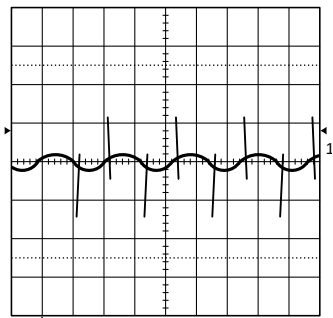
Conditions: Input Voltage = 48 VDC, Output Current = 5 A
Trace 1: Output Voltage Volts/div = 0.5 V
Horizontal Resolution = 1 msec/div

Figure 16. Output Voltage During Typical Startup



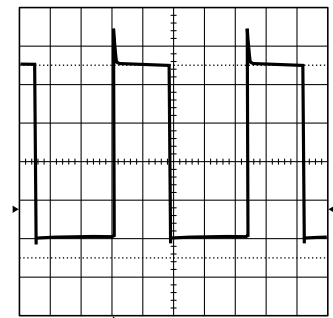
Conditions: Input Voltage = 48 VDC, Output Current = 5 A to 25 A
Trace 1: Output Voltage Volts/div = 0.5 V
Trace 2: Output Current, Amps/div = 10.0 A
Horizontal Resolution = 1 μ s/div

Figure 17. Transient Response



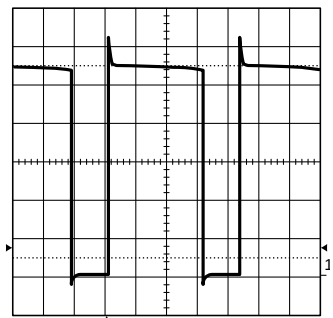
Conditions: Input Voltage = 48 VDC, Output Current = 30 A
Bandwidth Limit = 25 MHz
Trace 1: Output Ripple Voltage Volts/div = 50 mV
Horizontal Resolution = 2 μ s/div

Figure 18. Output Ripple



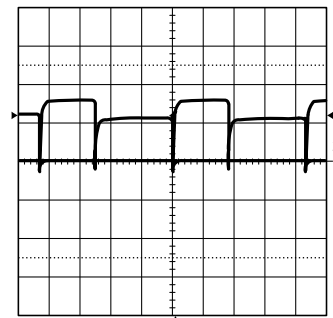
Conditions: Input Voltage = 38 VDC, Output Current = 25 A
Trace 1: Q1 drain voltage Volts/div = 20 V
Horizontal Resolution = 1 μ s/div

Figure 19. Drain Voltage



Conditions: Input Voltage = 78 VDC, Output Current = 25 A
Trace 1: Q1 drain voltage Volts/div = 20 V
Horizontal Resolution = 1 μ s/div

Figure 20. Drain Voltage



Conditions: Input Voltage = 48 VDC, Output Current = 5 A
Synchronous rectifier, Q3 gate Volts/div = 5 V
Trace 1: Synchronous rectifier, Q3 gate Volts/div = 5 V
Trace 2: Synchronous rectifier, Q5 gate Volts/div = 5 V
Horizontal Resolution = 1 μ s/div

Figure 21. Gate Voltages of the Synchronous Rectifiers

8.3 System Examples

Shown below is an application circuit with 36-V to 78-V input and 3.3-V, 30-A output capability.

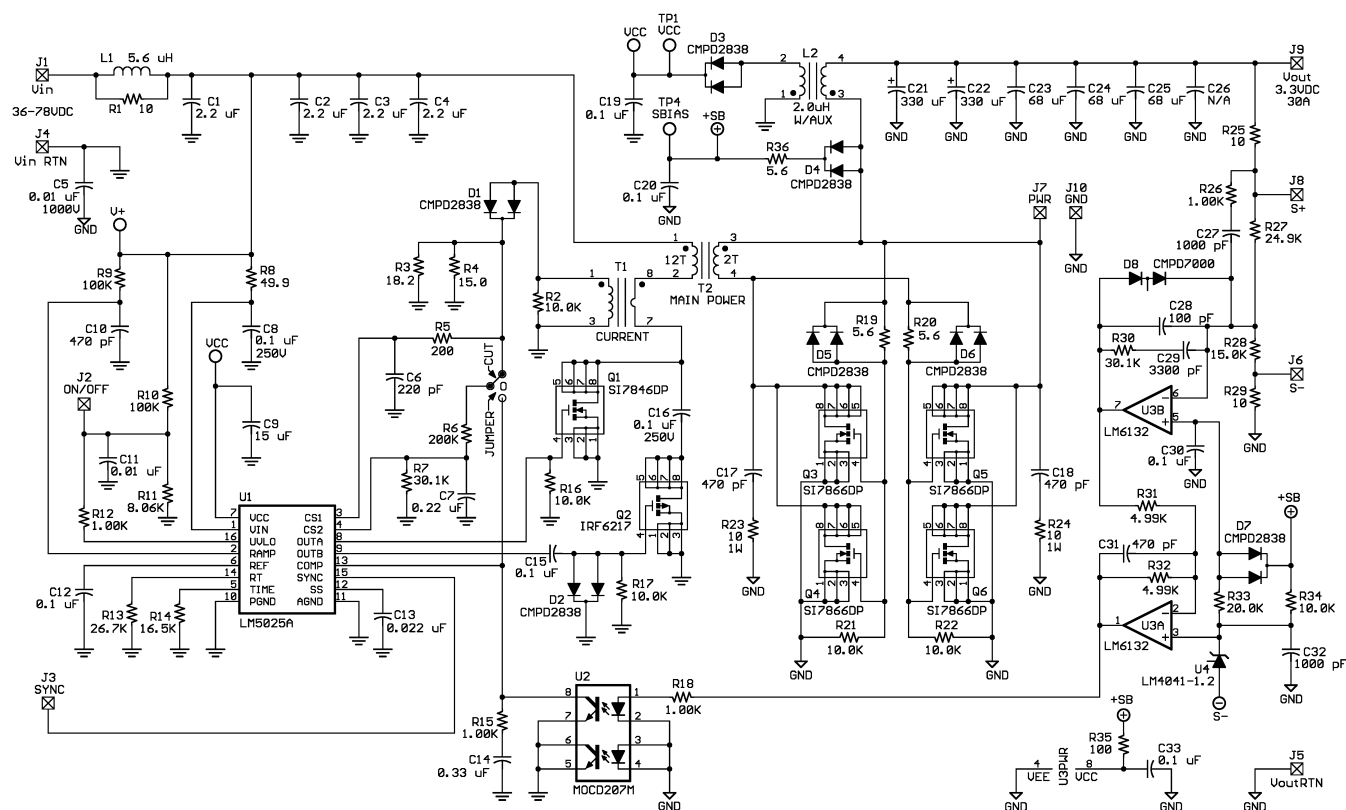


Figure 22. Application Circuit

9 Power Supply Recommendations

V_{CC} pin is the power supply for the device. There should be a 0.1- μ F~100- μ F capacitor directly from V_{CC} to ground. REF pin should be by-passed to ground as close as possible to the device using a 0.1- μ F capacitor.

10 Layout

10.1 Layout Guidelines

- Connect two grounds PGND (power ground) and AGND (analog ground) directly as device ground ICGND. The connection should be as close to the pins as possible.
- If there are multiple PCB layers and there is a inner ground layer, use two vias or one big via on GND and connect them to the inner ground layer (ICGND).
- The power stage ground PSGND should be separated with the ICGND. PSGND and ICGND should be connected at a single point close to the device.
- The bypass capacitors to the V_{CC} pin and REF pin should be as close as possible to the pins and ground (ICGND).
- The filtering capacitors connected to CS1 and CS2 pins should have connections as short as possible to ICGND; if an inner ground layer is available, use vias to connect the capacitors to the ground layer (ICGND).
- The resistors and capacitors connected to the timing configuration pins should be as close as possible to the pins and ground (ICGND).

10.2 Layout Example

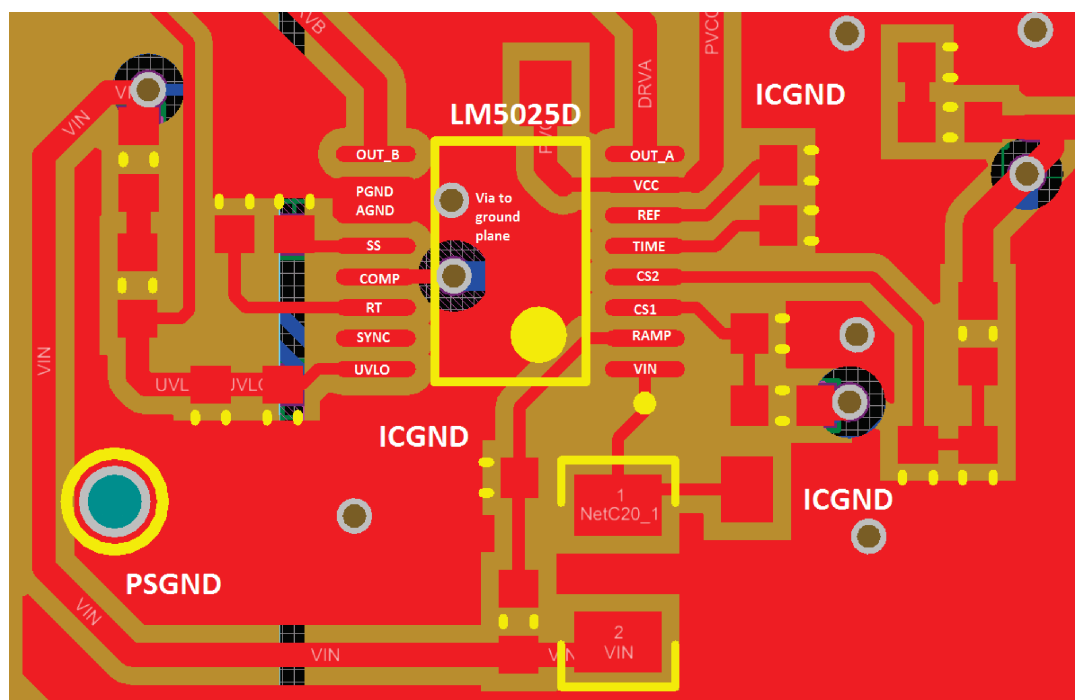


Figure 23. Layout Example

11 Device and Documentation Support

11.1 Trademarks

All trademarks are the property of their respective owners.

11.2 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.3 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
LM5025DMTC/NOPB	LIFEBUY	TSSOP	PW	16	92	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	L5025D MTC	
LM5025DMTCX/NOPB	LIFEBUY	TSSOP	PW	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	L5025D MTC	

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

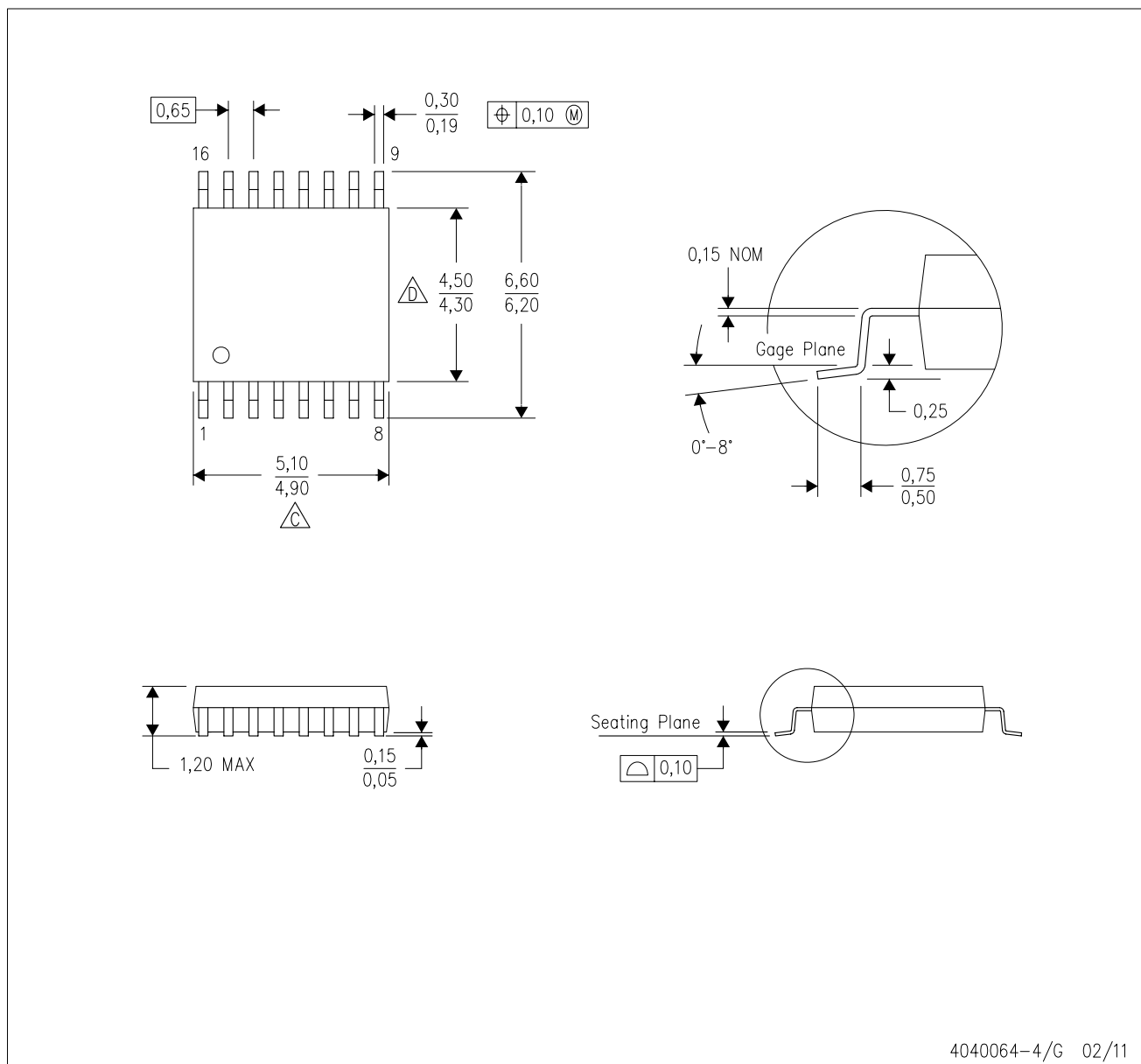
(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PW (R-PDSO-G16)

PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - B. This drawing is subject to change without notice.
 - C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
 - D. Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
 - E. Falls within JEDEC MO-153

IMPORTANT NOTICE

Texas Instruments Incorporated (TI) reserves the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete.

TI's published terms of sale for semiconductor products (<http://www.ti.com/sc/docs/stdterms.htm>) apply to the sale of packaged integrated circuit products that TI has qualified and released to market. Additional terms may apply to the use or sale of other types of TI products and services.

Reproduction of significant portions of TI information in TI data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such reproduced documentation. Information of third parties may be subject to additional restrictions. Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyers and others who are developing systems that incorporate TI products (collectively, "Designers") understand and agree that Designers remain responsible for using their independent analysis, evaluation and judgment in designing their applications and that Designers have full and exclusive responsibility to assure the safety of Designers' applications and compliance of their applications (and of all TI products used in or for Designers' applications) with all applicable regulations, laws and other applicable requirements. Designer represents that, with respect to their applications, Designer has all the necessary expertise to create and implement safeguards that (1) anticipate dangerous consequences of failures, (2) monitor failures and their consequences, and (3) lessen the likelihood of failures that might cause harm and take appropriate actions. Designer agrees that prior to using or distributing any applications that include TI products, Designer will thoroughly test such applications and the functionality of such TI products as used in such applications.

TI's provision of technical, application or other design advice, quality characterization, reliability data or other services or information, including, but not limited to, reference designs and materials relating to evaluation modules, (collectively, "TI Resources") are intended to assist designers who are developing applications that incorporate TI products; by downloading, accessing or using TI Resources in any way, Designer (individually or, if Designer is acting on behalf of a company, Designer's company) agrees to use any particular TI Resource solely for this purpose and subject to the terms of this Notice.

TI's provision of TI Resources does not expand or otherwise alter TI's applicable published warranties or warranty disclaimers for TI products, and no additional obligations or liabilities arise from TI providing such TI Resources. TI reserves the right to make corrections, enhancements, improvements and other changes to its TI Resources. TI has not conducted any testing other than that specifically described in the published documentation for a particular TI Resource.

Designer is authorized to use, copy and modify any individual TI Resource only in connection with the development of applications that include the TI product(s) identified in such TI Resource. NO OTHER LICENSE, EXPRESS OR IMPLIED, BY ESTOPPEL OR OTHERWISE TO ANY OTHER TI INTELLECTUAL PROPERTY RIGHT, AND NO LICENSE TO ANY TECHNOLOGY OR INTELLECTUAL PROPERTY RIGHT OF TI OR ANY THIRD PARTY IS GRANTED HEREIN, including but not limited to any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information regarding or referencing third-party products or services does not constitute a license to use such products or services, or a warranty or endorsement thereof. Use of TI Resources may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

TI RESOURCES ARE PROVIDED "AS IS" AND WITH ALL FAULTS. TI DISCLAIMS ALL OTHER WARRANTIES OR REPRESENTATIONS, EXPRESS OR IMPLIED, REGARDING RESOURCES OR USE THEREOF, INCLUDING BUT NOT LIMITED TO ACCURACY OR COMPLETENESS, TITLE, ANY EPIDEMIC FAILURE WARRANTY AND ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, AND NON-INFRINGEMENT OF ANY THIRD PARTY INTELLECTUAL PROPERTY RIGHTS. TI SHALL NOT BE LIABLE FOR AND SHALL NOT DEFEND OR INDEMNIFY DESIGNER AGAINST ANY CLAIM, INCLUDING BUT NOT LIMITED TO ANY INFRINGEMENT CLAIM THAT RELATES TO OR IS BASED ON ANY COMBINATION OF PRODUCTS EVEN IF DESCRIBED IN TI RESOURCES OR OTHERWISE. IN NO EVENT SHALL TI BE LIABLE FOR ANY ACTUAL, DIRECT, SPECIAL, COLLATERAL, INDIRECT, PUNITIVE, INCIDENTAL, CONSEQUENTIAL OR EXEMPLARY DAMAGES IN CONNECTION WITH OR ARISING OUT OF TI RESOURCES OR USE THEREOF, AND REGARDLESS OF WHETHER TI HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.

Unless TI has explicitly designated an individual product as meeting the requirements of a particular industry standard (e.g., ISO/TS 16949 and ISO 26262), TI is not responsible for any failure to meet such industry standard requirements.

Where TI specifically promotes products as facilitating functional safety or as compliant with industry functional safety standards, such products are intended to help enable customers to design and create their own applications that meet applicable functional safety standards and requirements. Using products in an application does not by itself establish any safety features in the application. Designers must ensure compliance with safety-related requirements and standards applicable to their applications. Designer may not use any TI products in life-critical medical equipment unless authorized officers of the parties have executed a special contract specifically governing such use. Life-critical medical equipment is medical equipment where failure of such equipment would cause serious bodily injury or death (e.g., life support, pacemakers, defibrillators, heart pumps, neurostimulators, and implantables). Such equipment includes, without limitation, all medical devices identified by the U.S. Food and Drug Administration as Class III devices and equivalent classifications outside the U.S.

TI may expressly designate certain products as completing a particular qualification (e.g., Q100, Military Grade, or Enhanced Product). Designers agree that it has the necessary expertise to select the product with the appropriate qualification designation for their applications and that proper product selection is at Designers' own risk. Designers are solely responsible for compliance with all legal and regulatory requirements in connection with such selection.

Designer will fully indemnify TI and its representatives against any damages, costs, losses, and/or liabilities arising out of Designer's non-compliance with the terms and provisions of this Notice.